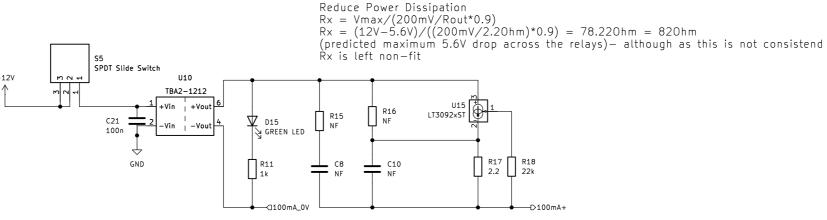


Set Output Current Isource = 10uA\*Rset/Rout Rset = 100mA/10uA\*2.2 = 22k

Supply
12V TBA used as can supply 165mA and 5.6V required
(The 5V version can supply 400mA BUT the Vce of the heated device may reverse bias 5V in extreme conditions).
The drop at maximal current can be as much as 5V (from looking at some 100 A IGBT e.g. IKQ50N120CH3)
So the true maximum voltage is 5.6V (5V drop at 100A + 0.6V drop at 100mA)

LED: |f = 12/1k = 12mA



 ${\sf NF}=220p$  could be used here to limit thermal noise on outputrisks instability

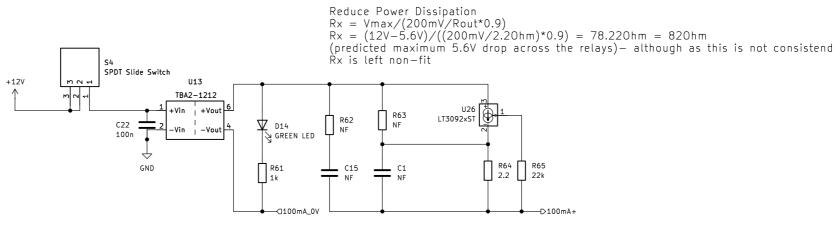
Nidec Drives	<b>PIC</b> Orives
Sheet: /Low Current/S5 100mA Internal/ File: LowCurrSource.kicad_sch	
Title: GAVIM V4 TEST 137	
Size: A3 Date: 2024-06-25	Rev: 00.00
KiCad E.D.A. 8.0.1	ld: 2/10

Set Output Current Isource = 10uA\*Rset/Rout Rset =  $100 \text{mA} / 10 \text{uA}^2 = 22 \text{k}$ 

Supply
12V TBA used as can supply 165mA and 5.6V required
(The 5V version can supply 400mA BUT the Vce of the heated device may reverse bias 5V in extreme conditions).
The drop at maximal current can be as much as 5V (from looking at some 100 A IGBT e.g. IKQ50N120CH3)
So the true maximum voltage is 5.6V (5V drop at 100A + 0.6V drop at 100mA)

