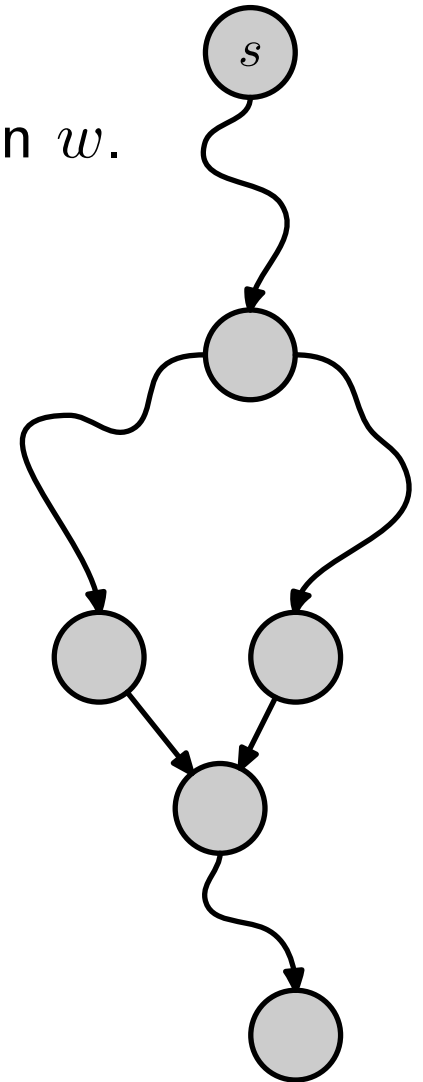


# Shortest paths

$G = (V, E)$  — a directed graph with weight function  $w$ .

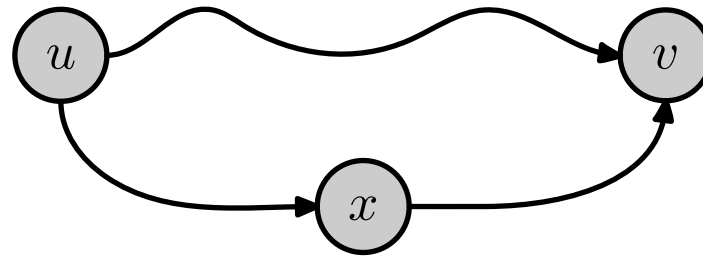
- $s$  is the *source* vertex.
- $w(u, v)$  is the weight of edge  $u \rightarrow v$ ,  $w(u, v) \geq 0$ .
- $\delta(u, v)$  is the weight of *shortest path*  $u \rightsquigarrow v$ .
- $d[v]$  is a shortest-path *estimate* from  $s$  to  $v$ .

Note that  $d[v] \geq \delta(s, v)$  for all  $v \in V$ .



# Triangle inequality

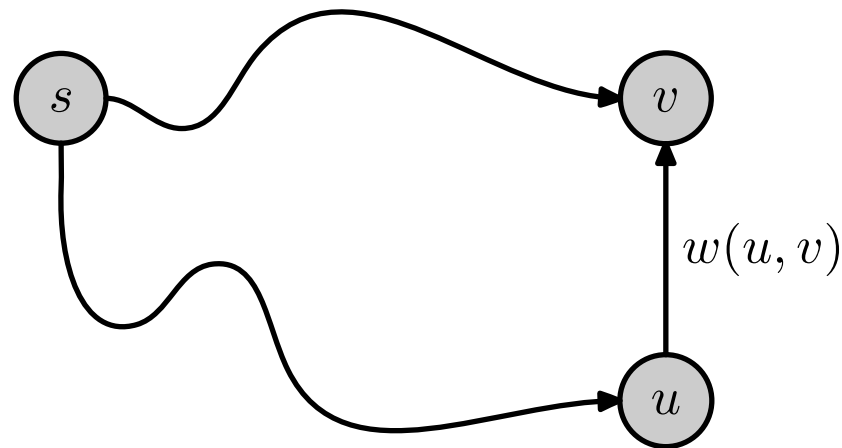
$$\delta(u, v) \leq \delta(u, x) + \delta(x, v)$$



## Relaxation: is it shorter to go via $u$ ?

RELAX( $u, v, w$ )

1.     **if**  $d[v] > d[u] + w(u, v)$
2.         **then**  $d[v] \leftarrow d[u] + w(u, v)$



