

# PAC-Bayesian Generalization Bounds for Knowledge Graph Representation Learning

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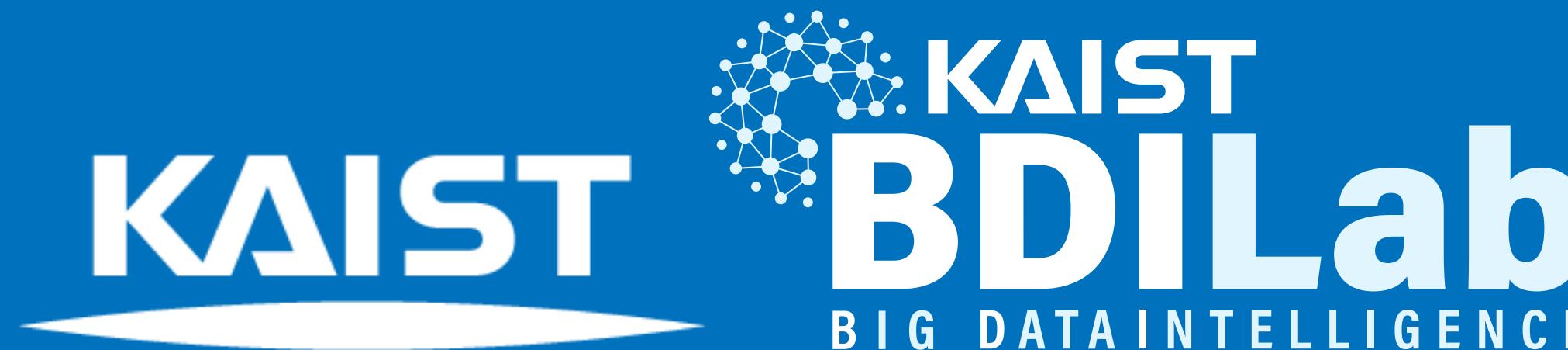
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## Main Contributions

- ReED framework representing at least 15 different KGRL methods
  - RAMP encoder in ReED is a comprehensive neural encoder for KGRL that can express models such as CompGCN and R-GCN
  - Formulate two types of triplet classification decoders in ReED
- Prove the generalization bounds for the ReED framework
  - The first study about PAC-Bayesian generalization bounds for KGRL
  - Analyze theoretical findings from a practical model design perspective
- Empirically show that the critical factors in generalization bounds can explain actual generalization errors on three real-world KGs

## Knowledge Graphs (KGs)

- Triplet classification on a KG
    - A model determines whether a given triplet is plausible or not
  - Knowledge Graph Representation Learning (KGRL)
    - By learning representations of the entities and relations, KGRL methods compute a score for each triplet
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## Generalization Bound

- Generalization Error
    - Difference between the losses computed on the full set and a training set
  - Generalization Bound
    - Theoretical upper bound of the generalization error
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## Transductive PAC-Bayesian Generalization Bounds

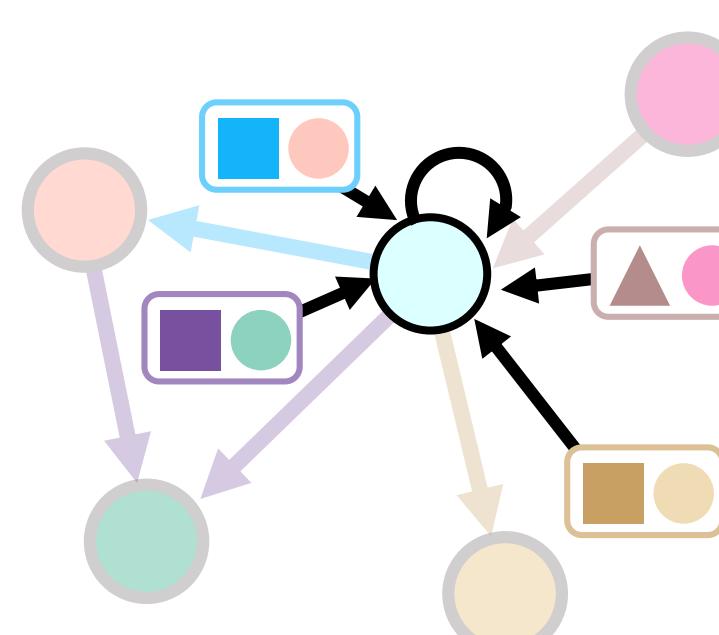
- Probably Approximately Correct (PAC) Theory
  - Fundamental tools for analyzing the generalization bounds
- PAC-Bayesian Generalization Bounds
  - Based on the difference between the prior and posterior distributions
- Transductive PAC-Bayesian Generalization Bounds
  - Training triplets are sampled without replacement from the finite full set

