

Topology of Piecewise-Linear Manifolds

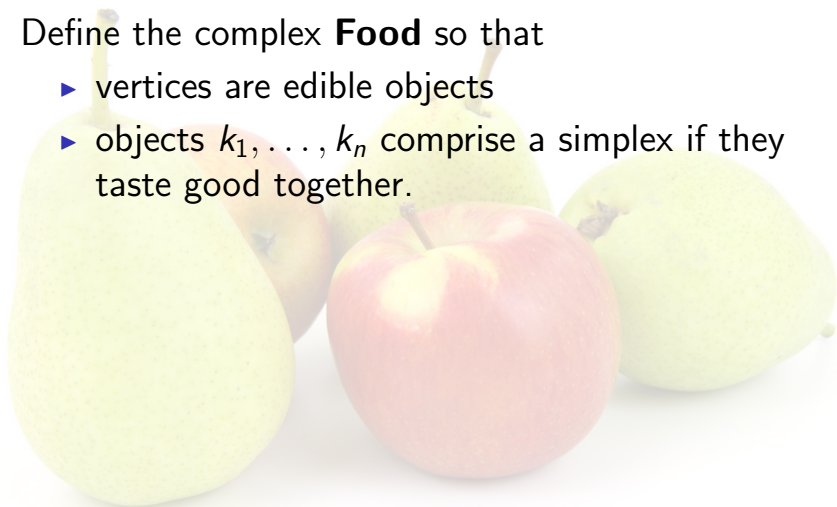
Jim Fowler

Lecture 3
Summer 2010

A simplicial complex joke

Define the complex **Food** so that

- ▶ vertices are edible objects
- ▶ objects k_1, \dots, k_n comprise a simplex if they taste good together.

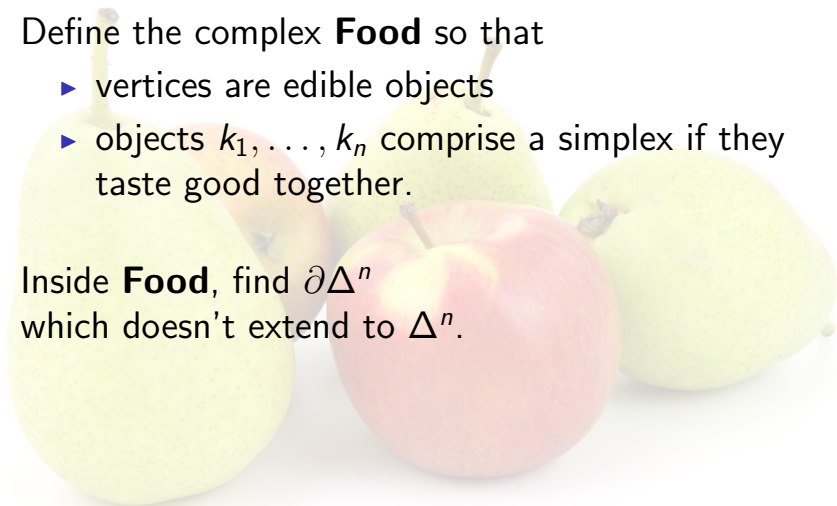


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Inside **Food**, find $\partial\Delta^n$
which doesn't extend to Δ^n .



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Three foods,
any two of which taste good together,
but the three aren't tasty altogether.

A simplicial complex which isn't funny

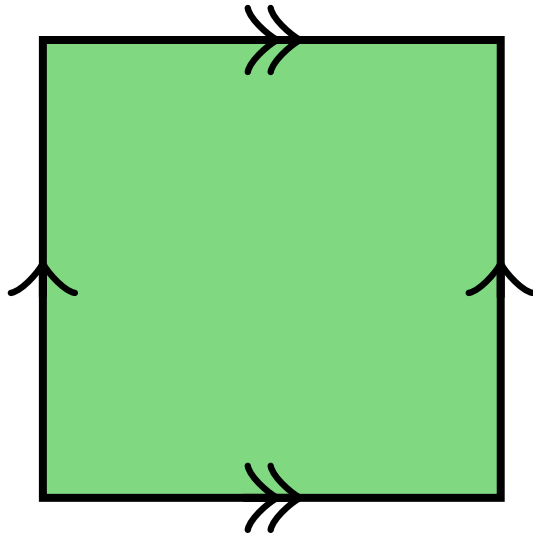
Define the complex **Market** so that

- ▶ vertices are securities
(e.g., stocks, bonds, currencies)
- ▶ objects k_1, \dots, k_n comprise a simplex
if they can be traded for each other

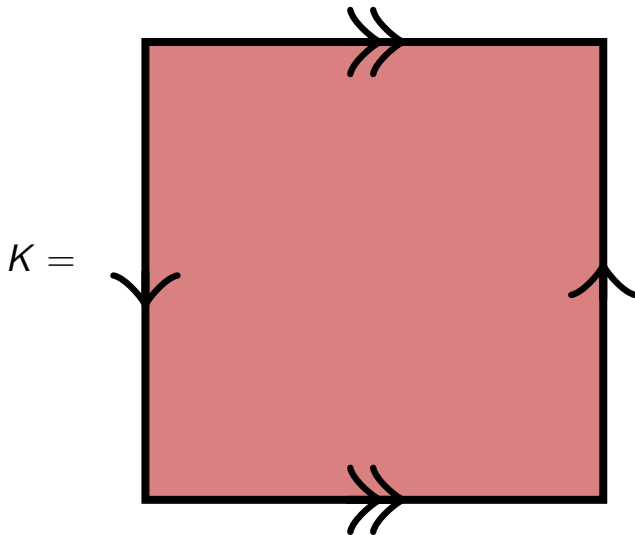
Move your money through the vertices.
Come back to where you started with more!

