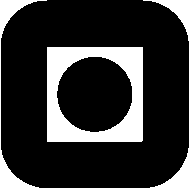
**NTNU Faculty of Information Technology,**

**Norwegian University of Mathematics and Electrical Engineering**

**Science and Technology Department of Engineering Cybernetics**



**MSC THESIS DESCRIPTION SHEET**

**Name:**

**Department:** Engineering Cybernetics

**Thesis title:** Autonomous landing of Fixed-Wing UAV in a stationary net  
- Path and Navigation system

**Thesis Description:**

**Start date:** 2016-01-11

**Due date:** 2016-06-20

**Thesis performed at:** Department of Engineering Cybernetics, NTNU

**Supervisor:** Professor Tor Arne Johansen, Dept. of Eng. Cybernetics, NTNU

**Co-Supervisor:** Professor Thor Inge Fossen, Dept. of Eng. Cybernetics, NTNU