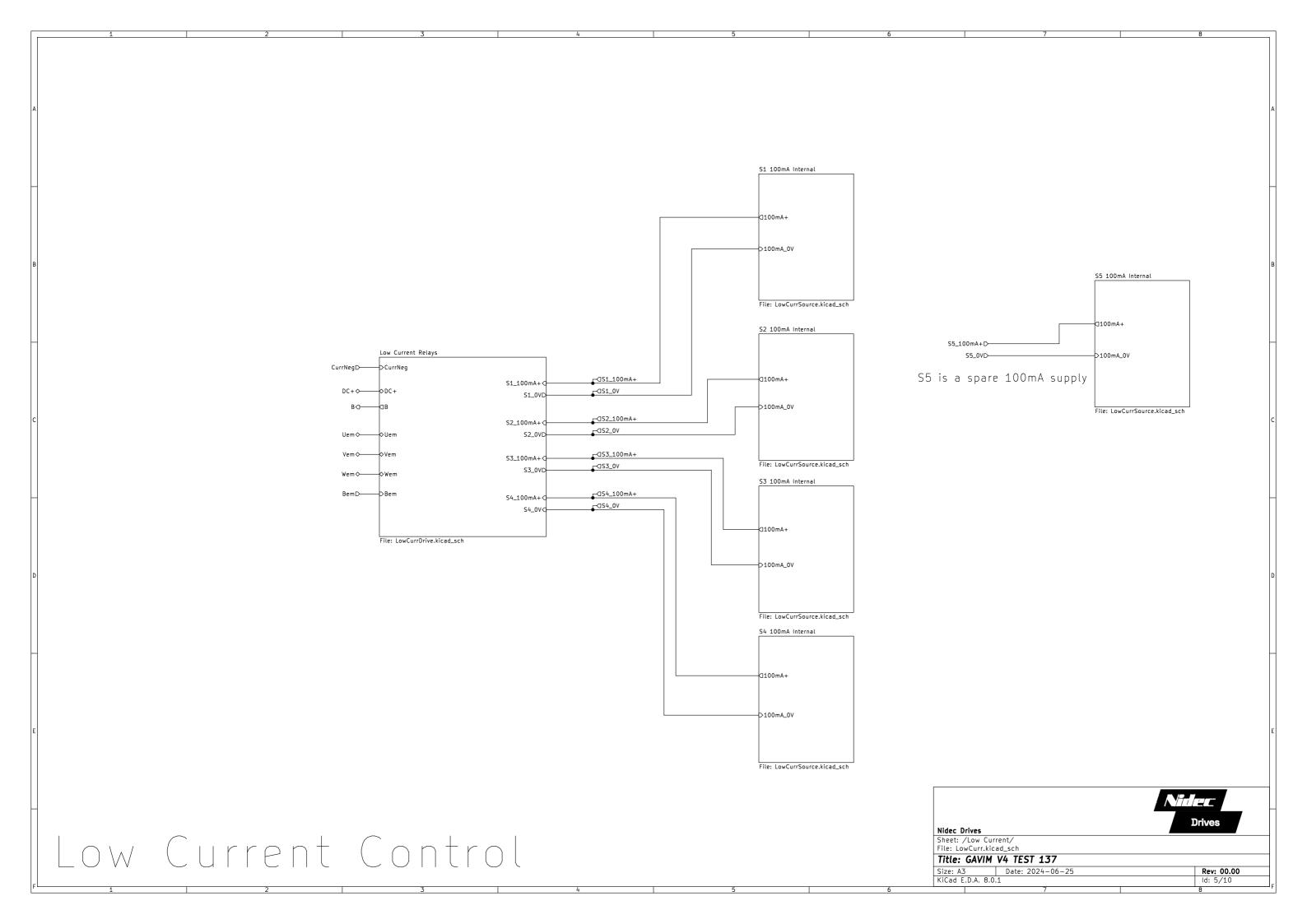
LED:

If = 12/1k = 12mA

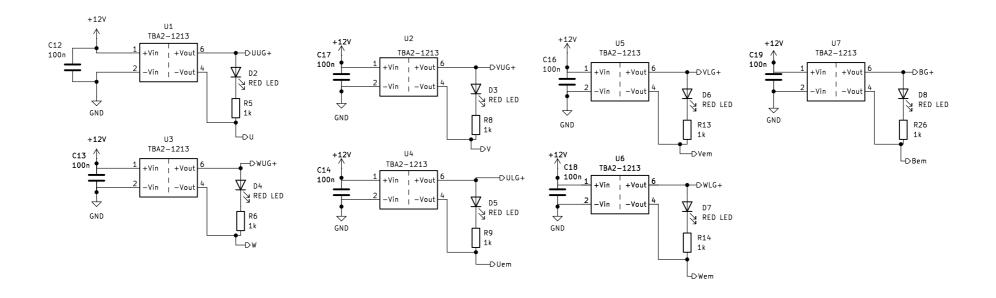


 ${\sf NF}=220p$  could be used here to limit thermal noise on outputrisks instability