The torus

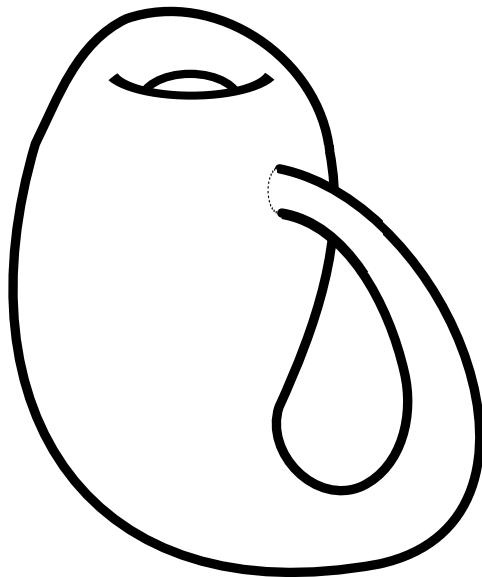
$$T^2 =$$



Klein Bottle



Klein Bottle









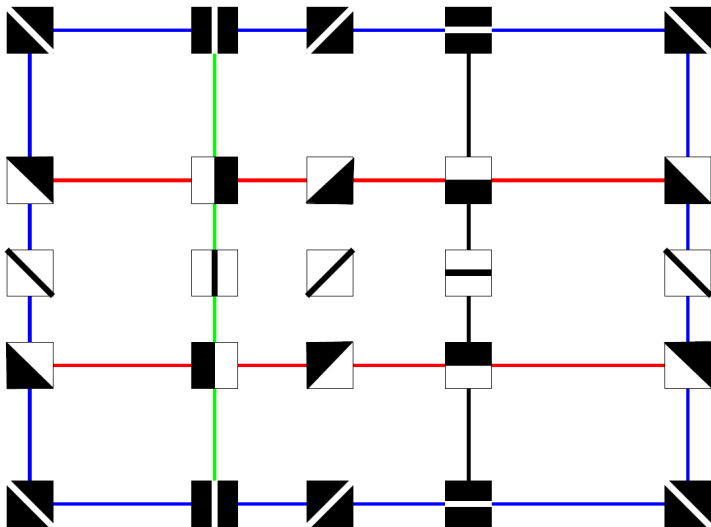




Look at 3×3 pixel subsets

Look at 3×3 pixel subsets

Get points in \mathbf{R}^9



From a paper of Gunnar Carlsson and Tigran Ishkhanov

I'm a cheerleader for geometry!

Dynamics and mixing taffy

Biology and yeast

Chemistry and isomers

Physics and symmetry

Neurology and Klein bottles

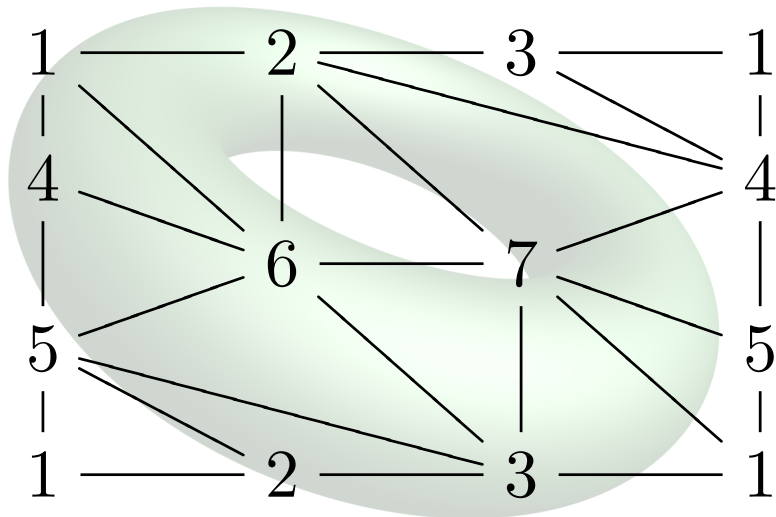
Economics and “least action”

Engineering and robots

Astronomy and the shape of space

Linguistics and document clustering

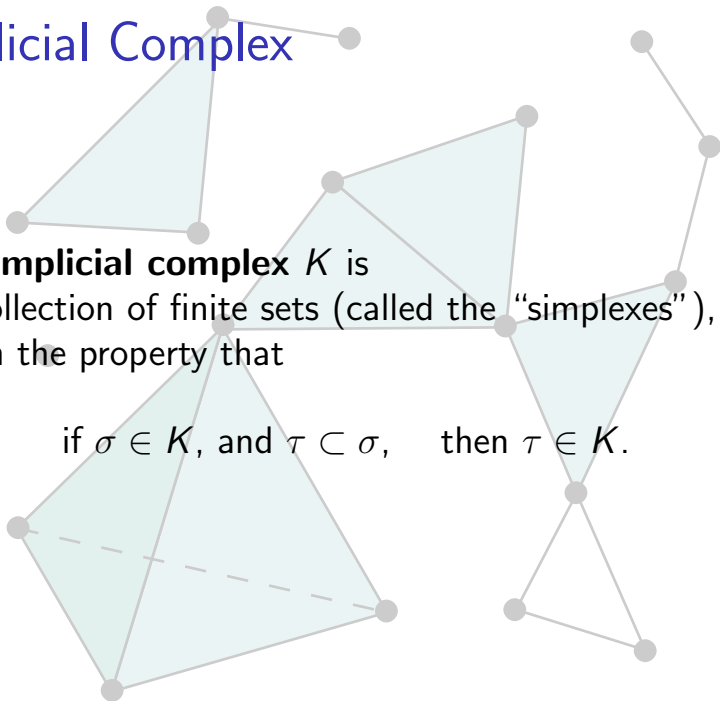
Triangulate a torus



Simplicial Complex

A **simplicial complex** K is a collection of finite sets (called the “simplexes”), with the property that

if $\sigma \in K$, and $\tau \subset \sigma$, then $\tau \in K$.



