Quicksort

Quicksort I

2. Terminate

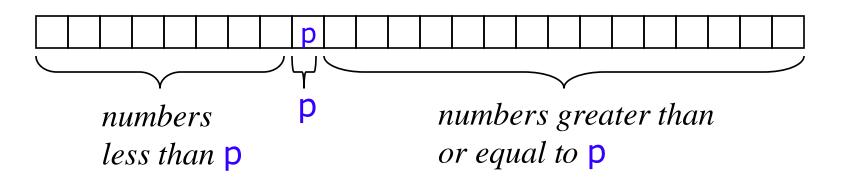
To sort a[left...right]:

 if left < right:
 Partition a[left...right] such that:
 all a[left...p-1] are less than a[p], and
 all a[p+1...right] are >= a[p]
 Quicksort a[left...p-1]
 Quicksort a[p+1...right]

2

Partitioning (Quicksort II)

- A key step in the Quicksort algorithm is partitioning the array
 - We choose some (any) number p in the array to use as a pivot
 - We partition the array into three parts:



Partitioning II

- Choose an array value (say, the first) to use as the pivot
- Starting from the left end, find the first element that is greater than or equal to the pivot
- Searching backward from the right end, find the first element that is less than the pivot
- Interchange (swap) these two elements
- Repeat, searching from where we left off, until done

Partitioning

- To partition a[left...right]:
- 1. Set pivot = a[left], l = left + 1, r = right;
- 2. while l < r, do
 - 2.1. while l < right & a[l] < pivot , set <math>l = l + 1
 - 2.2. while r > left & a[r] >= pivot, set r = r 1
 - 2.3. if l < r, swap a[l] and a[r]
- 3. Set a[left] = a[r], a[r] = pivot
- 4. Terminate

Example of partitioning

436924312189356 choose pivot: 436924312189356 search: 433924312189656 swap: 433924312189656 search: 433124312989656 swap: 433124312989656 search: 433122314989656 swap: 4 3 3 1 2 2 3 1 4 9 8 9 6 5 6 (left > right) search: 133122344989656 swap with pivot:

The partition method (Java)

```
static int partition(int[] a, int left, int right) {
   int p = a[left], l = left + 1, r = right;
   while (l < r) {
      while (l < right && a[l] < p) l++;
      while (r > left \&\& a[r] >= p) r--;
      if (l < r) {
         int temp = a[l]; a[l] = a[r]; a[r] = temp;
   a[left] = a[r];
   a[r] = p;
   return r;
```

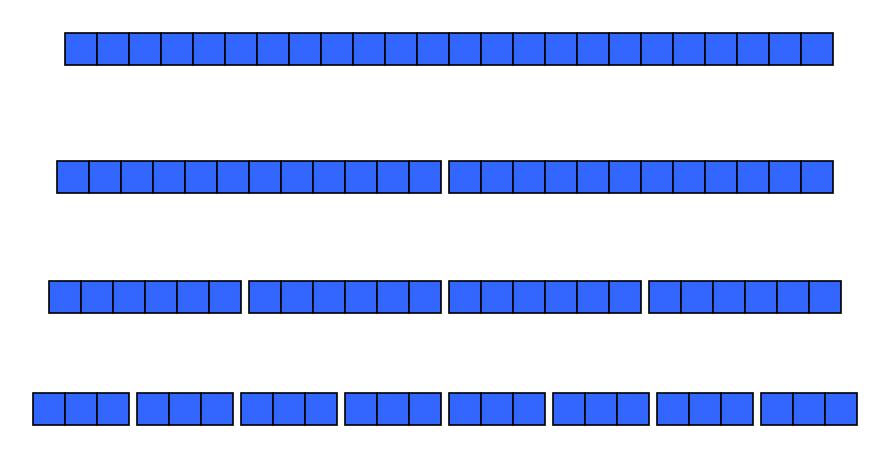
The quicksort method (in Java)

```
static void quicksort(int[] array, int left, int right) {
    if (left < right) {
        int p = partition(array, left, right);
        quicksort(array, left, p - 1);
        quicksort(array, p + 1, right);
    }
}</pre>
```

Analysis of quicksort—best case

- Suppose each partition operation divides the array almost exactly in half
- Then the depth of the recursion in log₂n
 - Because that's how many times we can halve n
- However, there are many recursions!
 - How can we figure this out?
 - We note that
 - Each partition is linear over its subarray
 - All the partitions at one level cover the array

