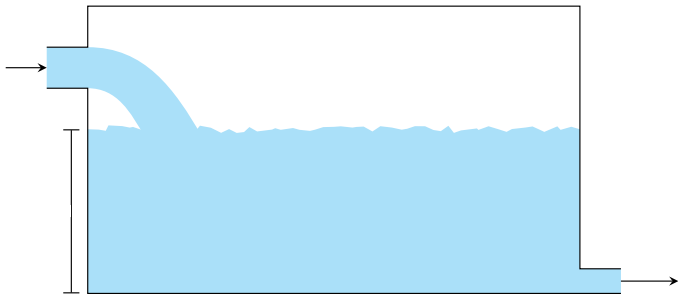


# Process Automation Laboratory - Modeling first-order systems

Kjartan Halvorsen

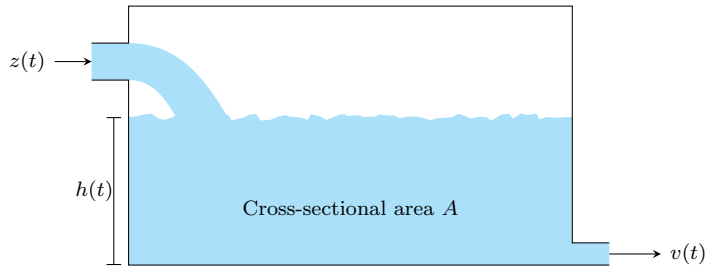
2020-08-17

## First-order system example: A tank



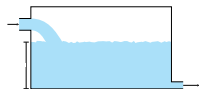
1. What is the **state** of the system?
2. What is the **input signal** and **output signal**?

## First-order system example: A tank

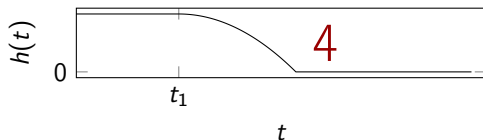
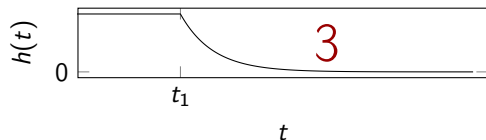
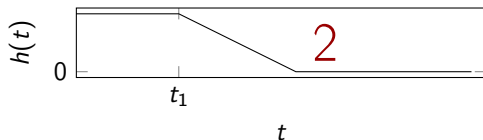
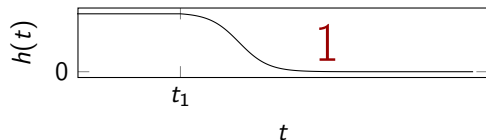


$$\begin{aligned}\frac{d}{dt}(Ah) &= z(t) - x(t) = z(t) - a\sqrt{2gh} \quad \Rightarrow \\ \frac{d}{dt}h(t) &= -\frac{a\sqrt{2g}}{A}\sqrt{h(t)} + \frac{1}{A}z(t)\end{aligned}$$

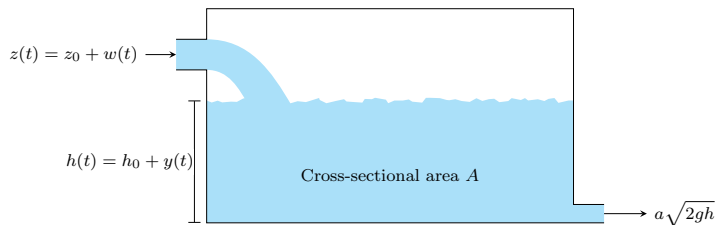
# Intuition



**Individual activity** A constant inflow has been present since forever, but at time  $t_1$  the flow in is suddenly shut off. Which of the responses of the water level  $h(t)$  below is correct?



