

# Program Analysis

Lecture 04: *Machine Language III*  
Winter term 2011/2012

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# Announcements

- Feedback for tool intro and first exercise?
  - Next exercise will be published next week
  - Subroutines, code analysis, CrackMe, ...
- Next Wednesday: talk by @vxradius and @matrosov
- See <http://www.nds.rub.de/teaching/lectures/471/>

# Last Week

- x86 registers
- x86 instruction set
- Intel vs. AT&T syntax
- x86 memory access / endianness
- Privileges
- Interrupts / exceptions

# Outline

- x86 subroutines
  - Overview
  - Calling conventions
- Higher-level structures
  - Control-flow structures
  - Loops

# x86 Subroutines

# Stack

- Memory area dedicated to local variables and calling information for subroutines
  - Meta data when calling functions
  - Synchronization (threads)
- Stack pointer `esp` indicates current top of stack
- Control stack with `push` and `pop` instructions

# Base/Frame Pointer

- In addition to stack pointer there is the so called *base pointer/frame pointer* `ebp`
- Before modifying the stack pointer to allocate space for local variables during the prolog, the content of this register is saved in base pointer `ebp`
- Base pointer is used to adress local variables and parameters
- Not always used, so called *frame pointer omission* (FPO)

# Subroutines

- Parameters are put on stack before function is called
- Use push instruction
- **Last parameter** is pushed **first!**

f(1, 2, 3)	
push	3
push	2
push	1
call	f



# Subroutines

- Parameters are put on stack before function is called
- Use push instruction
- **Last parameter** is pushed **first!**

f(1, 2, 3)

```
push 3
push 2
push 1
call f
```

Function f

```
push ebp      ; save old ebp
mov ebp, esp  ; load ebp with esp
sub esp, 10h  ; reserve space for
               ; local variables

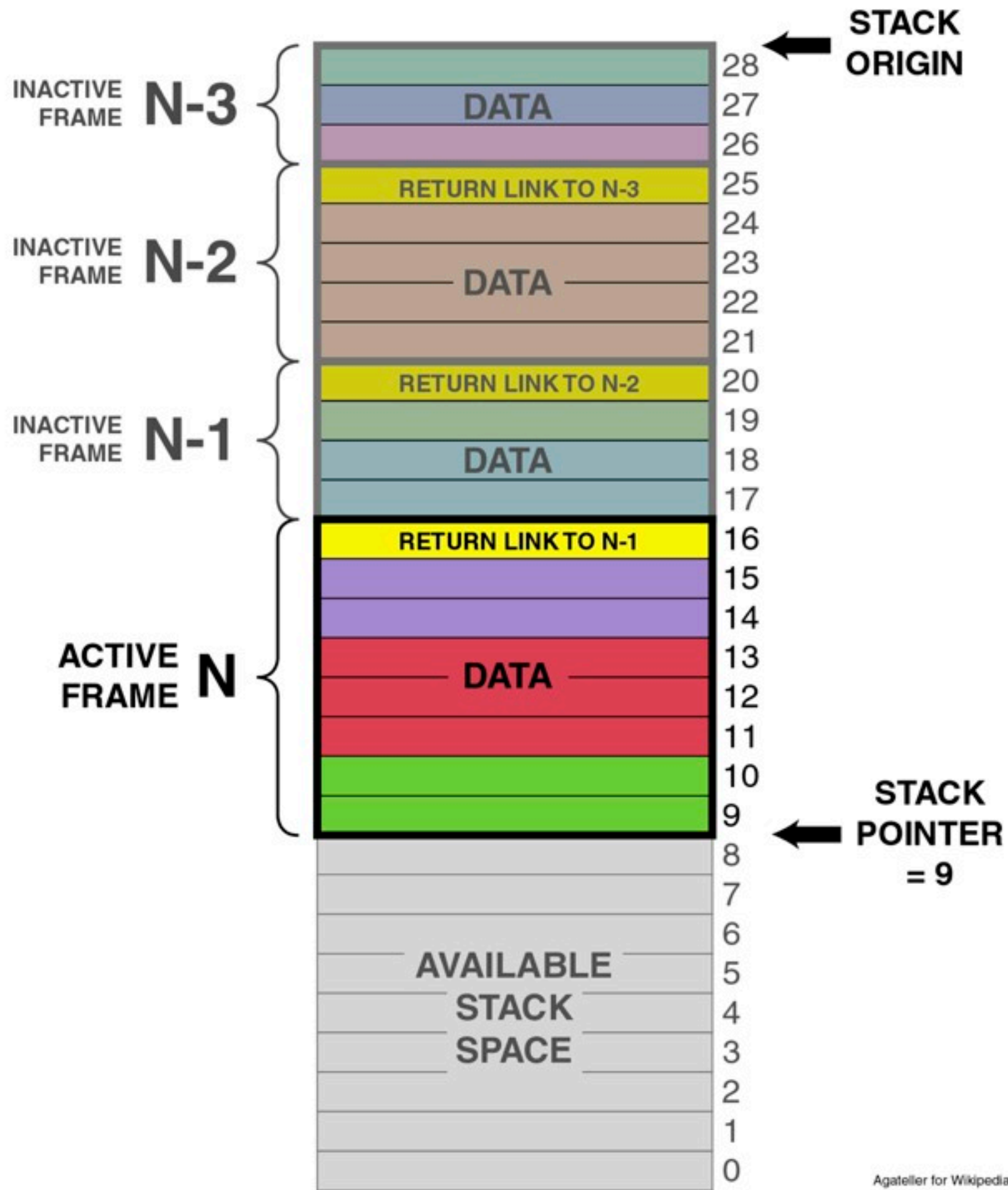
...

mov esp, ebp  ; load esp with ebp
pop ebp       ; restore ebp
ret           ; return
```

- Typical *prolog* / *epilog*

# Stack Frames

- Each function call has a so called *stack frame*
  - Input and output parameters (*stack parameters*)
  - Return address
  - Saved register contents (old ebp)
  - Local variables
- Base/frame pointer to address stack parameters and local variables (*FPO disabled*)



Agateller for Wikipedia  
Public Domain 2006

# Example

## High-level language

```
x = func1(y, 4);

stdcall int func1(int a, int b )
{
    int z;
    z = a * b;
    return z;
}
```

Assembler is executed  
step by step in the  
next few slides

## Assembler

```
push 4
push [var_y]
call func1
mov [var_x], eax ;RET
```

func1:

```
push ebp
mov ebp, esp
sub esp, 4
mov ecx, [ebp+0x8]
mul ecx, [ebp+0xC]
mov [ebp-4], ecx
mov eax, [ebp-4]
mov esp, ebp
pop ebp
ret 8
```

Prolog

Epilog

# Example

## High-level language

```
x = func1(y, 4);
```

```
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

ebp/esp



*Stack  
frame*



## Assembler

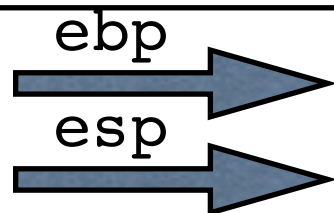


# Example

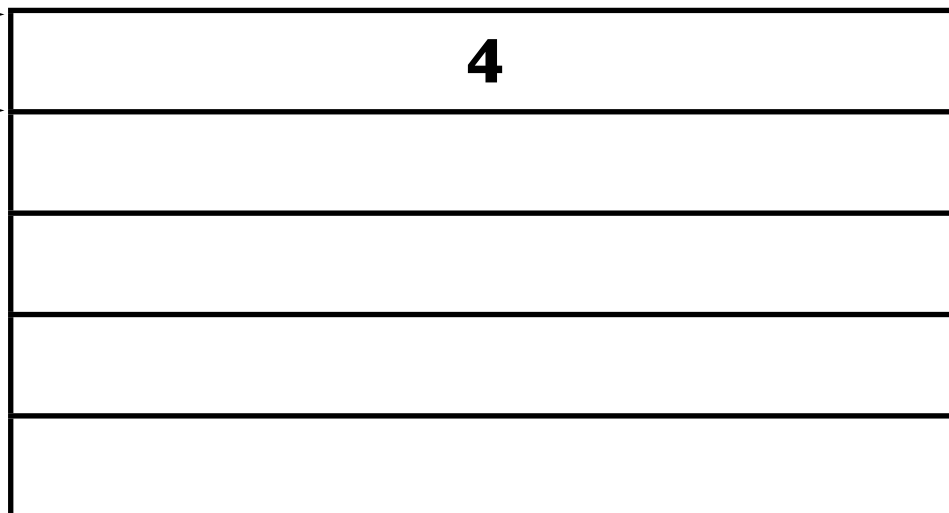
## High-level language