Star

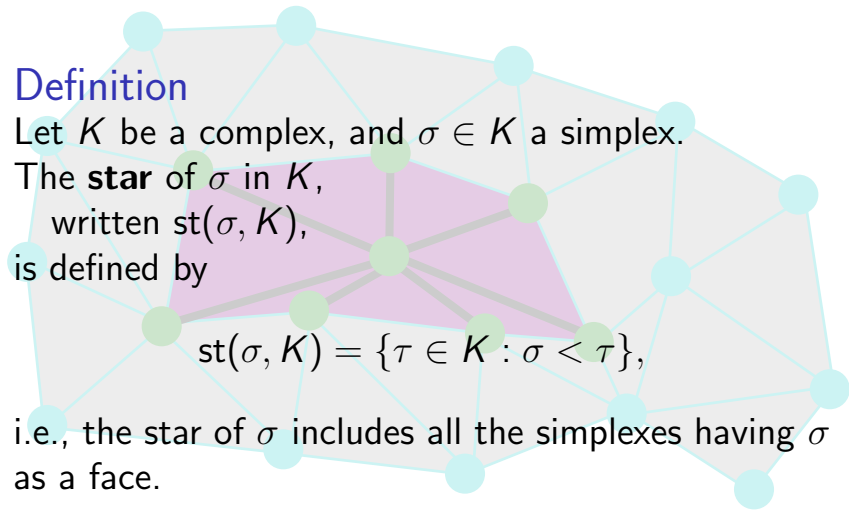
Definition

Let K be a complex, and $\sigma \in K$ a simplex.

The **star** of σ in K ,
written $\text{st}(\sigma, K)$,
is defined by

$$\text{st}(\sigma, K) = \{\tau \in K : \sigma < \tau\},$$

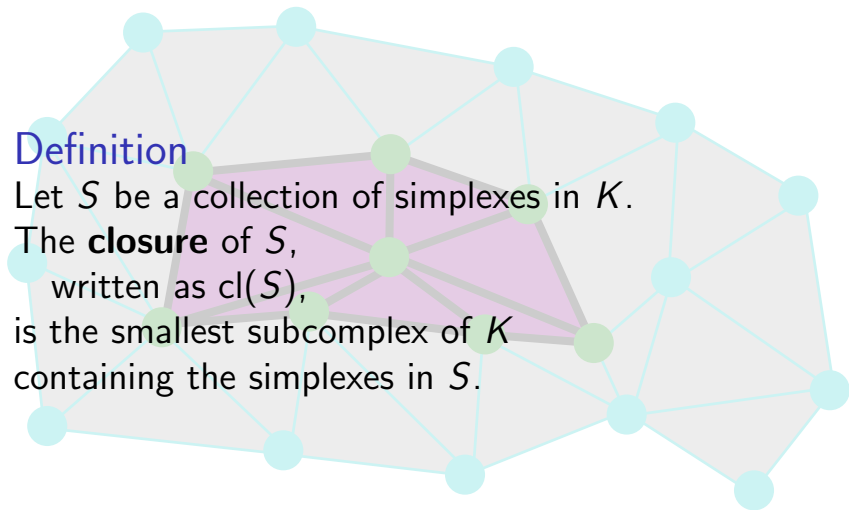
i.e., the star of σ includes all the simplexes having σ as a face.



Closure

Definition

Let S be a collection of simplexes in K .
The **closure** of S ,
written as $\text{cl}(S)$,
is the smallest subcomplex of K
containing the simplexes in S .



Link

Definition

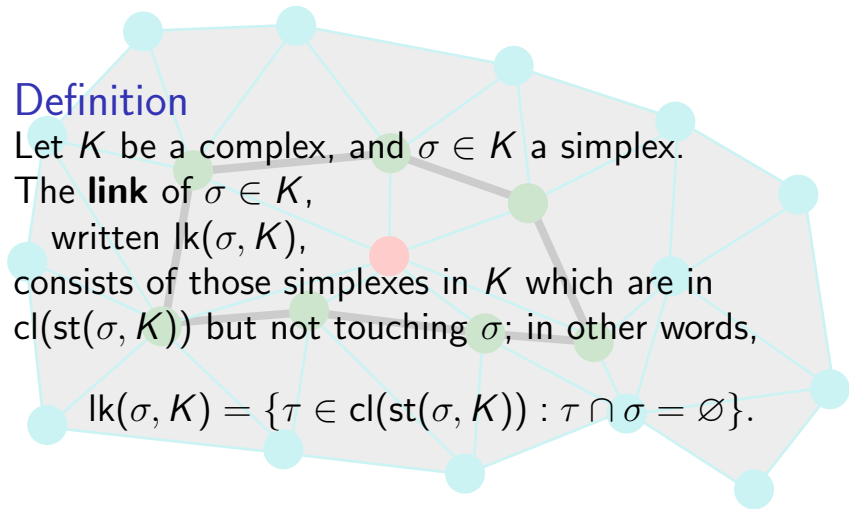
Let K be a complex, and $\sigma \in K$ a simplex.