## Deviation variables



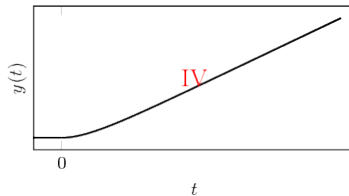
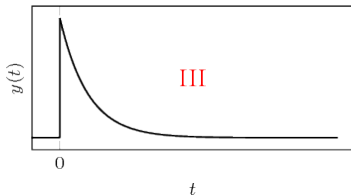
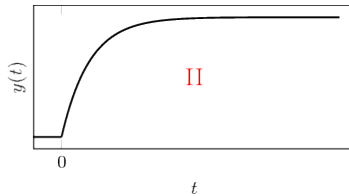
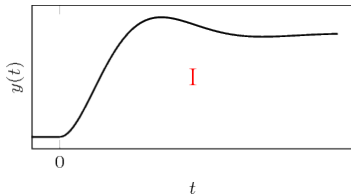
Flow in:  $z(t) = z_0 + w(t)$ . Level of water:  $h(t) = h_0 + y(t)$ . The constants  $h_0$  and  $z_0$  define an *operating point*.

$$\frac{d}{dt}h(t) = -\frac{a\sqrt{2g}}{A}\sqrt{h(t)} + \frac{1}{A}z(t)$$

**Individual activity** Given  $h_0$  determine the operating point for the inflow,  $z_0$ , such that the system is in equilibrium at the operating point.

# Intuition

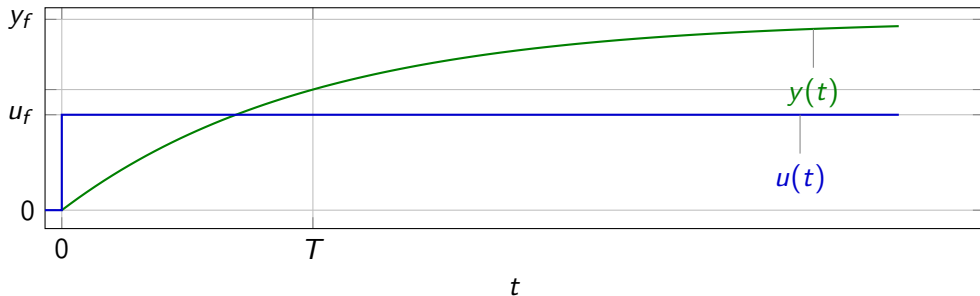
Which change  $y(t)$  in the water level corresponds to a step change  $w(t)$  in the inflow?



## Fitting a first-order model

Assuming a plant model of first-order with time-constant  $T$

$$Y(s) = \frac{K}{sT + 1} U(s) \quad U(s) \stackrel{u_f}{\Rightarrow} \frac{u_f}{s} \quad y(t) = u_f K (1 - e^{-\frac{t}{T}}) u_H(t)$$

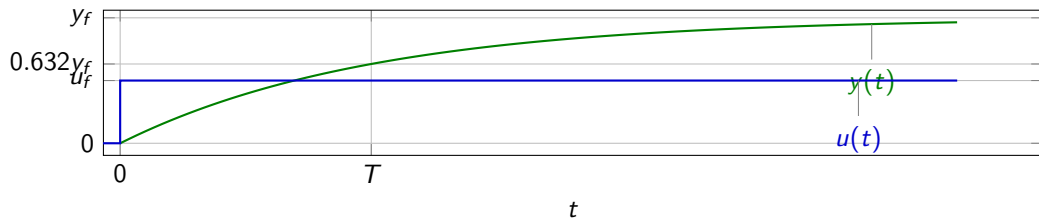


**Individual activity** Evaluate the response  $y(t)$  at the time instant  $t = T$  and for  $t \rightarrow \infty$ !

## Fitting a first-order model

Assuming a plant model of first-order with time-constant  $T$

$$Y(s) = \frac{K}{sT + 1} U(s) \quad U(s) = \frac{u_f}{s} \quad \Rightarrow \quad y(t) = u_f K (1 - e^{-\frac{t}{T}}) u_H(t)$$