## Relation-aware Encoder-Decoder Framework (ReED)

### Relation-Aware Message Passing Encoder (RAMP Encoder)

- Aggregating representations of the neighboring entities and relations

$$\begin{aligned} \mathbf{M}_r^{(l)}[v, :] &= [\mathbf{H}^{(l-1)}[v, :] \quad \mathbf{R}^{(l-1)}[r, :]] \quad v \in \mathcal{V}, r \in \mathcal{R} \\ \mathbf{H}^{(l)} &= \phi \left( \mathbf{H}^{(l-1)} \mathbf{W}_0^{(l)} + \rho \left( \sum_{r \in \mathcal{R}} S_r^{(l)} \psi(\mathbf{M}_r^{(l)}) \left[ \mathbf{W}_r^{(l)} \right] \right) \right) \\ \mathbf{R}^{(l)} &= \mathbf{R}^{(l-1)} \mathbf{U}_0^{(l)} \end{aligned}$$



### Triplet Classification Decoder

- Using the entity and relation representations, compute scores of triplets
- Translational Distance Decoder (TD decoder)
  - Distance between  $h$  and  $t$  after a relation-specific translation is carried out

$$f_w(h, r, t)[j] = - \left\| \mathbf{H}^{(L)}[h, :] \bar{\mathbf{W}}_r^{(j)} + \mathbf{R}^{(L)}[r, :] \bar{\mathbf{U}}_r^{(j)} - \mathbf{H}^{(L)}[t, :] \mathbf{V}_r^{(j)} \right\|_2$$

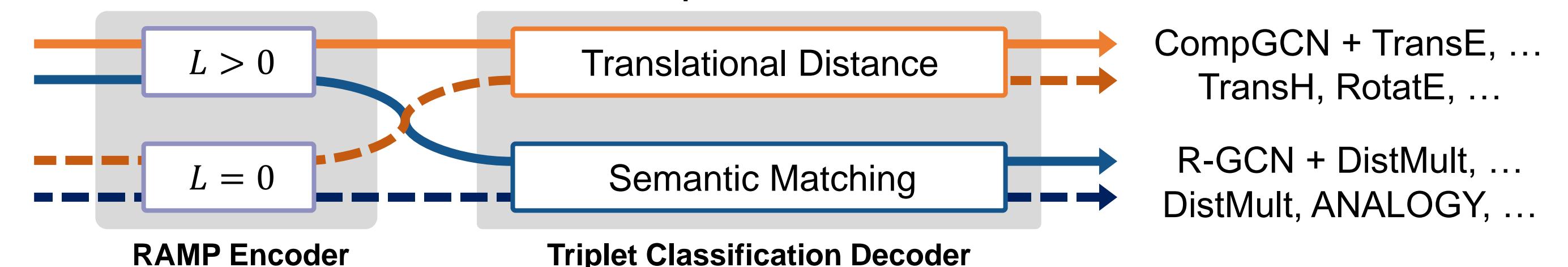
### Semantic Matching Decoder (SM decoder)

- Similarity between the individual components of the triplet

$$f_w(h, r, t)[j] = \mathbf{H}^{(L)}[h, :] \bar{\mathbf{U}}_r^{(j)} (\mathbf{H}^{(L)}[t, :])^\top$$

## Instantiations of ReED

- ReED can express various KGRL methods using different combinations of the RAMP encoder and the triplet classification decoder



