

CSC 317: Data Structures and Algorithm Analysis

Dilip Sarkar

Department of Computer Science
University of Miami



Outline I

- What is Dynamic Programming?
- Dynamic Programming Example 1: Rod Cutting
 - Dynamic Programming Algorithm for Rod cutting Problem
 - Problem with top-down recursive approach
 - Bottom-up approach (dynamic programming)
- Dynamic Programming Example 2: Matrix-chain multiplication I
 - Matrix-Chain Multiplication
 - Dynamic Programming Formulation
 - Pseudocode for the Dynamic Programming Algorithm
 - Example of matrix-chain multiplication
- Dynamic Programming Example 3: Optimal Binary Search Tree (BST)
 - Keys have different search probabilities
 - Dynamic Programming Formulation for Optimal BST
 - Pseudocode for Dynamic Programming Algorithm
 - Optimal BST: An example

Divide-and-Conquer or **Dynamic-programming**

- Divide-and-Conquer method
 - Partition the input into **disjoint** subsets and solve them (recursively)
 - Combine solutions of the subproblems
- If recursive calls share input data, then same problem is solved multiple time (we will see an example)
- **Dynamic programming method**
 - Solve problems in a bottom-up fashion and store the solution
 - Avoids solving same subproblems repeatedly
 - Find **multiple solution for same input-size**, and store the best solutions
- Typically dynamic-programming is applied to **optimization problems**

Steps for developing dynamic-programming algorithm

Characterize the structure of an optimal solution

- ① Recursively define the value of an optimal solution
- ② Compute the value of an optimal solution, typically in a bottom-up fashion
- ③ Compute an optimal solution from previously computed solutions to smaller problems

Steps 1 to 3 form the basis of a dynamic-programming solution to a problem

These three steps are fine to know value of an optimal solution

- ④ Need a 4th step for reconstructing an optimal solution

Rod Cutting Problem

Given a rod of length n and price p_k , of a rod length k .

Price table for rods.

Length l_i	1	2	3	4	5	6	7	8	9	10
Price p_i	1	5	8	9	10	17	17	20	24	30

How many cuts are possible?

2^{10-1} ,

Because there are $(10 - 1)$ locations and we can choose to cut or not to cut

- Example for a rod of length 4

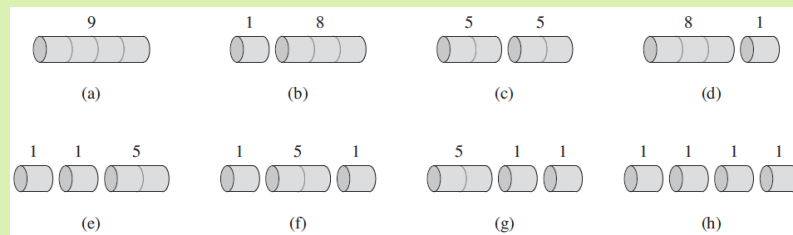


Figure: Possible cuts

- From the figure above, we can see that maximum revenue is 10

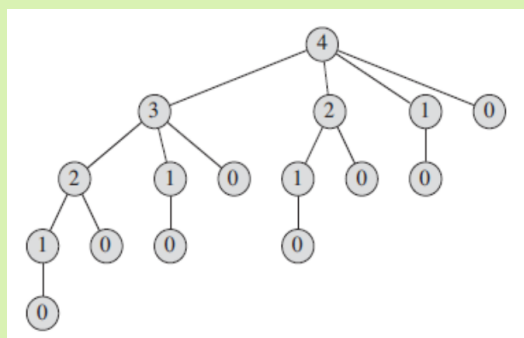
Problem with top-down recursive approach

A top-down recursive algorithm

```

CUT-ROD( $p, n$ )
1  if  $n == 0$ 
2    return 0
3   $q = -\infty$ 
4  for  $i = 1$  to  $n$ 
5     $q = \max(q, p[i] + \text{CUT-ROD}(p, n - i))$ 
6  return  $q$ 
    
```

Recursion tree



- We calculate max revenue for length 2 two times
- We calculate max revenue for length 1 four times
- We calculate max revenue for length 0 eight times
- We can **store max revenue for each length** in a table

Bottom-up approach (dynamic programming)