```
x = func1(y, 4);
```

```
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```



*Stack  
frame*



## Assembler

```
push 4
```

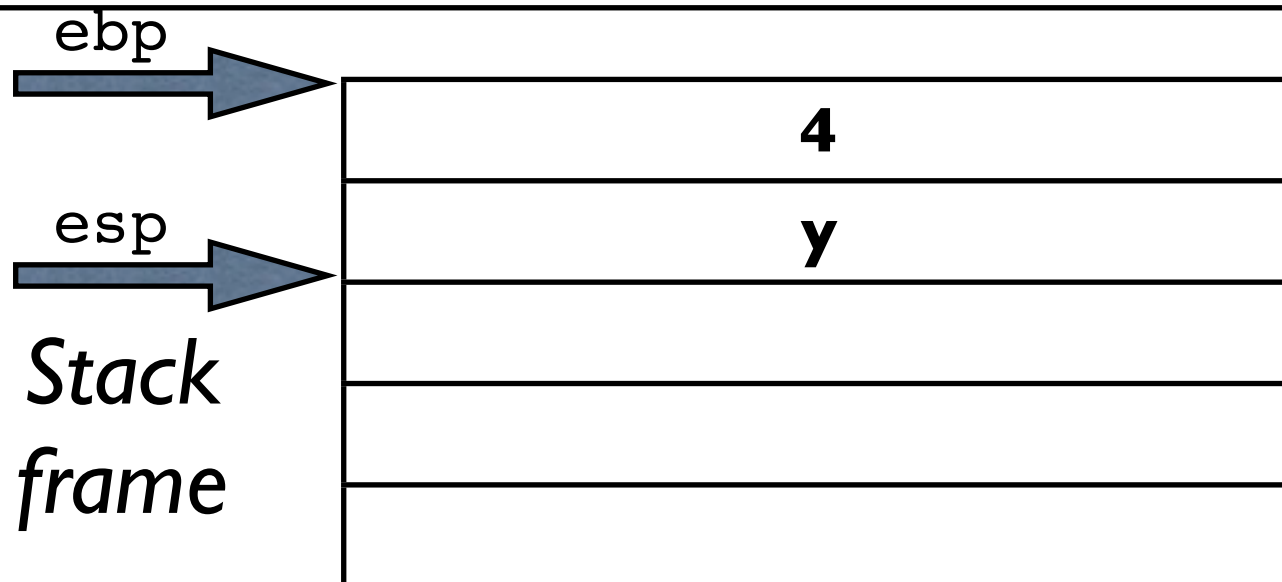
# Example

## High-level language

```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

## Assembler

```
push 4  
push [var_y]
```



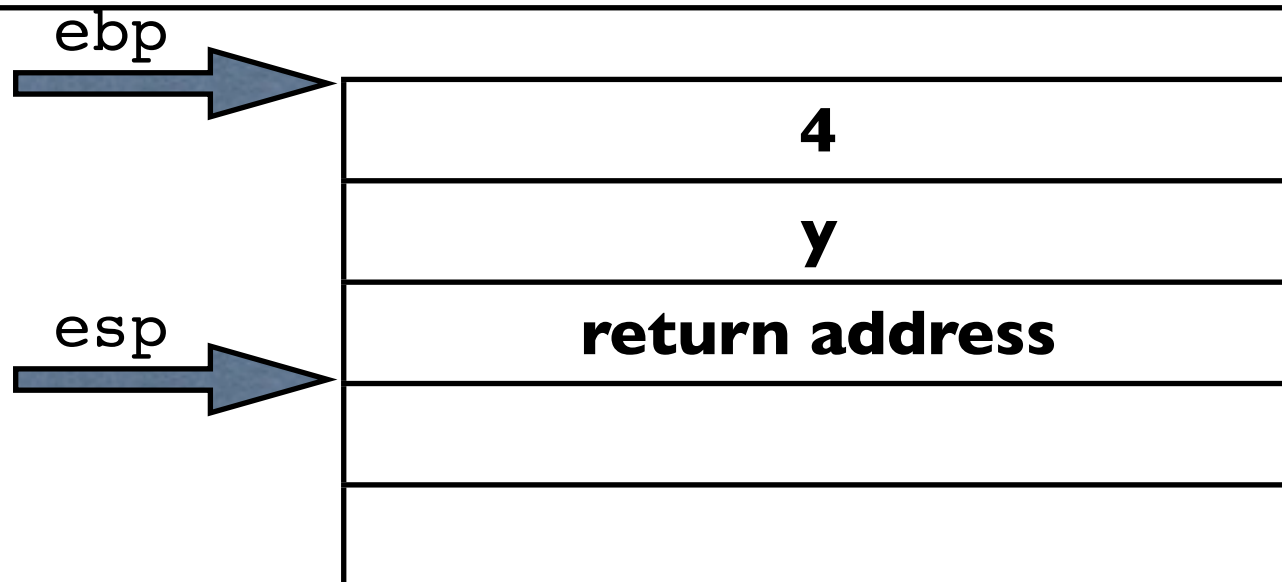
# Example

## High-level language

```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

## Assembler

```
push 4  
push [var_y]  
call func1
```





# Example

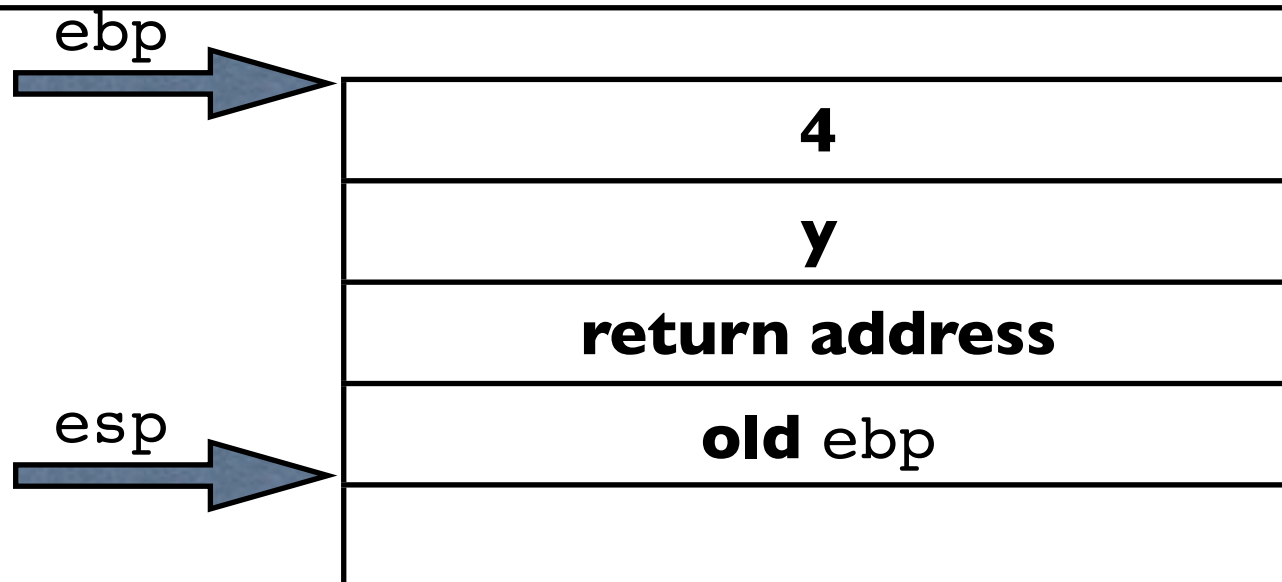
## High-level language

```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

## Assembler

