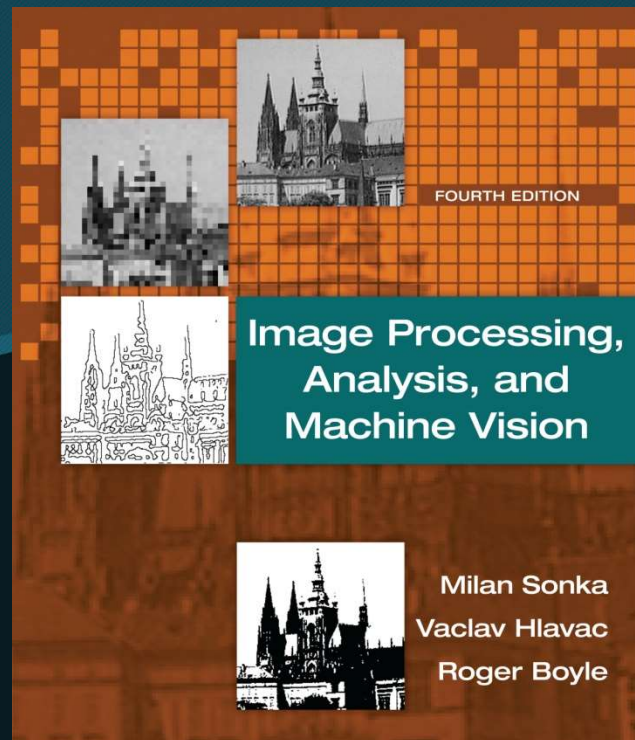


# Chapter 1

## Introduction



# Motivation

- Video
  - Frame v.s. image

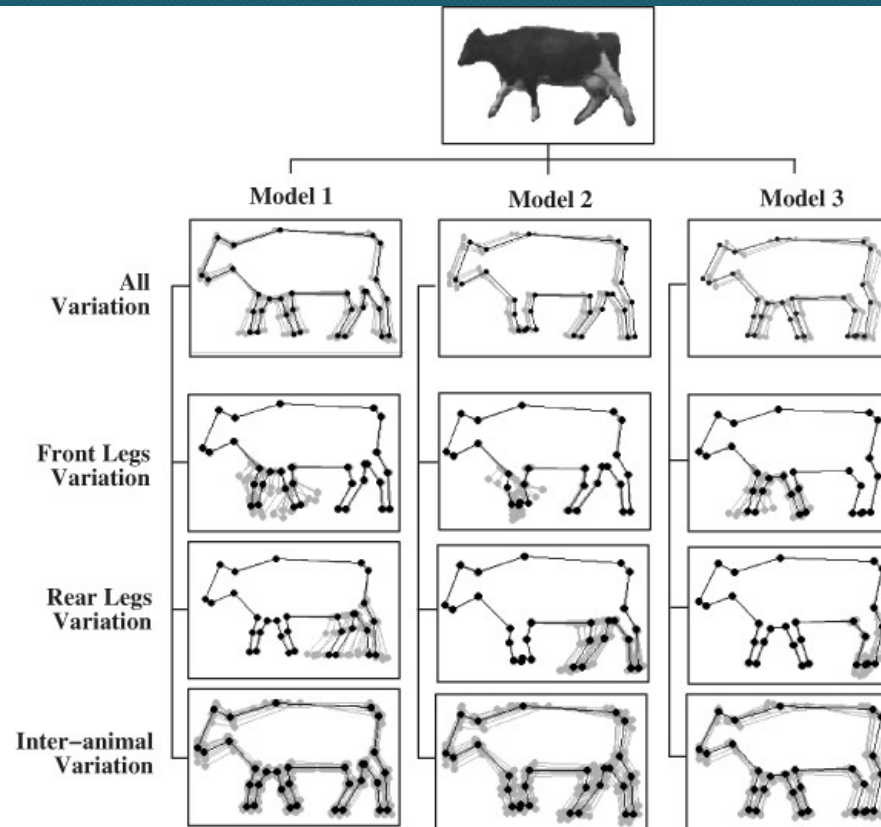


**Figure 1.1:** A frame from a video of a typical farmyard scene: the cow is one of a number walking naturally from right to left. *Courtesy of D. R. Magee, University of Leeds.*