Nidec Drives	<b>Nide</b>
Sheet: /Low Current/S4 100mA Internal/ File: LowCurrSource.kicad_sch	
Title: GAVIM V4 TEST 137	
Size: A3 Date: 2024-06-25	Rev: 00.00
KiCad E.D.A. 8.0.1	ld: 4/10



## Gate Drivers



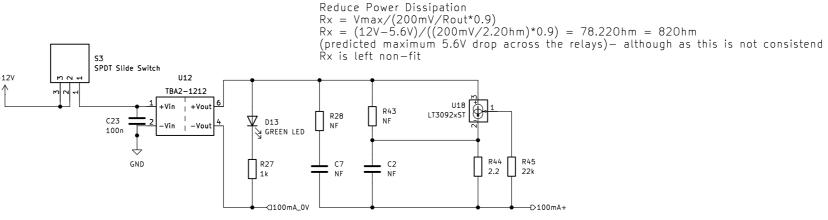
LED Resistance 15V/12mA = 1k

DC Supplies

lidas Daines		<b>Nide</b> Drives
<b>lidec Drives</b> Sheet: /DC Sup Tile: DCSupp.ki		
Title: GAVIM	1 V4 TEST 137	
Size: A3	Date: 2024-06-25	Rev: 00.00
(iCad E.D.A. 8.	0.1	ld: 6/10
	7	8

Set Output Current
Isource = 10uA\*Rset/Rout
Rset = 100mA/10uA\*2.2 = 22k

Supply
12V TBA used as can supply 165mA and 5.6V required
(The 5V version can supply 400mA BUT the Vce of the heated device may reverse bias 5V in extreme conditions).
The drop at maximal current can be as much as 5V (from looking at some 100 A IGBT e.g. IKQ50N120CH3)
So the true maximum voltage is 5.6V (5V drop at 100A + 0.6V drop at 100mA)



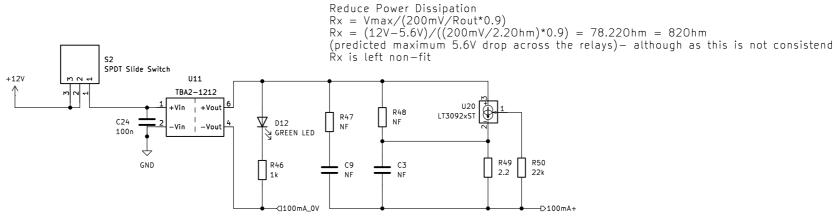
 ${\sf NF}=220p$  could be used here to limit thermal noise on outputrisks instability

Nidec Drives	Drives
Sheet: /Low Current/S3 100mA Internal/ File: LowCurrSource.kicad_sch	
Title: GAVIM V4 TEST 137	
Size: A3 Date: 2024-06-25	Rev: 00.00
KiCad E.D.A. 8.0.1	ld: 7/10
7	

Set Output Current Isource = 10uA\*Rset/Rout Rset = 100mA/10uA\*2.2 = 22k

Supply 12V TBA used as can supply 165mA and 5.6V required (The 5V version can supply 400mA BUT the Vce of the heated device may reverse bias 5V in extreme conditions). The drop at maximal current can be as much as 5V (from looking at some 100 A IGBT e.g. IKQ50N120CH3) So the true maximum voltage is 5.6V (5V drop at 100A + 0.6V drop at 100mA)

LED: |f = 12/1k = 12mA



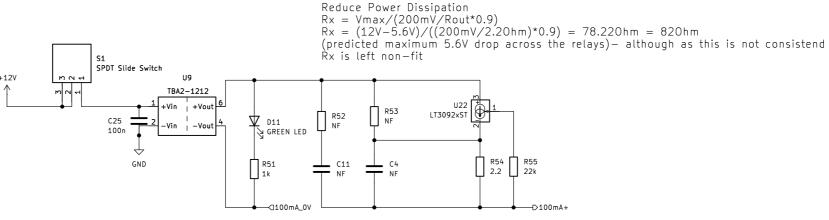
 ${\sf NF}=220p$  could be used here to limit thermal noise on outputrisks instability

