

Computer Vision

CVI620

Session 3

Overview

Digital cameras and digital images

Pixels

Channels

Color models

Reading images

Image attributes

Saving images

Showing images

NumPy arrays

```
# reading image
image = cv2.imread("Lucy.jpg")
print(f"image array is: {image}")

# showing image
cv2.imshow("cat", image)
cv2.waitKey(0)
cv2.destroyAllWindows()

# saving image
cv2.imwrite("lucy_green.jpg", image)

# shape of the image
print(f"image shape is: {image.shape}")
```

Agenda

Introduction to matplotlib

Min and Max

ROI

Slicing

Cropping

Split and Merge

Padding

Drawing shapes

Min and Max



Dynamic Range Adjustment: Normalizing pixel intensity for consistent brightness and contrast



Thresholding: Setting thresholds for binary segmentation or feature detection.



Error Detection: Identifying overexposed (max) or underexposed (min) areas in images.



Feature Extraction: Detecting edges or regions based on intensity differences.



Quality Control: Ensuring uniform intensity distribution in medical or industrial imaging.

Finding Max Pixel Value

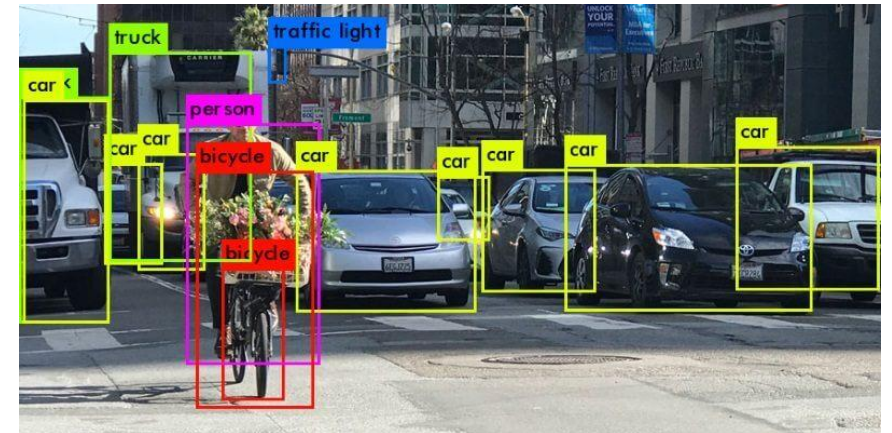
```
import cv2
img = cv2.imread("sample.png")
rows, cols, ncolor = img.shape
red = 2 # index of red values in (b,g,r)
max = 0
for i in range(rows):
    for j in range(cols):
        k = img.item(i, j, red)
        if k > max:
            max = k
print("Maximum red value in image is ", max)
```

Finding Max Red Value

- Find the maximum pixel value in red channel?

Region of Interest (ROI)

- A specific part of an image for focused processing
- Enhance efficiency by processing only the necessary area
- Common in object detection, image cropping, and analysis



Slicing

- Extracting a portion of a NumPy array

```
array[start:stop:step]
```

```
1 import numpy as np
2
3 matrix = np.array([[1, 2, 3], [4, 5, 6], [7, 8, 9]])
4 slice = matrix[0:2, 1:3]
5
```

```
1 import cv2
2 image = cv2.imread("image.jpg")
3 roi = image[50:200, 100:300] #crop
4 cv2.imshow("ROI", roi)
5 cv2.waitKey(0)
6
```

Cropping







```
cropped = img[411:1560, 1700:3000]
```



Exercise

- Copy an ROI from your image, and paste it in another region

Split and Merge

-  Color Channel Processing: Isolating specific channels for analysis or filtering (enhancing the red channel in an image)
-  Grayscale Conversion: Extracting a single channel to create a custom grayscale image
-  Channel-Based Feature Extraction: Using specific channels to detect features like edges or color patterns
-  Custom Image Composition: Replacing or modifying one channel and merging back to create new images.
-  Color Space Conversion: Manipulating individual channels in spaces like HSV, YUV, etc.
-  Image Masking: Applying operations to specific channels and merging them back for the final result.

```
# Split into 3 channels
b,g,r = cv2.split(img)
# Merge 3 channels into one image
img = cv2.merge((b,g,r))
```

