

Topology of Piecewise-Linear Manifolds

Jim Fowler

Lecture 5
Summer 2010

A photograph of a claw hammer and a adjustable wrench, both with light-colored wooden handles, resting on a white surface.

Why do you keep hitting your hand with a hammer?

Where are we?



Where are we?

Objects



Where are we?

Objects PL manifolds?



Where are we?

Objects

PL manifolds?

1 simplicial complexes



Where are we?

Objects

PL manifolds?

Boul. Laurier

1 simplicial complexes

Maps

St- Valerien
de- Milton

143

SORTIE

45

km / h.

Where are we?

Objects

PL manifolds?

Boul. Laurier

1 simplicial complexes

Maps

PL maps?

St- Valérien
de - Mi

143

SORTIE

45

km / h.

Where are we?

Objects

PL manifolds?

Boul. Laurier

1 simplicial complexes

Maps

PL maps?

simplicial maps



Where are we?

Objects

PL manifolds?

Boul. Laurier

1 simplicial complexes

Maps

PL maps?

143

simplicial maps

Invariants

Where are we?

Objects

PL manifolds? simplicial complexes

Maps

- MiPLnmaps? simplicial maps

Invariants

χ

Where are we?

Objects

PL manifolds?

Boul. Laurier

1 simplicial complexes

Maps

PL maps?