# Motivation

- Training
  - Creating model



**Figure 1.2:** Various models for a cow silhouette: a straight-line boundary approximation has been learned from training data and is able to adapt to different animals and different forms of occlusion. *Courtesy of D. R. Magee, University of Leeds.*



# Motivation

- Detection (testing)

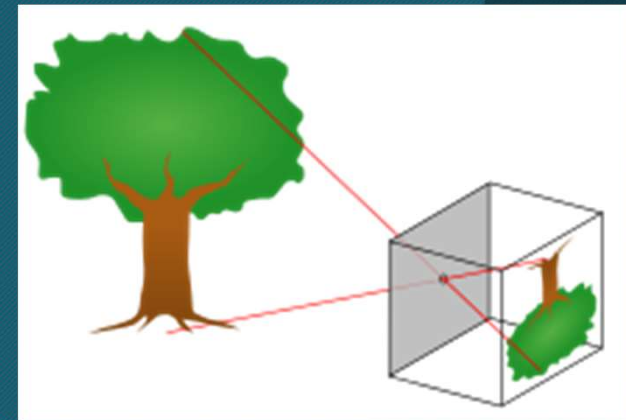
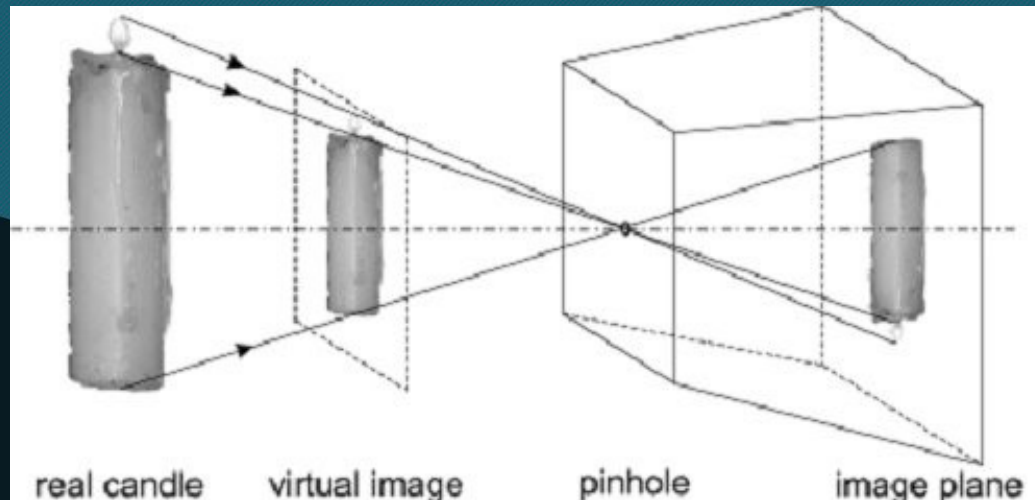


**Figure 1.3:** Three frames from a cow sequence: notice the model can cope with partial occlusion as the animal enters the scene, and the different poses exhibited. *Courtesy of D. R. Magee, University of Leeds.*



# Why is computer vision difficult?

- **Loss of information in 3D to 2D**
  - The **pinhole model** of imaging geometry does not distinguish size of objects.



[https://en.wikipedia.org/wiki/Pinhole\\_camera\\_model](https://en.wikipedia.org/wiki/Pinhole_camera_model)



# Why is computer vision difficult?

- **Interpretation**

- Interpretation: image data  $\rightarrow$  model
- There may be **several interpretations** of the same image(s).

- **Noise**

- Noise is inherently present in each measurement in the real world.

- **Too much data**

- Images are big, and **videos** are correspondingly bigger.