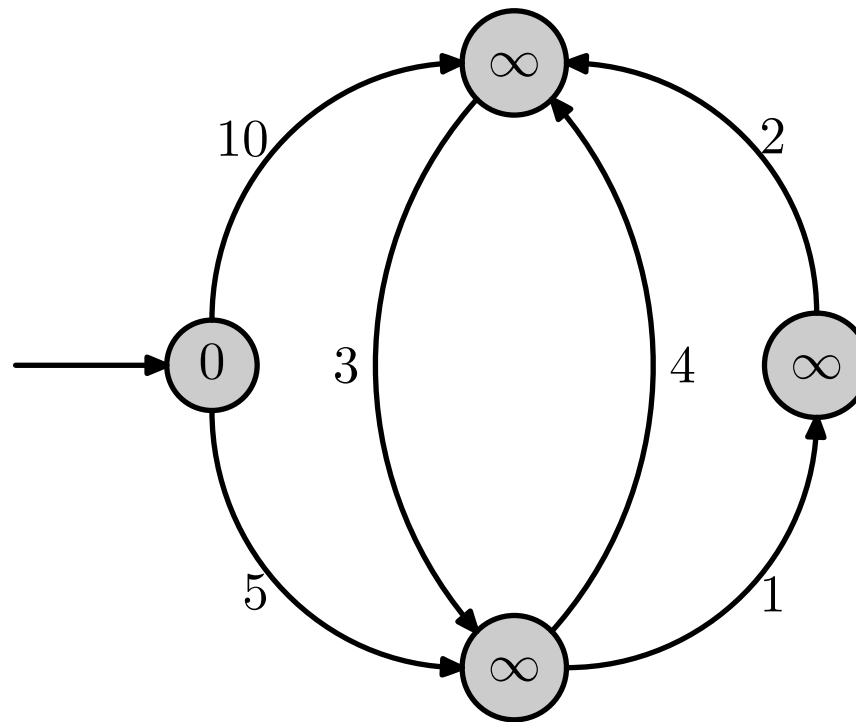
# Dijkstra's algorithm

DIJKSTRA( $G, w, s$ )

1.     **for** each  $v \in V$
2.         **do**  $d[v] \leftarrow \infty$
3.      $d[s] \leftarrow 0$
4.      $S \leftarrow \emptyset$
5.      $Q \leftarrow V$
6.     **while**  $Q \neq \emptyset$
7.         **do**  $u \leftarrow \text{EXTRACT-MIN}(Q)$
8.          $S \leftarrow S \cup \{u\}$
9.         **for** each  $v \in \text{Adj}[u]$
10.             **do** RELAX( $u, v, w$ )

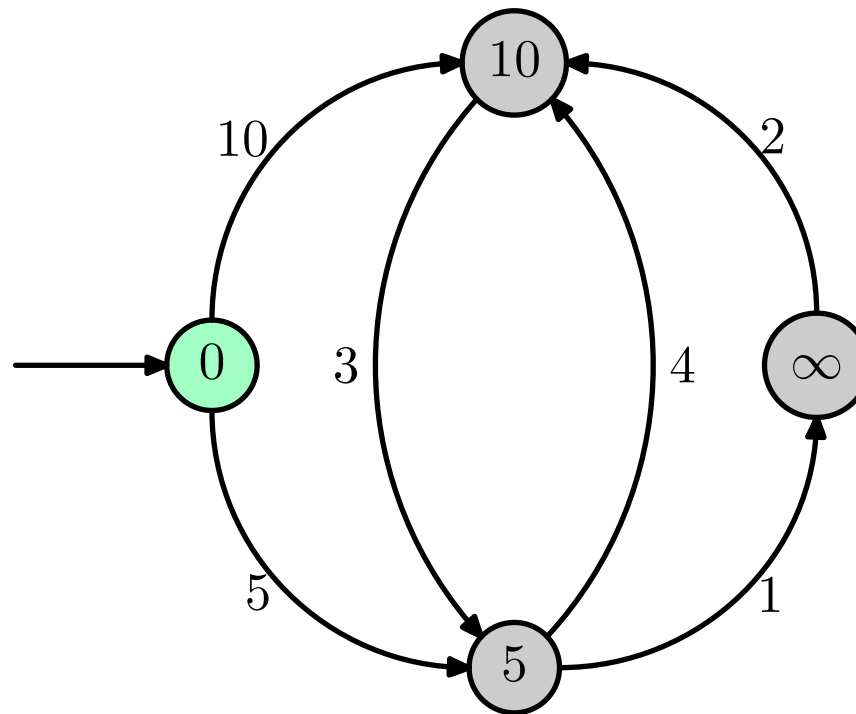
**Observe:** setting  $d[v]$  (line 10) updates  $Q$  (DECREASE-KEY)

