

# Hash Table

1. Introduction
2. Collision Resolution
3. External Hashing

# Introduction

# Want $\Theta(1)$ -Time Operations

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- Array or linked list
  - Overall  $O(n)$  time
- Binary search trees
  - Expected  $\theta(\log n)$ -time search, insertion, and deletion
  - But,  $\theta(n)$  in the worst case
- Balanced binary search trees
  - Guarantees  $O(\log n)$ -time search, insertion, and deletion
  - Red-black tree, AVL tree
- Balanced  $k$ -ary trees
  - Guarantees  $O(\log n)$ -time search, insertion, and deletion w/ smaller constant factor
  - 2-3 tree, 2-3-4 tree, B-trees
- Hash table
  - Expected  $\theta(1)$ -time search, insertion, and deletion

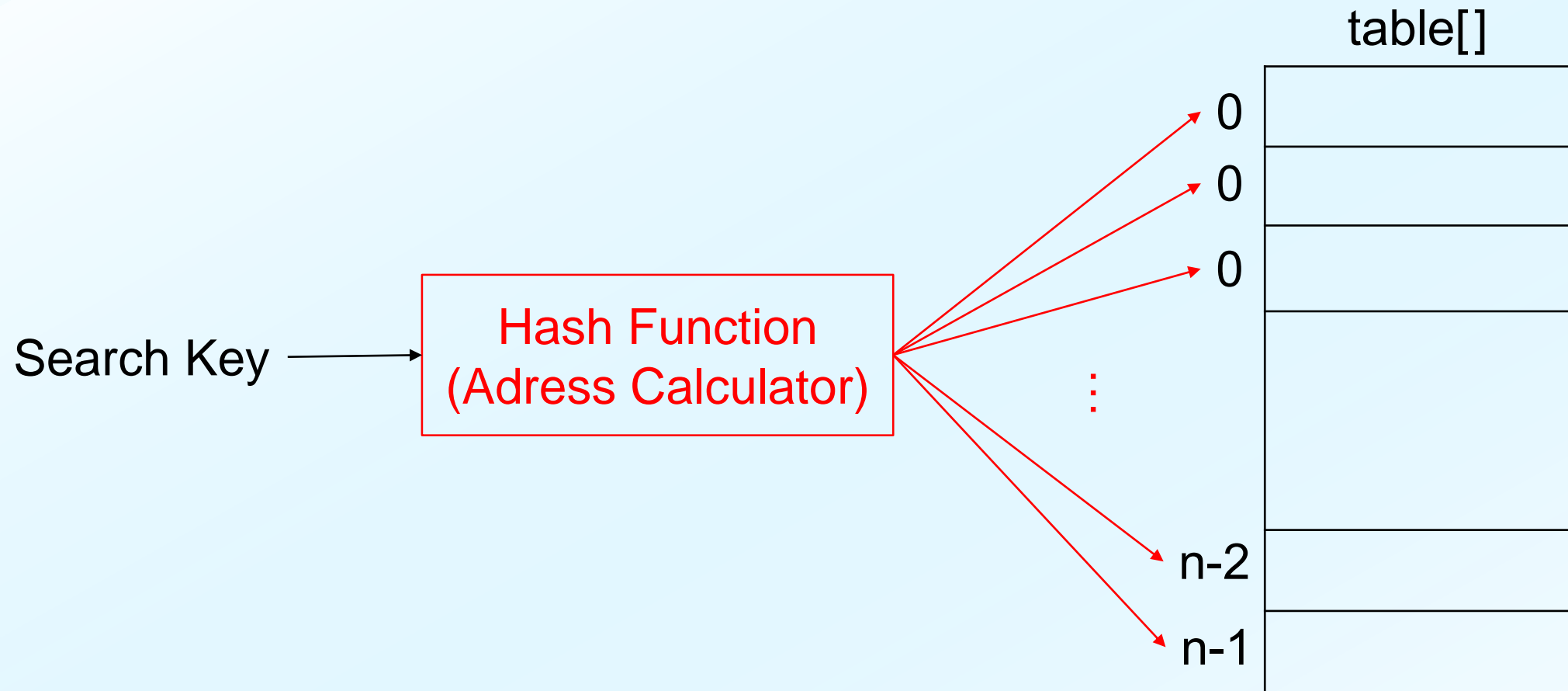
# Hash Tables

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- Stack, queue, priority queue
  - do not support *search* operation
- Hash table support quick search, insertion, and deletion
  - But, does not support finding the minimum (or maximum) element
- Applications that need very fast operations
  - 119 emergent calls and locating caller's address
  - Air flight information system
  - 주민등록 시스템

