Carnegie Mellon University

# ADVANCED DATABASE SYSTEMS

OLTP Indexes (Whole-Key Data Structures)

@Andy\_Pavlo // 15-721 // Spring 2020

# UPCOMING DATABASE EVENTS

# **Snowflake Optimizer Talk**

- → Monday Feb 3<sup>rd</sup> @ 4:30pm
- → GHC 9115





## WHOLE-KEY DATA STRUCTURE

A "whole-key" order preserving data structure stores all the digits of a key together in nodes.

→ A worker thread has to compare the entire search key with keys in the data structure during traversal.

We will discuss "partial-key" data structures (i.e., tries) next class.



## TODAY'S AGENDA

In-Memory T-Tree

Latch-Free Bw-Tree

B+Tree Optimistic Latching



## OBSERVATION

The original B+Tree was designed for efficient access of data stored on slow disks.

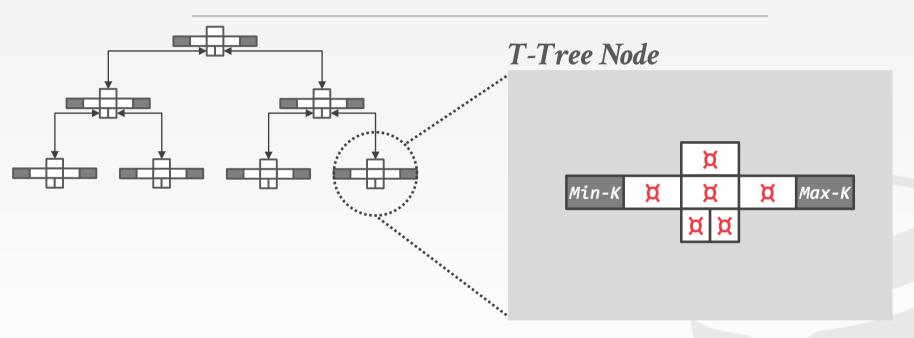
Is there an alternative data structure that is specifically designed for in-memory databases?

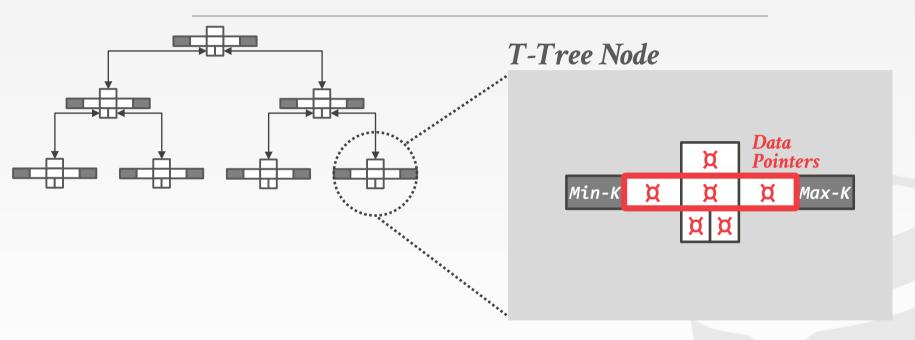


Based on AVL Trees. Instead of storing keys in nodes, store pointers to their original values.

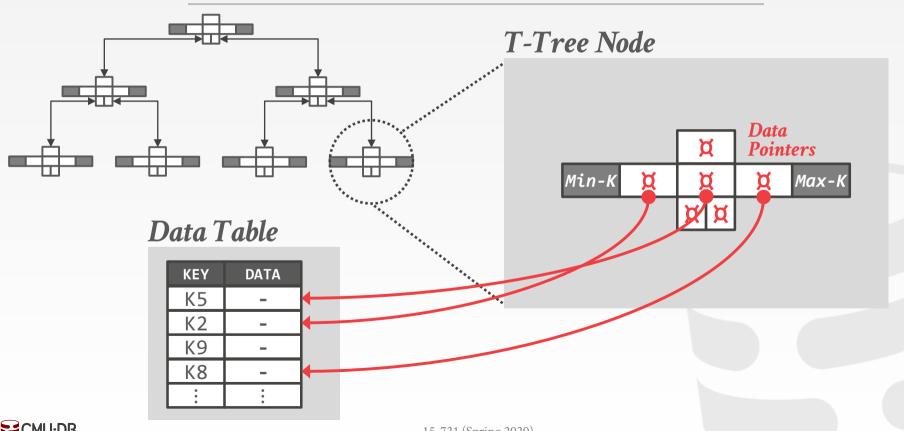
Proposed in 1986 from Univ. of Wisconsin Used in TimesTen and other early in-memory DBMSs during the 1990s.

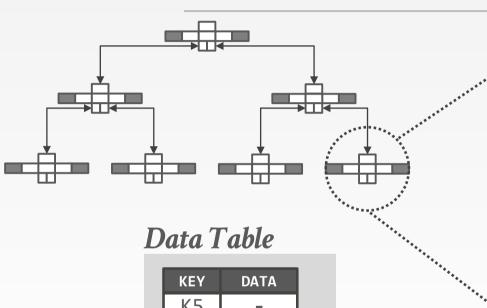




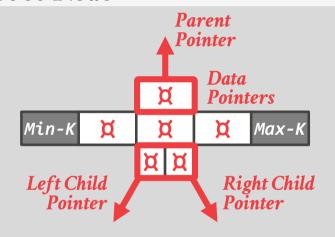


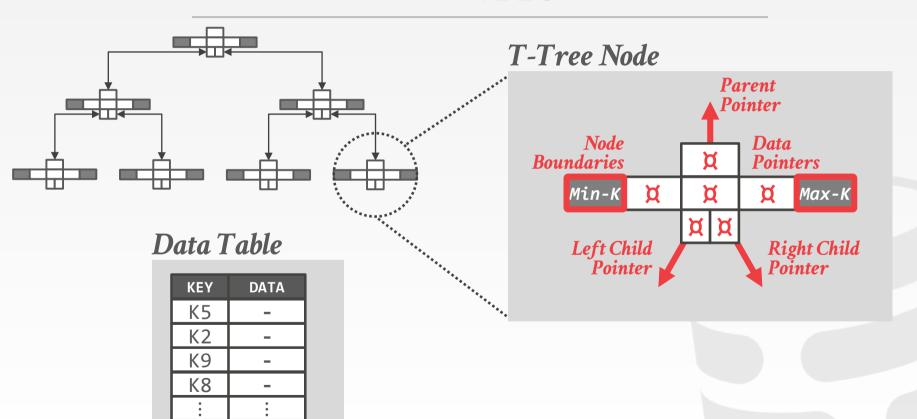






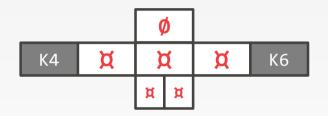
T-Tree Node

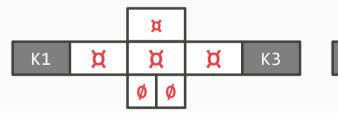






#### Find K2



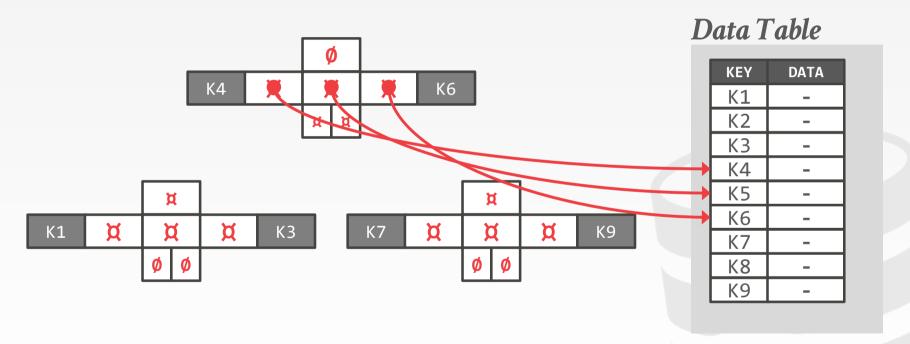




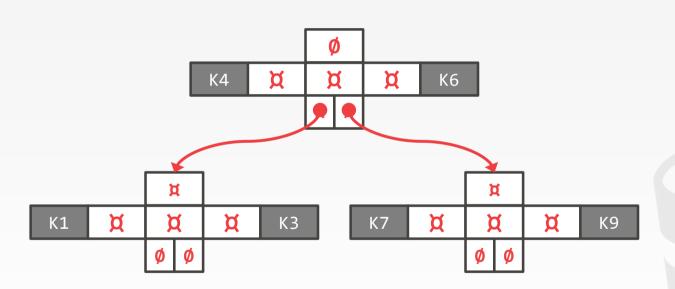
KEY	DATA
K1	-
K2	-
К3	-
K4	-
K5	-
K6	-
K7	-
K8	-
K9	_