Padding

Preserve Dimensions: Maintain spatial size during convolutions in CNNs

Data Augmentation: Enable cropping, shifting, or rotation without losing content

Standardization: Resize images to uniform dimensions

Object Detection: Keep bounding boxes within image boundaries

Edge Processing: Avoid truncation of features at image borders

Image Alignment: Align images of different sizes for stitching or other operations

Padding

- src: It is the source image
- top: It is the border width in number of pixels in top direction
- bottom: It is the border width in number of pixels in bottom direction
- left: It is the border width in number of pixels in left direction
- right: It is the border width in number of pixels in right direction
- borderType: It depicts what kind of border to be added. It is defined by flags like cv2.BORDER_CONSTANT, cv2.BORDER_REFLECT, etc
- value: It is an optional parameter which depicts color of border if border type is cv2.BORDER_CONSTANT.

```
padded_img = cv2.copyMakeBorder(img, 10, 10, 20, 20, cv2.BORDER_CONSTANT, value=[0, 0, 0])
```

BorderType

`cv2.BORDER_CONSTANT`: It adds a constant colored border. The value should be given as a keyword argument

`cv2.BORDER_REFLECT`: The border will be mirror reflection of the border elements. Suppose, if image contains letters "abcdefg" then output will be "gfedcba|abcdefg|gfedcba".

`cv2.BORDER_REFLECT_101` or `cv2.BORDER_DEFAULT`: It does the same works as reflect

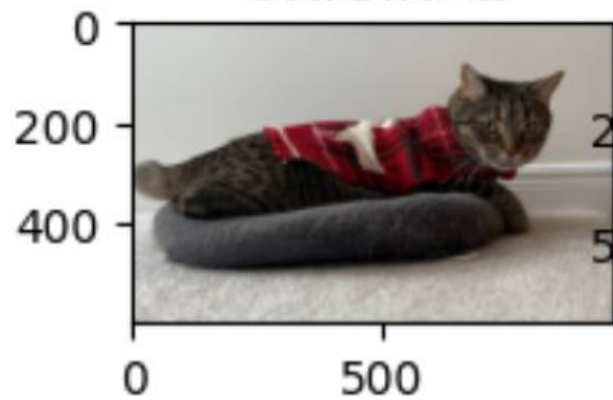
`cv2.BORDER_REFLECT` but with slight change. Suppose, if image contains letters "abcdefgh" then output will be "gfedcb|abcdefgh|gfedcba".

`cv2.BORDER_REPLICATE`: It replicates the last element. Suppose, if image contains letters "abcdefgh" then output will be "aaaaa|abcdefgh|hhhhh".

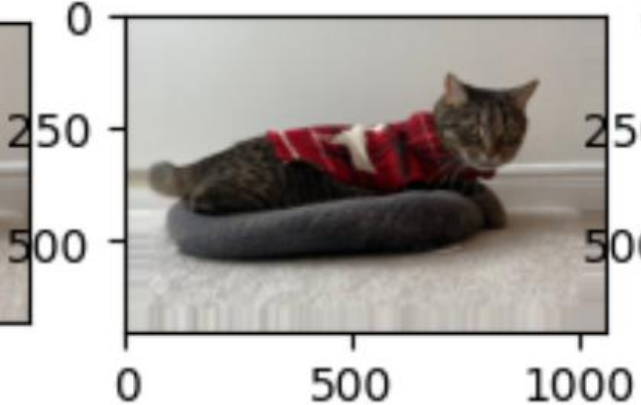
```
import cv2
import matplotlib.pyplot as plt

BLUE = [255,0,0]
bsz = 50
img1 = cv2.imread('Lucy.jpg')
replicate = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REPLICATE)
reflect = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REFLECT)
reflect101 = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REFLECT_101)
wrap = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_WRAP)
constant= cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_CONSTANT,value=BLUE)
plt.subplot(231), plt.imshow(cv2.cvtColor(img1,cv2.COLOR_BGR2RGB)), plt.title('ORIGINAL')
plt.subplot(232), plt.imshow(cv2.cvtColor(replicate,cv2.COLOR_BGR2RGB)), plt.title('REPLICATE')
plt.subplot(233), plt.imshow(cv2.cvtColor(reflect,cv2.COLOR_BGR2RGB)), plt.title('REFLECT')
plt.subplot(234), plt.imshow(cv2.cvtColor(reflect101,cv2.COLOR_BGR2RGB)), plt.title('REFLECT 101')
plt.subplot(235), plt.imshow(cv2.cvtColor(wrap,cv2.COLOR_BGR2RGB)), plt.title('WRAP')
plt.subplot(236), plt.imshow(cv2.cvtColor(constant,cv2.COLOR_BGR2RGB)), plt.title('CONSTANT')
plt.show()
```