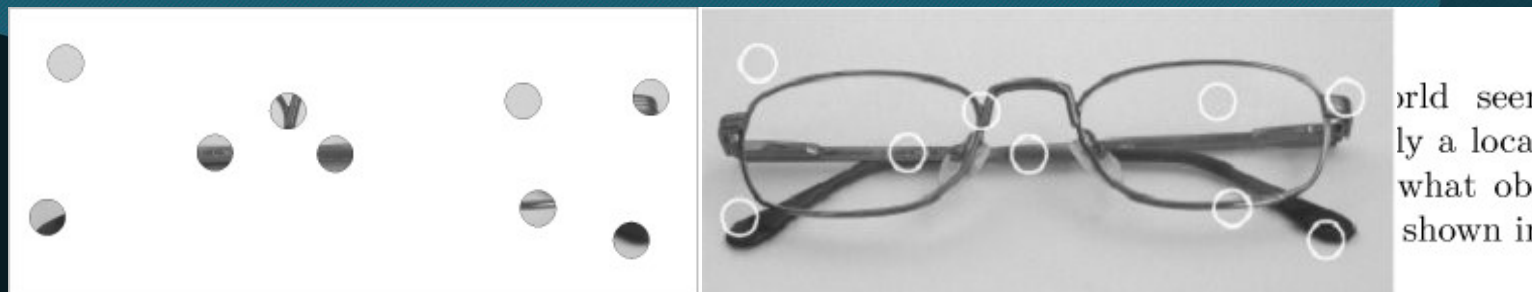
- **Brightness measured**

- Brightness measured in images is given by complicated image formation physics.
- The brightness depends on the light source type, intensity and position, the observer's position, the surface local geometry, and the surface reflectance properties.
- The inverse tasks are **ill-posed**.