# Address Calculator

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# Hash Functions

- Toy functions
  - Selection digits
    - $h(001\textcolor{red}{3}6482\textcolor{red}{5}) = 35$
  - Folding
    - $h(\textcolor{brown}{0}0\textcolor{brown}{1}\textcolor{red}{3}\textcolor{red}{6}\textcolor{blue}{4}\textcolor{green}{8}2\textcolor{green}{5}) = 1190$
- Modulo arithmetic
  - $h(x) = x \bmod \textit{tableSize}$
  - *tableSize* is recommended to be prime
- Multiplication method
  - $h(x) = (xA \bmod 1) * \textit{tableSize}$
  - *A*: constant in (0, 1)
  - *tableSize* is not critical, usually  $2^p$  for an integer  $p$

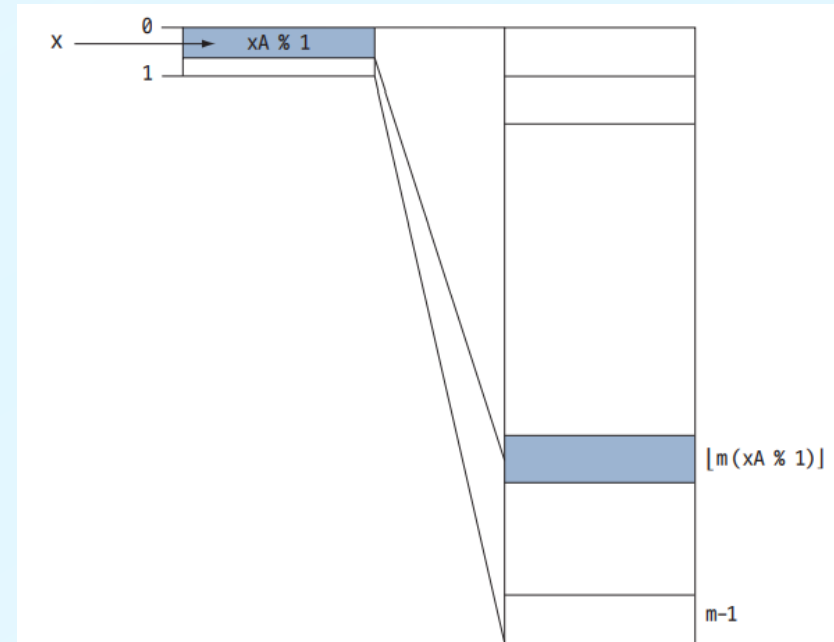


그림 12-3 곱하기 방법의 작동 원리

# Collision Resolution

# Collision

A key maps to an occupied location in the hash table

$$h(224) = 224 \bmod 101 = 22$$

Table[22] is occupied.  
Collision!

table[]	
0	
	⋮
22	123
	⋮
100	

An example:  $h(x) = x \bmod 101$



# Collision Resolution

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- Resolves collision by a seq. of hash values
- $h_0(x)(=h(x)), h_1(x), h_2(x), h_3(x), \dots$
- The core of hash-table management

# Collision-Resolution Methods

## Open addressing (resolves in the array)

- Linear probing
  - $h_i(x) = (h_0(x) + i) \bmod \text{tableSize}$
- Quadratic probing
  - $h_i(x) = (h_0(x) + i^2) \bmod \text{tableSize}$
- Double hashing
  - $h_i(x) = (h_0(x) + i \cdot f(x)) \bmod \text{tableSize}$
  - $f(x)$ : another hash function