The **link** of $\sigma \in K$,

written $\text{lk}(\sigma, K)$,

consists of those simplexes in K which are in $\text{cl}(\text{st}(\sigma, K))$ but not touching σ ; in other words,

$$\text{lk}(\sigma, K) = \{\tau \in \text{cl}(\text{st}(\sigma, K)) : \tau \cap \sigma = \emptyset\}.$$



Stellar Subdivision

Definition

Let K be a complex, and $\sigma \in K$ a simplex.

The **stellar subdivision** of K at σ is a new complex K_σ with:

- ▶ the vertices of K with a new vertex v .
- ▶ the simplexes of K not in $\text{st}(\sigma, K)$,
along with the simplexes in $v * (\partial\sigma) * \text{lk}(\sigma, K)$.

We might say:

$$K_\sigma := (K - \text{st}(\sigma, K)) \cup (v * (\partial\sigma) * \text{lk}(\sigma, K))$$

subdivision = repeated stellar subdivision

Definition

Let K, L be complexes.

If K can be produced through a (possibly empty) sequence of stellar subdivisions of L , we say that K is a **subdivision** of L , and write $K \triangleleft L$.

Piecewise linear maps

Definition

Let K, K', L, L' be complexes,
with $K' \triangleleft K$ and $L' \triangleleft L$.

If $f : K' \rightarrow L'$ is a simplicial map,
we call $f : K \rightarrow L$ a **piecewise linear map**
(or a **PL map** for short).

We call $f : K' \rightarrow L'$ an **underlying simplicial map**.

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As we will see, the *real* definition of subdivision is
more general than this.

Goal. Problem Set 2 introduces *abstract simplicial complexes*, the main object of study. You should be warned that what follows is not the only way to formalize our intuition. As usual, **problems marked with a • should be written up and handed in.**

Definition. Geometrically, an n -dimensional **simplex** (written Δ^n , and usually called an n -simplex for short) is the n -dimensional analog of a triangle; just as a triangle is the smallest convex set containing 3 points which do not lie on a line, the n -simplex Δ^n is the smallest convex set containing $n + 1$ points in “general position.”

But for us, the important feature of a simplex is the relationship between the faces. Indeed, topologically, we do not care about the size of the simplexes, or where they are sitting in space—so we will abstract away the geometry, leaving only the combinatorics behind.

A simplex A is a **face** of a simplex B if the vertices determining A are a subset of the vertices determining B . We write $A < B$ if A is a face of B . Specifically, some v for which $\{v\} \in B$ is called a **vertex** of B .

A **simplicial complex** K is a collection of finite sets (called the **simplices** of K) with the property that if $\sigma \in K$, and $\tau < \sigma$ (i.e., if $\tau \subset \sigma$ when thought of as finite sets), then $\tau \in K$.

In words, a simplicial complex is a collection of simplexes, where any face of a simplex is also in the complex. We can think of a simplicial complex as a geometric object by gluing together actual simplexes along their faces (the “gluing” is the geometric realization of the complex), or as a combinatorial object described by the finite sets.

Anytime we define a mathematical object, we must also describe the maps between such objects. Let K and L be complexes. A **simplicial map** $f : K \rightarrow L$ is a function $f : \sigma \in K \rightarrow \tau \in L$ with the property that if $\tau \in K$, then $f(\tau) \in L$.

- **Problem 1.** Find an injective simplicial map $f : K_7 \rightarrow T^2$; here, T^2 is the torus, and K_7 denotes 7 points connected in pairs by all $\binom{7}{2} = 21$ edges. Use this to triangulate T^2 as a simplicial complex with as few triangles as possible.

Problem 2. Does there exist an injective map $f : K_{3,3} \rightarrow S^2$? What about $f : K_{3,3} \rightarrow T^2$? Here, $K_{3,3}$ denotes six points, connected by nine lines, as shown on the right.



Subcomplexes

Definition. If K and L are complexes, and every simplex in K is a simplex of L , then we write $K \subset L$ and say that K is a **subcomplex** of L .

Example. The n -dimensional **skeleton** (usually called the n -skeleton) of a complex K consists of all those simplexes which contain $n + 1$ or fewer points (i.e., are at most n -dimensional). Write $K^{(n)}$ for the n -skeleton. We say that a complex K is an n -complex if $K = K^{(n)}$.

- **Problem 3.** Prove that the n -skeleton of a simplicial complex K is still a simplicial complex.

from the last
homework

Joins

Definition

Let K and L be complexes
with disjoint sets of vertices

(we call such complexes **joinable**).

Define a new complex, the **join** of K and L , by

$$K * L := \{\sigma \cup \tau : \sigma \in K, \tau \in L\}.$$

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*What is $S^0 * S^0$?*

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Problem

*What is $S^n * S^m$?*

This is the end of the beginning. Problem Set 3 introduces *manifolds*, and with that, the last of the introductory topics; Please submit answers to problems marked with a •.

- **Problem 1.** Suppose K is a simplicial complex, with subdivisions $K_1 \triangleleft K$ and $K_2 \triangleleft K$. Is there a subdivision K' so that $K' \triangleleft K_1$ and $K' \triangleleft K_2$?

Problem 2. Let K, L, M be complexes. If $f: K \rightarrow L$ and $g: L \rightarrow M$ are PL maps, how should we define the PL map $g \circ f: K \rightarrow M$?

Problem 3. For $n \geq 3$, let P_n be the boundary of an n -gon. Prove that $P_n \cong P_m$ for $n, m \geq 3$. Thus, any P_n is topologically an S^1 .

Definition. A complex K is **path-connected** if for any two vertices $v, w \in K$, there exists a map $f: \Delta^1 \rightarrow K$ sending the boundary of Δ^1 to v and w .

Problem 4. Prove that being path-connected is a topological property meaning it is preserved under PL homeomorphisms.