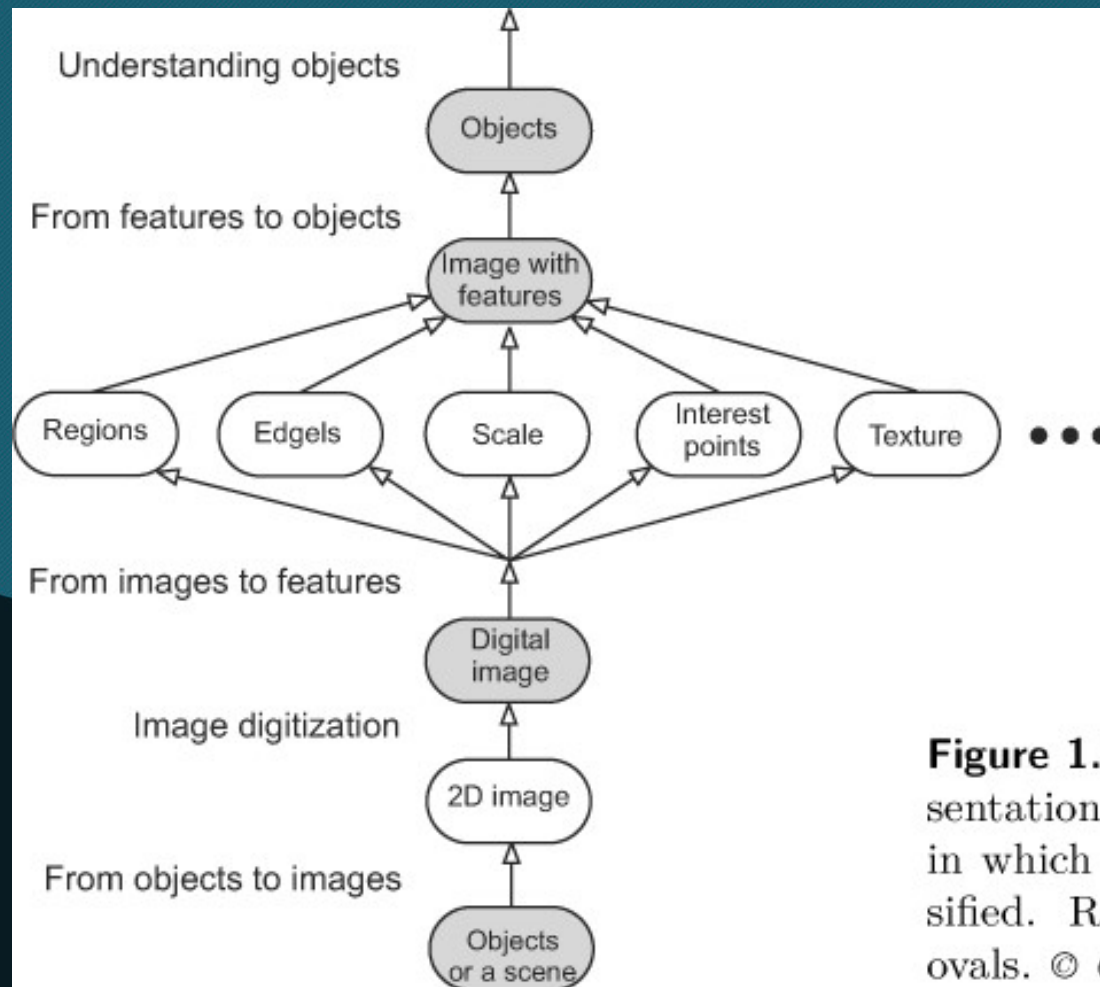


# Why is computer vision difficult?

- **Local window v.s. need for global view**
  - Commonly, image analysis algorithms analyze a particular storage bin in an operational memory and its local neighborhood.
  - The computer sees the image through a keyhole.
  - This makes it very difficult to understand more **global** context.



# Image representation and image analysis task

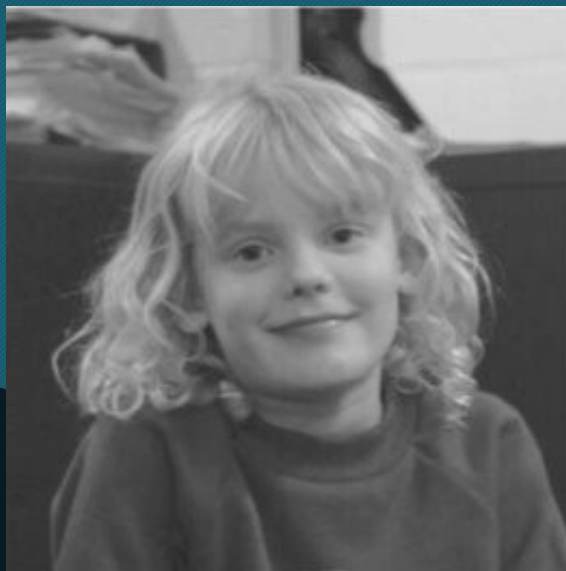


**Figure 1.7:** Four possible levels of image representation suitable for image analysis problems in which objects have to be detected and classified. Representations are depicted as shaded ovals. © Cengage Learning 2015.

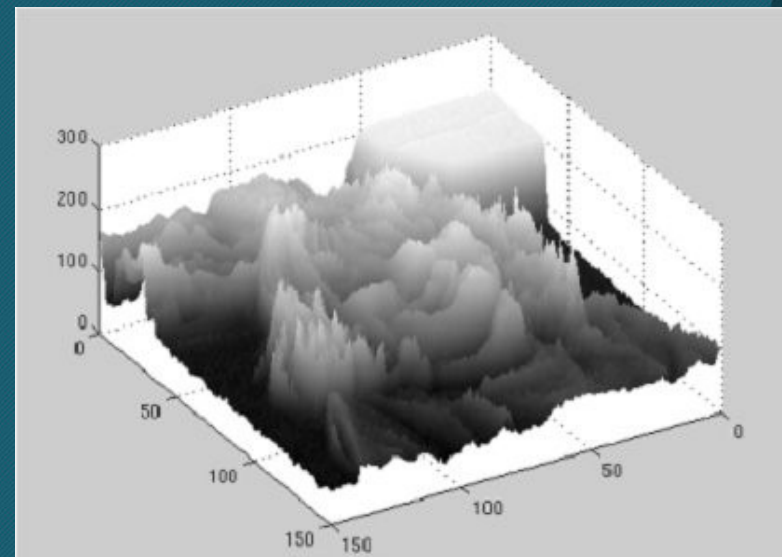


# Image representation and image analysis task

- Both representations contain exactly the same information.
  - Human observer v.s. machine recognizer