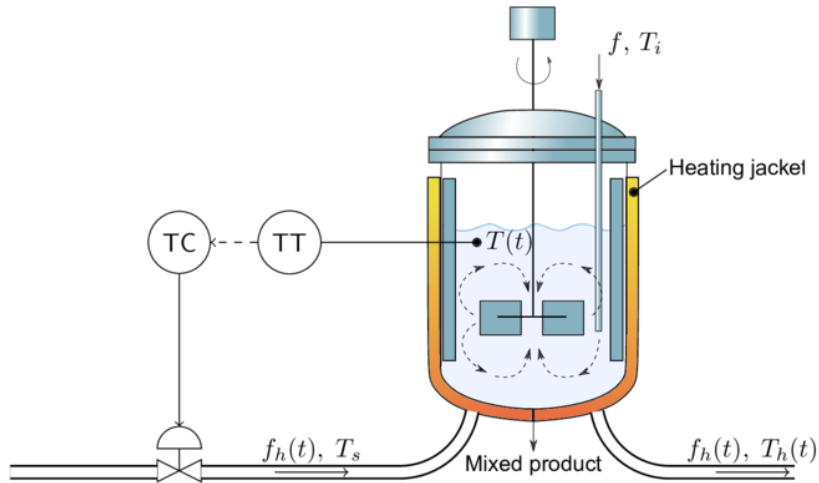


**Time-constant:** Find the time  $t = T$  at which the response has reached 63.2% of its final value

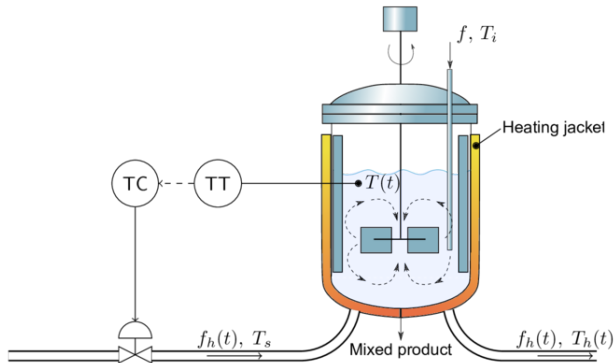
**Gain:**  $y_f = \lim_{t \rightarrow \infty} y(t) = Ku_f \quad \Rightarrow \quad K = \frac{y_f}{u_f}$



# A Continuous Stirred Tank Reactor



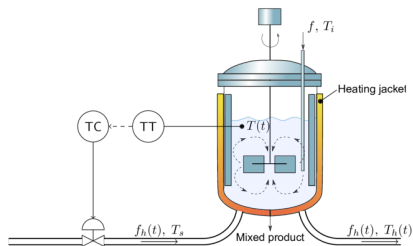
# A Continuous Stirred Tank Reactor



Assume:

- ▶ constant flow  $f$  through the tank reactor
- ▶ constant temperatures  $T_i$  and  $T_s$
- ▶ isothermic reaction

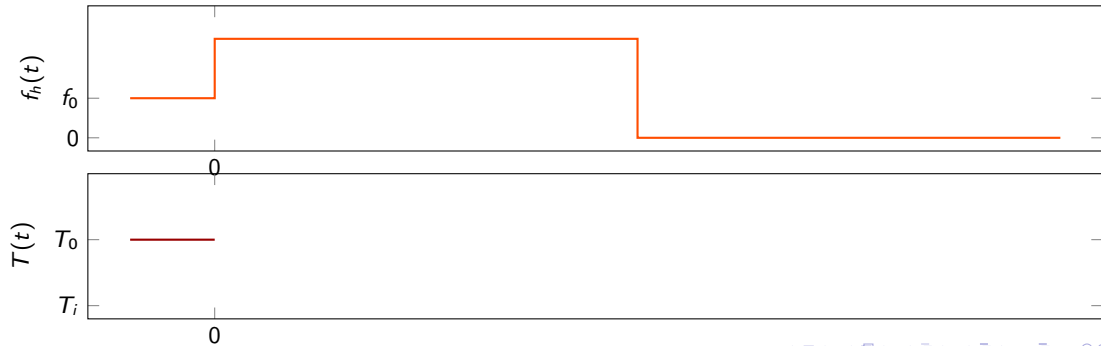
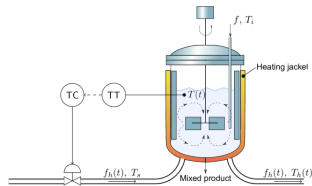
# A Continuous Stirred Tank Reactor