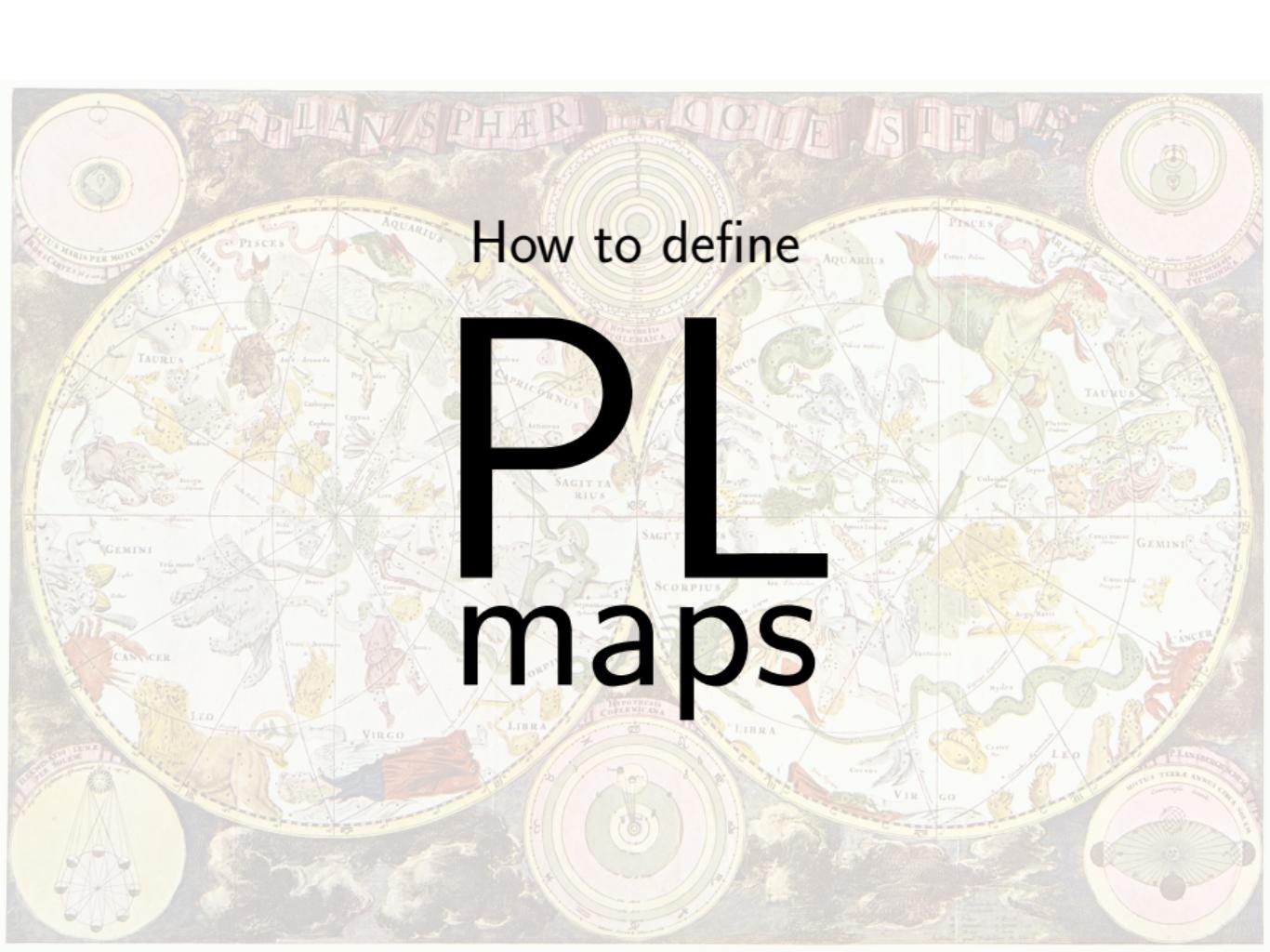
simplicial maps

Invariants

χ

b_0

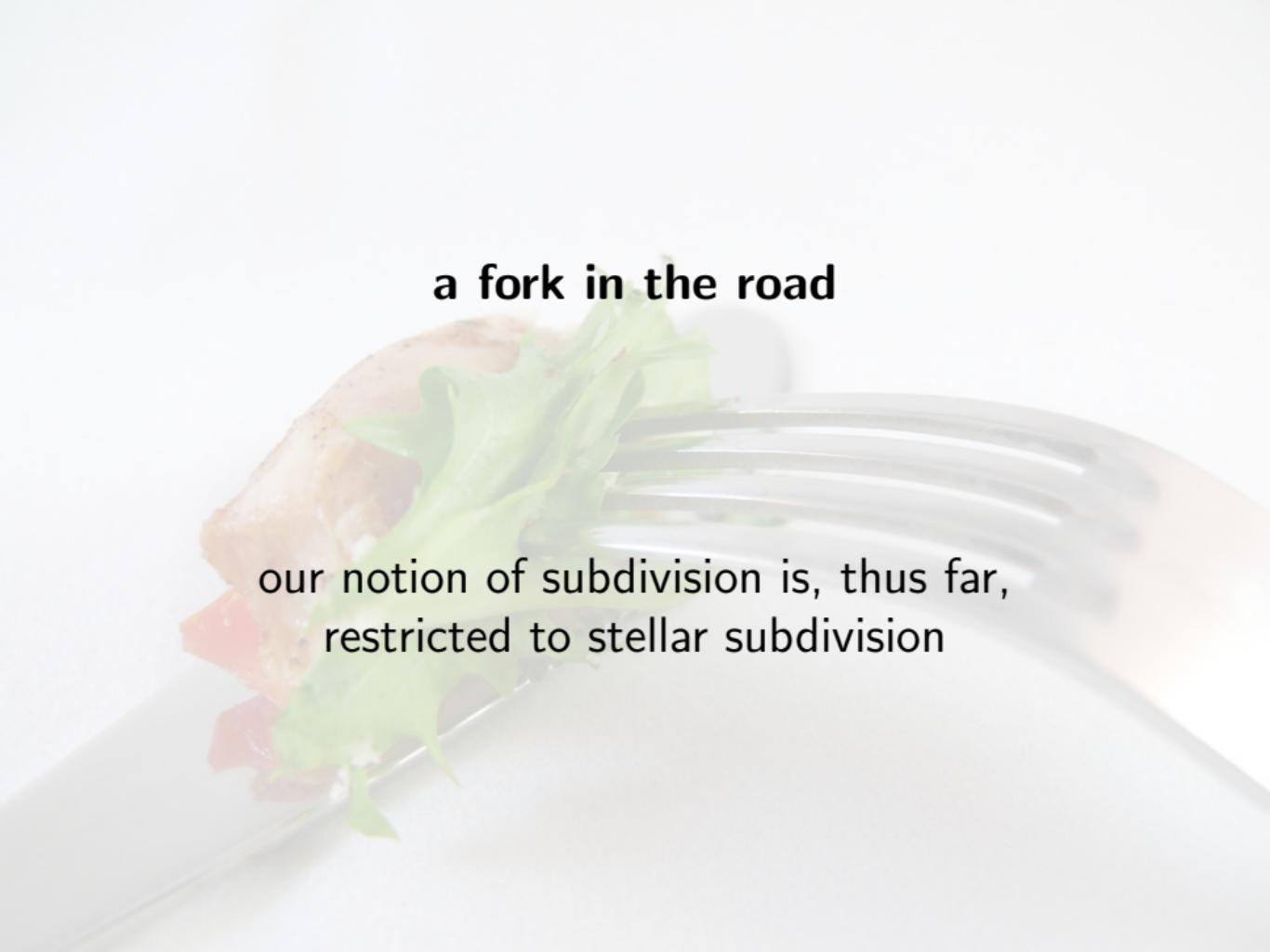




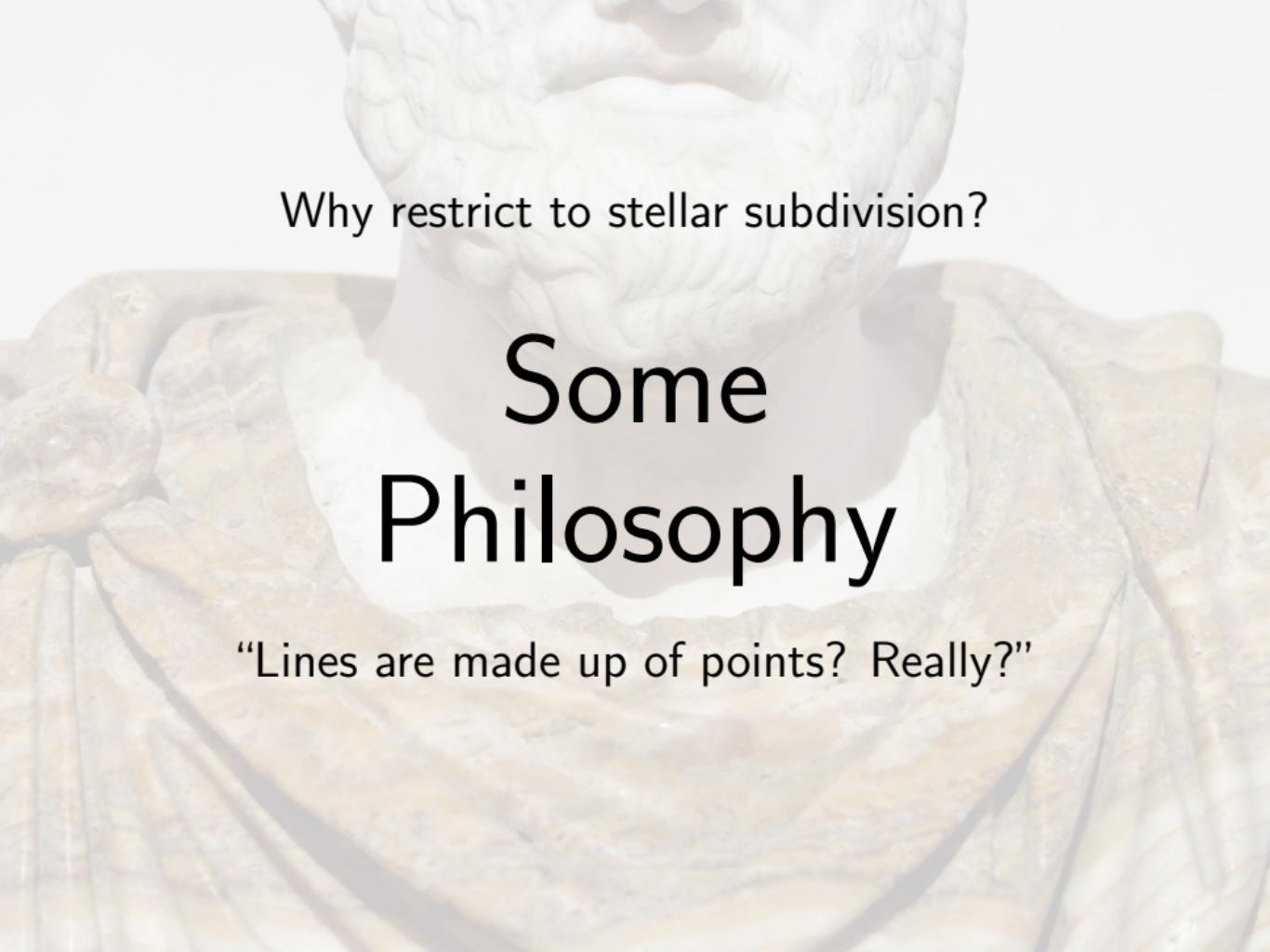
A detailed historical map of the sky, featuring the zodiac constellations and various other star patterns. The map is set against a background of concentric circles representing the Ptolemaic model of the universe. The title at the top reads "PLANISPHARII COLE STELLARUM". The map includes labels for Pisces, Aquarius, Aries, Taurus, Gemini, Cancer, Leo, Virgo, Libra, Scorpius, Sagittarius, Capricornus, and Pisces. It also shows numerous smaller constellations and mythological figures.