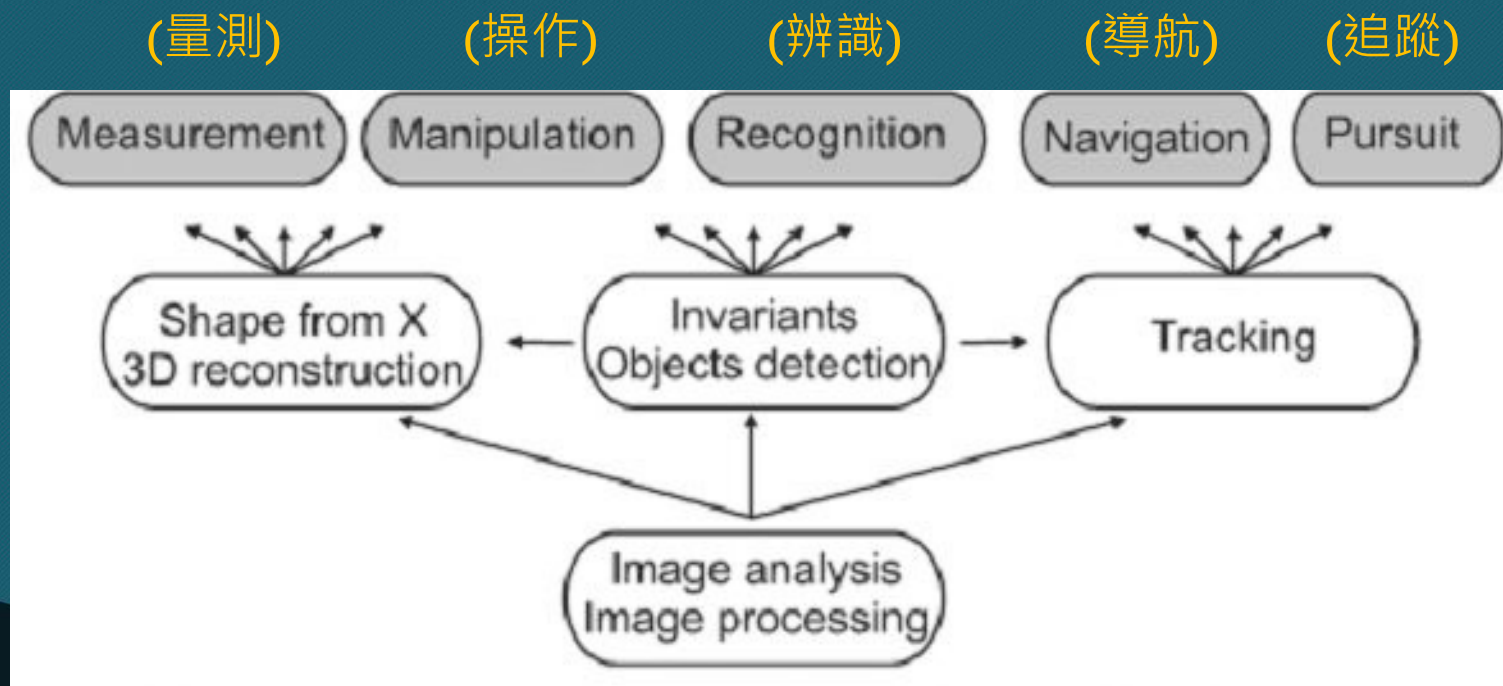
**Figure 1.9:** Another representation of Figure 1.8.  
© R.D. Boyle 2015.



**Figure 1.8:** An unusual image representation.  
© R.D. Boyle 2015.



# Image representation and image analysis task



- Several 3D computer vision tasks from the **user's point of view** are on the upper line.
- **Algorithm components** on different hierarchical levels support it in a bottom-up fashion.



# Homework 1 : image read/write and rotation

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## 作業一： 影像的讀寫與旋轉