#### Find K2



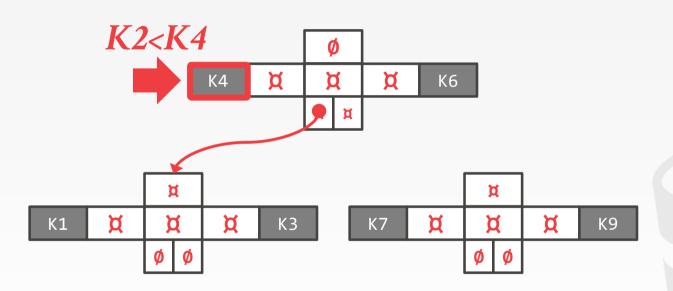
#### Find K2



KEY	DATA
K1	-
K2	-
К3	-
K4	-
K5	-
K6	-
K7	-
K8	-
К9	-



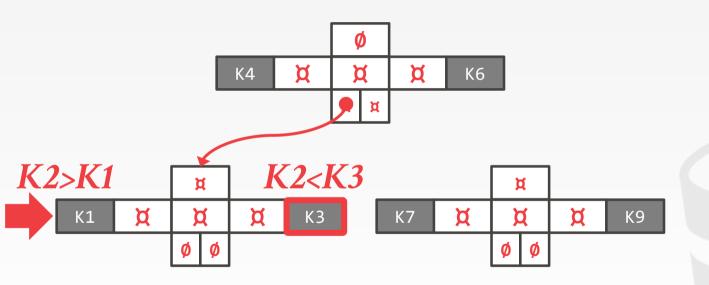
#### Find K2



$\overline{}$	
KEY	DATA
K1	-
K2	-
К3	-
K4	-
K5	-
K6	-
K7	-
K8	-
К9	-



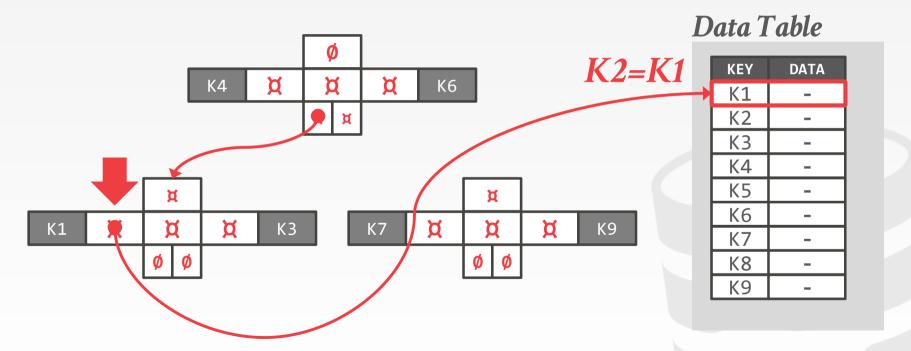
#### Find K2



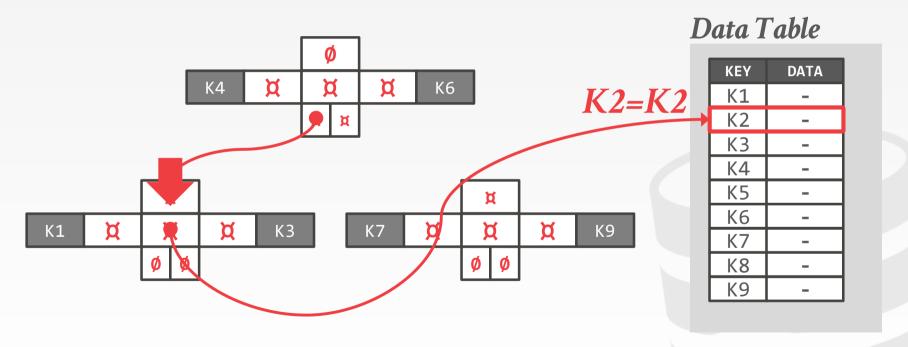
KEY	DATA
K1	-
K2	-
К3	-
K4	-
K5	-
K6	-
K7	-
K8	-
К9	-



#### Find K2



#### Find K2



#### T-TREE: ADVANTAGES

Uses less memory because it does not store keys inside of each node.

The DBMS evaluates all predicates on a table at the same time when accessing a tuple (i.e., not just the predicates on indexed attributes).



## T-TREES: DISADVANTAGES

Difficult to rebalance.

Difficult to implement safe concurrent access.

Must chase pointers when scanning range or performing binary search inside of a node.

→ This greatly hurts cache locality.



#### OBSERVATION

Because CaS only updates a single address at a time, this limits the design of our data structures

→ We cannot build a latch-free B+Tree because we need to update multiple pointers on split/merge operations.

What if we had an indirection layer that allowed us to update multiple addresses atomically?



#### BW-TREE

Latch-free B+Tree index built for the Microsoft Hekaton project.

#### Key Idea #1: Deltas

- → No updates in place
- → Reduces cache invalidation.

## **Key Idea #2: Mapping Table**

→ Allows for CaS of physical locations of pages.