Nidec Drives	<b>Ninter</b> Drives
Sheet: /Low Current/S2 100mA Internal/ File: LowCurrSource.kicad_sch	
Title: GAVIM V4 TEST 137	
Size: A3 Date: 2024-06-25	Rev: 00.00
KiCad E.D.A. 8.0.1	ld: 8/10

Set Output Current Isource = 10uA\*Rset/Rout Rset =  $100 \text{mA} / 10 \text{uA}^2 = 22 \text{k}$ 

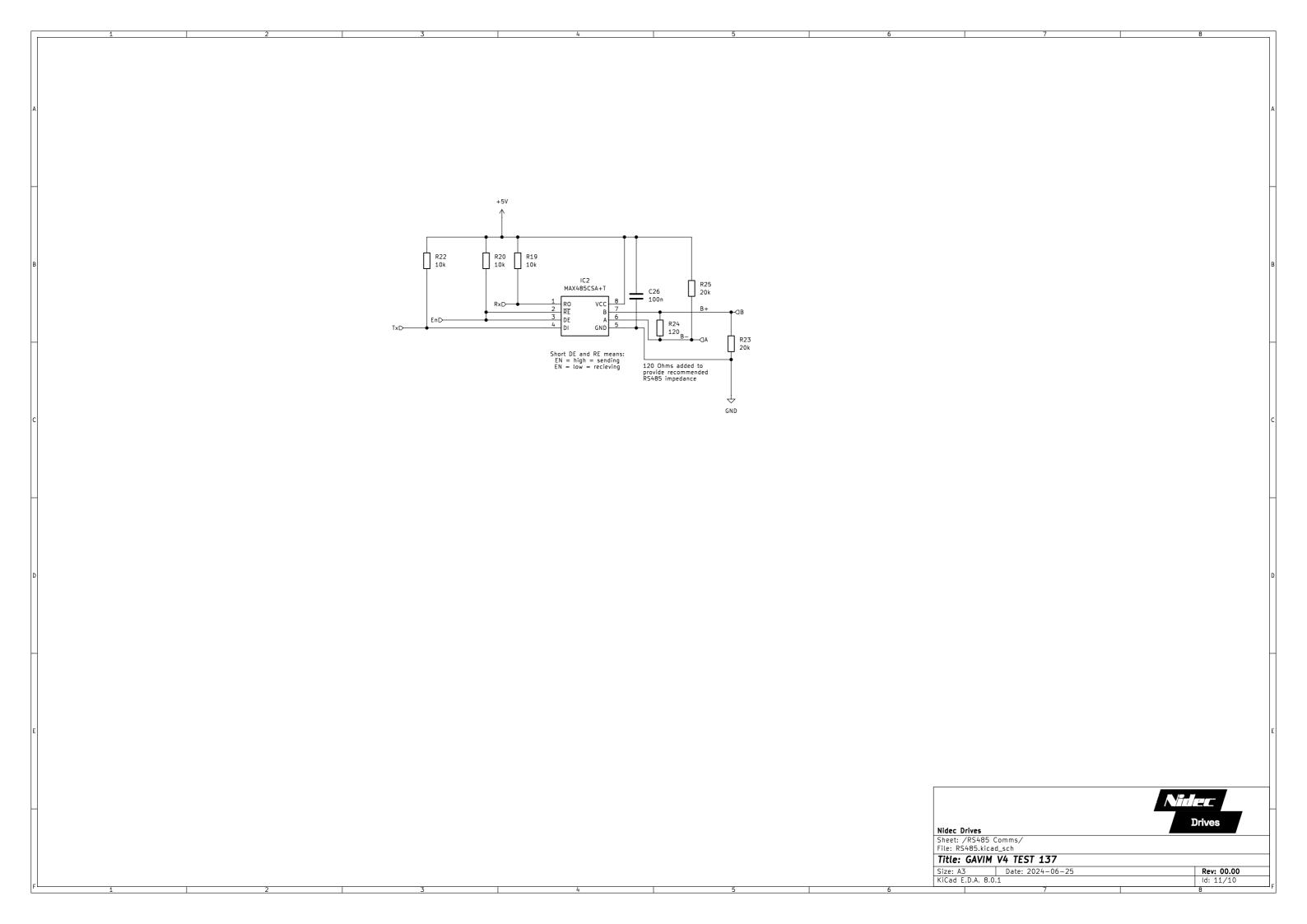
Supply
12V TBA used as can supply 165mA and 5.6V required
(The 5V version can supply 400mA BUT the Vce of the heated device may reverse bias 5V in extreme conditions).
The drop at maximal current can be as much as 5V (from looking at some 100 A IGBT e.g. IKQ50N120CH3)
So the true maximum voltage is 5.6V (5V drop at 100A + 0.6V drop at 100mA)