Simple version

Full version:

$$h_i(x) = (h_0(x) + ai^2 + bi + c) \bmod \text{tableSize}$$

## Separate chaining

- Each  $\text{table}[i]$  is maintained by a linked list

# 개방 주소 방법 Open Addressing

## 선형 탐색 Linear Probing

$$h_i(x) = (h_0(x) + i) \% m$$

1차 군집 Primary Clustering에 취약

$$h_3(729) = (h_0(729) + 3) \% 101 \xrightarrow[i = 3]{x = 729}$$

table[]		삽입 순서: 123, 24, 224, 22, 729, ...
0		
	⋮	
22	123	$h_0(123)=h_0(224)=h_0(22)=h_0(729)=22$
23	224	$h_0(729)+1$
24	24	$h_0(24) = 24 \quad h_0(729)+2$
25	22	$h_0(729)+3$
	729	$h_0(729)+4$
	⋮	
100		

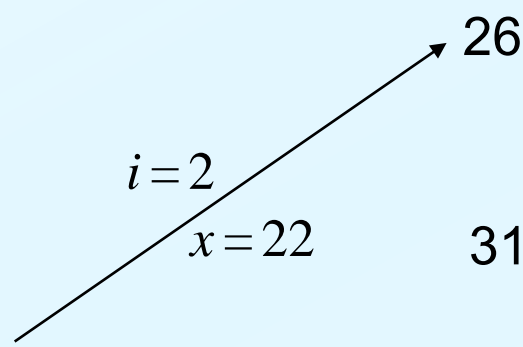
# 개방 주소 방법

## 이차원 탐색 Quadratic Probing

$$h_i(x) = (h_0(x) + i^2) \% m$$

2차 군집 Secondary Clustering에 취약

$$h_2(22) = (h_0(22) + 2^2) \% 101$$



table[]		
	⋮	
22	123	$h_0(123) = h_0(224) = 22$
23	224	$h_0(22) + 1^2$
	24	
26	22	$h_0(22) + 2^2$
	⋮	
31	729	
	⋮	

# 개방 주소 방법

## 더블 해싱 Double hashing

$$h_i(x) = (h_0(x) + i \cdot f(x)) \% 101$$

$$h_0(x) = x \% 101$$
$$f(x) = 1 + (x \% 97)$$

$$h_1(224) = (h_0(224) + 1 \cdot f(224)) \% 101 = 53$$
$$f(224) = 1 + (224 \% 97) = 31$$

table[]		
	⋮	
22	123	$h_0(123) = h_0(224) = h_0(22) = h_0(729) = 22$
	⋮	
45	22	$f(22) = 23, h_1(22) = 45$
	⋮	
53	224	$f(224) = 31, h_1(224) = 53$
	⋮	
73	729	$f(729) = 51, h_1(729) = 73$
	⋮	

# 삭제시 조심할 것

0	13
1	1
2	15
3	16
4	28
5	31
6	38
7	7
8	20
9	
10	
11	
12	25

(a) 원소 1 삭제

0	13
1	
2	15
3	16
4	28
5	31
6	38
7	7
8	20
9	
10	
11	
12	25

(b) 38 검색, 문제발생

0	13
1	DELETED
2	15
3	16
4	28
5	31
6	38
7	7
8	20
9	
10	
11	
12	25

(c) 표식을 해두면 문제없다

# Insertion

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**hashInsert( $x$ ):**

◀ table[]: hash table,  $x$ : new key to insert

**if** (table[ $h(x)$ ] is not occupied)

    table[ $h(x)$ ]  $\leftarrow x$

**else**

    Find an appropriate location  $i$  by a collision-resolution method

    table[ $i$ ]  $\leftarrow x$

numItems++

# Deletion

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**hashDelete( $x$ ):**

◀ table[]: hash table,  $x$ : key to delete

Find the location  $i$  of  $x$  by search

**if** (search was successful)

    table[ $i$ ]  $\leftarrow$  DELETED

    numItems--



# Increasing the size of hash table

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- Load factor  $\alpha$ 
  - The rate of occupied slots in the table
  - A high load factor harms performance
    - We need to increase the size of hash table
- Increasing the hash table
  - Roughly double the table size
  - Rehash all the items on the new table