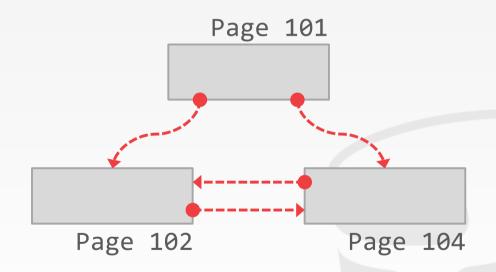


# BW-TREE: MAPPING TABLE

# Mapping Table

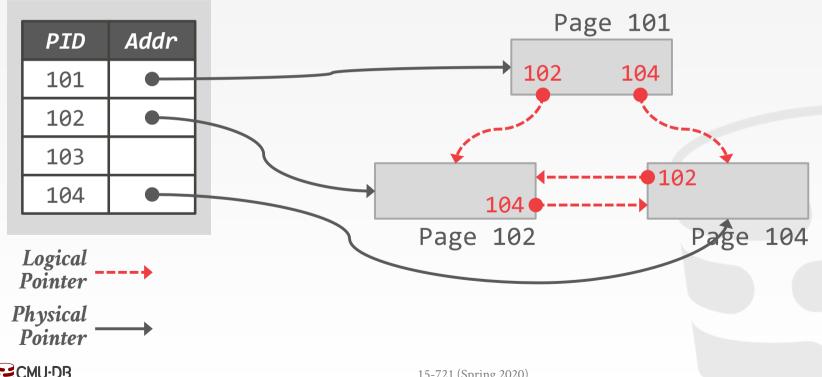
PID	Addr
101	
102	
103	
104	



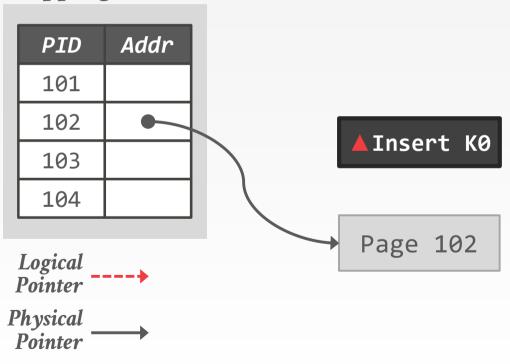


# BW-TREE: MAPPING TABLE

# Mapping Table



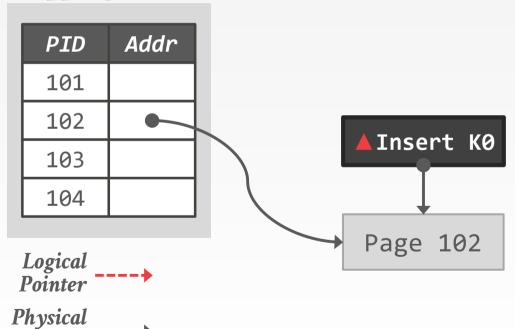




Each update to a page produces a new delta.



# Mapping Table



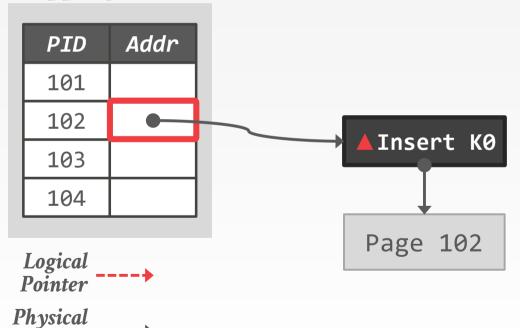
Each update to a page produces a new delta.

Delta physically points to base page.

Install delta address in physical address slot of mapping table using CaS.

**Pointer** 

# Mapping Table



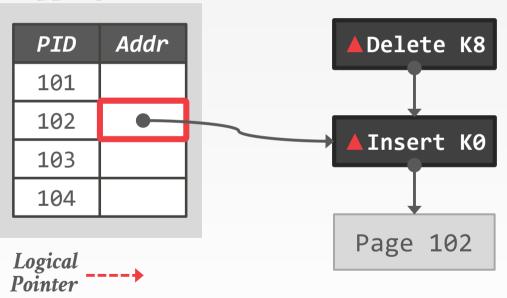
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# Mapping Table

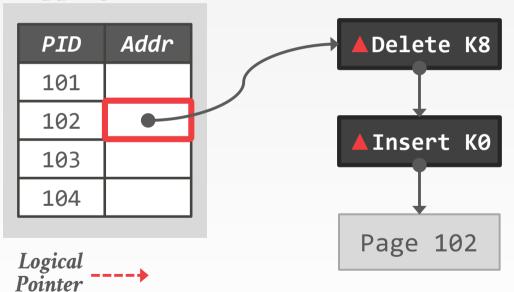


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# Mapping Table



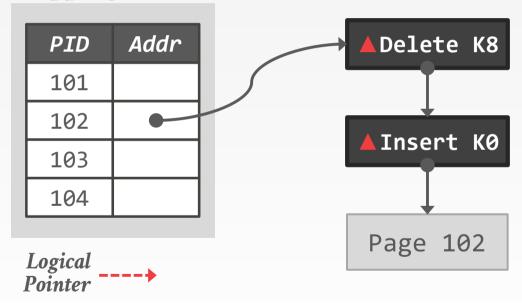
Each update to a page produces a new delta.

Delta physically points to base page.

Install delta address in physical address slot of mapping table using CaS.

#### BW-TREE: SEARCH

# Mapping Table

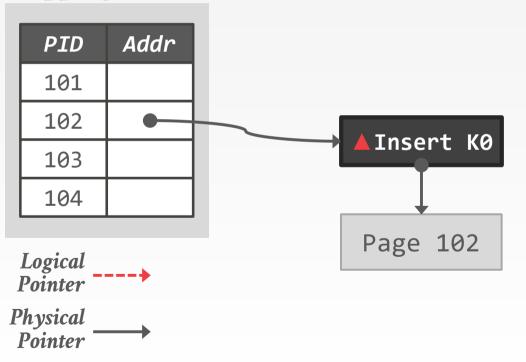


Traverse tree like a regular B+tree.

If mapping table points to delta chain, stop at first occurrence of search key.

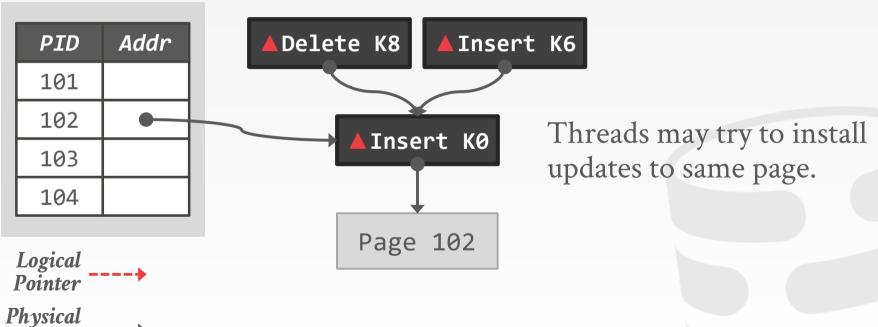
Otherwise, perform binary search on base page.

# Mapping Table



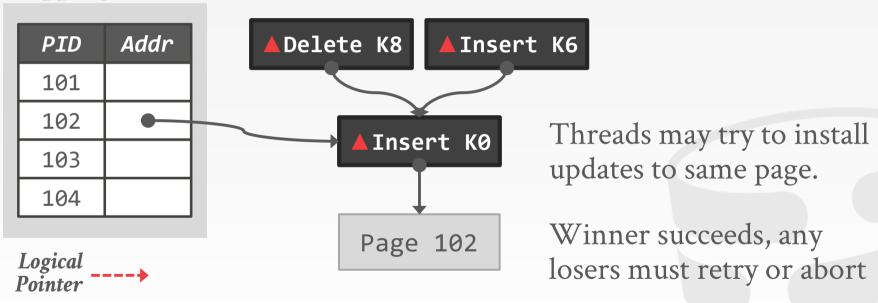
Threads may try to install updates to same page.