Homeomorphisms

Problem 5. Is PL homeomorphism an equivalence relation? That is, is it

reflexive, meaning, is A homeomorphic to A ?

symmetric, meaning, if $A \cong B$, is it true that $B \cong A$, and

transitive, meaning, if $A \cong B$ and $B \cong C$, is it true that $A \cong C$?

- **Problem 6.** Is join well-defined with respect to homeomorphism? That is, if we have PL homeomorphic complexes $K \cong K'$ and $L \cong L'$, is it true the case that $K * L \cong K' * L'$?

Problem 7. Let X_n consist of n points. For which $n \in \mathbb{N}$ is it the case that for every two injective maps $f, g: X_n \rightarrow S^1$, there is a homeomorphism $h: S^1 \rightarrow S^1$ so that $h \circ f = g$?

Problem 8. Let X_n be the disjoint union of n circles (e.g., $X_3 = S^1 \cup S^1 \cup S^1$). For this problem, call two maps $f, g: X_n \rightarrow S^2$ “equivalent” if there exists a homeomorphism $h: S^2 \rightarrow S^2$ so that $h \circ f = g$. Count the equivalence classes of maps from X_5 to S^2 ?

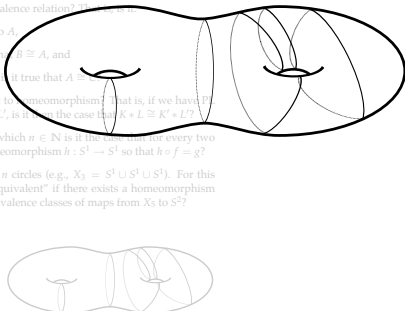
Problem 9. To the right, three curves are pictured on $T^2 \# T^2$, which is our notation for a two-holed surface. For which pairs of curves α and β does there exist a homeomorphism

$$f: T^2 \# T^2 \rightarrow T^2 \# T^2$$

so that $f(\alpha) = \beta$?

on today's

homework



PL Homeomorphism

Definition

A **piecewise linear homeomorphism**
(a **PL homeomorphism** for short)
is a PL map $f : K \rightarrow L$
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If there exists a homeomorphism between A and B , then A and B are **homeomorphic**.

Write $A \cong B$ if A and B are homeomorphic.

PL Manifold

A complex M is an n -dimensional **PL manifold**
(for short, an n -manifold)
if for every vertex v of M ,
 $\text{lk}(v, M)$ is PL homeomorphic to S^{n-1} .

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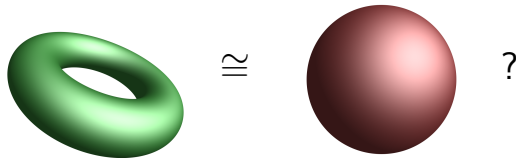
Is S^2 a manifold?

Problem

Is T^2 a manifold?

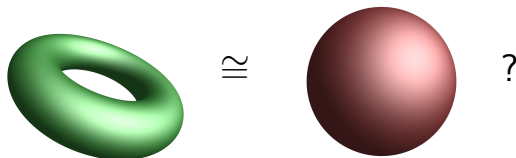
Going back, rethinking everything...

Is there a PL homeomorphism
between S^2 and T^2 ?



Going back, rethinking everything...

Is there a PL homeomorphism
between S^2 and T^2 ?



Check χ is unchanged after stellar subdivision
(we must also check more general subdivisions!)

Euler characteristic

$$K_\sigma := (K - \text{st}(\sigma, K)) \cup (v * (\partial\sigma) * \text{lk}(\sigma, K))$$

Need to check $\chi(K) = \chi(K_\sigma)$.

Euler characteristic and join

$$p_K(x) = 1/x + k_0 + k_1x + \cdots + k_nx^n$$

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$$p_{K*L}(x) = p_K(x) \cdot p_L(x) \cdot x$$

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Since $\chi(K) = p_K(-1) + 1$,

$$\begin{aligned}\chi(K * L) &= p_{K*L}(-1) + 1 \\ &= (\chi(K) - 1)(\chi(L) - 1) \cdot (-1) + 1\end{aligned}$$

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Since $\chi(K) = p_K(-1) + 1$,

$$\begin{aligned}\chi(K * L) &= p_{K*L}(-1) + 1 \\ &= (\chi(K) - 1)(\chi(L) - 1) \cdot (-1) + 1 \\ &= \chi(K) + \chi(L) - \chi(K)\chi(L).\end{aligned}$$

More joins!

$$\chi(K * L * M)$$

More joins!

$$\chi(K * L * M) = \chi(K * L) + \chi(M) - \chi(K * L)\chi(M)$$

More joins!

$$\begin{aligned}\chi(K * L * M) &= \chi(K * L) + \chi(M) - \chi(K * L)\chi(M) \\ &= \chi(K) + \chi(L) - \chi(K)\chi(L) + \chi(M) - \\ &\quad (\chi(K) + \chi(L) - \chi(K)\chi(L))\chi(M)\end{aligned}$$

More joins!