Energy balance:

$$\frac{dT(t)}{dt} = k_1(T_i - T(t)) + k_2(T_h(t) - T(t))$$
$$\frac{dT_h(t)}{dt} = k_3 f_h(t)(T_s - T_h(t)) - k_4(T_h(t) - T(t))$$

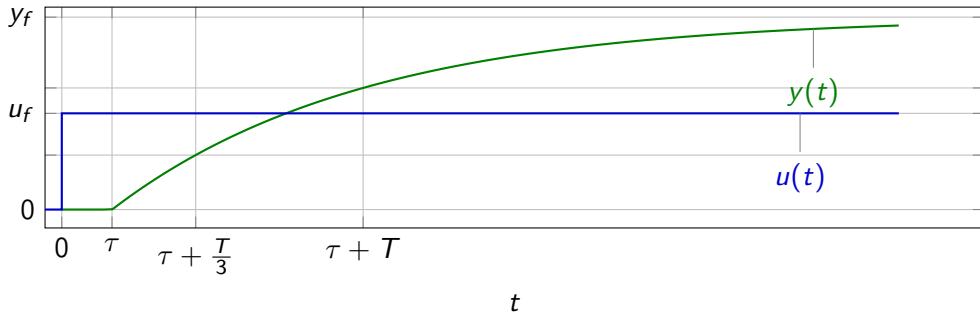
# Intuition



## Fitting first-order model with delay

Assuming a plant model of first-order with time constant  $T$  and delay  $\tau$

$$Y(s) = \frac{Ke^{-s\tau}}{sT + 1} U(s) \quad U(s) = \frac{u_f}{s} \quad \Rightarrow \quad y(t) = u_f K (1 - e^{-\frac{t-\tau}{T}}) u_H(t - \tau)$$

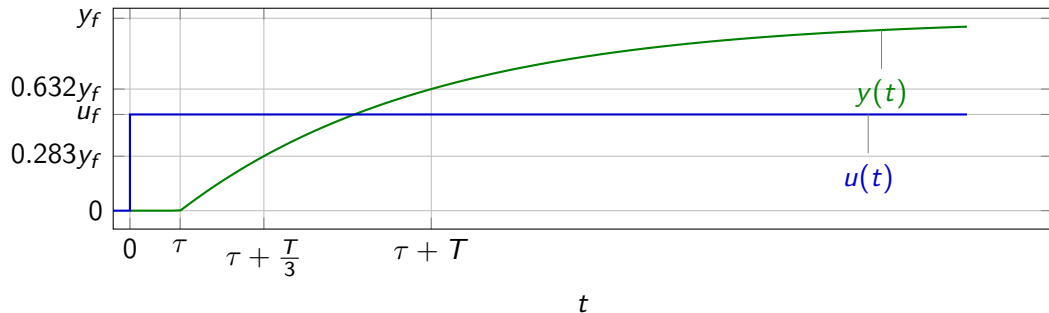


**Individual activity** Evaluate the response  $y(t)$  at the two time instants  $t = \tau + \frac{T}{3}$  and  $t = \tau + T$ !