# Mapping Table

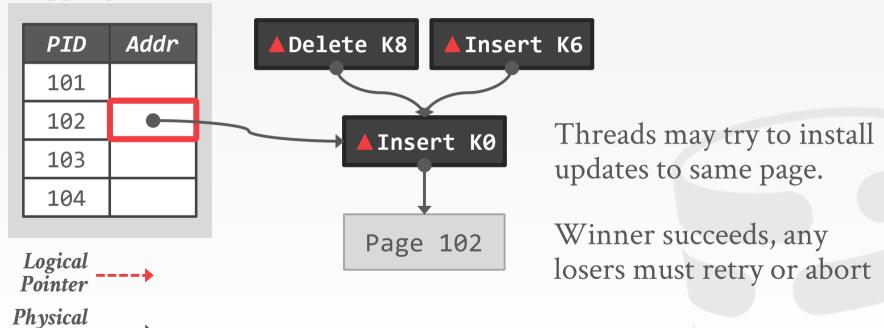


**Pointer** 

# Mapping Table

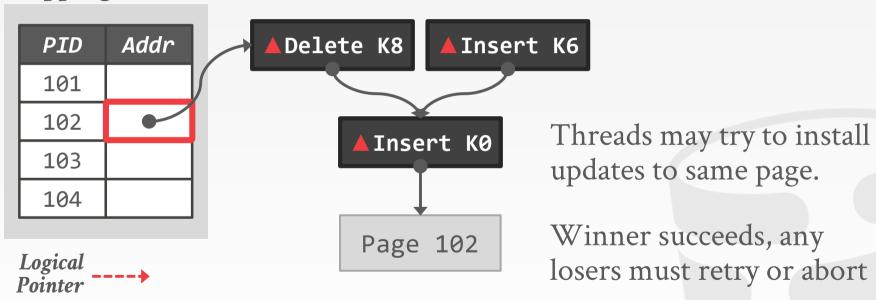


# Mapping Table

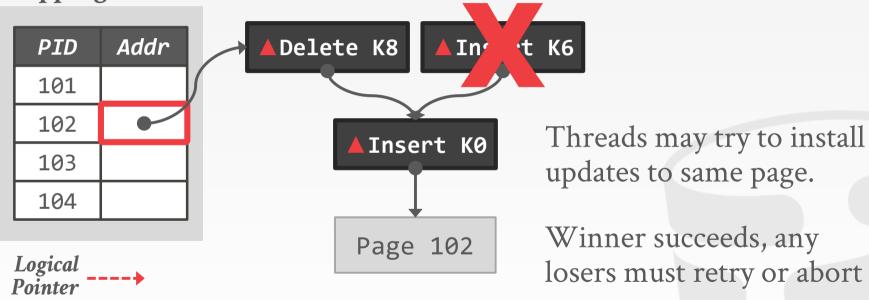


**Pointer** 

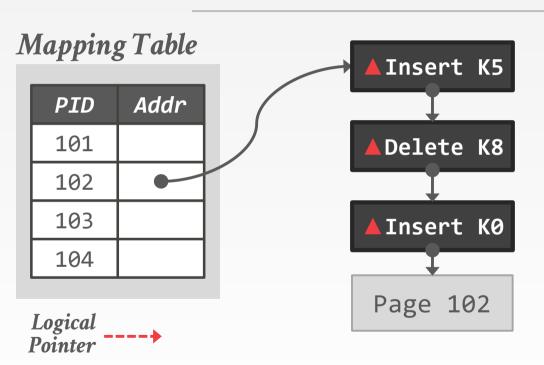
## Mapping Table



# Mapping Table

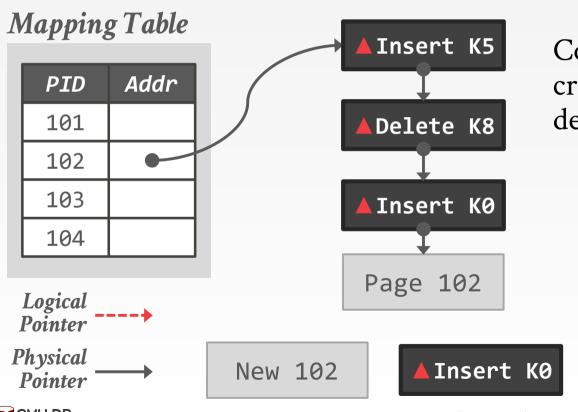






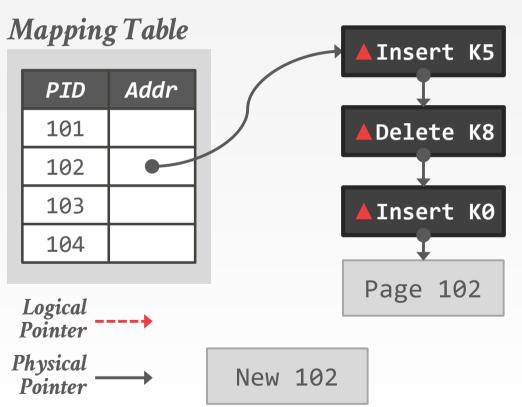
Consolidate updates by creating new page with deltas applied.

Physical Pointer



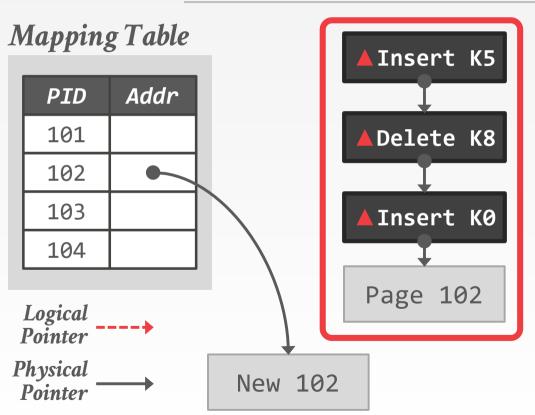
Consolidate updates by creating new page with deltas applied.

**CMU·DB** 



Consolidate updates by creating new page with deltas applied.

CaS-ing the mapping table address ensures no deltas are missed.



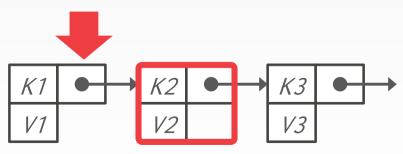
Consolidate updates by creating new page with deltas applied.

CaS-ing the mapping table address ensures no deltas are missed.

Old page + deltas are marked as garbage.

We need to know when it is safe to reclaim memory for deleted nodes in a latch-free index.

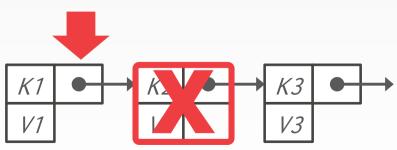
- → Reference Counting
- $\rightarrow$  Epoch-based Reclamation
- → Hazard Pointers
- → Many others...





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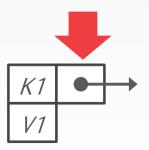
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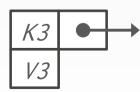




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- $\rightarrow$  Many others...

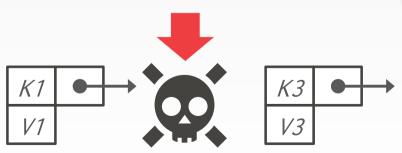






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- → Reference Counting
- $\rightarrow$  Epoch-based Reclamation
- → Hazard Pointers
- $\rightarrow$  Many others...





# REFERENCE COUNTING

Maintain a counter for each node to keep track of the number of threads that are accessing it.

- → Increment the counter before accessing.
- → Decrement it when finished.
- $\rightarrow$  A node is only safe to delete when the count is zero.

### This has bad performance for multi-core CPUs

→ Incrementing/decrementing counters causes a lot of cache coherence traffic.



### OBSERVATION

We don't care about the actual value of the reference counter. We only need to know when it reaches zero.

We don't have to perform garbage collection immediately when the counter reaches zero.

Source: <u>Stephen Tu</u>



# EPOCH GARBAGE COLLECTION

Maintain a global **epoch** counter that is periodically updated (e.g., every 10 ms).

→ Keep track of what threads enter the index during an epoch and when they leave.

Mark the current epoch of a node when it is marked for deletion.

→ The node can be reclaimed once all threads have left that epoch (and all preceding epochs).

Also known as Read-Copy-Update (RCU) in Linux.