How to define PL maps

a fork in the road

A white plate holds a piece of salmon with a golden-brown crust, some green leafy vegetables, and a small red garnish. A silver fork lies across the plate, its tines pointing towards the right. The background is plain white.

our notion of subdivision is, thus far,
restricted to stellar subdivision



Why restrict to stellar subdivision?

Some Philosophy

“Lines are made up of points? Really?”

State of the art

Theorem

*Two n -dimensional simplicial complexes
are PL homeomorphic
if and only if
they are stellar equivalent.*

State of the art

Theorem

*Two n -dimensional simplicial complexes
are PL homeomorphic
if and only if
they are stellar equivalent.*

Theorem

*A PL map $f : K \rightarrow L$ is a simplicial map
from a subdivision of K
to a stellar subdivision of L .*

Warning: The subdivision of K needn't be stellar.

State of the art

Theorem

*Two n -dimensional simplicial complexes
are PL homeomorphic
if and only if
they are stellar equivalent.*

Theorem

*A PL map $f : K \rightarrow L$ is a simplicial map
from a subdivision of K
to a stellar subdivision of L .*

Warning: The subdivision of K needn't be stellar.

Question: What does “subdivision” mean?

The combinatorial part

- ▶ simplicial complex
- ▶ join
- ▶ link
- ▶ star
- ▶ Euler characteristic
- ▶ PL manifold: a complex K the link of each vertex PL homeomorphic (meaning stellar equivalent) to a sphere.

The non-combinatorial part

The notion of PL map is not quite general enough:
a simplicial map from a stellar subdivision of K
to a stellar subdivision of L is a PL map,
but we will need more general maps.

To do this, we will place our simplexes in \mathbb{R}^n .

\mathbb{R}^n

The join of $A, B \subset \mathbb{R}^n$ is

$$\{\lambda a + (1 - \lambda)b : a \in A, b \in B, \lambda \in [0, 1]\}$$

Polyhedron

$P \subset \mathbb{R}^n$ is a **polyhedron**

if for each $p \in P$

there is a neighborhood $N \ni p$

so that $N = p * L$,

with L closed and bounded.

Polyhedron

$P \subset \mathbb{R}^n$ is a **polyhedron**

if for each $p \in P$

there is a neighborhood $N \ni p$

so that $N = p * L$,

with L closed and bounded.

For example, $N = \{q \in P : d(p, q) \leq \epsilon\}$, but we allow more general neighborhoods.

Polyhedron

$P \subset \mathbb{R}^n$ is a **polyhedron**

if for each $p \in P$

there is a neighborhood $N \ni p$

so that $N = p * L$,

with L closed and bounded.

For example, $N = \{q \in P : d(p, q) \leq \epsilon\}$, but we allow more general neighborhoods.

N is called a **closed star** around p .

L is a **link** of p .

Piecewise linear map

Let P, Q be polyhedra.

$f : P \rightarrow Q$ is a PL map

if each point $p \in P$

has a closed star $N = p * L$

so that $f(\lambda p + (1 - \lambda)x) = \lambda f(p) + (1 - \lambda)f(x)$

for $x \in L$ and $\lambda \in [0, 1]$.

In short, it locally maps conical rays to conical rays.

