# Computer Vision

CVI620

Session 2

#### cameras



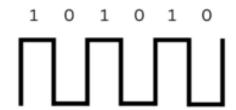
#### Digital vs Analog

- Continuous signals
- Infinite values in a range

- Discrete signals
- Finite values (0s and 1s)



#### Digital



### Digital Images



Everything is signal



A representation of visual information stored digitally.



Humans are sensitive to light at wavelengths between 400 nm and 700 nm and hence most camera image sensors are



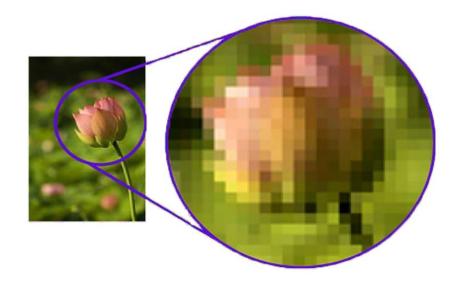
designed to be sensitive at those wavelengths.



Composed of pixels (picture elements).

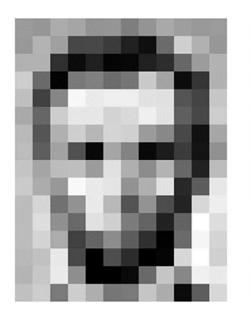
#### Pixels

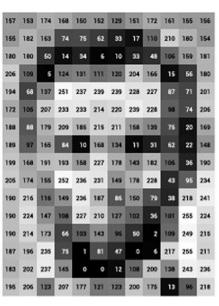
- Smallest unit of a digital image.
- Represents color or intensity information.
- Images are made of a grid of pixels.
- Higher resolution = more pixels = better detail.
- Pixels are typically organized in a 2D array (image matrix), with rows and columns corresponding to their position in the image.
- Size of the picture is the number of pixels in rows and columns (width\*height)
- Resolution is number of pixels

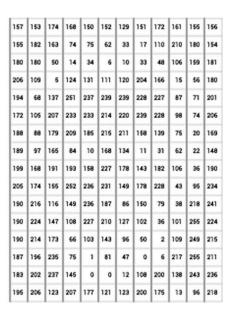


#### Pixel Values

#### Each pixel can have a value between 0 to 255 Reduced processing costs

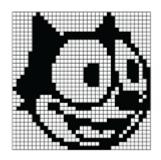




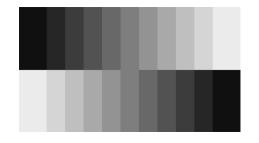




#### Color Models



Binary: 0 or 1 - black or white



Grayscale: 0 (black) to 255 (white)

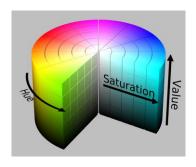


RGB: Combination of Red, Green, Blue (RGB)





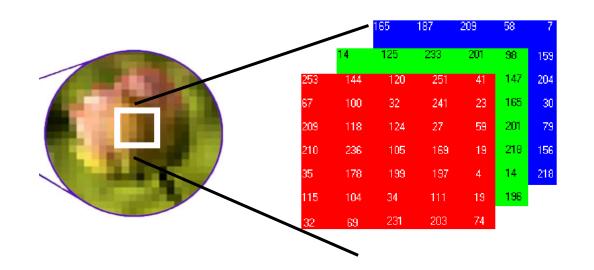
CMYK: Cyan, Magenta, Yellow, and Key (Black)



HSV: Hue, Saturation, Value

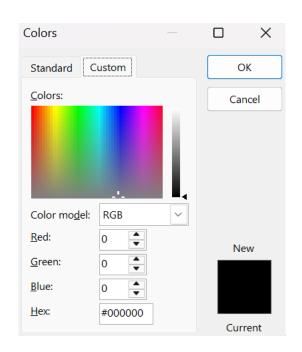
#### Channels

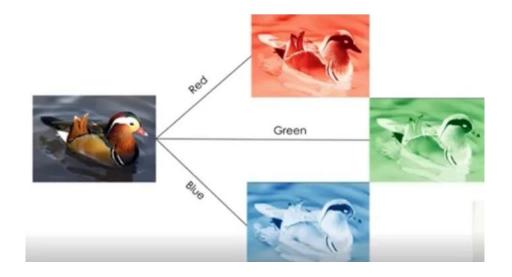
- 3 main pigmentation were introduced to represent color: Red, Green, Blue
- We call each one a channel
- 256\*256\*256 = 2^24 different possible colors

