

### Definition 6.4

If  $L: V \rightarrow W$  is a linear transformation, then the range of  $L$  or image of  $V$  under  $L$ , denoted by  $\text{range } L$  is the set of all vectors  $\vec{w} \in W$  such that  $L(\vec{v}) = \vec{w}$  for some  $\vec{v} \in V$ .

$L$  is called onto whenever  $\text{range } L = W$

Example: Define  $L$  from  $\mathbb{R}^3 \rightarrow \mathbb{R}^2$  by

$$L\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} -x_3 \\ x_2 \end{bmatrix}$$

What is  $\ker L$

$$\ker L = \left\{ \begin{bmatrix} x_1 \\ 0 \\ 0 \end{bmatrix}, x_1 \in \mathbb{R} \right\}$$

What is  $\text{range } L$ ?

$$\text{Range } L = \mathbb{R}^2$$

Why?

Given  $\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \in \mathbb{R}^2$

$$L\left(\begin{bmatrix} 0 \\ v_2 \\ -v_1 \end{bmatrix}\right) = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

So, any vector in  $\mathbb{R}^2$  can be achieved by  $L$ ,

alternately  $L\left[\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right] = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = e_1$  and  $L\left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right] = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = e_2$

$\underbrace{\hspace{10em}}_{\text{standard basis.}}$

In this case,  $L$  is onto.

Example:  $L: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is defined by

$$L\left(\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}\right) = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 2 & 1 & 3 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$$

(a) Is  $L$  onto?

Given any  $\vec{w} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$  in  $\mathbb{R}^3$

If  $L$  is onto, there exists  $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \in \mathbb{R}^3$

such that  $L(\vec{u}) = \vec{w}$

$$L(\vec{u}) = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 2 & 1 & 3 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

look at linear system,

$$\left[ \begin{array}{ccc|c} 1 & 0 & 1 & a \\ 1 & 1 & 2 & b \\ 2 & 1 & 3 & c \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & 1 & a \\ 0 & 1 & 1 & b-a \\ 0 & 1 & 1 & c-2a \end{array} \right]$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 1 & a \end{array} \right]$$

$$\begin{bmatrix} 0 & 1 & 1 & b-a \\ 0 & 0 & 0 & c-b-a \end{bmatrix}$$

not all  $a, b, c$  behaves like  $c-b-a=0$ ,

so,  $L$  is not onto.

cb) Find a basis for Range  $L$

Range of  $L$  is the set of vectors  $\left\{ \begin{bmatrix} a \\ b \\ c \end{bmatrix} \right\}$

such that  $c-b-a=0$

$$c = a+b$$

so, range of  $L$  is all vectors of the form

$$\begin{bmatrix} a \\ b \\ a+b \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

Therefore, the basis for Range  $L$  is  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$

$$\dim(\text{Range } L) = 2$$

range  $L$  is the column space of  $A$ .

c) Find  $\ker L$

need solutions to

$$L\left(\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 1 & 1 & 2 & 0 \\ 2 & 1 & 3 & 0 \end{array} \right] \text{ i.e. Find the null space of the matrix}$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 1 & 1 & 2 & 0 \\ 2 & 1 & 3 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\ker L = \begin{bmatrix} u_1 \\ u_1 \\ -u_1 \end{bmatrix} \quad \dim(\ker L) = 1, \text{ Basis is } \left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \right\}$$

(d) Is  $L$  one-to-one?

No, because  $\dim(\ker L) > 0$ .

Theorem 6.6 (Rank-Nullity)

If  $L: V \rightarrow W$  is a linear transformation, and  $\dim V = n$ ,

Then  $\dim(\ker L) + \dim(\text{Range } L) = \dim V$

Proof: let  $k = \dim(\ker L)$ ,  $k \leq n$ ,

suppose  $k = n$ , in this case,  $\ker L = V$

so  $\text{range } L = \{ \vec{0}_W \}$   $\dim(\text{Range } L) = 0$

$$\dim(\text{Ker } L) + \dim(\text{Range } L) = n + 0 = n = \dim V$$

Now, suppose  $1 \leq k < n$ , let  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$  be a basis for kernel

Extend this to a full basis for  $V$ ,

$$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k, \dots, \vec{v}_n\}$$

Show

$\{L(\vec{v}_{k+1}), L(\vec{v}_{k+2}), \dots, L(\vec{v}_n)\}$  is a basis for range  $L$

suppose  $\vec{w} \in \text{Range } L$

$$L(\vec{v}) = \vec{w} \text{ for some } \vec{v} \in V$$

$$L(a_1\vec{v}_1 + a_2\vec{v}_2 + \dots + a_k\vec{v}_k + a_{k+1}\vec{v}_{k+1} + \dots + a_n\vec{v}_n) = \vec{w}$$

$$a_1 L(\vec{v}_1) + a_2 L(\vec{v}_2) + \dots + a_k L(\vec{v}_k) + a_{k+1} L(\vec{v}_{k+1}) + \dots + a_n L(\vec{v}_n) = \vec{w}$$

So,  $\{L(\vec{v}_1), L(\vec{v}_2), \dots, L(\vec{v}_n)\}$  spans Range of  $L$

$$\text{but } a_{k+1} L(\vec{v}_{k+1}) + \dots + a_n L(\vec{v}_n) = \vec{w}$$

then  $\{L(\vec{v}_{k+1}), \dots, L(\vec{v}_n)\}$  spans Range of  $L$

need  $\{L(\vec{v}_{k+1}), \dots, L(\vec{v}_n)\}$  linearly independent.

suppose there exists  $c_{k+1} \dots c_n \in \mathbb{R}$

$$c_{k+1}\vec{v}_{k+1} + \dots + c_n\vec{v}_n = \vec{0}$$

$$L(c_{k+1}\vec{v}_{k+1} + \dots + c_n\vec{v}_n) = \vec{0}$$

$$c_{k+1}\vec{v}_{k+1} + \dots + c_n\vec{v}_n \in \ker L$$

there is no way for this to be in the  $\ker L$  with

basis  $\{\vec{v}_1, \dots, \vec{v}_k\}$  unless  $c_{k+1} \dots c_n = 0$

hence  $\{L(\vec{v}_{k+1}), \dots, L(\vec{v}_n)\}$  is linearly independent,

hence it is the basis for the range  $L$

$$\dim(\text{Range } L) = n - k$$

When  $k=0$ , similar argument as before, shows

$$\dim(\text{Range } L) = n$$

Corollary: 6.2.

If  $L: V \rightarrow W$  is a linear transformation and  $\dim V = \dim W$

then  $L$  is <sup>①</sup> one-to-one and <sup>②</sup> onto.

Proof ①:  $\dim \ker L = 0$  so  $\dim \text{Range } L = n = \dim W$

②  $L$  is one-to-one  $\Rightarrow$  onto.

$$\text{Range } L = W$$

$$\dim \text{Range } L = \dim W = \dim V,$$

$$\dim \ker L = 0.$$

Theorem 6.7 A linear transformation  $L: V \rightarrow W$  is invertible

if and only if  $L$  is one-to-one and onto.