A bottom-up algorithm using a table for optimal values

```

BOTTOM-UP-CUT-ROD( $p, n$ )
1  let  $r[0..n]$  be a new array
2   $r[0] = 0$ 
3  for  $j = 1$  to  $n$ 
4       $q = -\infty$ 
5      for  $i = 1$  to  $j$ 
6           $q = \max(q, p[i] + r[j - i])$ 
7       $r[j] = q$ 
8  return  $r[n]$ 

```

Trace of the bottom-up algorithm

	i	1	2	3	4	5	Max revenue
j		-	-	-	-	-	
1a		$p(1)+r(0)$	-	-	-	-	
1b		1	-	-	-	-	1
2a		$p(1)+r(1)$	$p(2)+r(0)$	-	-	-	
2b		2	5	-	-	-	5
3a		$p(1)+r(2)$	$p(2)+r(1)$	$p(3)+r(0)$	-	-	
3b		6	6	8	-	-	8
4a		$p(1)+r(3)$	$p(2)+r(2)$	$p(3)+r(1)$	$p(4)+r(0)$	-	
4b		9	10	9	9	-	10
5a		$p(1)+r(4)$	$p(2)+r(3)$	$p(3)+r(2)$	$p(4)+r(1)$	$p(5)+r(0)$	
5b		11	13	13	10	10	13

Rod Cutting Problem: pseudo-code

A bottom-up algorithm using a table for optimal values and cut positions

```

EXTENDED-BOTTOM-UP-CUT-ROD( $p, n$ )
1  let  $r[0..n]$  and  $s[0..n]$  be new arrays
2   $r[0] = 0$ 
3  for  $j = 1$  to  $n$ 
4       $q = -\infty$ 
5      for  $i = 1$  to  $j$ 
6          if  $q < p[i] + r[j - i]$ 
7               $q = p[i] + r[j - i]$ 
8               $s[j] = i$ 
9       $r[j] = q$ 
10 return  $r$  and  $s$ 

```

Figure: Array 's' stores locations of the cut.

Complexity of matrix multiplication

Matrix multiplication algorithm

```

MATRIX-MULTIPLY(A, B)
1  if A.columns ≠ B.rows
2      error "incompatible dimensions"
3  else let C be a new A.rows × B.columns matrix
4      for i = 1 to A.rows
5          for j = 1 to B.columns
6              cij = 0
7              for k = 1 to A.columns
8                  cij = cij + aik · bkj
9  return C
    
```

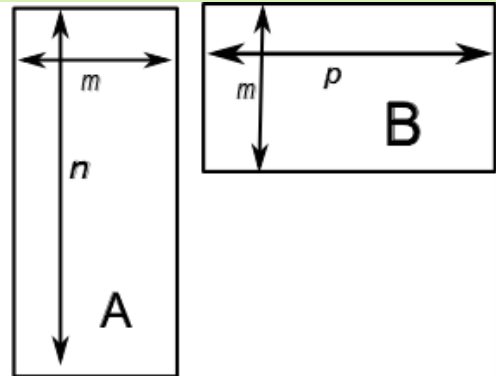


Figure: Matrix multiplication algorithm

If A is a $n \times m$ matrix and B is a $m \times p$ matrix then

Number of operations = $O(mnp)$ and for $m = n = p$, we have $O(n^3)$.

Matrix-chain multiplication

Let us consider four matrices:

A_1, A_2, A_3 , and A_4

Let $A = A_1 \times A_2 \times A_3 \times A_4$

- How many ways can we compute A ?
 - Recall the **Associative property** of matrix multiplication:
 - $A_1 \times (A_2 \times A_3) = (A_1 \times A_2) \times A_3$
- The answer is 5
 - $(A_1 \times (A_2 \times (A_3 \times A_4)))$,
 - $(A_1 \times ((A_2 \times A_3) \times A_4))$,
 - $((A_1 \times A_2) \times (A_3 \times A_4))$,
 - $((A_1 \times (A_2 \times A_3)) \times A_4)$, and
 - $((A_1 \times A_2) \times (A_3 \times A_4))$.

This relates to a counting problem: how many ways we can parenthesize a sequence of n matrices?

$$C(n) = \sum_{k=1}^{n-1} C(k) \cdot C(n-k) = \frac{1}{n+1} \binom{2n}{n} = \Omega\left(\frac{4^n}{n^{3/2}}\right)$$

Too complex to find optimal order of multiplications exhaustively.