## Fitting first-order model with delay

Assuming a plant model of first-order with time constant  $T$  and delay  $\tau$

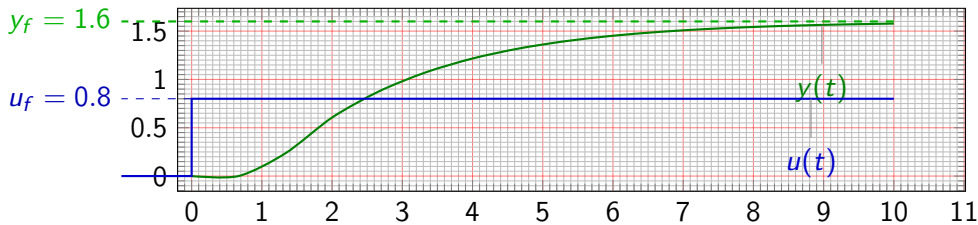
$$Y(s) = \frac{Ke^{-s\tau}}{sT + 1} U(s) \quad U(s) = \frac{u_f}{s} \quad \Rightarrow \quad y(t) = u_f K (1 - e^{-\frac{t-\tau}{T}}) u_H(t - \tau)$$



$$y_f = \lim_{t \rightarrow \infty} y(t) = u_f K \quad \Rightarrow \quad K = \frac{y_f}{u_f}$$

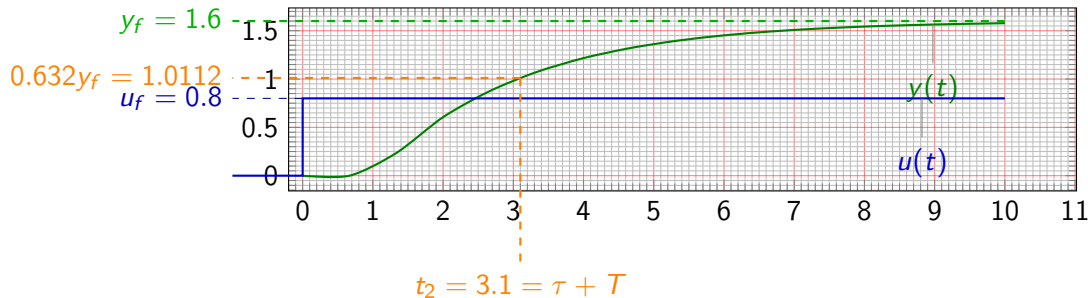
## First-order model with delay - example

$$Y(s) = \frac{Ke^{-s\tau}}{sT + 1} U(s) \quad U(s) = \frac{u_f}{s} \quad \Rightarrow \quad y(t) = u_f K \left(1 - e^{-\frac{t-\tau}{T}}\right) u_s(t - \tau)$$



## First-order model with delay - example

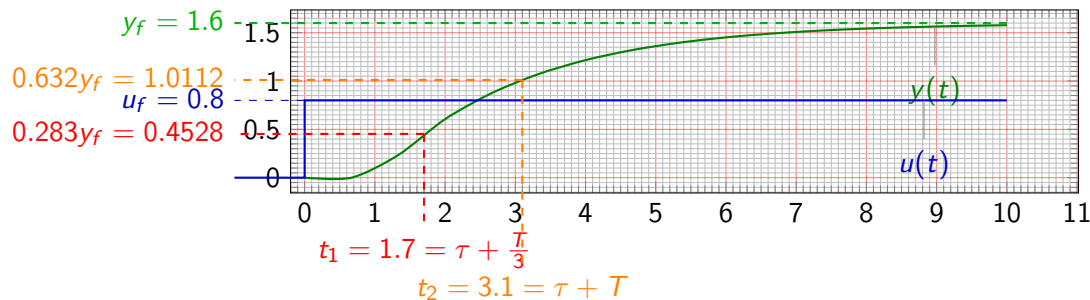
$$Y(s) = \frac{Ke^{-s\tau}}{sT + 1} U(s) \quad \xrightarrow{U(s) = \frac{u_f}{s}} \quad y(t) = u_f K \left(1 - e^{-\frac{t-\tau}{T}}\right) u_s(t - \tau)$$