```
push 4  
push [var_y]  
call func1
```

```
func1:  
    push ebp
```



# Example

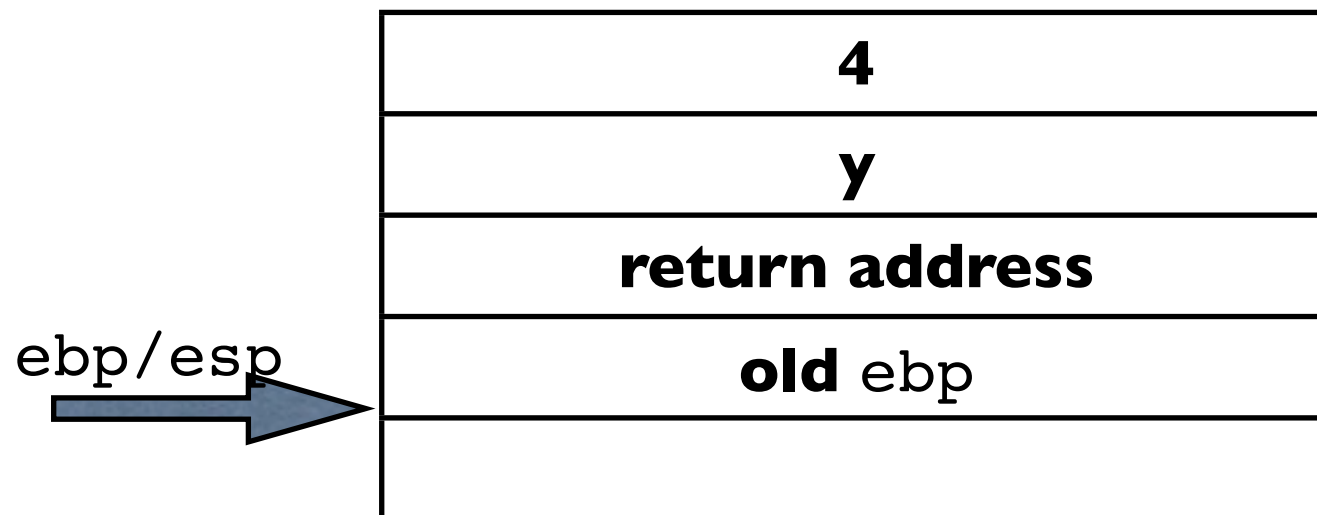
## High-level language

```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

## Assembler

```
push 4  
push [var_y]  
call func1
```

```
func1:  
    push ebp  
    mov ebp, esp
```



# Example

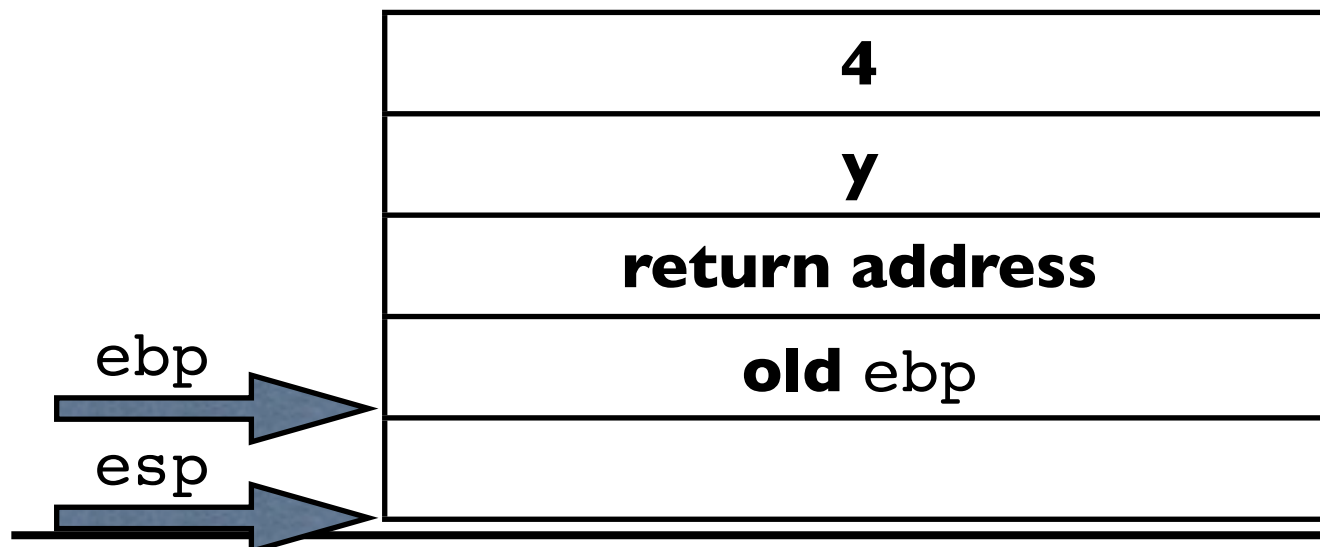
## High-level language

```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

## Assembler

```
push 4  
push [var_y]  
call func1
```

```
func1:  
    push ebp  
    mov ebp, esp  
    sub esp, 4
```



# Example

## High-level language

```
x = func1(y, 4);

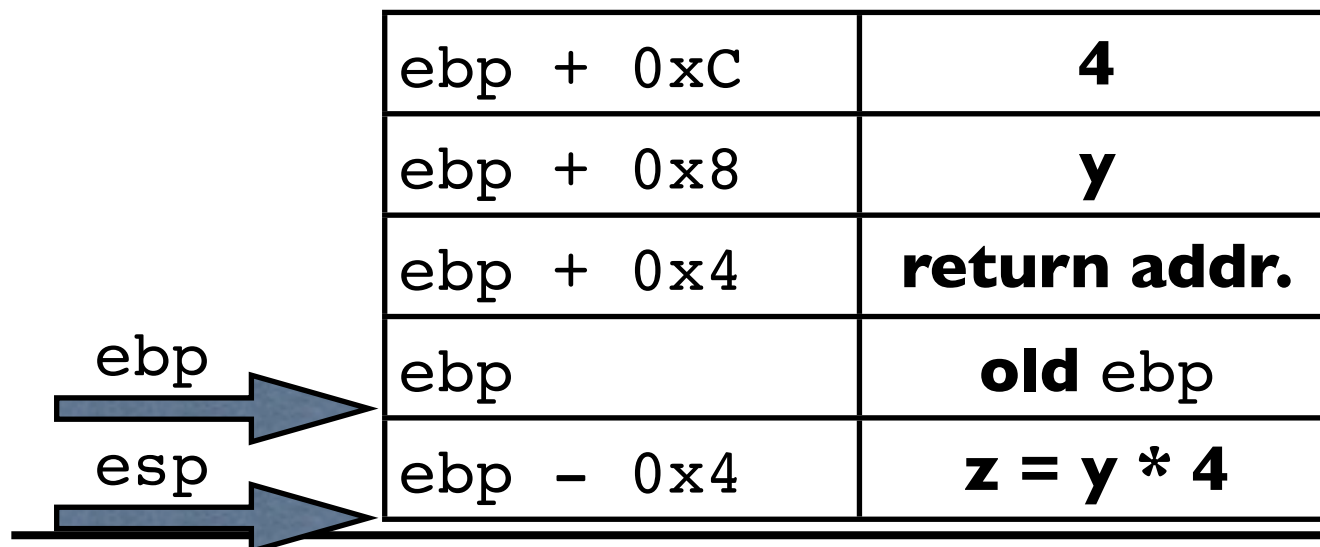
stdcall int func1(int a, int b )
{
    int z;
    z = a * b;
    return z;
}
```

## Assembler

```
push 4
push [var_y]
call func1
```

func1:

