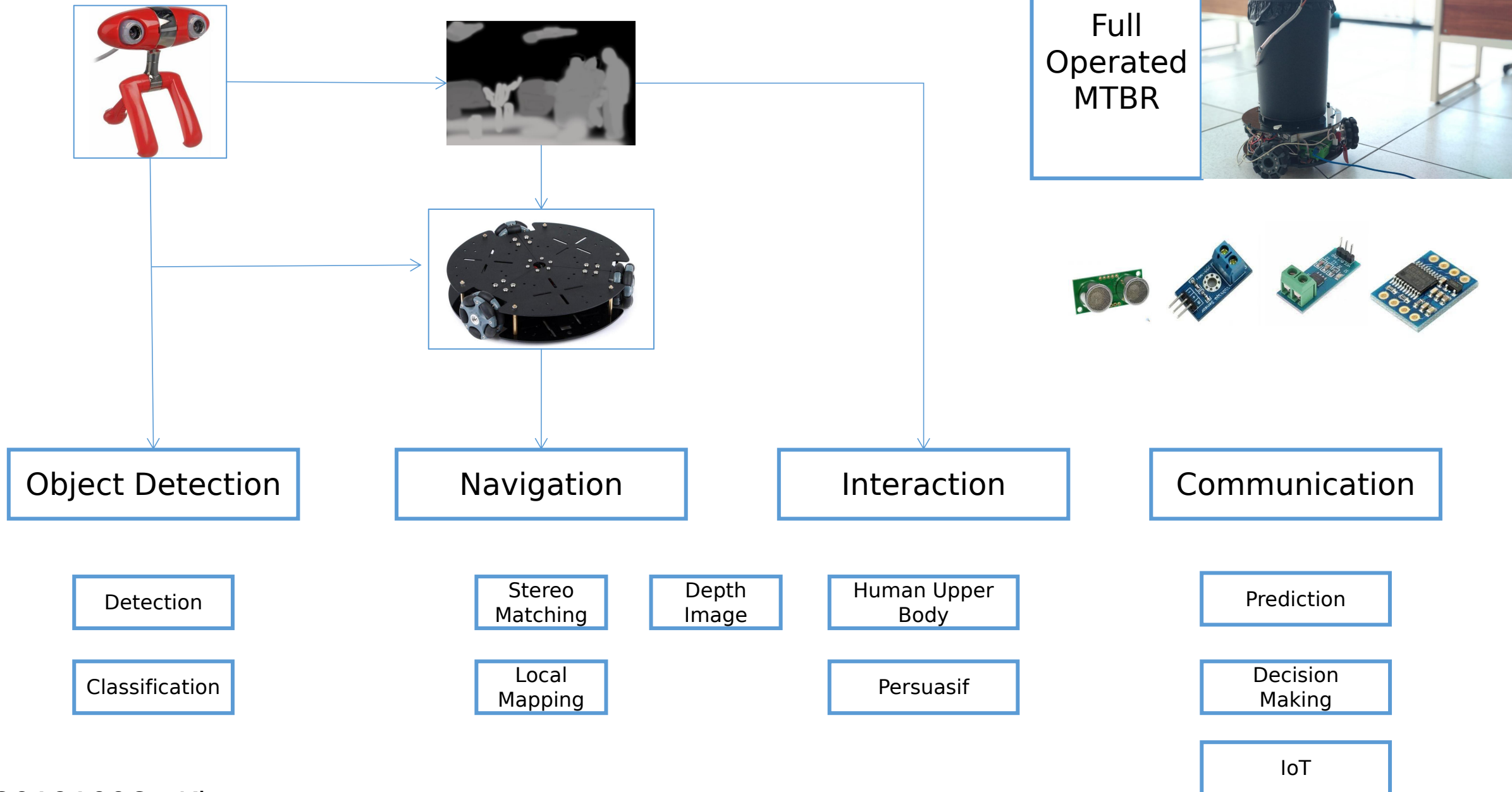


Weekly Progress - 17/9/2019





Already Done

- Installing ROS and QT Creator
- Access camera using ROS
- Create simple publisher subscriber (txt and img)
- Try roserial to send data from arduino to PC
- Looks for journals reference

On going

- Stereo camera calibration
- Looking for reference journal
- Learning Process to getting Depth images
- Getting Depth Images

Problem

- enter the calibration results into the depth function.
- what is the best title for my thesis ?

Next task

Try research that has been made before in ROS platform :

- Object Detection
- Navigation
- Communication (my project)