Next steps

9

Next steps

- ▶ New constructions

Next steps

- ▶ New constructions
connected sum

Next steps

- ▶ New constructions
connected sumand
Cartesian product, using polyhedra

Next steps

- ▶ New constructions
connected sumand
Cartesian product, using polyhedra
- ▶ New invariant

Next steps

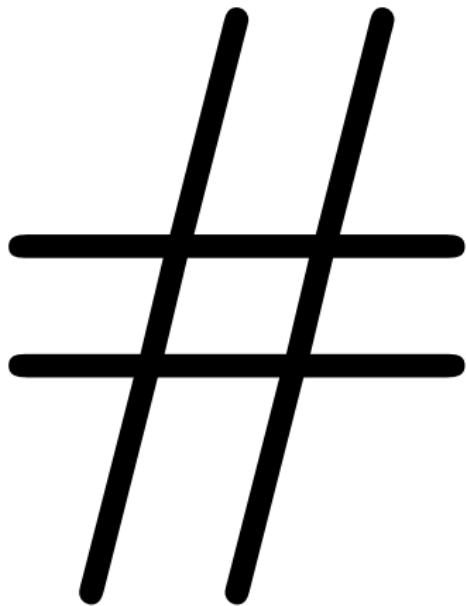
- ▶ New constructions
connected summand
Cartesian product, using polyhedra
- ▶ New invariant
orientability, w_1

Next steps

- ▶ New constructions
connected summand
Cartesian product, using polyhedra
- ▶ New invariant
orientability, w_1
- ▶ New kind of equivalence

Next steps

- ▶ New constructions
connected summand
Cartesian product, using polyhedra
- ▶ New invariant
orientability, w_1
- ▶ New kind of equivalence
simple homotopy equivalence



connected sum

Connected sum

Definition

Suppose K and L are two n -manifolds.

Let K' be K with one n -simplex removed.

$$L' \quad L$$

Define $K \# L = K' \cup_{\partial \Delta^n} L'$.

Connected sum

Definition

Suppose K and L are two n -manifolds.

Let K' be K with one n -simplex removed.

$$L' \quad L$$

Define $K \# L = K' \cup_{\partial \Delta^n} L'$.

Problem

What is $T^2 \# T^2$?

Connected sum

Definition

Suppose K and L are two n -manifolds.

Let K' be K with one n -simplex removed.

$$L' \quad L$$

Define $K \# L = K' \cup_{\partial \Delta^n} L'$.

Problem

What is $T^2 \# T^2$?

Problem

What is $S^2 \# T^2$?





#



||





In general, Σ_g = genus g surface,



In general, Σ_g = genus g surface,
and $T^2 \# \Sigma_g = \Sigma_{g+1}$.

Covering map

Definition

$f : M \rightarrow N$ is an n -fold **covering map**
if for every k -simplex $\tau \in N$,
 $f^{-1}(\tau)$ consists of n copies of a k -simplex.

Gift-wrapping surfaces

Problem

*When is there an n -fold covering map
from a genus g surface
to a genus g' surface?*

Gift-wrapping surfaces

Problem

*When is there an n -fold covering map
from a genus g surface
to a genus g' surface?*

Theorem

*If $f : M \rightarrow N$ is an n -fold covering map
then $\chi(M) = n \cdot \chi(N)$.*

Gift-wrapping surfaces

Problem

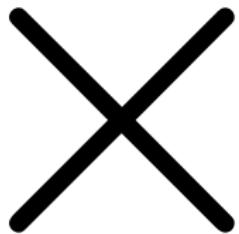
*When is there an n -fold covering map
from a genus g surface
to a genus g' surface?*

Theorem

*If $f : M \rightarrow N$ is an n -fold covering map
then $\chi(M) = n \cdot \chi(N)$.*

Problem

What is $\chi(\text{genus } g \text{ surface})$?



Cartesian product

Products, geometrically

Definition

Suppose $K \subset \mathbb{R}^n$, and $L \subset R^m$.

The product of K and L is

$$K \times L = \{(k, \ell) \in \mathbb{R}^{n+m} : k \in K, \ell \in L\}.$$

Products, geometrically

Definition

Suppose $K \subset \mathbb{R}^n$, and $L \subset R^m$.

The product of K and L is

$$K \times L = \{(k, \ell) \in \mathbb{R}^{n+m} : k \in K, \ell \in L\}.$$

Could we do this for a simplicial complex?

Product of simplexes

How do we take a product of Δ^1 and Δ^1 ?

Product of simplexes

How do we take a product of Δ^1 and Δ^2 ?

Product of simplexes

How do we take a product of Δ^2 and Δ^2 ?

Product of simplexes

How do we take a product of Δ^2 and Δ^2 ?
Hard to see, so let's take a step back.

Vertices of $\Delta^n \times \Delta^m$ are pairs
 (i, j) with $0 \leq i \leq n + 1$ and $0 \leq j \leq m + 1$.

