sensor: afl_h, terrain noise: no_noise, no signal noise, mean of 500 samples AMOS II Terrain Classification: Simulated Sensory Output 1.5_{1} concrete carpet grass mud wood swamp plastic ice rock 1.0 sand foam snow rubber gravel 0.5 sensor values 0.0 -0.5-1.0100 20 40 60 80 timesteps