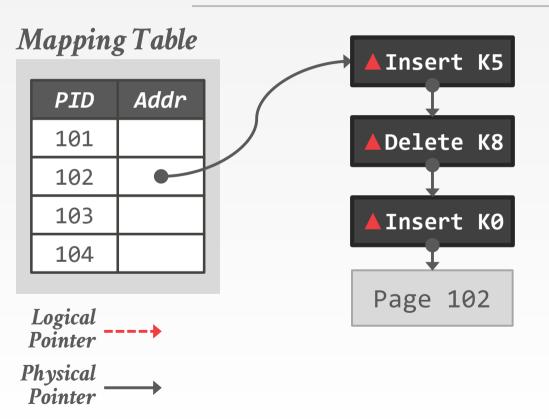


# Operations are tagged with an **epoch**

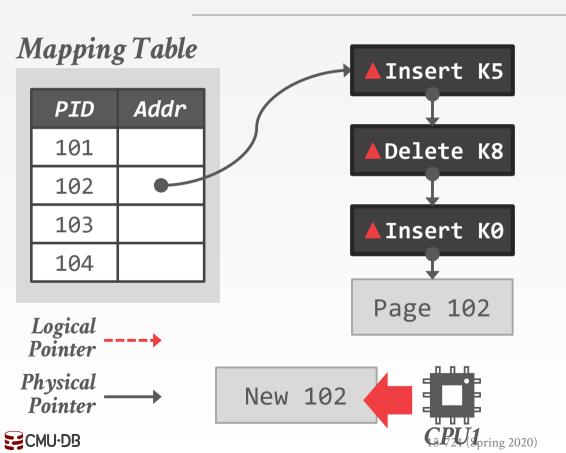
- → Each epoch tracks the threads that are part of it and the objects that can be reclaimed.
- → Thread joins an epoch prior to each operation and post objects that can be reclaimed for the current epoch (not necessarily the one it joined)

Garbage for an epoch reclaimed only when all threads have exited the epoch.

