LAB2

lab2 package

eater.py
/eater_node

Publisher

Subscriber

Service Server

Service Client

turtlesim_plus package

turtlesim_plus_node.py
/turtlesim_plus

Publisher

Subscriber

Service Server

Service Client

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killer.py
/killer_node

Publisher

Subscriber

Service Server

Service Client

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rviz2
/rviz

Publisher

Subscriber

Service Server

Service Client

Terminal

Publisher

Subscriber

Service Server

Service Client

----

turtlesim_pose.py
/odom_pub

Publisher

Subscriber

Service Server

Service Client