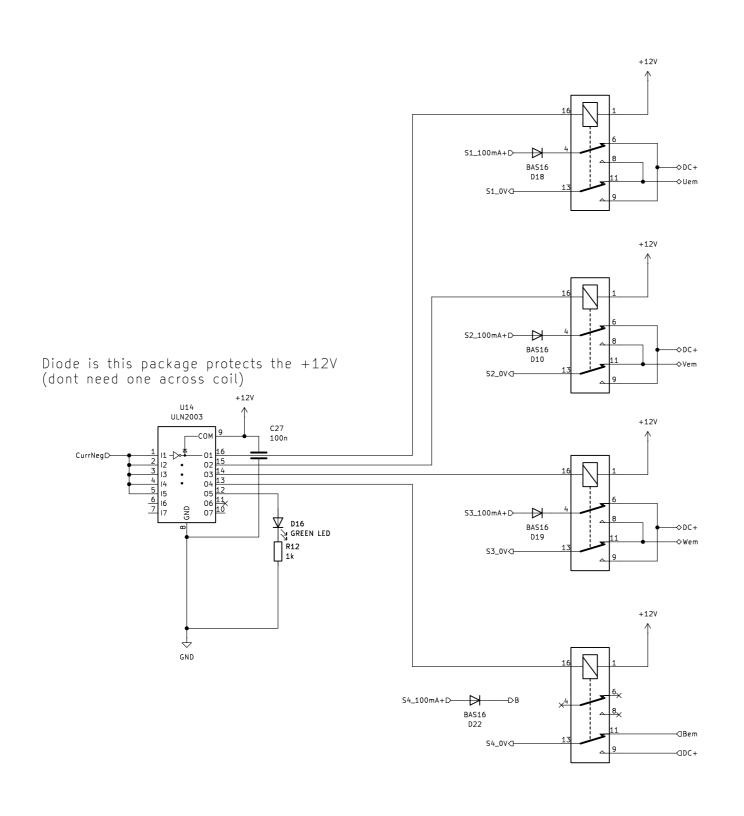
LED: If = 12/1k = 12mA



 ${\sf NF}=220p$  could be used here to limit thermal noise on outputrisks instability

Nidec Drives		Drives	
Sheet: /Low Cur File: LowCurrSou	rent/S1 100mA Internal/ rce.kicad_sch		
Title: GAVIM	V4 TEST 137		
Size: A3	Date: 2024-06-25	Rev: 00.00	
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SSR and RLY indicator If = 12/1k = 12mA

Coil current is 100mA ULN2002 is 500mA per driver

Arduino pin is 20mA 2.7k is base resistor (from datasheet): 5V/2.7k \* 4 (for all drivers) = 7.4mA

Low Current Relay Driver

		Nidec
Nidec Drives		Drives
	Current/Low Current Relays/ Drive.kicad_sch	
Title: GAV	IM V4 TEST 137	
Size: A3	Date: 2024-06-25	Rev: 00.00
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	7	8