Vertices of $\Delta^n \times \Delta^m$ are pairs
 (i, j) with $0 \leq i \leq n + 1$ and $0 \leq j \leq m + 1$.

A simplex of $\Delta^n \times \Delta^m$ is [REDACTED]

Some counting problems

$\Delta^1 \times \Delta^n$ has $(n + 1)!$ triangulations.

Some counting problems

$\Delta^1 \times \Delta^n$ has $(n + 1)!$ triangulations.

$\Delta^2 \times \Delta^n$ has [REDACTED] triangulations.

Some counting problems

$\Delta^1 \times \Delta^n$ has $(n + 1)!$ triangulations.

$\Delta^2 \times \Delta^n$ has [REDACTED] triangulations.

So maybe it would be nice if we could handle these cases without resorting to simplexes.

Product of polyhedra is a polyhedron

P, Q polyhedra.

Is $P \times Q$ a polyhedron?

Product of polyhedra is a polyhedron

P, Q polyhedra.

Is $P \times Q$ a polyhedron?

Need neighborhood of $(p, q) \in P \times Q$.

Product of polyhedra is a polyhedron

P, Q polyhedra.

Is $P \times Q$ a polyhedron?

Need neighborhood of $(p, q) \in P \times Q$.

$p \in P$ has a neighborhood $p * L_p$

$q \in Q$ has a neighborhood $q * L_q$

Product of polyhedra is a polyhedron

P, Q polyhedra.

Is $P \times Q$ a polyhedron?

Need neighborhood of $(p, q) \in P \times Q$.

$p \in P$ has a neighborhood $p * L_p$

$q \in Q$ has a neighborhood $q * L_q$

Use $(p, q) * (L_p * L_q)$.

Some 4-manifolds

Some 4-manifolds

$$S^3 \times S^1$$

Some 4-manifolds

$$S^3 \times S^1$$

$$S^2 \times S^2$$

Some 4-manifolds

$$S^3 \times S^1$$

$$S^2 \times S^2$$

$$\Sigma_g \times \Sigma_h$$

W1

orientability

The torus versus the Klein bottle

Since $\chi(T^2) = \chi(K) = 0$,
we can't distinguish T^2 and K using χ .

The torus versus the Klein bottle

Since $\chi(T^2) = \chi(K) = 0$,
we can't distinguish T^2 and K using χ .

We need a new invariant.

Orientation

An orientation of a simplex is
a choice of ordering of the vertices,
up to an even permutation.

Orientation

An orientation of a simplex is a choice of ordering of the vertices, up to an even permutation.

Definition

An orientation on a manifold M^n is an orientation of each n -simplex so that neighboring n -simplexes induce opposite orientations on the shared $(n - 1)$ -simplex.

Orientation

An orientation of a simplex is a choice of ordering of the vertices, up to an even permutation.

Definition

An orientation on a manifold M^n is an orientation of each n -simplex so that neighboring n -simplexes induce opposite orientations on the shared $(n - 1)$ -simplex.

If M admits an orientation, $w_1(M) = 0$. Otherwise, $w_1(M) = 1$.

Orientability for surfaces

Theorem

A surface Σ is not orientable iff Σ contains a Möbius strip.

Orientability for surfaces

Theorem

A surface Σ is not orientable iff Σ contains a Möbius strip.

Problem

What is $w_1(T^2)$?

Orientability for surfaces

Theorem

A surface Σ is not orientable iff Σ contains a Möbius strip.

Problem

What is $w_1(T^2)$?

Problem

What is $w_1(K)$?

Orientability for surfaces

Theorem

A surface Σ is not orientable iff Σ contains a Möbius strip.

Problem

What is $w_1(T^2)$?

Problem

What is $w_1(K)$?

Problem

Is w_1 a PL homeomorphism invariant?

Distinguishing other manifolds?

Can we distinguish T^3 and S^3 with Euler characteristic?

Distinguishing other manifolds?

Can we distinguish T^3 and S^3 with Euler characteristic?

No

Distinguishing other manifolds?

Can we distinguish T^3 and S^3 with Euler characteristic?

No. . .

We need more invariants,

Distinguishing other manifolds?

Can we distinguish T^3 and S^3 with Euler characteristic?

No...

We need more invariants,
or a looser notion of “the same.”



Simplicial Collapse

Principal Simplexes

Definition

Let K be a complex, and

$\sigma \in K$ a simplex.