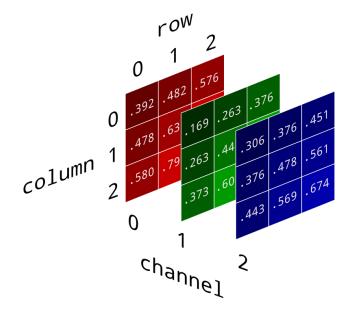




#### Channels





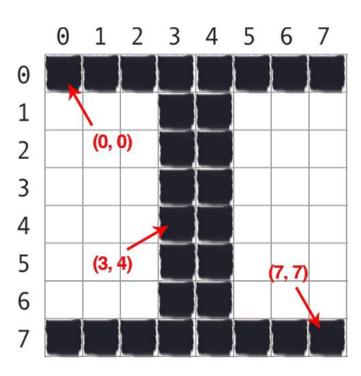


### Binary Image

- 0 or 255
- 255 is represented with a logical 1
- 1 or no channels

1	1	1	1	1	1	1	1	1	1
1	0	0	0	1	1	0	0	0	1
1	1	0	1	1	1	1	0	1	1
1	1	0	1	1	1	1	0	1	1
1	1	0	٦	1	7	1	0	1	1
1	1	0	0	0	0	0	0	1	1
1	1	0	٦	1	٦	1	0	1	1
1	1	0	1	1	1	1	0	1	1
1	1	0	1	1	1	1	0	1	1
1	0	0		1	1	0	0	0	1
1	1	1	1	1	1	1	1	1	1

## Image Coordinates



### Reading Image

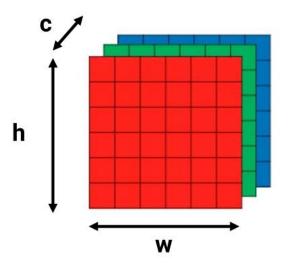
```
import cv2
import numpy as np

image_array = cv2.imread('Lucy.jpg')
print(f"Image shape: {image_array.shape}")
```

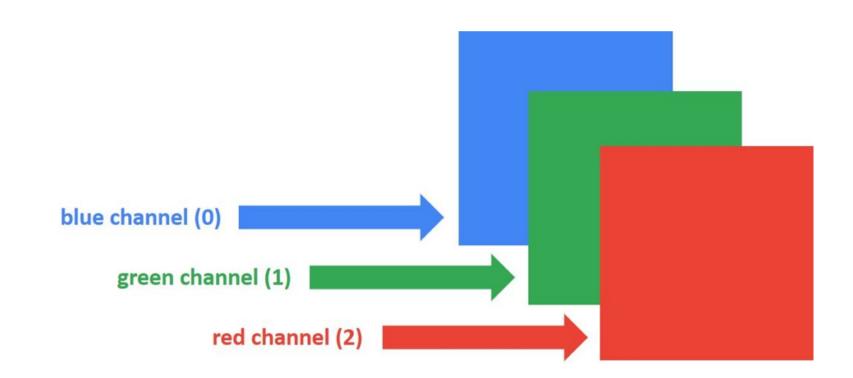
https://opencv24-python-tutorials.readthedocs.io/en/latest/index.html

## Image Shape

h, w, c = img.shape



#### Channel Extraction



### Saving Image

• Store processed images for later use or analysis

```
import cv2
image = cv2.imread("input.jpg")
gray_image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)

cv2.imwrite("output.jpg", gray_image)
```

### Saving Image

- Compresses image to specific format
- Writes compressed image to file

cv2.imwrite(filename, image[, params])

filename: The path and name of the file where the image will be saved.

Example: 'output.jpg'

image: The image array to be saved (e.g., a NumPy array).

params (optional): Format-specific save parameters, such as compression quality for .jpg or .png.

```
import cv2
image = 255 * np.ones((100, 100, 3), dtype=np.uint8)
cv2.imwrite('output.jpg', image)
```

#### Image Formats

- File types that store visual information in various ways.
- For communicating with Hardware. Like a "protocol".
- They determine how images are saved, compressed, and displayed.
- To balance quality and file size for different use cases.
- Specific formats cater to unique needs like transparency, animation, or high-resolution printing
- Optimize images for web, print, or storage purposes
- Storage formats (e.g., BMP, JPEG, PNG) compress and encode pixel data for efficient use.



### Format Examples

#### JPEG (JPG):

- Best for: Photographs and complex images.
- Features: Lossy compression (small size, lower quality at high compression).
- No transparency support.

#### PNG:

- Best for: Graphics, logos, and transparent images.
- Features: Lossless compression and transparency support.

#### TIFF:

- Best for: High-quality printing and professional imaging.
- Features: Lossless or lossy compression, supports layers, and large file sizes.

## Showing Image

```
1 cv2.imshow('img', image_array)
2 cv2.waitKey()
3 # cv2.destroyAllWindows(0)
```

https://opencv24-python-tutorials.readthedocs.io/en/latest/py\_tutorials/py\_gui/py\_image\_display/py\_image\_display.html

### NumPy Arrays

- Core data structure for images in OpenCV.
- Represent images as multi-dimensional arrays:
- Grayscale: 2D (Height x Width)
- Color: 3D (Height x Width x Channels).

```
pixel = image_array[60, 17] # (B, G, R) for color images
image_array[5, 80] = [255, 0, 0] # Set pixel to blue
roi = image_array[50:200, 100:300]
```

## NumPy Coordinates