# Java Code

```
public class OpenHashTable implements IndexInterface<Integer>{
    private Integer table[];
    int numItems;
    static final Integer DELETED = -12345, NOT_FOUND = -1; //auto boxing
    public OpenHashTable(int n) {
        table = new Integer[n];
        numItems = 0;
        for (int i = 0; i < n; i++) table[i] = null;
    }
    private int hash(int i, Integer x) {
        return (x + i) % table.length; // Linear probing
    }
    public Integer search(Integer x) {
        int slot;
        for (int i = 0; i < table.length; i++) {
            slot = hash(i, x);
            if (table[slot] == null)
                return NOT_FOUND;
            else if (table[slot].compareTo(x) == 0)
                return slot; // Found at table[slot]
        }
        return NOT_FOUND;
    }
}
```

...

```

public void insert(Integer x) {
    int slot;
    if (numItems == table.length) { /* 에러 처리 */ }
    else {
        for (int i = 0; i < table.length; i++) {
            slot = hash(i, x);
            if (table[slot] == null || table[slot].compareTo(DELETED) == 0) {
                table[slot] = x;
                numItems++;
                break;
            }
        }
        // 여기에 도착하면 에러(해시 함수가 universal 하지 않음)
    }
}

public void delete(Integer x) {
    int slot;
    for (int i = 0; i < table.length; i++) {
        slot = hash(i, x);
        if (table[slot] == null) break; // 또는 에러 처리
        else if (table[slot] == x) {
            table[slot] = DELETED;
            numItems--;
            break;
        }
    }
    // x가 존재하지 않으면 아무 영향도 미치지 않고 끝나거나, 에러 처리
}

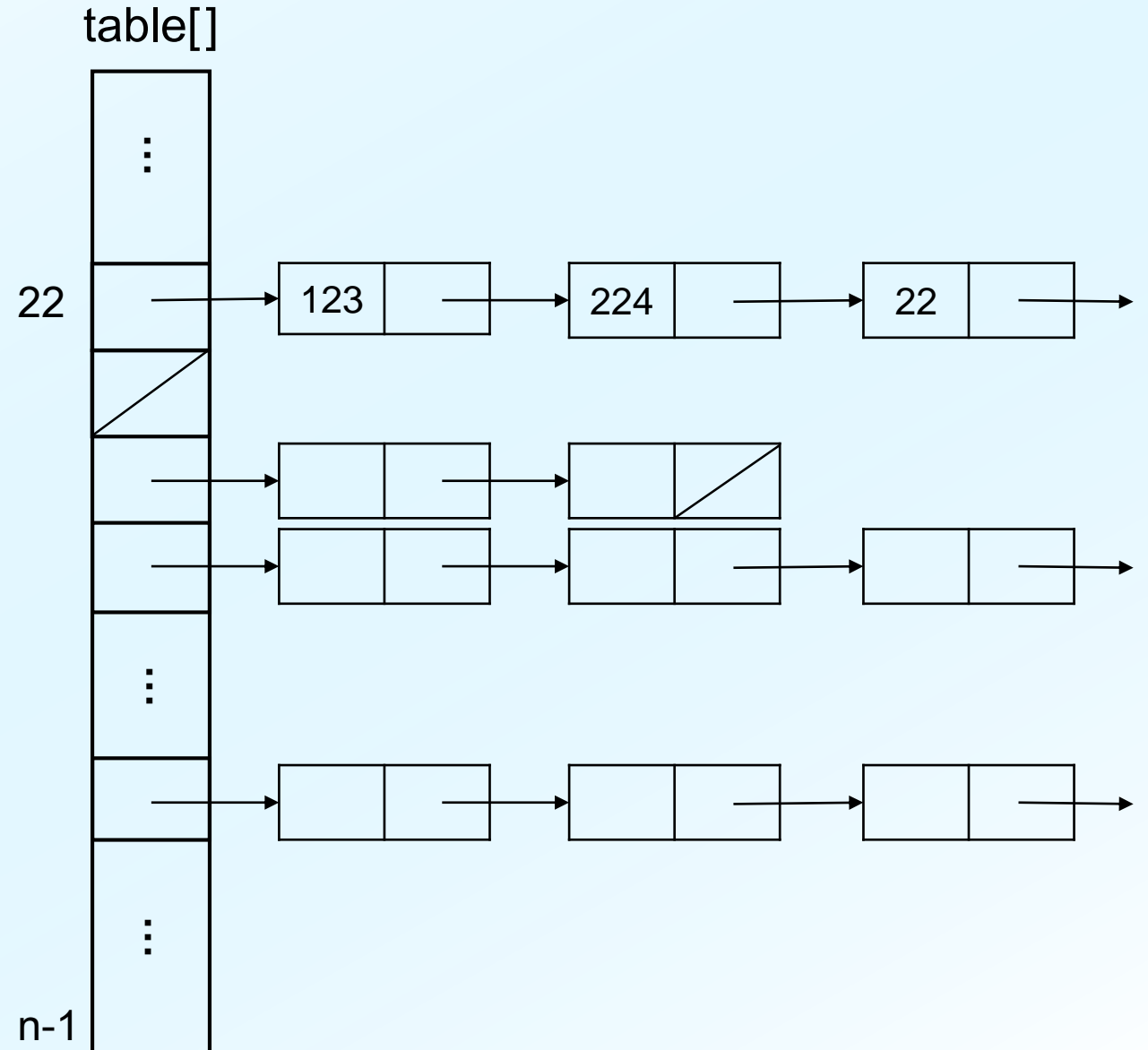
// isEmpty() and clear() are trivial
} // end class OpenHashTable