```
push ebp
mov ebp, esp
sub esp, 4
mov ecx, [ebp+0x8]
mul ecx, [ebp+0xC]
mov [ebp-4], ecx
```



# Example

## High-level language

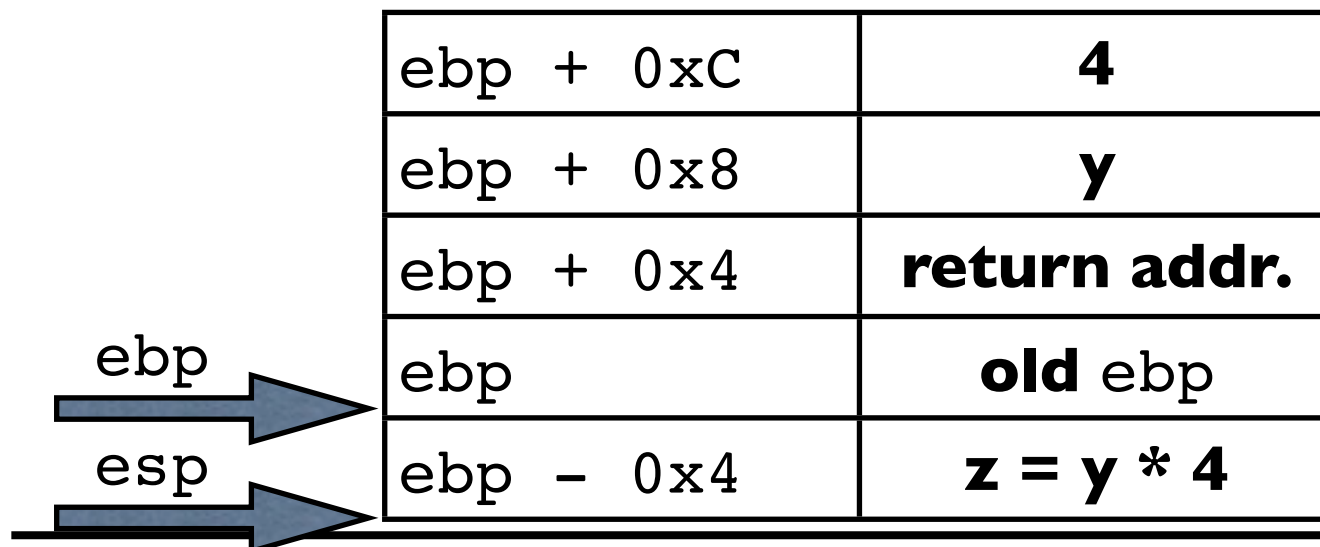
```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

## Assembler

```
push 4  
push [var_y]  
call func1
```

func1:

```
push ebp  
mov ebp, esp  
sub esp, 4  
mov ecx, [ebp+0x8]  
mul ecx, [ebp+0xC]  
mov [ebp-4], ecx
```



First stack argument can be found at `[ebp+08]`, with local variables typically at a negative displacement from `ebp`.

# Example

## High-level language

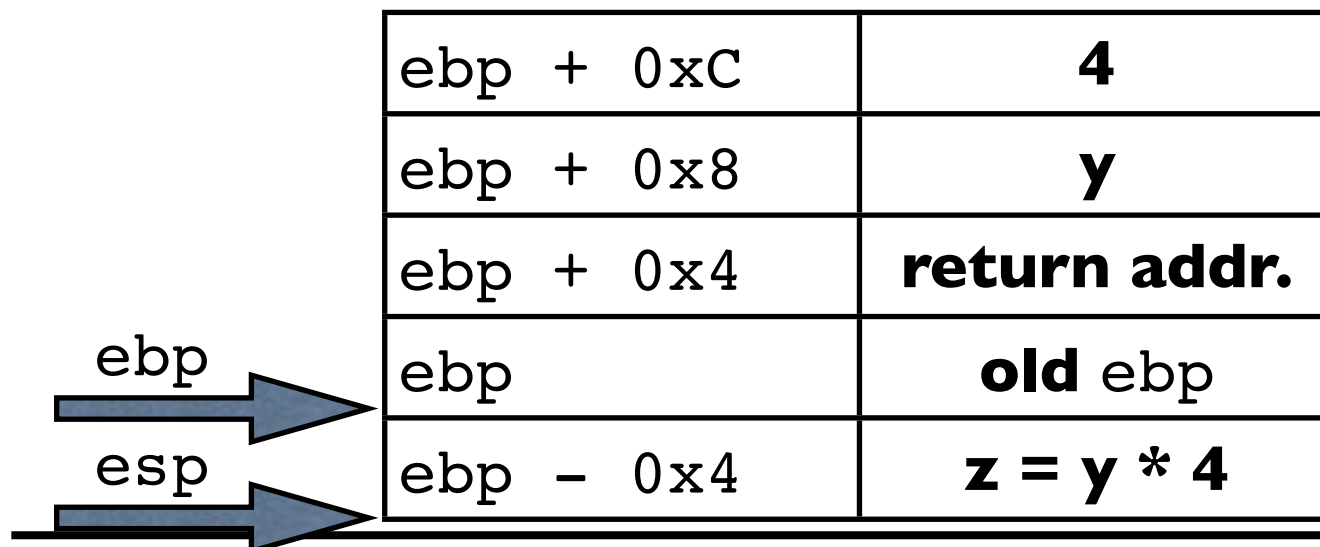
```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

## Assembler

```
push 4  
push [var_y]  
call func1
```

func1:

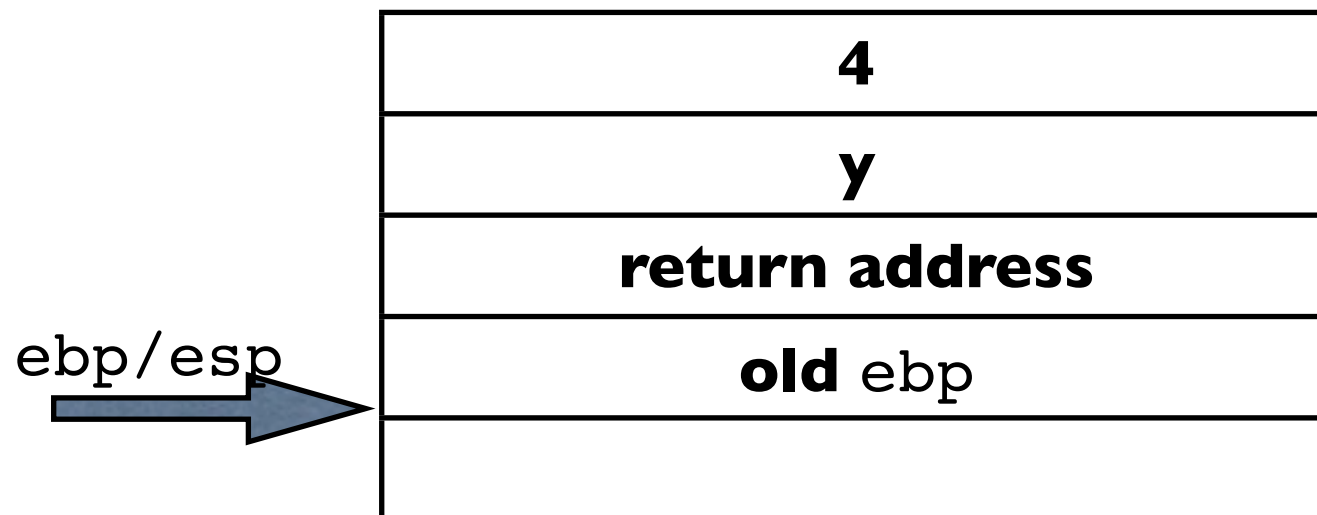
```
push ebp  
mov ebp, esp  
sub esp, 4  
mov ecx, [ebp+0x8]  
mul ecx, [ebp+0xC]  
mov [ebp-4], ecx  
mov eax, [ebp-4]
```



# Example

## High-level language