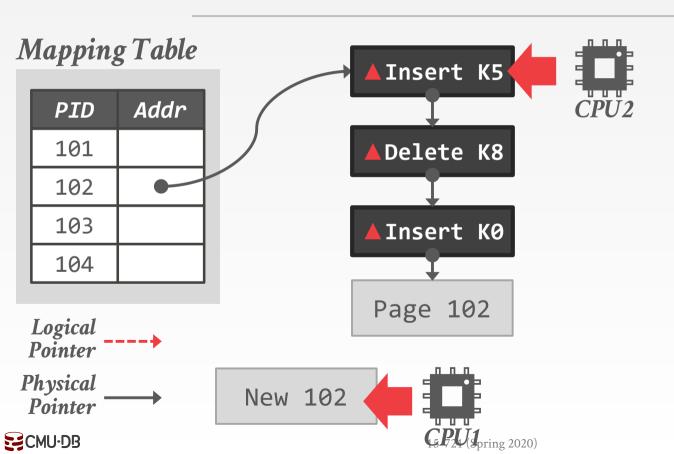


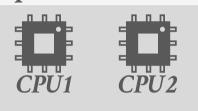


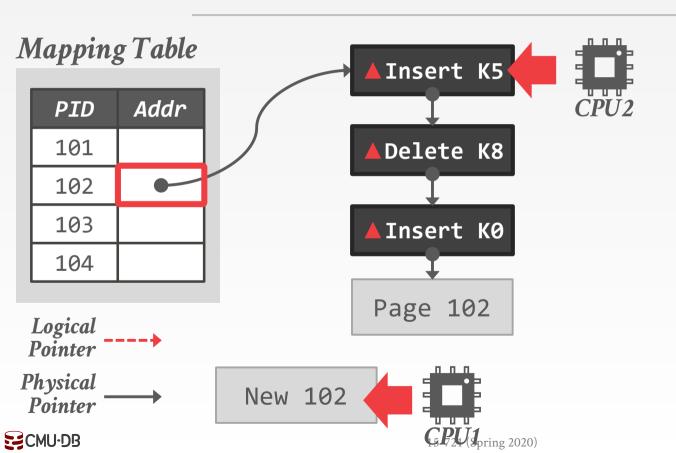


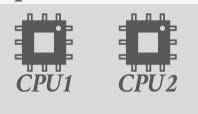


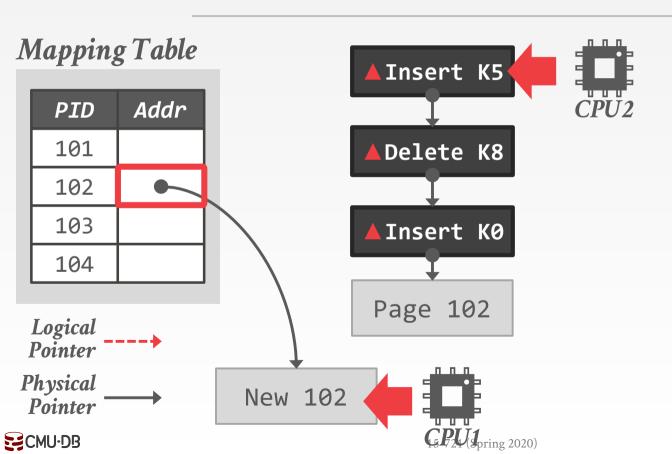


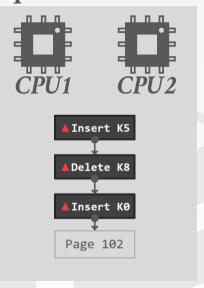


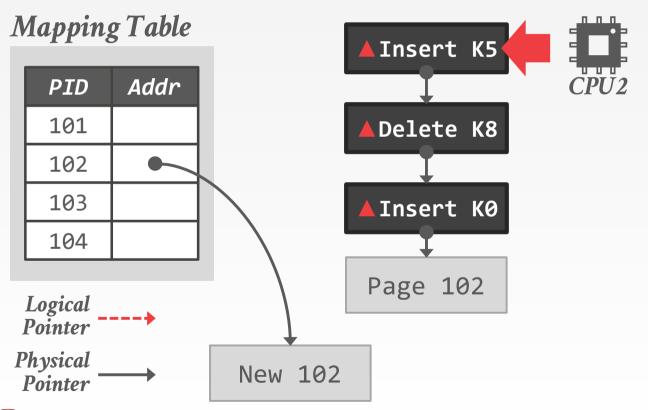


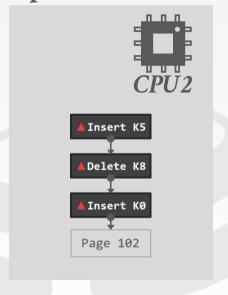


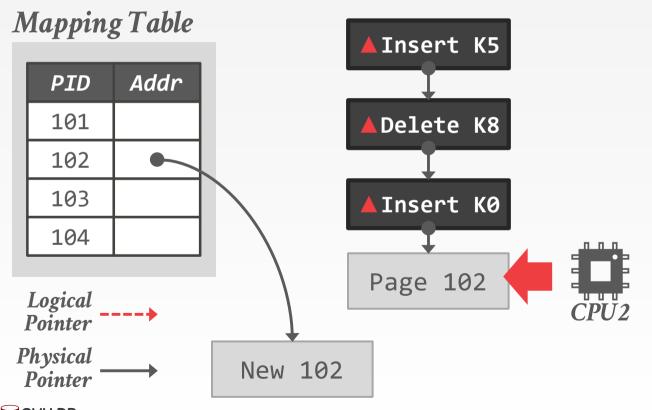


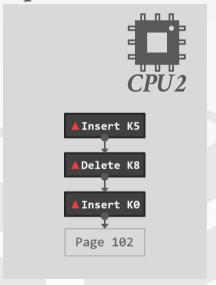


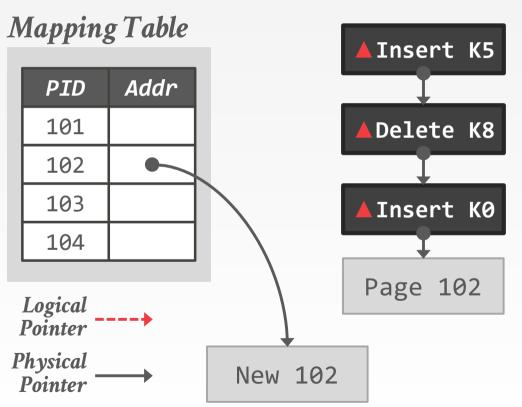


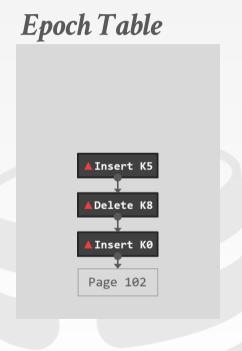


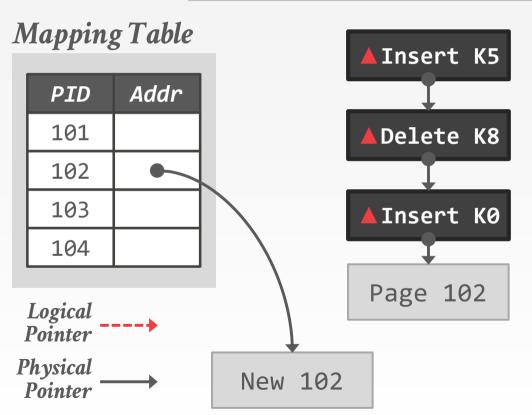


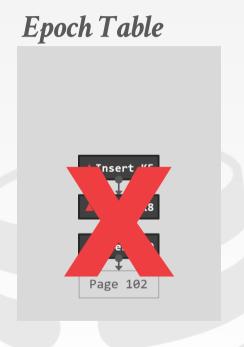












#### Split Delta Record

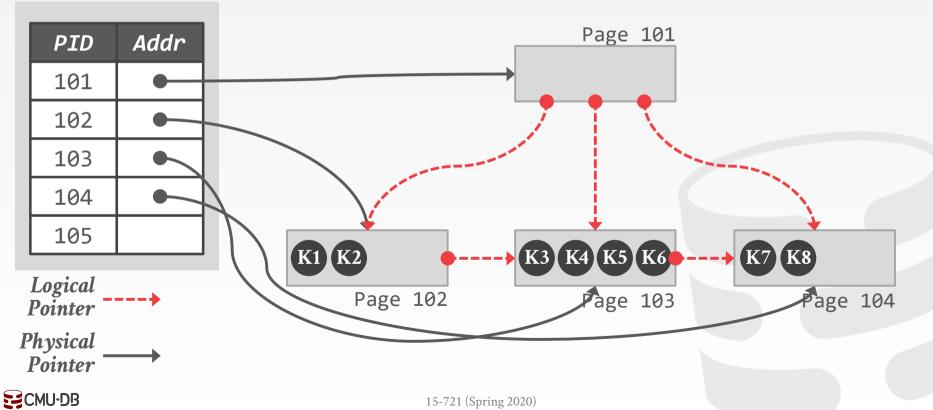
- → Mark that a subset of the base page's key range is now located at another page.
- $\rightarrow$  Use a logical pointer to the new page.

### Separator Delta Record

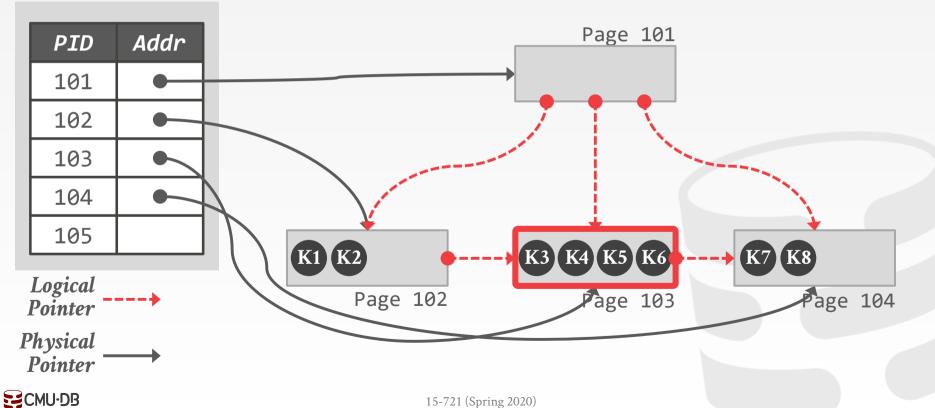
→ Provide a shortcut in the modified page's parent on what ranges to find the new page.