Dynamic Programming formulation I

Let us develop a dynamic programming algorithm applying four steps:

- ① Characterize the structure of an optimal solution.
- ② Recursively define the value of an optimal solution.
- ③ Computer the value of an optimal solution.
- ④ Construct an optimal solution from computed information.

Notations: $A = A_1 \times A_2 \times \cdots \times A_n$

Matrix A_i is a $p_{i-1} \times p_i$ matrix.

Let $A_{i..j}$ be the product of sequence of matrix $(A_i, A_{i+1}, \cdots, A_j)$

Now let us split this sequence into two subsequences

$(A_i, A_{i+1}, \cdots, A_k)$ and $(A_{k+1}, A_{k+2}, \cdots, A_j)$

NOTE: $(A_i, A_{i+1}, \cdots, A_k)$ is a $p_{i-1} \times p_k$ matrix

NOTE: $(A_{k+1}, A_{k+2}, \cdots, A_j)$ is a $p_k \times p_j$ matrix

of operations for $(A_i, A_{i+1}, \cdots, A_k) \times (A_{k+1}, A_{k+2}, \cdots, A_j)$?

$p_{i-1} p_k p_j$

Dynamic Programming formulation II

Let us develop a dynamic programming algorithm applying four steps:

Let $A_{i..j}$ be the product of sequence of matrix $(A_i, A_{i+1}, \cdots, A_j)$

Now let us split this sequence into two subsequences

$(A_i, A_{i+1}, \cdots, A_k)$ and $(A_{k+1}, A_{k+2}, \cdots, A_j)$

- $\text{cost}(A_{i..j}) = \text{cost}(A_{i..k}) + \text{cost}(A_{k+1..j}) + \text{cost}(A_{i..k} \times A_{k+1..j})$

Recall that the cost for the cost for $(A_{i..k} \times A_{k+1..j}) = p_{i-1} p_k p_j$

- Thus, $\text{cost}(A_{i..j}) = \text{cost}(A_{i..k}) + \text{cost}(A_{k+1..j}) + p_{i-1} p_k p_j$

denoting $\text{cost}(A_{i..j})$ by $m([i, j])$, we have

$\Rightarrow m([i, j]) = m(i, k) + m(k + 1, j) + p_{i-1} p_k p_j$

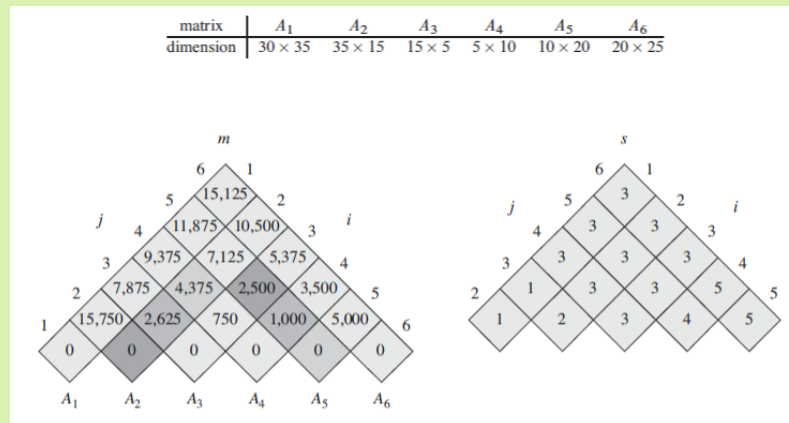
- We want to find k for which total cost is minimized

$$m([i, j]) = \begin{cases} 0 & \text{if } i = j \\ \min_{i \leq k < j} \{m([i, k]) + m[k + 1, j] + p_{i-1} p_k p_j\} & \text{if } i < j \end{cases}$$

Example of matrix-chain multiplication I

$$m([i, j]) = \begin{cases} 0 & \text{if } i = j \\ \min_{i \leq k < j} \{ m([i, k]) + m([k+1, j]) + p_{i-1}p_kp_j \} & \text{if } i < j \end{cases}$$