## Empirical and Expected Losses of a Triplet Classifier

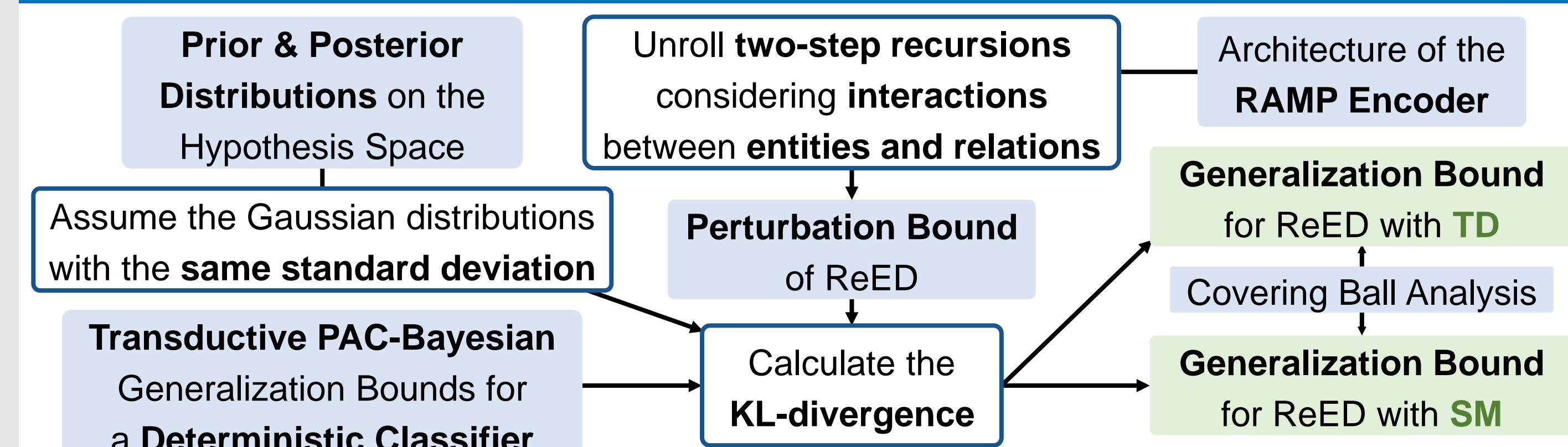
- Empirical Loss of Triplet Classifier  $f_w$ : Measured on a training triplet set  $\hat{\mathcal{E}}$

$$\mathcal{L}_{\gamma, \hat{\mathcal{E}}}(f_w) = \frac{1}{|\hat{\mathcal{E}}|} \sum_{(h, r, t) \in \hat{\mathcal{E}}} \mathbf{1}[f_w(h, r, t)[y_{hrt}] \leq \gamma + f_w(h, r, t)[1 - y_{hrt}]]$$

- Expected Loss of Triplet Classifier  $f_w$ : Measured on the full triplet set  $\mathcal{E}$

$$\mathcal{L}_{0, \mathcal{E}}(f_w) = \frac{1}{|\mathcal{E}|} \sum_{(h, r, t) \in \mathcal{E}} \mathbf{1}[f_w(h, r, t)[y_{hrt}] \leq f_w(h, r, t)[1 - y_{hrt}]]$$

## Generalization Bounds for ReED: Proof Sketch



## PAC-Bayesian Generalization Bounds for ReED

- The generalization bounds for ReED with the TD decoder and SM decoder

**Theorem 4.4 & 4.5** For any  $L \geq 0$ , let  $f_w: \mathcal{V} \times \mathcal{R} \times \mathcal{V} \rightarrow \mathbb{R}^2$  be a triplet classifier designed by the combination of the RAMP encoder with  $L$ -layers and the triplet classification decoder. Let  $k_r$  be the maximum of the infinity norms for all possible  $S_r^{(l)}$  in the RAMP encoder. Then, for any  $\delta, \gamma > 0$ , with probability at least  $1 - \delta$  over a training triplet set  $\hat{\mathcal{E}}$ , for any  $w$ , we have

$$\mathcal{L}_{0, \hat{\mathcal{E}}}(f_w) \leq \mathcal{L}_{\gamma, \hat{\mathcal{E}}}(f_w) + \begin{cases} \mathcal{O}\left(\sqrt{\left(\frac{1}{|\hat{\mathcal{E}}|} - \frac{1}{|\mathcal{E}|}\right)} \left[ N_w L^2 \zeta_L^2 s^{2L} d \ln(N_w d) + \ln \frac{\theta(|\hat{\mathcal{E}}|, |\mathcal{E}|)}{\delta}\right]\right) & (\text{TD}) \\ \mathcal{O}\left(\sqrt{\left(\frac{1}{|\hat{\mathcal{E}}|} - \frac{1}{|\mathcal{E}|}\right)} \left[ N_w L^2 \eta_L^4 s^{4L} d \ln(N_w d) + \ln \frac{\theta(|\hat{\mathcal{E}}|, |\mathcal{E}|)}{\delta}\right]\right) & (\text{SM}) \end{cases}$$