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Euler characteristic and union

The usual inclusion-exclusion business gives

$$\chi(K \cup L) = \chi(K) + \chi(L) - \chi(K \cap L)$$

Euler characteristic

$$\chi(K_\sigma)$$

$$= \chi(K).$$

Euler characteristic

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$$= \chi((K - \text{st}(\sigma, K)) \cup (v * (\partial\sigma) * \text{lk}(\sigma, K)))$$

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$$\begin{aligned} &= \chi(K - \text{st}(\sigma, K)) \\ &\quad + \chi(v * (\partial\sigma) * \text{lk}(\sigma, K)) \\ &\quad - \chi(\text{lk}(\sigma, K)) \end{aligned}$$

$$= \chi(K).$$

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$$+ \chi(v * (\partial\sigma) * \text{lk}(\sigma, K))$$

$$- \chi(\text{lk}(\sigma, K))$$

$$= \chi(K - \text{st}(\sigma, K)) + \chi(v * (\partial\sigma))$$

$$- \chi(v * (\partial\sigma)) \cdot \chi(\text{lk}(\sigma, K))$$

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$$= \chi(K - \text{st}(\sigma, K)) + \chi(\text{cl}(\text{st}(\sigma, K))) - \chi(\text{lk}(\sigma, K))$$

$$= \chi(K).$$

Upshot

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Haiku

The sphere and torus,
what with their differing χ ,
are not the same space.

The torus versus the Klein bottle

Since $\chi(T^2) = \chi(K) = 0$,

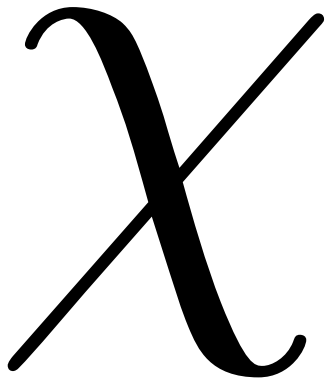
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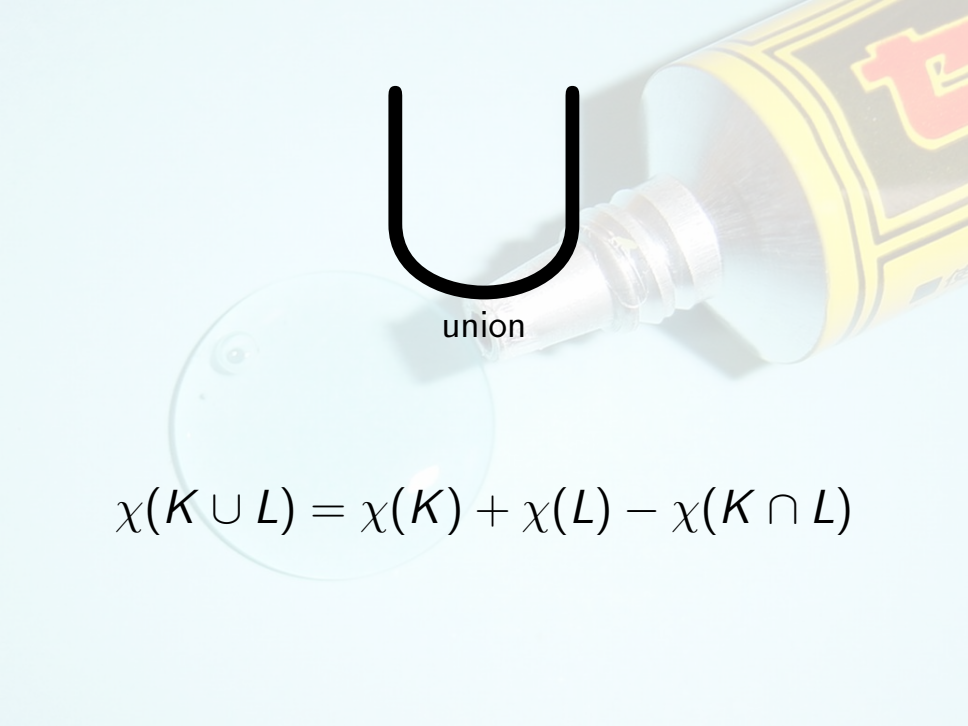
The torus versus the Klein bottle

Since $\chi(T^2) = \chi(K) = 0$,
and ... um ...

χ is not a complete invariant.



Let's think about Euler characteristic



U

union

$$\chi(K \cup L) = \chi(K) + \chi(L) - \chi(K \cap L)$$

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We want a new invariant.
Call it F .

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So $F(I) = F(\text{point})$.

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$$F(\Delta^2 \cup_I \Delta^2) = F(\Delta^2) + F(\Delta^2) - F(I).$$

So $F(\Delta^2) = F(I)$.

Similarly, $F(\Delta^n) = F(I)$.

A “new” invariant

Congratulations!

A “new” invariant

Congratulations! You have invented F ,

A “new” invariant

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Theorem

*An additive topological invariant is,
up to rescaling,
the Euler characteristic.*

A “new” invariant

Congratulations! You have invented F ,
a rescaled version of the Euler characteristic.

Theorem

*An additive topological invariant is,
up to rescaling,
the Euler characteristic.*

New invariants cannot be precisely additive.

Connected components

Define $b_0(K)$ to be the number of connected components of K .

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Vertices v, w of K belong to the same component if there exists a PL map $f : I \rightarrow K$ so that $f(0) = v$ and $f(1) = w$.