Matrices for our example



Pseudocode for the Dynamic Programming Algorithm

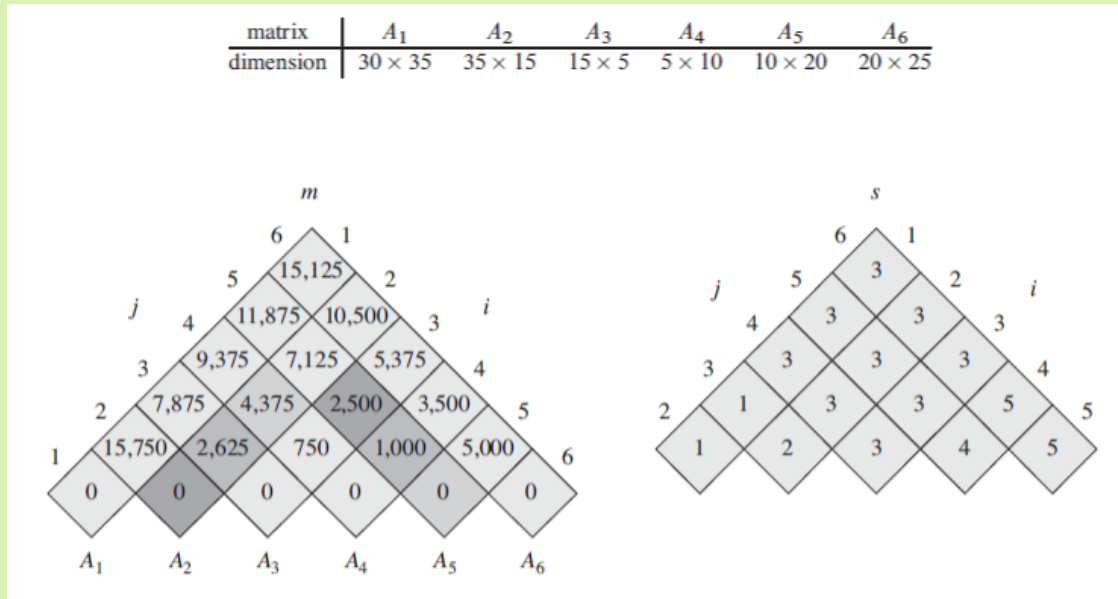
MATRIX-CHAIN-ORDER(p)

```

1   $n = p.length - 1$ 
2  let  $m[1..n, 1..n]$  and  $s[1..n-1, 2..n]$  be new tables
3  for  $i = 1$  to  $n$ 
4       $m[i, i] = 0$ 
5  for  $l = 2$  to  $n$            //  $l$  is the chain length
6      for  $i = 1$  to  $n - l + 1$ 
7           $j = i + l - 1$ 
8           $m[i, j] = \infty$ 
9          for  $k = i$  to  $j - 1$ 
10              $q = m[i, k] + m[k + 1, j] + p_{i-1}p_kp_j$ 
11             if  $q < m[i, j]$ 
12                  $m[i, j] = q$ 
13                  $s[i, j] = k$ 
14  return  $m$  and  $s$ 
```

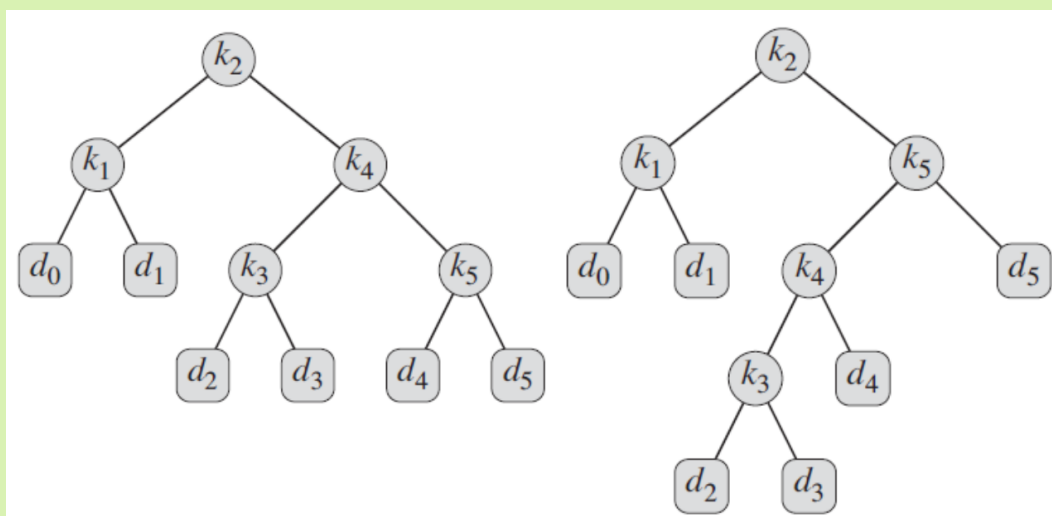
- m stores the optimal cost
- s stores location of partition
- Time complexity:
 - initialization: lines 3 and 4
 - Cost n .
 - 3 nested for loops
 - Total is $O(n^3)$