Call σ a **principal simplex**

if the only simplex containing σ
is σ itself

(i.e., it isn't contained in a larger simplex).

Principal Simplexes

Definition

Let K be a complex, and

$\sigma \in K$ a simplex.

Call σ a **principal simplex**

if the only simplex containing σ
is σ itself

(i.e., it isn't contained in a larger simplex).

Problem

Does every complex have a principal simplex?

Free faces

Definition

Let K be a complex,
and $\sigma \in K$ a simplex,
and $\tau < \sigma$ a face.

Call τ a **free face** of σ
if the only simplexes containing τ
are τ and σ .

Free faces

Definition

Let K be a complex,
and $\sigma \in K$ a simplex,
and $\tau < \sigma$ a face.

Call τ a **free face** of σ
if the only simplexes containing τ
are τ and σ .

Problem

Does every complex have a simplex with a free face?

Free faces

Definition

Let K be a complex,
and $\sigma \in K$ a simplex,
and $\tau < \sigma$ a face.

Call τ a **free face** of σ
if the only simplexes containing τ
are τ and σ .

Problem

Does every complex have a simplex with a free face?
Does any complex have a simplex with a free face?

Elementary simplicial collapse

Definition

Let L and $K = L \cup \text{cl}\{\sigma, \tau\}$ be complexes

If σ is a principal simplex of K , and

τ is a free face of σ , then

L is an **elementary simplicial collapse** of K .

Simplicial collapse

Definition

Let K_1, K_2, \dots, K_n be complexes, with
 K_{i+1} an elementary simplicial collapse of K_i .

Call K_n a **simplicial collapse** of K_1 , and
write $K_1 \searrow K_n$.

Call K_1 a **simplicial expansion** of K_n , and
write $K_n \nearrow K_1$.

Simple homotopy equivalence

Definition

K is **simple homotopy equivalent** to L

(sometimes abbreviated s.h.e.)

if you can reach transform K into L
via a sequence of

- ▶ PL homeomorphisms,
- ▶ simplicial collapses,
- ▶ simplicial expansions.

In this case, we write $K \downarrow\uparrow L$.

UNKNOTTING SPHERES IN FIVE DIMENSIONS

BY E. C. ZEEMAN

Communicated by S. Eilenberg, December 26, 1959

Given a semi-linear embedding of S^2 in euclidean 5-space, we show that it is unknotted.

Join it up to a vertex V in general position. If the cone VS^2 is non-singular we are finished. Otherwise, for dimensional reasons, there are at most a finite number of singularities, where just two points of S^2 are collinear with V . Let's have V away on one side, so that at each singularity we can call one point "near" and the other point "far." Now separate the near and far points by an equator S^1 , so that all the near points lie in the northern hemisphere A , and all the far points lie in the southern hemisphere B .

Let \hat{S}^2 be the sphere $VS^1 \cup B$. Then \hat{S}^2 is equivalent to S^2 , because they differ by the boundary of the ball VA , whose interior does not meet them. But \hat{S}^2 is unknotted because it bounds, and does not meet the interior of, the ball VB . Hence S^2 is unknotted.

REMARK 1. The argument generalizes to unknotting S^n in k -space, $k \geq (3/2)(n+1)$.

UNKNOTTING SPHERES IN FIVE DIMENSIONS

BY E. C. ZEEMAN

Communicated by S. Eilenberg, December 26, 1959

Given a semi-linear embedding of S^2 in euclidean 5-space, we show that it is unknotted.

Join it up to a vertex V in general position. If the cone VS^2 is non-singular we are finished. Otherwise, for dimensional reasons, there

- ▶ **Regular neighborhoods**

are at most five singularities, where just two points of S^2 are collinear with V . Let's have V away on one side, so that at each singularity we can call one point "near" and the other point "far."

- ▶ **Unknotting S^1 in S^3**

Now separate the near and far points by a local collar S^1 , so that all the near points lie in the northern hemisphere A , and all the far points lie in the southern hemisphere B .

Let \hat{S}^2 be the sphere $VS^1 \cup B$. Then \hat{S}^2 is equivalent to S^2 , because they differ by the boundary of the ball VA , whose interior does not meet them. But \hat{S}^2 is unknotted because it bounds, and does not meet the interior of, the ball VB . Hence S^2 is unknotted.

REMARK 1. The argument generalizes to unknotting S^n in k -space, $k \geq (3/2)(n+1)$