view\_frames Result Recorded at time: 14.636 map Broadcaster: /rtabmap/rtabmap Average rate: 20.225 Hz Most recent transform: 14.718 (-0.082 sec old) Buffer length: 4.450 sec odom Broadcaster: /gazebo Average rate: 10.227 Hz Most recent transform: 14.601 ( 0.035 sec old) Buffer length: 4.400 sec robot\_footprint Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (14.636 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /rtabmap/kinect\_correction Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10.183 Hz Average rate: 10.225 Hz Average rate: 10000.000 Hz Average rate: 10.225 Hz Most recent transform: 0.000 (14.636 sec old) Most recent transform: 0.000 (14.636 sec old) Most recent transform: 14.673 (-0.037 sec old) Most recent transform: 14.601 (0.035 sec old) Most recent transform: 14.601 (0.035 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.419 sec Buffer length: 4.401 sec Buffer length: 4.401 sec camera\_rgbd\_frame camera\_rgbd hokuyo left\_wheel right\_wheel