## After initialization



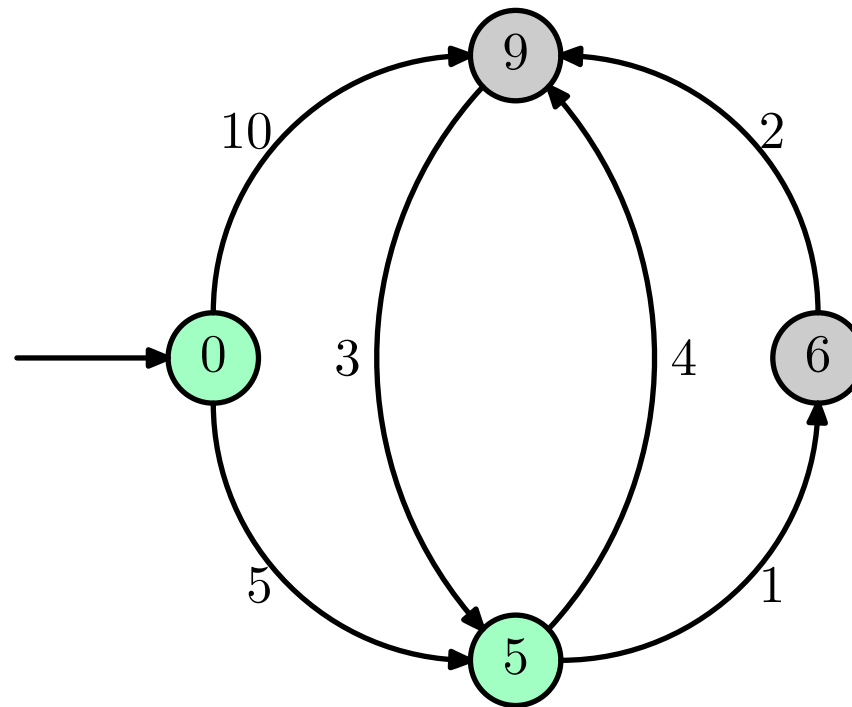
Note:  $d[\cdot]$  is shown within each vertex.

# First iteration



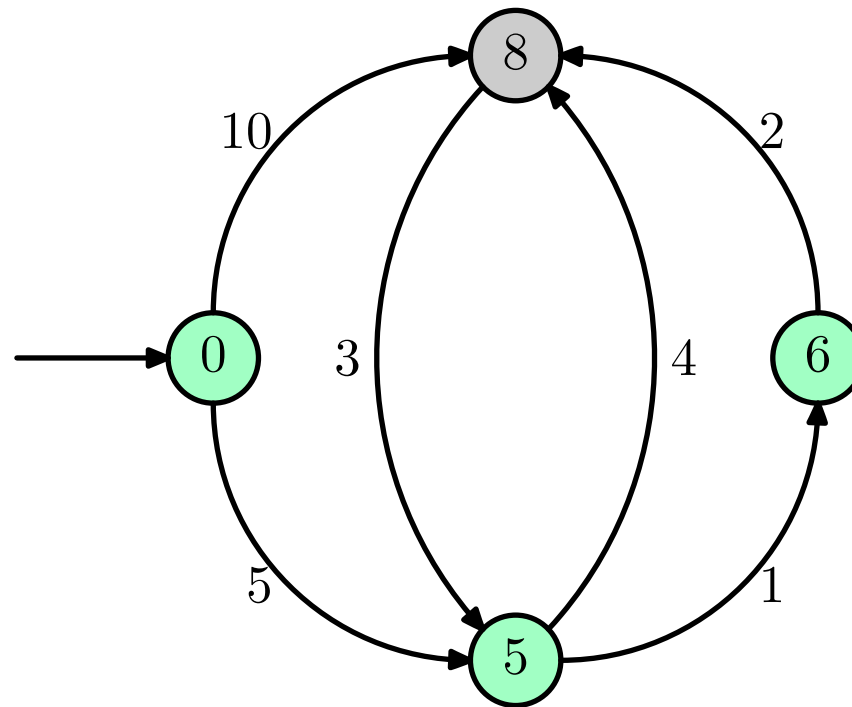
Note:  $d[\cdot]$  is shown within each vertex.

## Second iteration



Note:  $d[\cdot]$  is shown within each vertex.

## Third iteration



Note:  $d[\cdot]$  is shown within each vertex.