Connected components

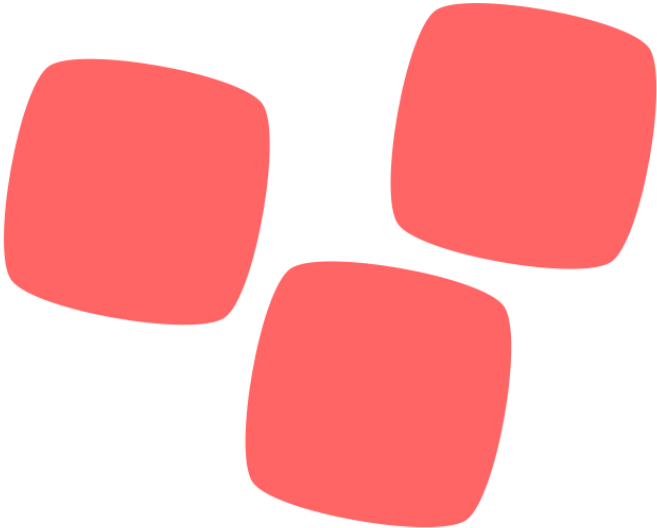
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Problem

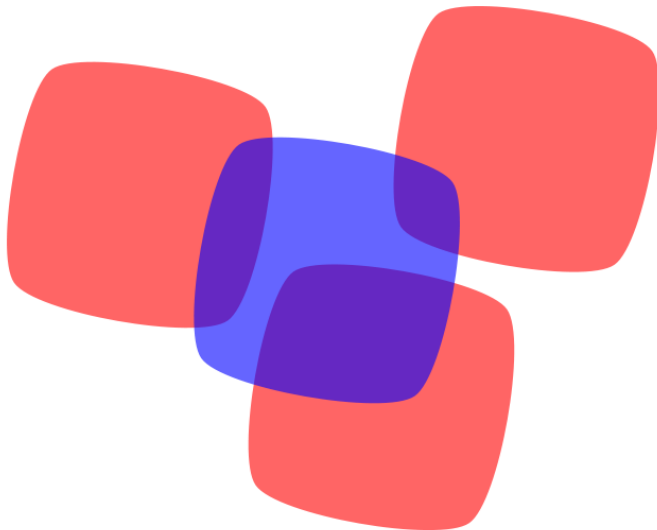
Is “belong to the same component” an equivalence relation on the vertices of K ?

Connected components



three

Connected components



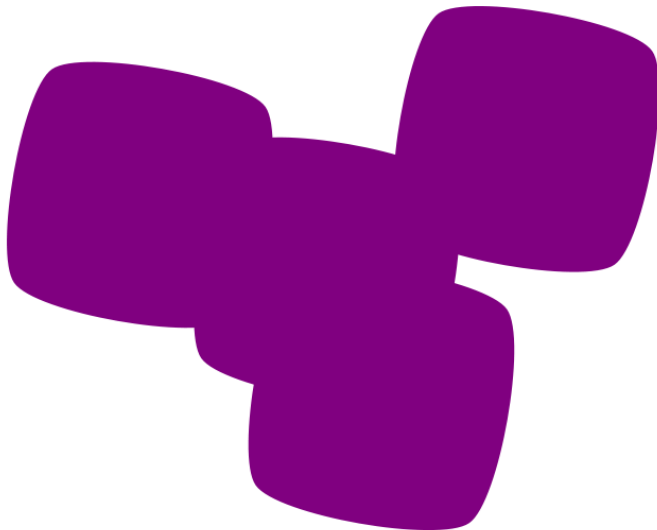
three + one

Connected components



three + one - three

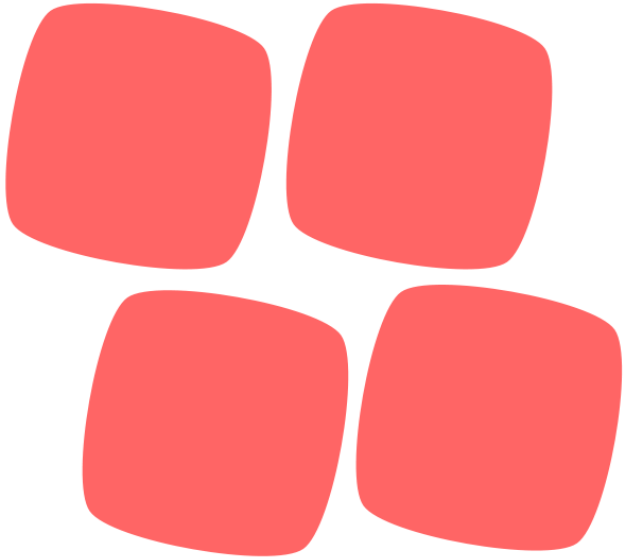
Connected components



$$\text{three} + \text{one} - \text{three} = \text{one}$$

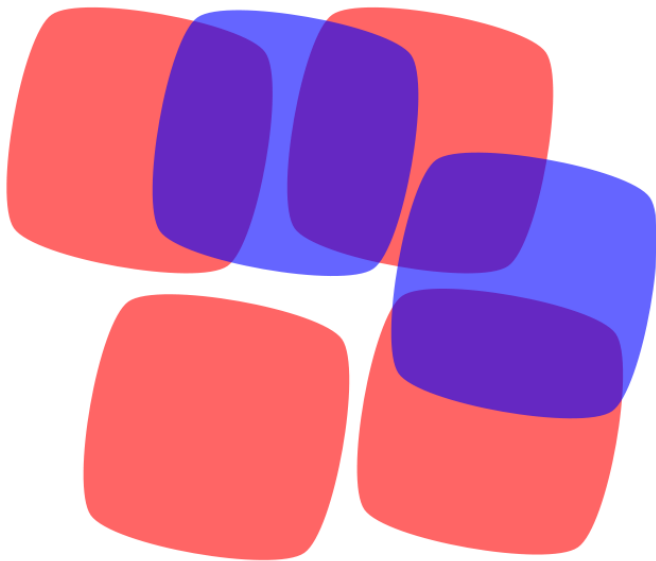
$$b_0(K \cup L) = b_0(K) + b_0(L) - b_0(K \cap L)?$$