```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```



## Assembler

```
push 4  
push [var_y]  
call func1
```

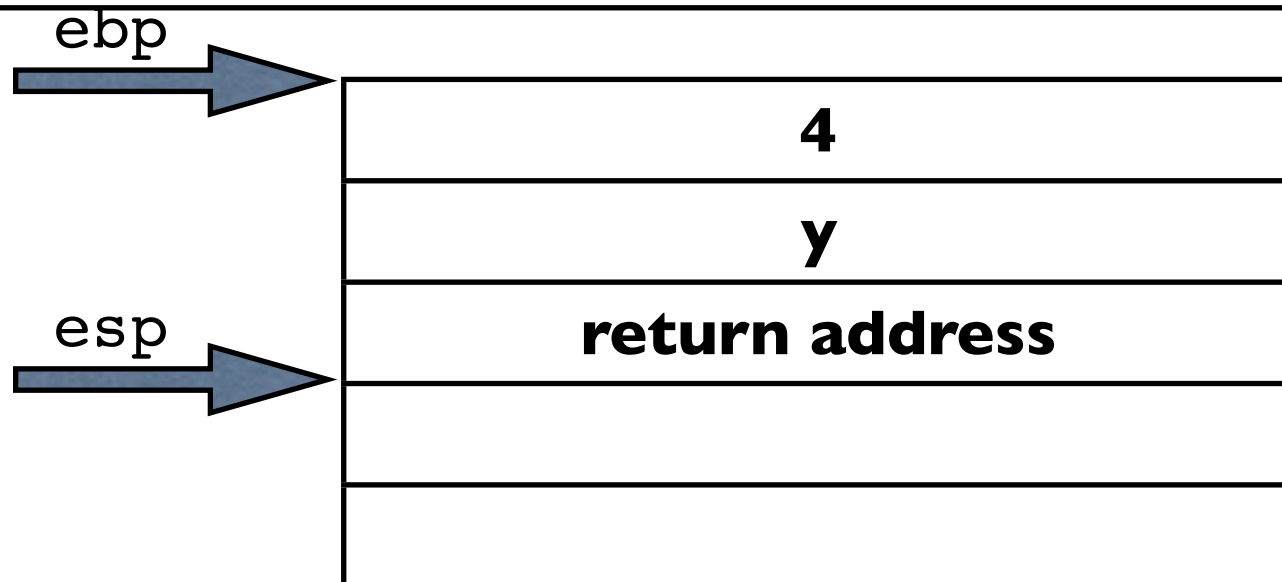
```
func1:  
    push ebp  
    mov ebp, esp  
    sub esp, 4  
    mov ecx, [ebp+0x8]  
    mul ecx, [ebp+0xC]  
    mov [ebp-4], ecx  
    mov eax, [ebp-4]  
    mov esp, ebp
```



# Example

## High-level language

```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```



## Assembler

```
push 4  
push [var_y]  
call func1
```

func1:

```
push ebp  
mov ebp, esp  
sub esp, 4  
mov ecx, [ebp+0x8]  
mul ecx, [ebp+0xC]  
mov [ebp-4], ecx  
mov eax, [ebp-4]  
mov esp, ebp  
pop ebp
```



# Example

## High-level language

```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

ebp/esp



## Assembler

```
push 4  
push [var_y]  
call func1
```

func1:

```
push ebp  
mov ebp, esp  
sub esp, 4  
mov ecx, [ebp+0x8]  
mul ecx, [ebp+0xC]  
mov [ebp-4], ecx  
mov eax, [ebp-4]  
mov esp, ebp  
pop ebp  
ret 8
```

# Example

## High-level language

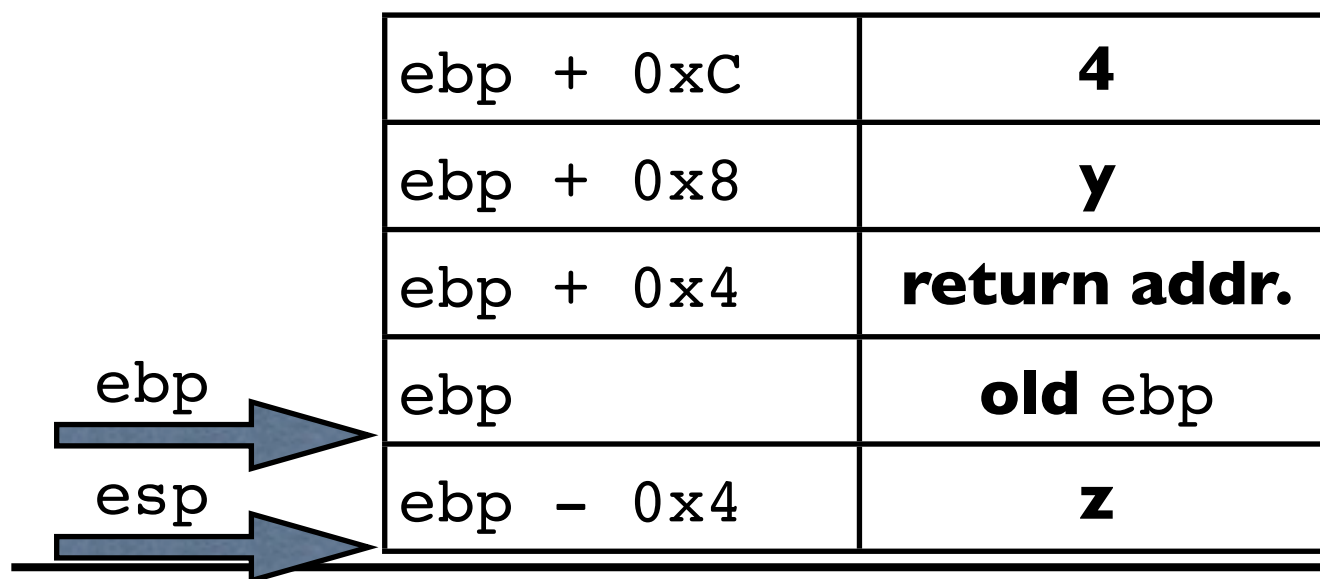
```
x = func1(y, 4);  
  
stdcall int func1(int a, int b )  
{  
    int z;  
    z = a * b;  
    return z;  
}
```

## Assembler

```
push 4  
push [var_y]  
call func1  
mov [var_x], eax ;RET
```

func1:

```
push ebp  
mov ebp, esp  
sub esp, 4  
mov ecx, [ebp+0x8]  
mul ecx, [ebp+0xC]  
mov [ebp-4], ecx  
mov eax, [ebp-4]  
mov esp, ebp  
pop ebp  
ret 8
```



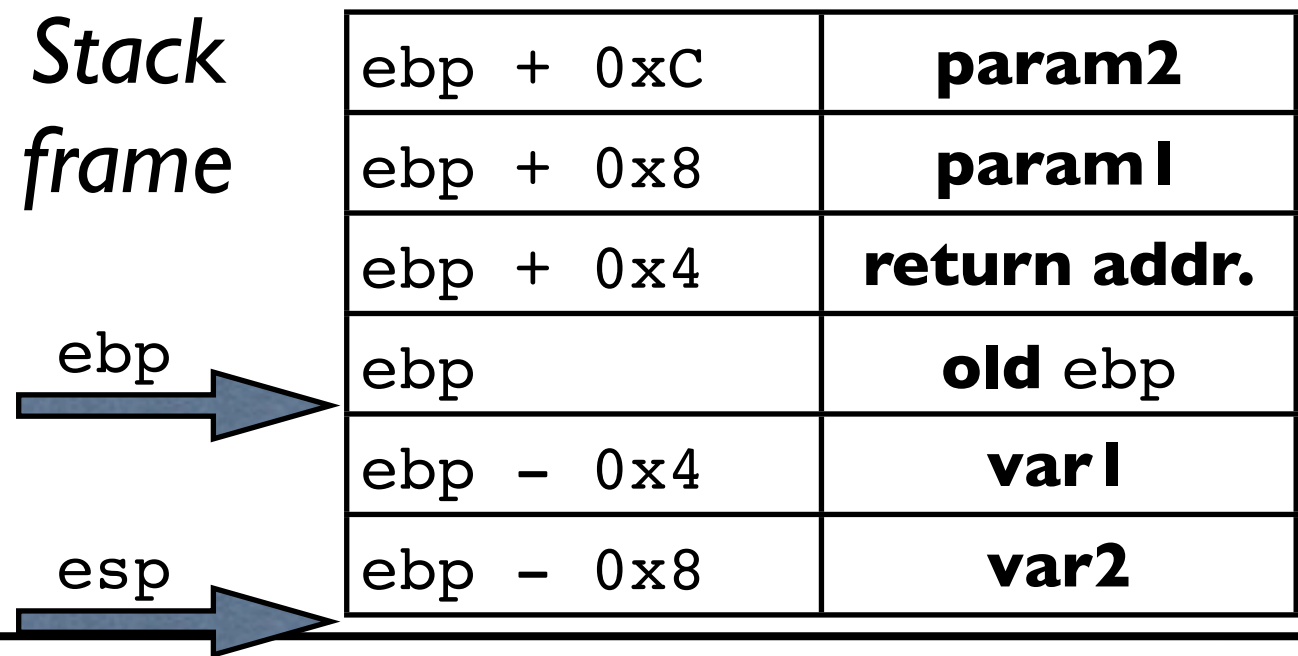
# Example II

## High-level language

```
void f(int param1, int param2) {  
    int var1 = 0;  
    int var2 = 1;  
    param1 = var1;  
    param2 = var2;  
}
```

