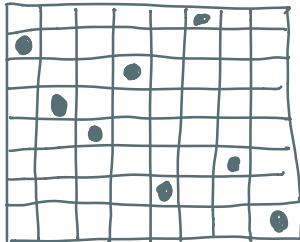


Hill Climbing / Genetic Algorithm

Ex. 8-queens, place 8 queens such that they do not attack each other

- Hard to know the goal state
- Hard to know successor state
- Cannot enumerate

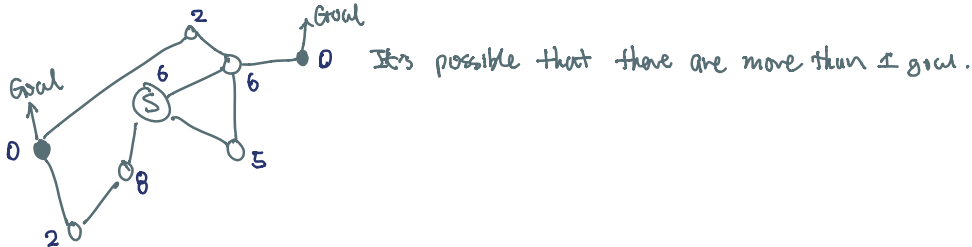


$$S = \{2, 4, 5, 3, 7, 1, 6, 8\}$$

$$\text{succ}(S) = \{T, T \text{ differs from } S \text{ by one column}\}$$

$$= \left\{ \begin{array}{l} (1, 4, 5, 3, 7, 1, 6, 8) \\ (2, \dots, \dots, \dots) \\ (3, \dots, \dots, \dots) \\ (4, \dots, \dots, \dots) \\ (\vdots) \\ (8, \dots, \dots, \dots) \end{array} \right\}$$

This will form a graph with direction, and connected.



Create a quality on each state, such that the quality on Goal state is very good.

The quality is the number of queens attacking each other.

Hence, a score function

$$\text{score } f(S) := \# \text{ of queens being attacked in } S$$

Imagine the graph is a 3-D graph, where the z-axis represents the score

$$\text{Optimization: } \min_{S \in \mathcal{S}} f(S)$$

state space

Hill-Climbing
-greedy!



global minimum
if $\forall T \in \mathcal{S}, f(S) < f(T)$

local minimum
 S is a local minimum if $\forall T \in \text{succ}(S), f(S) < f(T)$

Hill Climbing with random restart

population = set of states (init)

$S_0 = (2, 8, 1, 7, 6, 4, 5, 3)$
 $S_1 = (\quad)$
 $S_2 = (\dots)$

fitness $f(s)$

$$\frac{[q - f(s_i)]}{\sum_{j=0}^n [q - f(s_j)]} = p_i \quad \text{probability of state } S_i \quad i=0 \dots n$$

draw $i \sim (p_0, \dots, p_n)$
 $j \sim (p_0, \dots, p_n)$

$i \in \{0, 1, \dots, n\}$

$S_i = (1, 3, 2, 5, 4, 6, 8, 7)$
 $S_j = (5, 2, 3, 4, 8, 7, 1, 6)$

$pos \sim \text{unif}(1 \dots 8)$
 e.g. $pos = 3$

$t_1 = (1, 3, 2, 4, 8, 7, 1, 6)$
 $t_0 = (5, 2, 3, 5, 4, 6, 8, 7)$

randomly choose n , and change value arbitrary (mutation)