# Why does Dijkstra's algorithm work?

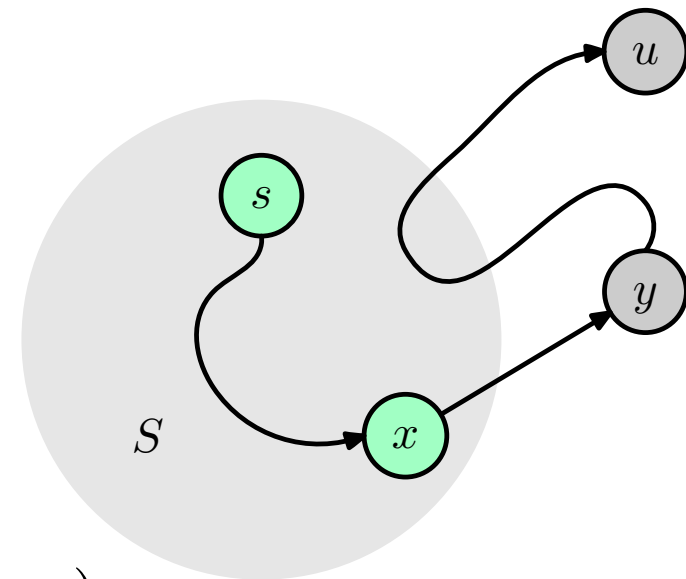
Show that whenever  $u$  is added to  $S$ ,  $d[u] = \delta(s, u)$ .

**Proof.** Assume by contradiction that  $u$  is the first vertex added to  $S$ , where  $d[u] \neq \delta(s, u)$ .

Consider the shortest path from  $s$  to  $u$ . It may walk in and out of  $S$ , or it may not. Either way, its cost is  $\delta(s, u)$ .

Let  $y$  be the *first* vertex outside  $S$  along that shortest path.

**Claim.** When  $x$  was added to  $S$ ,  $d[y] = \delta(s, y)$ .



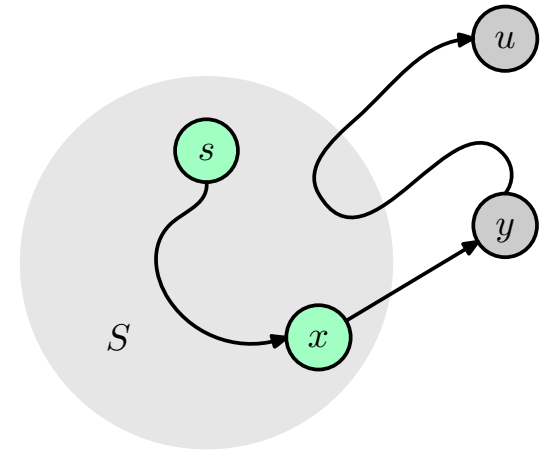
**Claim.** When  $x$  was added to  $S$ ,  $d[y] = \delta(s, y)$ .

Why? Because:

- RELAX( $x, y$ ) compared  $d[y]$  to  $d[x] + w(x, y)$ .

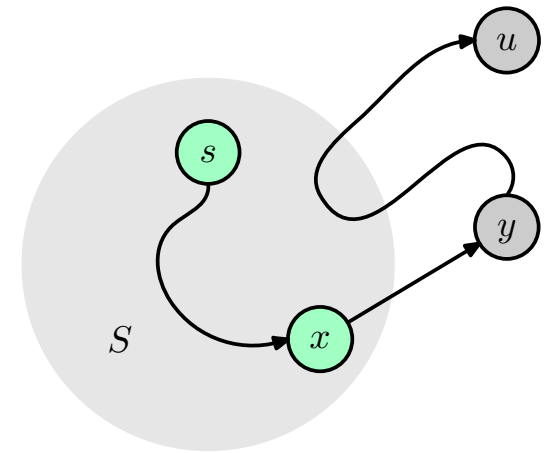
And  $d[x] = \delta(s, x)$  holds because  $u$  was the *first* vertex with  $d[u] \neq \delta(s, u)$ .

- The path to  $y$  uses only vertices in  $S$ .
- We don't have to compare  $d[y]$  to  $d[z] + w(z, y)$  for all other  $z \in S$  because that happened before, when those  $z$ 's were added.



Now, if  $d[y] = \delta(s, y)$  then

$$\begin{aligned} d[u] &> \delta(s, u) \\ &= \delta(s, y) + \delta(y, u) \quad \triangleright y \text{ on shortest path} \\ &= d[y] + \delta(y, u) > d[y] \end{aligned}$$



But if  $d[u] > d[y]$ , the algorithm would have chosen  $y$  next, not  $u$ .

Thus, we have derived a contradiction.  $\square$