Example of matrix-chain multiplication I



$$m([2, 5]) = \min \begin{cases} m[2, 2] + m[3, 5] + p_1 p_2 p_5 = 0 + 2500 + 35 \cdot 15 \cdot 20 = 13,000 \\ m[2, 3] + m[4, 5] + p_1 p_3 p_5 = 2625 + 1000 + 35 \cdot 5 \cdot 20 = 7,125 \\ m[2, 4] + m[5, 5] + p_1 p_5 p_5 = 4375 + 0 + 35 \cdot 10 \cdot 20 = 11,375 \end{cases}$$

Optimal BST when Keys have different search Probabilities



k_1 to k_5 are five keys

d_0 to d_5 are 'dummy' nodes

A failed search ends at one the dummy nodes

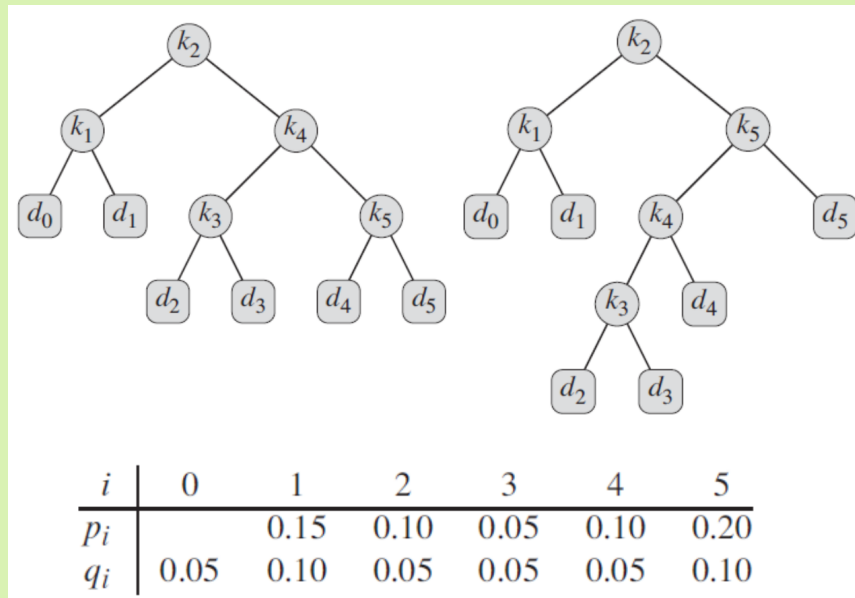
Which is a better search tree?

It depends on the probability of search of keys

Let us see an example

Optimal BST when Keys have different search Probabilities

II



p_i is the probability of searching k_i

q_i is the probability of search ending at d_i , and $\sum_{i=1}^n p_i + \sum_{i=0}^n q_i = 1$

Expected search cost for tree to the left is 2.8

Expected search cost for tree to the right is 2.75

Dynamic Programming Formulation

- Notations:

Let $e[i, j]$ be the cost of searching an optimal subtree with keys k_i, k_{i+1}, \dots, k_j

Let $w[i, j]$ be the sum of probabilities of a subtree containing keys

k_i, k_{i+1}, \dots, k_j

That is, $w(i, j) = \sum_{l=i}^j p_l + \sum_{l=i-1}^j q_l$

- Computation of optimal cost:

A search tree can have any key from k_i, k_{i+1}, \dots, k_j as root.

To find an optimal tree we must consider all of them as potential root.