Connected components



four

Connected components



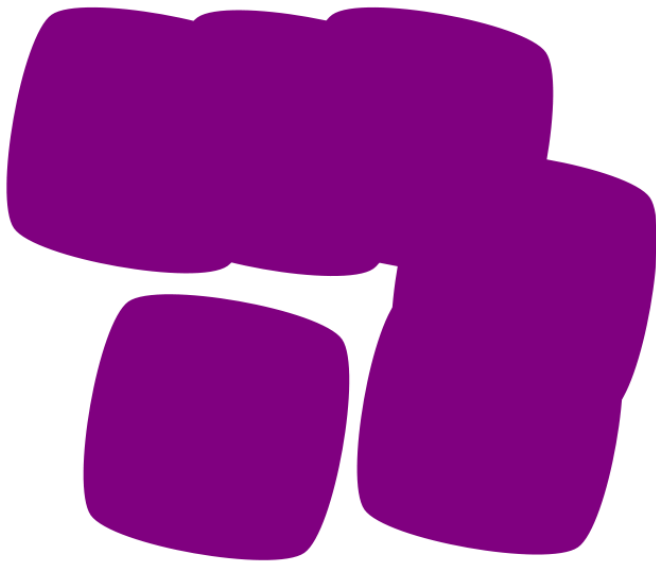
four + two

Connected components



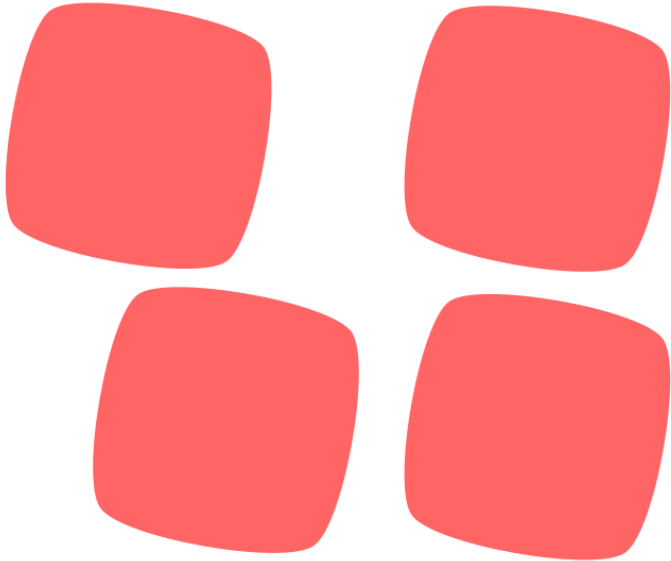
$$\text{four} + \text{two} - \text{four}$$

Connected components



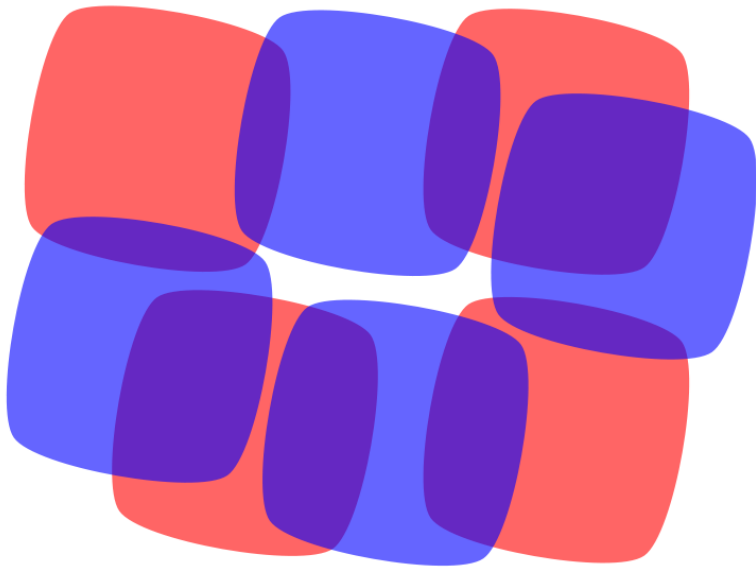
$$\text{four} + \text{two} - \text{four} = \text{two}$$

Connected components



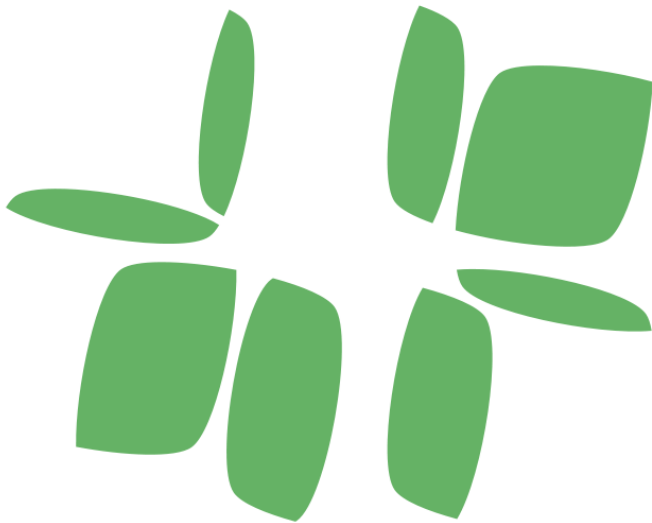
four

Connected components



four + four

Connected components



four + four - eight

Connected components



$$\text{four} + \text{four} - \text{eight} = \text{zero} \neq \text{one}$$

We will invent new invariants.

These invariants will not *quite* be additive.

The failure of additivity gives a new invariant,
itself not quite additive.

The failure will be captured by a deeper invariant,
itself not quite additive.

The failure will be captured by ...

This is **homology**.

The end of the beginning

What's next?

- ▶ manifolds
- ▶ simplicial collapse
- ▶ simple homotopy equivalence
- ▶ knots
- ▶ unknotting theorems
- ▶ return to (co)homology