Partitioning at various levels



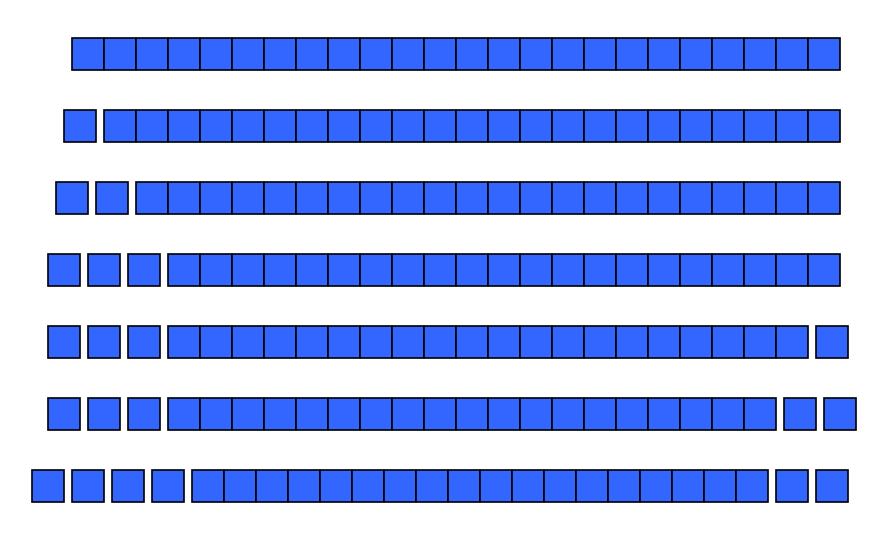
Best case II

- We cut the array size in half each time
- So the depth of the recursion in log₂n
- At each level of the recursion, all the partitions at that level do work that is linear in n
- $O(\log_2 n) * O(n) = O(n \log_2 n)$
- Hence in the average case, quicksort has time complexity O(n log₂n)
- What about the worst case?

Worst case

- In the worst case, partitioning always divides the size n array into these three parts:
 - A length one part, containing the pivot itself
 - A length zero part, and
 - A length n-1 part, containing everything else
- We don't recur on the zero-length part
- Recurring on the length n-1 part requires (in the worst case) recurring to depth n-1

Worst case partitioning



Worst case for quicksort

- In the worst case, recursion may be n levels deep (for an array of size n)
- But the partitioning work done at each level is still n
- $O(n) * O(n) = O(n^2)$
- So worst case for Quicksort is $O(n^2)$
- When does this happen?
 - There are many arrangements that *could* make this happen
 - Here are two common cases:
 - When the array is already sorted
 - When the array is *inversely* sorted (sorted in the opposite order)

Typical case for quicksort

- If the array is sorted to begin with, Quicksort is terrible: $O(n^2)$
- It is possible to construct other bad cases
- However, Quicksort is usually O(n log₂n)
- The constants are so good that Quicksort is generally the fastest algorithm known
- Most real-world sorting is done by Quicksort

Tweaking Quicksort

- Almost anything you can try to "improve"
 Quicksort will actually slow it down
- One *good* tweak is to switch to a different sorting method when the subarrays get small (say, 10 or 12)
 - Quicksort has too much overhead for small array sizes
- For large arrays, it *might* be a good idea to check beforehand if the array is already sorted
 - But there is a better tweak than this

Picking a better pivot

- Before, we picked the *first* element of the subarray to use as a pivot
 - If the array is already sorted, this results in $O(n^2)$ behavior
 - It's no better if we pick the *last* element
- We could do an *optimal* quicksort (guaranteed O(n log n)) if we always picked a pivot value that exactly cuts the array in half
 - Such a value is called a median: half of the values in the array are larger, half are smaller
 - The easiest way to find the median is to *sort* the array and pick the value in the middle (!)

Median of three

- Obviously, it doesn't make sense to sort the array in order to find the median to use as a pivot
- Instead, compare just *three* elements of our (sub)array—the first, the last, and the middle
 - Take the *median* (middle value) of these three as pivot
 - It's possible (but not easy) to construct cases which will make this technique $O(n^2)$
- Suppose we rearrange (sort) these three numbers so that the smallest is in the first position, the largest in the last position, and the other in the middle
 - This lets us simplify and speed up the partition loop

Final comments

- Quicksort is the fastest known sorting algorithm
- For optimum efficiency, the pivot must be chosen carefully
- "Median of three" is a good technique for choosing the pivot
- However, no matter what you do, there will be some cases where Quicksort runs in $O(n^2)$ time