where  $\theta(|\hat{\mathcal{E}}|, |\mathcal{E}|) = 3\sqrt{|\hat{\mathcal{E}}|(1 - \frac{|\hat{\mathcal{E}}|}{|\mathcal{E}|}) \ln |\hat{\mathcal{E}}|}$ ,  $\zeta_L = 2\tau^L \|X_{\text{ent}}\|_2 + 2\kappa \|X_{\text{ent}}\|_2 (\sum_{i=0}^{L-1} \tau^i) + \|X_{\text{rel}}\|_2$ ,  $\eta_L = \tau^L \|X_{\text{ent}}\|_2 + \kappa \|X_{\text{rel}}\|_2 (\sum_{i=0}^{L-1} \tau^i)$ ,  $\tau = C_\phi + \kappa$ ,  $\kappa = C_\phi C_p C_\psi \sum_{r \in \mathcal{R}} k_r$ ,  $N_w$  is the total number of learnable matrices,  $d$  is the maximum dimension, and  $s$  is the maximum Frobenius norm of the learnable matrices

## Generalization Bounds for ReED: a Simplified Form

- Leaving model-dependent terms and regarding the rest as a constant

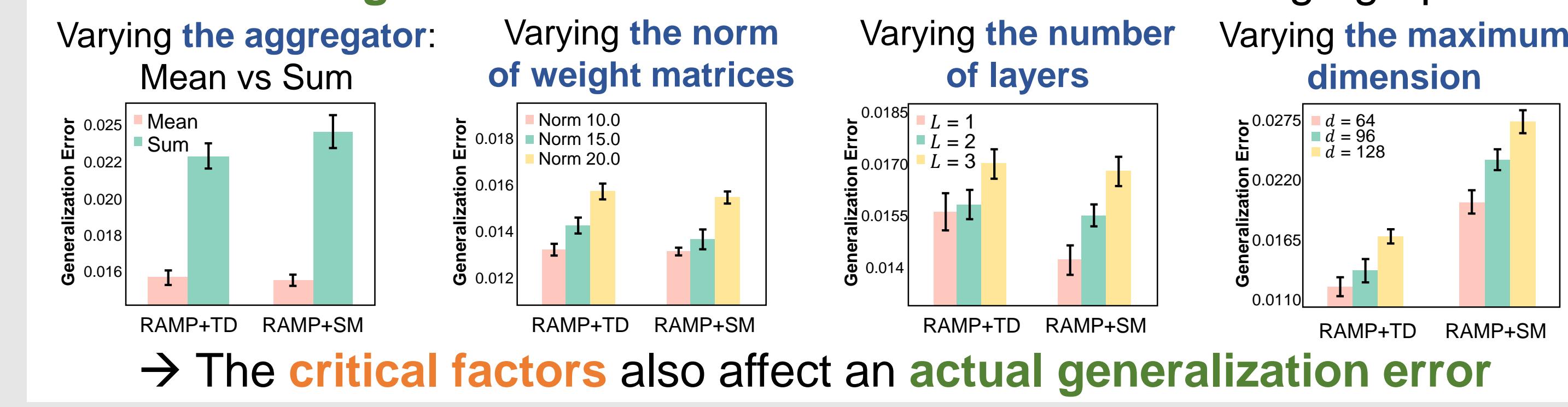
$$\mathcal{L}_{0, \hat{\mathcal{E}}}(f_w) \leq \mathcal{L}_{\gamma, \hat{\mathcal{E}}}(f_w) + \begin{cases} \mathcal{O}(L(\sum_{r \in \mathcal{R}} k_r)^L s^L \sqrt{N_w \ln N_w}) & (\text{TD}) \\ \mathcal{O}(L(\sum_{r \in \mathcal{R}} k_r)^{2L} s^{2L} \sqrt{N_w \ln N_w}) & (\text{SM}) \end{cases}$$

- Practical implications that can guide the desirable designs of KGRL

- $k_r$ : Maximum of the infinity norms for all possible  $S_r^{(l)}$
- A mean aggregator can be a better option than a sum aggregator
- $N_w$ : Total number of learnable matrices ( $= \mathcal{O}(|\mathcal{R}|L)$ )
  - Parameter-sharing strategies & basis/block decomposition ideas
- $s$ : Maximum Frobenius norm of the learnable matrices
  - Weight normalization & Normalization of entity representations

## Experimental Results

- Measure the generalization errors on real-world knowledge graphs



## Conclusion

- A novel ReED framework expressing at least 15 KGRL methods
- The first PAC-Bayesian generalization bounds for ReED with two different types of decoders: TD decoder and SM decoder
- Provide theoretical grounds for commonly used tricks in KGRL
- Empirically show the relationship between the critical factors in the theoretical bounds and the actual generalization errors