## Assembler

```
push    ebp  
mov     ebp, esp  
sub     esp, 8  
mov     [ebp-4], 0  
mov     [ebp-8], 1  
mov     eax, [ebp-4]  
mov     [ebp+8], eax  
mov     ecx, [ebp-8]  
mov     [ebp+12], ecx  
mov     esp, ebp  
pop     ebp  
retn
```



# Calling Conventions

- Three problems
  - How are parameters passed?
  - When is the stack pointer modified during a call to a subroutine?
  - Which registers need to be saved during a subroutine call?
- No problem within the same program, compiler decides which *calling convention* to use

# Calling Conventions

- What happens with external code?
  - For example: API in external library
- Calling and called function need to use same calling convention
- Needs to be known during compile time
- There are four relevant calling conventions: *cdecl*, *stdcall*, *fastcall* and *thiscall*

# Calling Conventions

cdecl	stdcall	fastcall
<ul style="list-style-type: none"><li>- All parameters are pushed to stack</li><li>- <b>Calling</b> function cleans the stack after the function call returns</li><li>- C semantic</li><li>- <i>Advantage</i>: variable number of parameters (printf &amp; co.)</li></ul>	<ul style="list-style-type: none"><li>- All parameters are pushed to stack</li><li>- <b>Callee</b> is responsible to cleanup the stack (e.g., ret 12)</li></ul>	<ul style="list-style-type: none"><li>- First three parameters in eax, edx and ecx (Windows: first two parameters in ecx and edx)</li><li>- All other parameters on stack</li><li>- <b>Callee</b> is responsible to cleanup the stack</li></ul>

# Calling Conventions

cdecl	stdcall	fastcall
<ul style="list-style-type: none"><li>- <code>eax</code>, <code>ecx</code>, and <code>edx</code> are available for use in the function</li><li>- Return value available in <code>eax</code></li></ul>	<ul style="list-style-type: none"><li>- <code>eax</code>, <code>ecx</code>, and <code>edx</code> are available for use in the function</li><li>- Return value available in <code>eax</code></li><li>- Standard calling convention for Win32 API</li></ul>	<ul style="list-style-type: none"><li>- Return value available in <code>eax</code></li><li>- Typically only used internally by OS</li></ul>

# Example

cdecl	stdcall	fastcall
<p>Call:</p> <pre>push 3 push 2 push 1 call F add esp, 12 cmp eax, 0 jz error</pre>	<p>Call:</p> <pre>push 3 push 2 push 1 call F cmp eax, 0 jz error</pre>	<p>Call:</p> <pre>mov ecx, 3 mov edx, 2 mov eax, 1 call F cmp eax, 0 jz error</pre>
<p>Subroutine F:</p> <pre>push ebp mov ebp, esp ... pop ebp ret</pre>	<p>Subroutine F:</p> <pre>push ebp mov ebp, esp ... pop ebp ret 12</pre>	<p>Subroutine F:</p> <pre>push ebp mov ebp, esp ... pop ebp ret</pre>



# Example

- Content of registers need to be saved when entering the function...
- ... and restored when leaving the function again
- First push to stack, then pop in reverse order

```
push ebx
push esi
push ebp
mov ebp, esp
...
mov ebx, 0
...
mov esi, DEADBEEFh
...
pop ebp
pop esi
pop ebx
ret
```

# cdecl

- Advantage of cdecl if number of parameter is not fixed
- Called subroutine does not need to know the number of parameters
- Supports semantic required by C

```
printf(„Integer: %d“, i, someothervar);
```

```
push [someothervar]  
push [i]  
push offset IntegerStr  
call printf  
add esp, 12  
ret
```

# Summary: Calling function

- Push parameter to stack (or pass in registers)
- Return value in `eax`
- Optionally: remove parameters from stack

# Summary: Callee

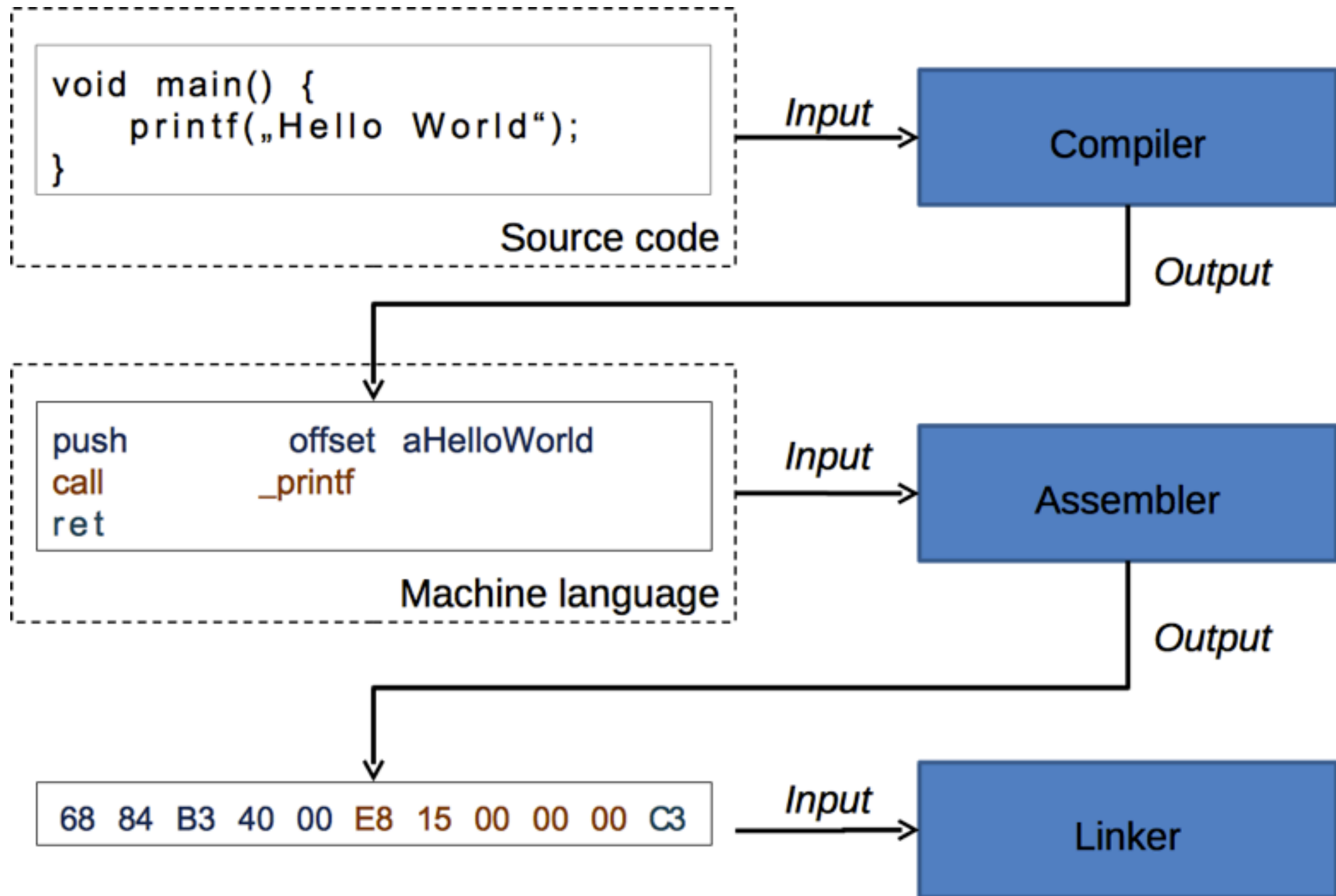
- Prolog
  - Save old ebp, esp is new ebp
  - Reserve memory space for local variables on stack
- Epilog
  - Restore old ebp
  - Jump to return address
  - Optionally: remove parameters from stack