Let k_l for $i \leq l \leq j$, be the root.

The left subtree will have keys k_i to k_{l-1} and

the right subtree will have keys k_{l+1} to k_j

Average cost for searching a tree rooted at k_l is cost of searching left and right subtrees plus $(w(i, l) + w(l+1, j) + p_l = w(i, j))$

For optimal cost

$$e[i, j] = \min_{l=i}^j \{ (e[i, l-1] + w(i, l-1)) + (e[l+1, j] + w(l+1, j)) + p_l \}$$

$$\text{That is, } e[i, j] = \min_{l=i}^j \{ e[i, l-1] + (e[l+1, j] + w(i, j)) \}$$

Dynamic Programming Algorithm for Optimal Binary Search Trees II

```

OPTIMAL-BST( $p, q, n$ )
1  let  $e[1..n+1, 0..n]$ ,  $w[1..n+1, 0..n]$ ,
   and  $root[1..n, 1..n]$  be new tables
2  for  $i = 1$  to  $n+1$ 
3       $e[i, i-1] = q_{i-1}$ 
4       $w[i, i-1] = q_{i-1}$ 
5  for  $l = 1$  to  $n$ 
6      for  $i = 1$  to  $n-l+1$ 
7           $j = i+l-1$ 
8           $e[i, j] = \infty$ 
9           $w[i, j] = w[i, j-1] + p_j + q_j$ 
10         for  $r = i$  to  $j$ 
11              $t = e[i, r-1] + e[r+1, j] + w[i, j]$ 
12             if  $t < e[i, j]$ 
13                  $e[i, j] = t$ 
14                  $root[i, j] = r$ 
15  return  $e$  and  $root$ 
    
```

Array e stores optimal cost

Array w stores weights of probabilities of the subtree

Array r stores selected roots

Optimal BST: An example

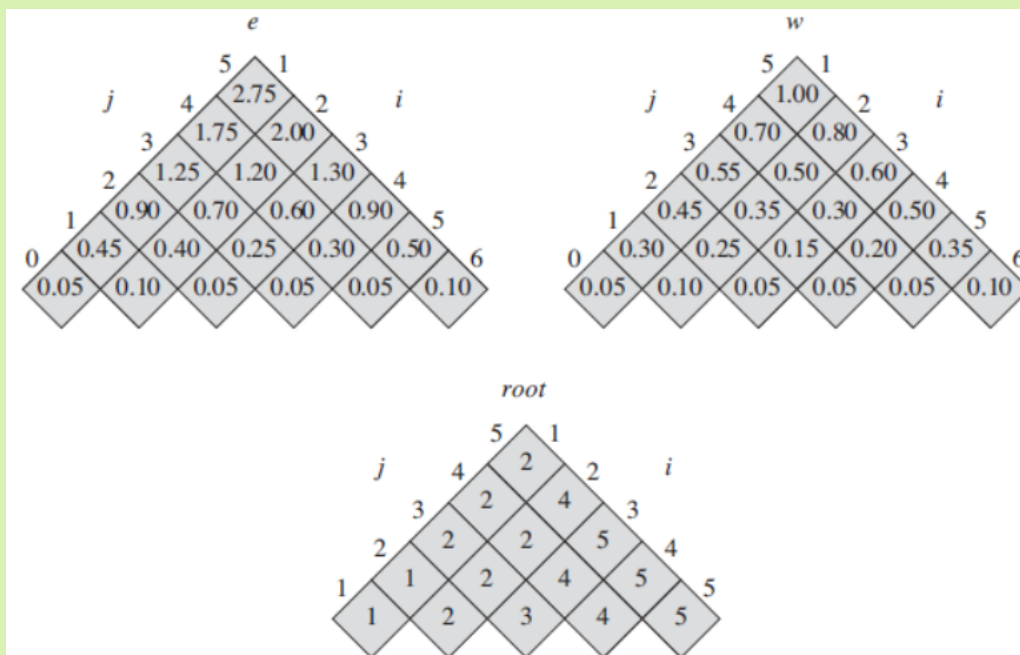


Figure 15.10 The tables $e[i, j]$, $w[i, j]$, and $root[i, j]$ computed by OPTIMAL-BST on the key distribution shown in Figure 15.9. The tables are rotated so that the diagonals run horizontally.