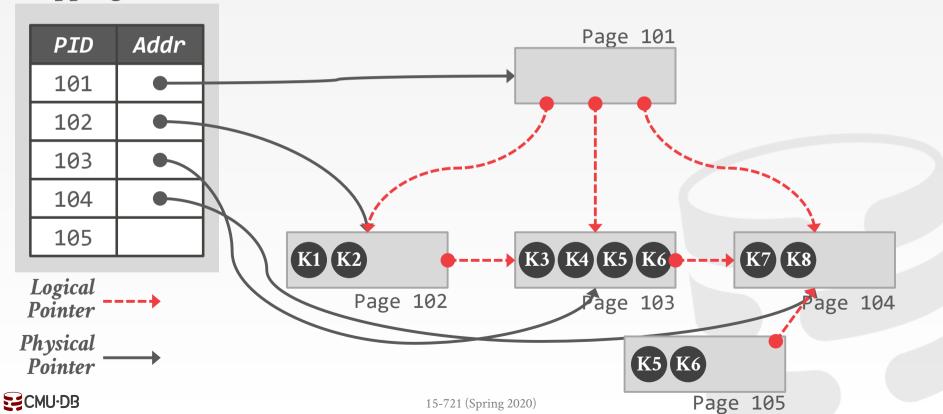
# Mapping Table



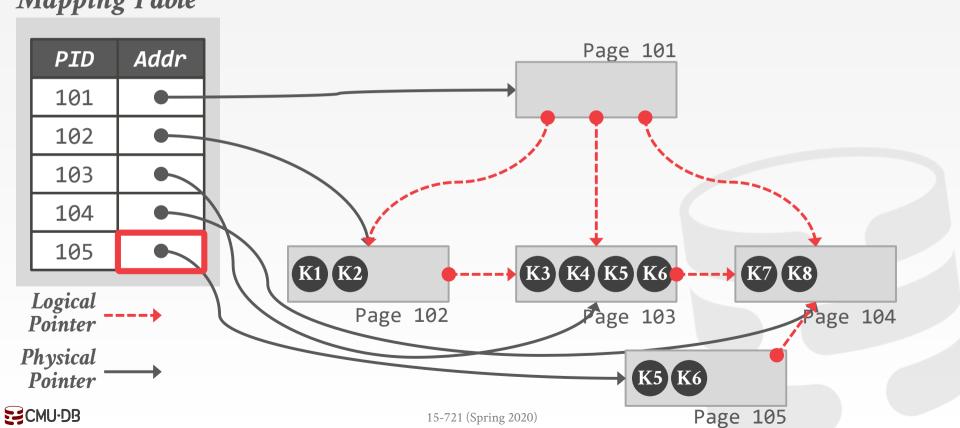
# Mapping Table



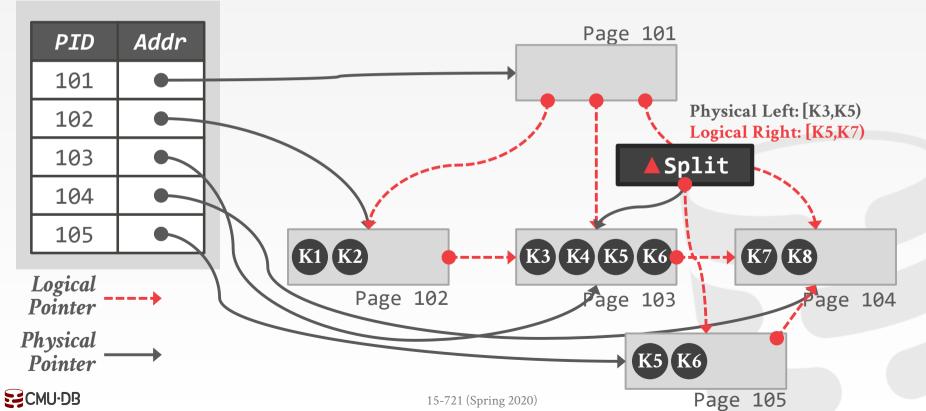




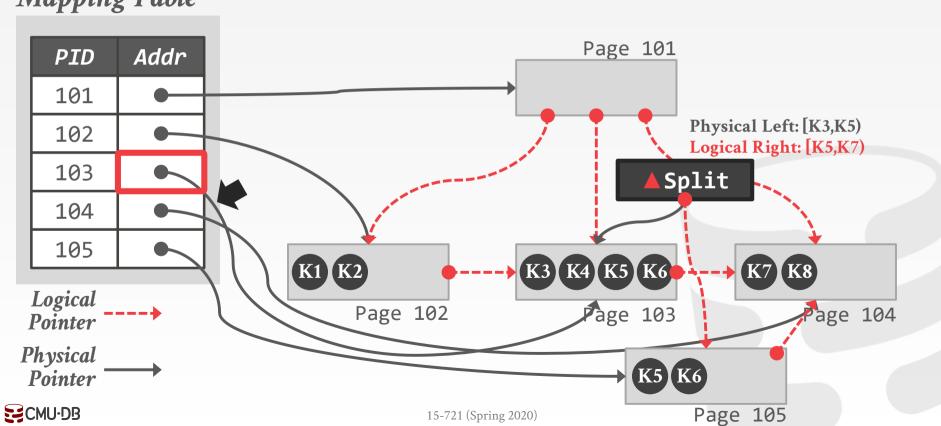






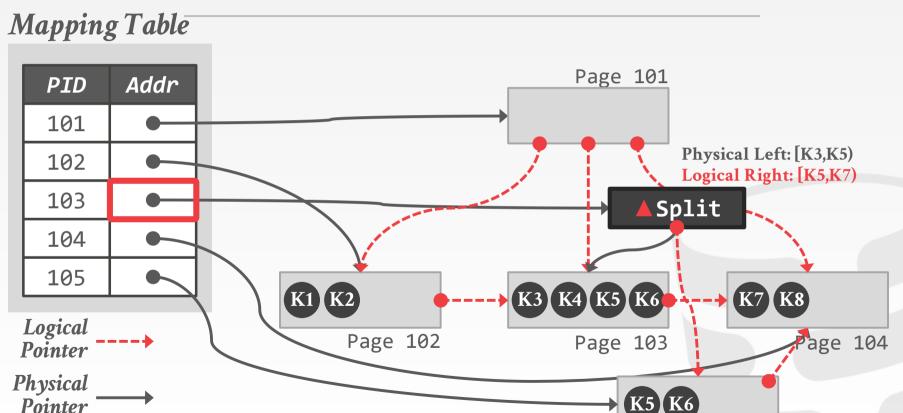






Page 105

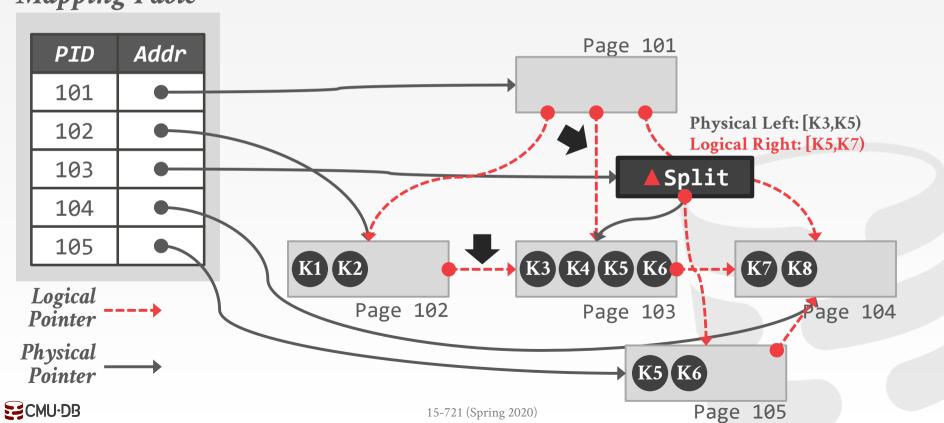
### BW-TREE: STRUCTURE MODIFICATIONS



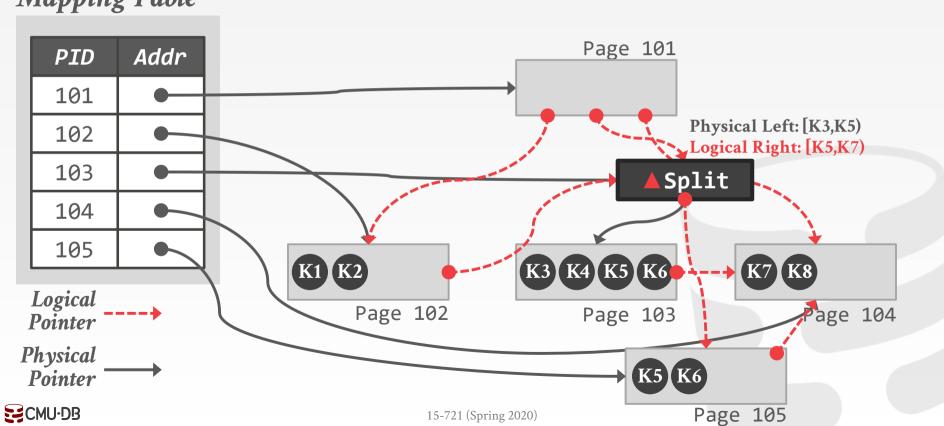
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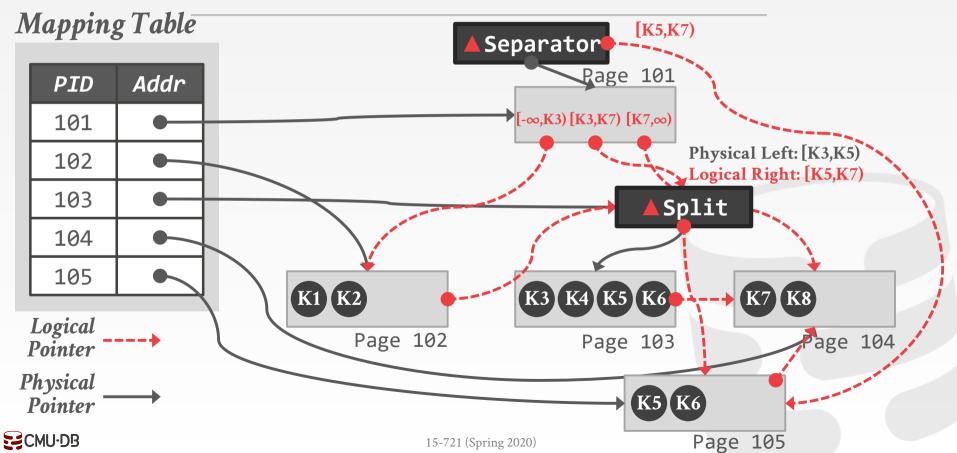
**CMU-DB** 