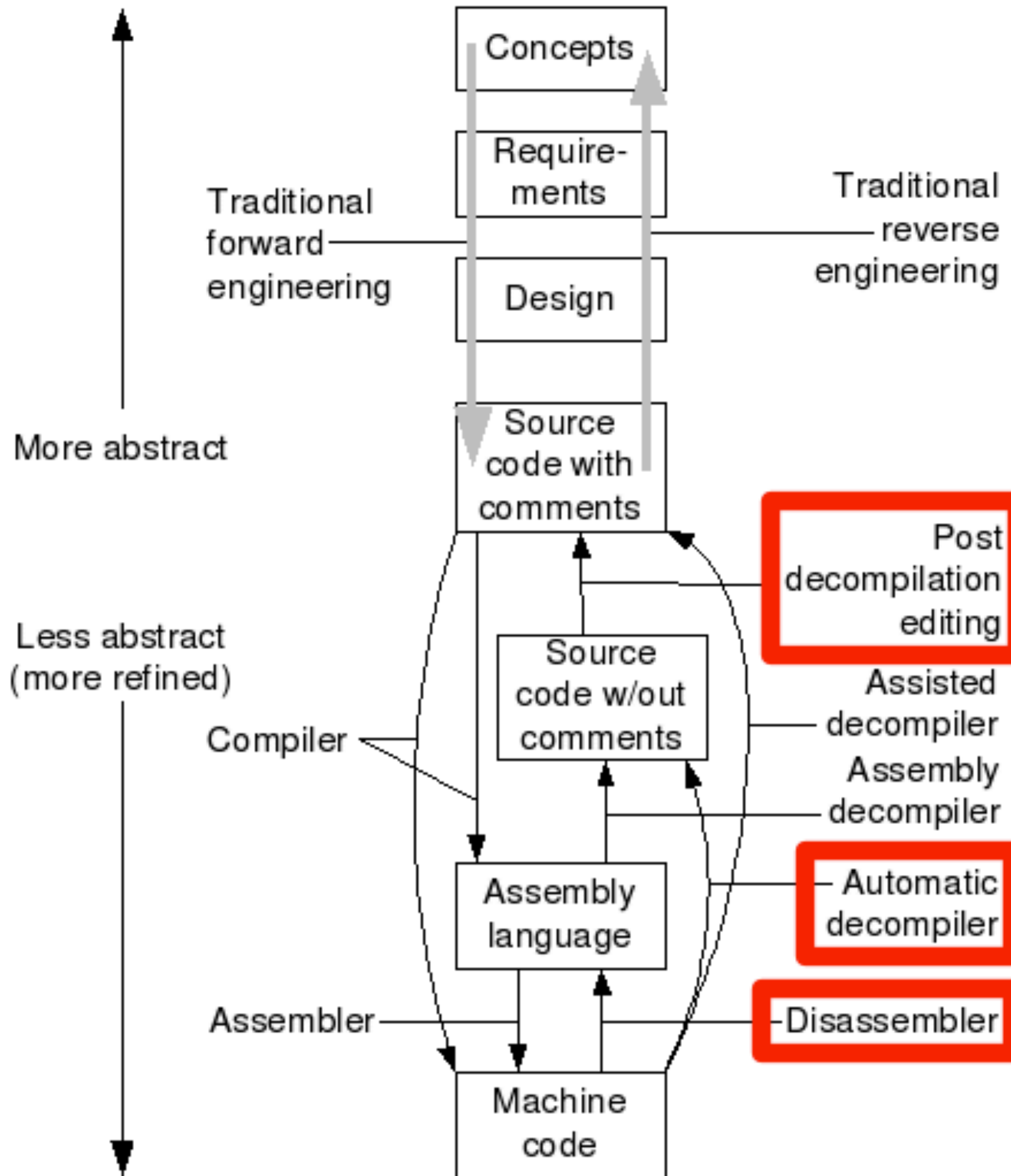
# Higher-level Structures

# Higher-level Languages

- Programming in assembler is cumbersome
  - Hard to understand and maintain
  - Code is not portable
  - Nowadays commonly used in performance-critical applications, malware/shellcode, and similar areas
- Typically programmers implement in higher-level languages like C/C++, Java, Python, ...

# Compiler Overview







# Reverse Engineering

- Typical goal: reconstruct code information and data structures from a given binary program
- Assembler  $\Rightarrow$  Higher-level language
- Several exercises deal with this topic
- To understand this, we take a look at examples
  - Higher-level language  $\Rightarrow$  Assembler
  - Getting a feeling of how compilers transform code

# Example

## High-level language

```
x = func1(y, 4);

stdcall int func1(int a, int b )
{
    int z;
    z = a * b;
    return z;
}
```

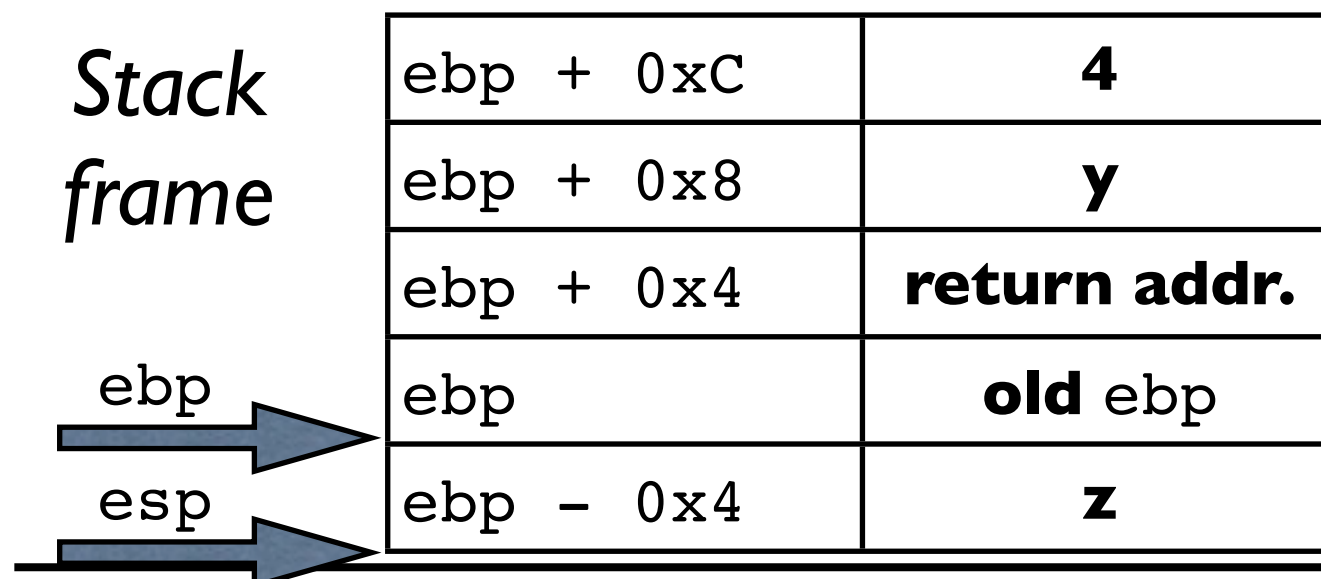
## Assembler

```
push 4
push [var_y]
call func1
mov [var_x], eax ;RET
```

func1:

```
push ebp
mov ebp, esp
sub esp, 4
mov ecx, [ebp+0x8]
mul ecx, [ebp+0xC]
mov [ebp-4], ecx
mov eax, [ebp-4]
mov esp, ebp
pop ebp
ret 8
```

*Stack  
frame*



# Control-flow Structures

- Conditional expressions
  - IF ...THEN ...
- Branches
  - IF ...THEN ... ELSE ...
  - SWITCH ... CASE ...
- Loops (WHILE ... DO, DO ...WHILE, FOR ... DO ...)
- Function calls

# Conditional Expressions

## High-level language

```
IF( SomeVar == 0 ) THEN  
    function1()
```

## Assembler

```
mov eax, [SomeVar]  
test eax, eax  
jnz lab_end  
call function1  
lab_end:  
...
```

# Branches

## High-level language

```
IF( Var1 == 1 )  
    THEN function1()  
ELSE IF( Var1 == 2 )  
    THEN function2()  
ELSE function3()
```