```

# Separate Chaining

Hash table은 linked list의 header들

No interference bet'n keys not collided



# Operations in Chained Hash Table

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**search**(table[],  $x$ ):  
Search  $x$  in the list table[ $h(x)$ ]

**insert**(table[],  $x$ ):  
Insert  $x$  in the list table[ $h(x)$ ]

**delete**(table,  $x$ ):  
Delete  $x$  in the list table[ $h(x)$ ]

# Java Code

```
public class ChainedHashTable implements IndexInterface<Node<Integer>> {
    private LinkedList<Integer>[] table;
    int numItems = 0;
    public ChainedHashTable(int n) {
        table = (LinkedList<Integer>[]) new LinkedList[n];
        //컴파일러는 불평하지만 ok
        for (int i = 0; i < n; i++)
            table[i] = new LinkedList<>();
        numItems = 0;
    }
    private int hash(Integer x) {
        return x % table.length; // 간단한 예
    }
    public void insert(Integer x) {
        int slot = hash(x);
        table[slot].add(0, x);
        numItems++;
    }
    ...
}
```

```

public Node<Integer> search(Integer x) {
    int slot = hash(x);
    if (table[slot].isEmpty()) return null;
    else {
        int i = table[slot].indexOf(x);
        if (i == -1) return null;
        else return table[slot].getNode(i);
    }
}

public void delete(Integer x) {
    if (isEmpty()) { /* 예외 처리 */ }
    else {
        int slot = hash(x);
        if table[slot].removeItem(x)
            numItems--;
    }
}

public boolean isEmpty() {
    return numItems == 0;
}

public void clear() {
    for (int i = 0; i < table.length; i++)
        table[i] = new LinkedList<>();
    numItems = 0;
}

} // end class ChainedHashTable

```

# Efficiency of Hashing

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Approximate average # of comparisons w/ keys for a search

- Linear probing
  - $\frac{1}{2}(1 + \frac{1}{1-\alpha})$  for a successful search
  - $\frac{1}{2}(1 + \frac{1}{(1-\alpha)^2})$  for an unsuccessful search
- Quadratic probing and double hashing
  - $-\ln(1-\alpha) / \alpha$  for a successful search
  - $1/(1-\alpha)$  for an unsuccessful search
- Separate chaining (assume sorted lists)
  - $\alpha/2$  for a successful search
  - $\alpha$  for an unsuccessful search



# Good Hash Functions

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- should be easy and fast to compute
- should scatter the data evenly on the hash table

# Observation

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- Load factor가 낮을 때는 probing 방법들은 대체로 큰 차이가 없다.
- Successful search는 insertion할 당시의 궤적을 그대로 밟는다.

