

# Grad CAM

Grad CAM stands for Gradient-Weighted Class Activation Mapping. This technique is used to produce visual explanations for decisions made by convolutional neural networks (CNNs). By calculating gradients of a target concept (e.g., a classification label) with respect to the final convolutional layer's feature maps, it generates a heat map highlighting important regions in an image.

**“Which regions of the image were most important for this specific class prediction?”**

## Terminology

- Let  $y^c$  denote the score (logit) for class  $c$ .
- Let  $A^k$  denote the  $k$ -th feature map of the chosen convolutional layer.
- Let  $A_{ij}^k$  denote the activation at spatial location  $(i, j)$  in the  $k$ -th feature map.

## Steps

### Step 1: Compute gradients

Take the gradient of the class score with respect to each feature map activation:

$$\frac{\partial y^c}{\partial A_{ij}^k}$$

This measures how sensitive the class score  $y^c$  is to changes at spatial location  $(i, j)$  in feature map  $k$ .

### Step 2: Global Average Pooling (importance weights)

Compute a single scalar weight for each feature map:

$$\alpha_k^c = \frac{1}{Z} \sum_i \sum_j \frac{\partial y^c}{\partial A_{ij}^k}$$

where  $Z$  is the total number of spatial locations in the feature map.

These weights  $\alpha_k^c$  represent the importance of feature map  $k$  for class  $c$ .

### **Step 3: Weighted combination**

Compute the class-specific localization map by linearly combining the feature maps:

$$L_{\text{Grad-CAM}}^c = \sum_k \alpha_k^c A^k$$

### **Step 4: ReLU**

Apply a ReLU operation:

$$\text{Grad-CAM}^c = \text{ReLU}(L_{\text{Grad-CAM}}^c)$$

The ReLU retains only positive values, highlighting regions that have a positive influence on the class prediction, while discarding regions that suppress the class.