## Assembler

```
cmp [Var1],1  
jne lab_else1  
call function1  
jmp lab_end  
lab_else1:  
    cmp [Var1],2  
    jne lab_else2  
    call function2  
    jmp lab_end  
lab_else2:  
    call function3  
lab_end:  
    ...
```

# Expressions: OR

## High-level language

```
IF(  Var1 == 1  ||  
    Var1 == 2  ||  
    Var2 >= 5  )  
    THEN function1()
```

## Assembler

```
cmp [Var1], 1  
je lab_then  
cmp [Var1], 2  
je lab_then  
cmp [Var2], 5  
jae lab_then  
jmp lab_end  
lab_then:  
    call function1  
lab_end:  
    ...
```

# Switch Statements

- Switch statements are common

```
switch( condition ) {  
    case value1: ...; break;  
    case value2: ...; break;  
    case value3: ...; break;  
    default: ...; break }
```

- Often implemented as
  - *Table*: if values are near each other, complexity  $O(1)$
  - *Tree*: if values are far away, complexity  $O(\log(n))$

# Example: Table Lookup I

## High-level language

```
switch( Var1 )
{
    case 0: RC = 0; break;
    case 1: RC = 1; break;
    case 2: RC = 2; break;
    case 3: RC = 3; break;
    default: RC = 0; break;
}
```

**switch\_table:**

```
0x00: dd offset lab_case0
0x04: dd offset lab_case1
0x08: dd offset lab_case2
0x0C: dd offset lab_case3
```

## Assembler

```
cmp [Var1], 3
ja lab_default
mov ecx, [Var1]
jmp switch_table[ecx*4]
lab_case0:
    mov [RC], 0
    jmp lab_end
lab_case1:
    mov [RC], 1
    jmp lab_end
...
lab_default
    mov [RC], 0
    jmp lab_end
lab_end:
...
```



# Example: Table Lookup II

## High-level language

```
switch( Var1 )
{
    case 0: RC = 0; break;
    case 1: RC = 1; break;
    case 2: RC = 2; break;
    case 4: RC = 4; break;
    default: RC = 0; break;
}
```

```
switch_table:
0x00: dd offset lab_case0
0x04: dd offset lab_case1
0x08: dd offset lab_case2
0x0C: dd offset lab_default
0x10: dd offset lab_case4
```

## Assembler

```
cmp [Var1], 4
ja lab_default
mov ecx, [Var1]
jmp switch_table[ecx*4]
lab_case0:
    mov [RC], 0
    jmp lab_end
...
lab_case4:
    mov [RC], 4
    jmp lab_end
...
lab_default:
    mov [RC], 0
    jmp lab_end
lab_end:
```

# Example: Table Lookup II

## High-level language

```
switch( Var1 )
{
    case 0: RC = 0; break;
    case 1: RC = 1; break;
    case 2: RC = 2; break;
    case 4: RC = 4; break;
    default:
}
```

## Assembler

```
cmp [Var1], 4
ja lab_default
mov ecx, [Var1]
jmp switch_table[ecx*4]
lab_case0:
```

If there are “holes”: use default value in lookup table

```
switch_table:
0x00: dd offset lab_case0
0x04: dd offset lab_case1
0x08: dd offset lab_case2
0x0C: dd offset lab_default
0x10: dd offset lab_case4
```

```
mov [RC], 4
jmp lab_end

...
lab_default
mov [RC], 0
jmp lab_end
lab_end:
```

# Example: Tree Lookup

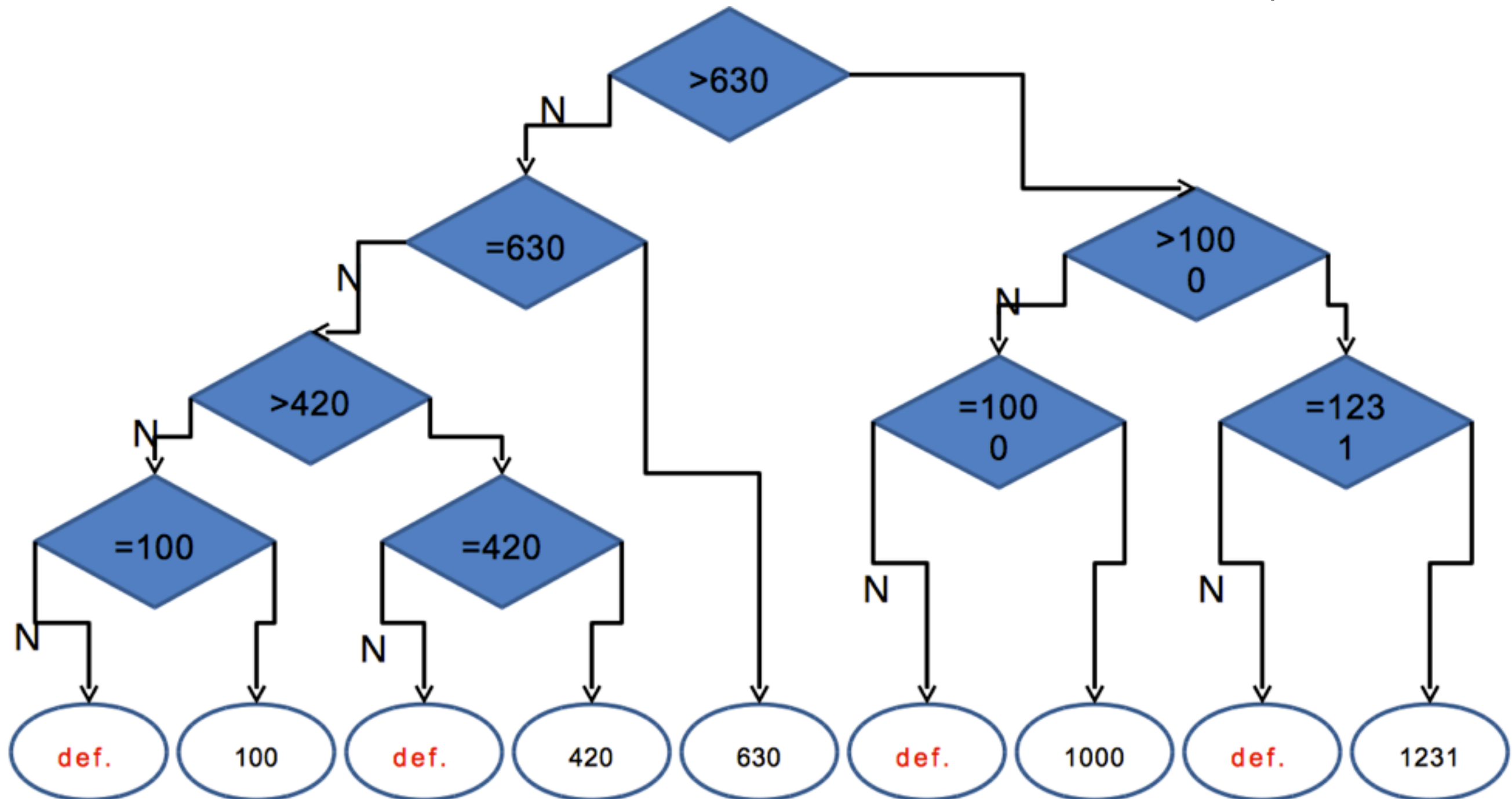
## High-level language

```
switch( Var1 )
{
    case 0x0: ...
    case 0x100: ...
    case 0x150: ...
    case 0x172: ...
    case 0x210: ...
    case 0x230: ...
    case 0x2A0: ...
    default: ...
}
```

## Assembler

```
cmp [Var1], 0x172
jg lab_above_0x172
cmp [Var1], 0x172
je lab_0x172
cmp [Var1], 0x100
jg lab_above_0x100
cmp [Var1], 0x100
je lab_0x100
cmp [Var1], 0x0
je lab_0x0
jmp lab_default
lab_above_0x100:
    cmp [Var1], 0x150
    je lab_0x150
    jmp lab_default
lab above 0172: ...
```

# Example: Tree Lookup



# Questions?

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Systems Security  
Ruhr-University Bochum

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More information:

<http://syssec.rub.de>

<http://moodle.rub.de>



# Sources

- Lecture *Software Reverse Engineering* at University of Mannheim, spring term 2010 (Ralf Hund, Carsten Willems and Felix Freiling)