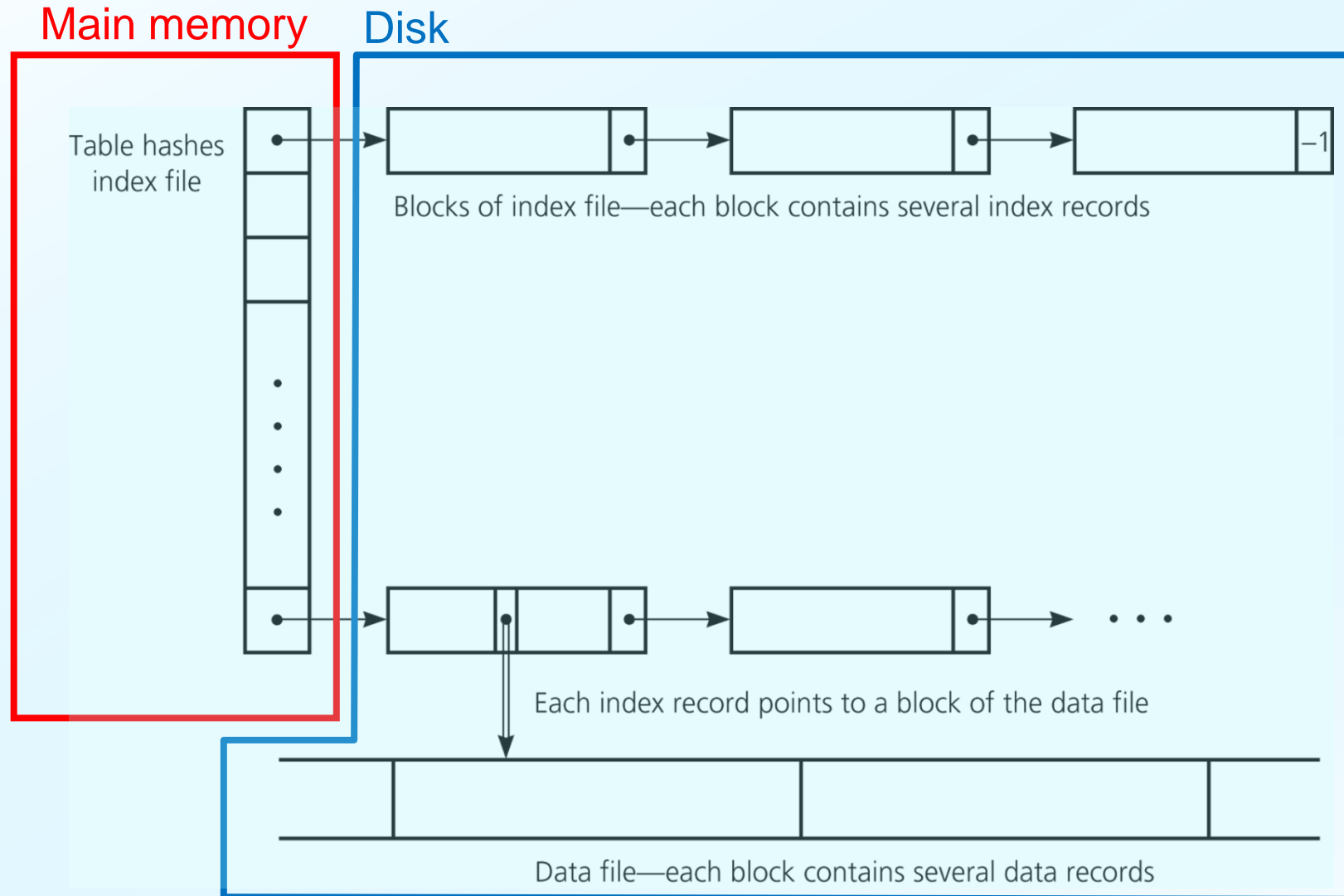
# External Hashing

# Internal/External Hashing

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- Hash table이 main memory에 있는지 disk에 있는지에 따라 나뉜다
  - Main memory: internal hashing
  - Disk: external hashing
- External hashing은 disk 접근 횟수가 중요하다

# External Hash Table



# 생각 해보기

Index에서 disk access 몇 번 필요하겠는가?

## Given situation

1 조개의 records in disk  
12 bytes/key  
4 bytes for page number  
Main memory allowed: 4G bytes  
Disk block size: 32K

# B-Tree와 비교해보자

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## Given situation

1 조개의 records in disk

12 bytes/key

4 bytes for page number

Main memory allowed: 4G bytes

Disk block size: 32K