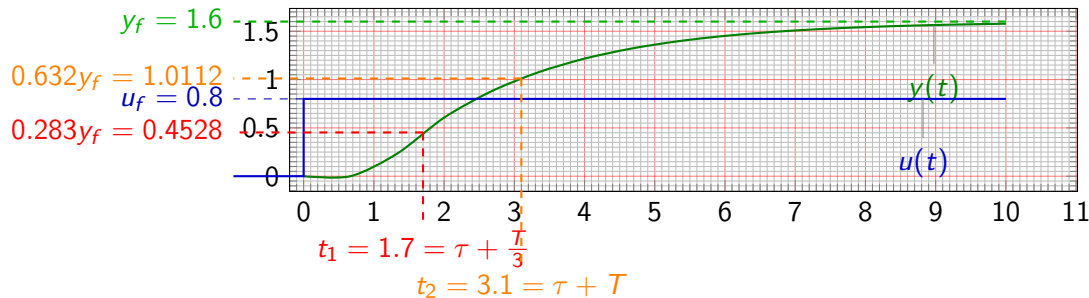
## First-order model with delay - example

$$Y(s) = \frac{Ke^{-s\tau}}{sT + 1} U(s) \quad \xrightarrow{U(s) = \frac{u_f}{s}} \quad y(t) = u_f K \left(1 - e^{-\frac{t-\tau}{T}}\right) u_s(t - \tau)$$



## First-order model with delay - example

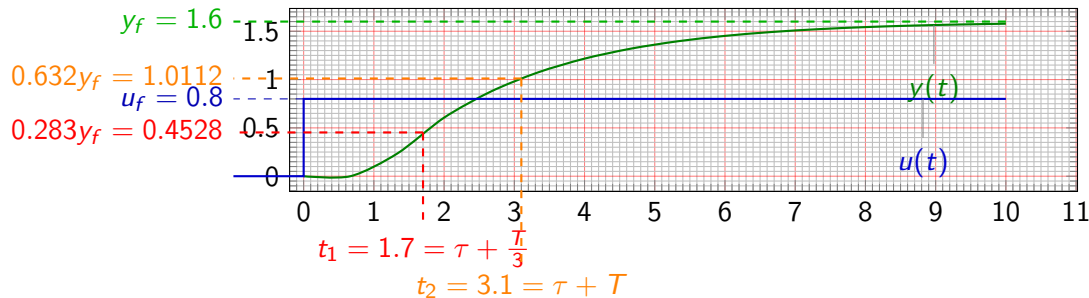
$$Y(s) = \frac{Ke^{-s\tau}}{sT + 1} U(s) \quad \xrightarrow{U(s) = \frac{u_f}{s}} \quad y(t) = u_f K \left(1 - e^{-\frac{t-\tau}{T}}\right) u_s(t - \tau)$$



$$\begin{cases} 1.7 = \tau + \frac{T}{3} \\ 3.1 = \tau + T \end{cases} \Rightarrow \begin{cases} \tau = 1 \\ T = 2.1 \end{cases}, \quad K = \frac{y_f}{u_f} = \frac{1.6}{0.8} = 2$$

## First-order model with delay - example

$$Y(s) = \frac{Ke^{-s\tau}}{sT + 1} U(s) \quad \xrightarrow{U(s) = \frac{u_f}{s}} \quad y(t) = u_f K \left(1 - e^{-\frac{t-\tau}{T}}\right) u_s(t - \tau)$$



$$\begin{cases} 1.7 = \tau + \frac{T}{3} \\ 3.1 = \tau + T \end{cases} \Rightarrow \begin{cases} \tau = 1 \\ T = 2.1 \end{cases}, \quad K = \frac{y_f}{u_f} = \frac{1.6}{0.8} = 2$$