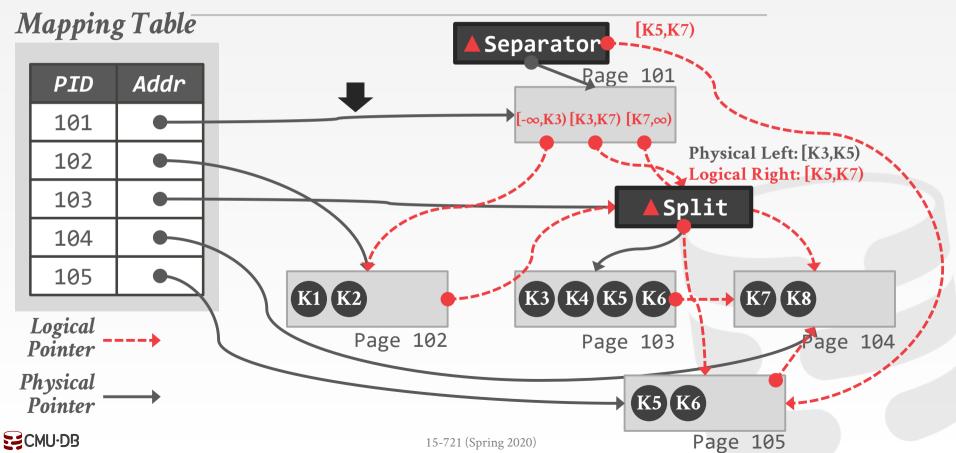


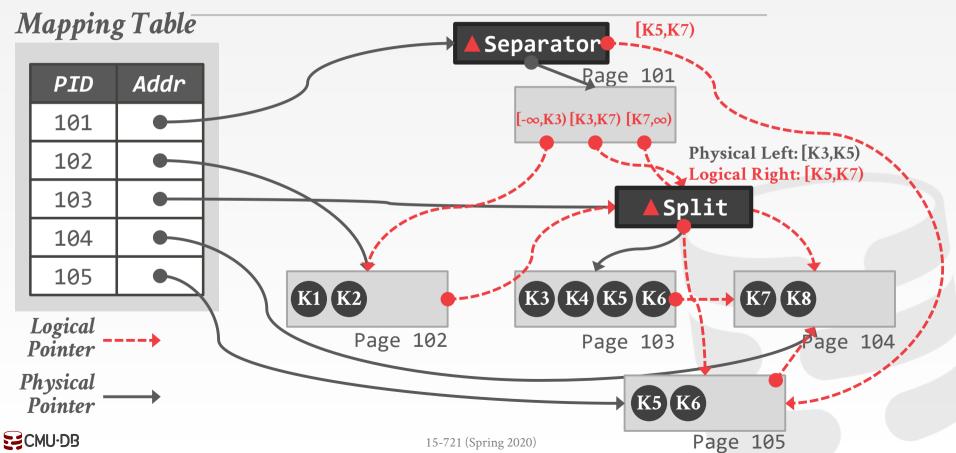












#### Optimization #1: Pre-Allocated Delta Records

- $\rightarrow$  Store the delta chain directly inside of a page.
- → Avoids small object allocation, list traversal.

### Mapping Table

PID	Addr
102	
102	





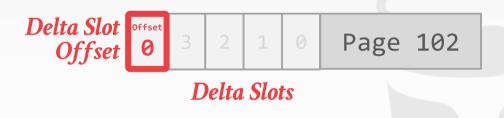


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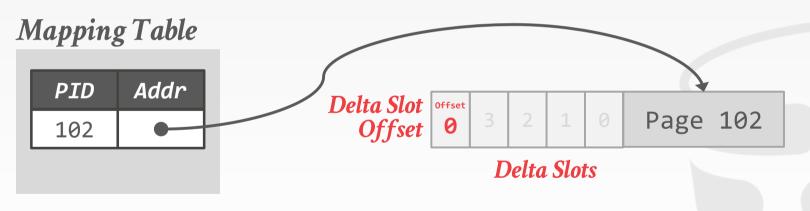
PID	Addr
102	
	•







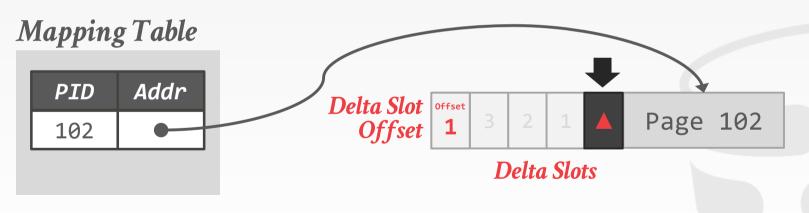
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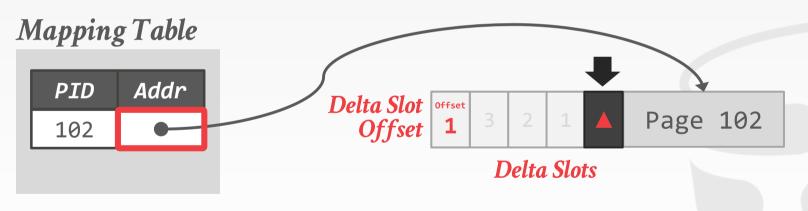
- $\rightarrow$  Store the delta chain directly inside of a page.
- → Avoids small object allocation, list traversal.







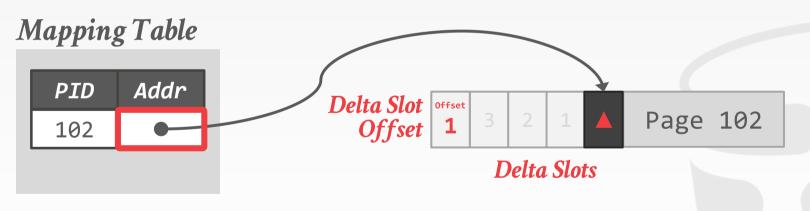
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# Optimization #2: Mapping Table Expansion

- $\rightarrow$  Fastest associative data structure is a plain array.
- → Allocating the full array for each index is wasteful
- $\rightarrow$  Old Peloton: 1m nodes per index = 8MB

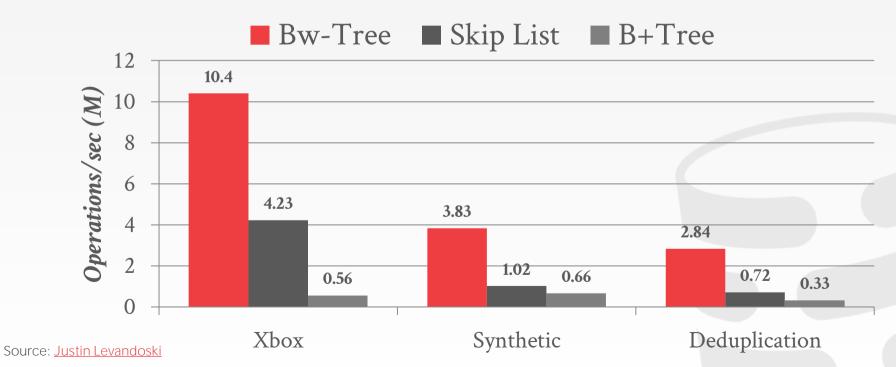
Use virtual memory to allocate the entire array without backing it with physical memory.

→ Only need to allocate physical memory when threads access higher offsets in the array.



### BW-TREE: PERFORMANCE

Processor: 1 socket, 4 cores w/ 2×HT



#### BW-TREE: PERFORMANCE

Processor: 1 socket, 10 cores w/ 2×HT Workload: 50m Random Integer Keys (64-bit)



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### BW-TREE: PERFORMANCE

Processor: 1 socket, 10 cores w/ 2×HT Workload: 50m Random Integer Keys (64-bit)

■ Open Bw-Tree ■ Skip List ■ B+Tree ■ Masstree ■ ART



**≥**CMU·DB

#### PARTING THOUGHTS

Managing a concurrent index looks a lot like managing a database.

A Bw-Tree is hard to implement.

Versioned latch coupling provides some the benefits of optimistic methods with wasting too much work.



# NEXT CLASS

Latch Implementations
Trie Data Structures