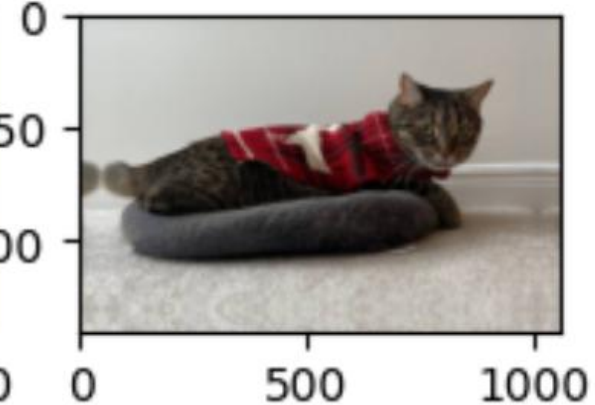

ORIGINAL



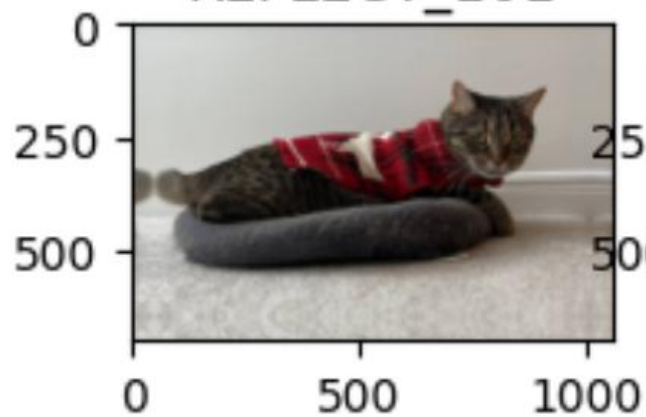
REPLICATE



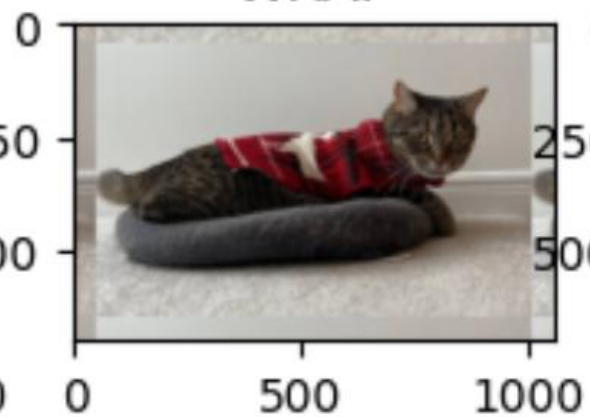
REFLECT



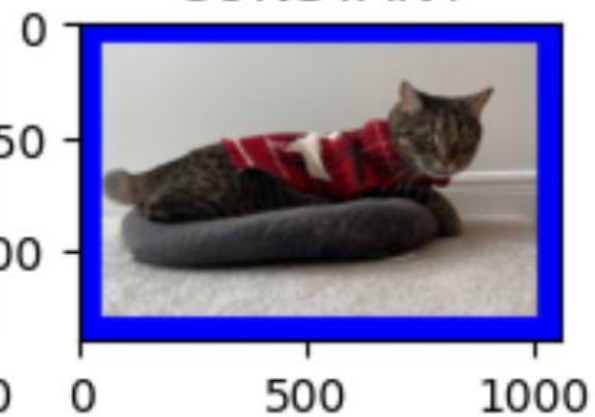
REFLECT_101



WRAP



CONSTANT



Convert Channels

Changing the color format or extracting individual color channels.

```
cv2.cvtColor(image, conversion_code)
```

cv2.COLOR_BGR2GRAY - Convert to grayscale

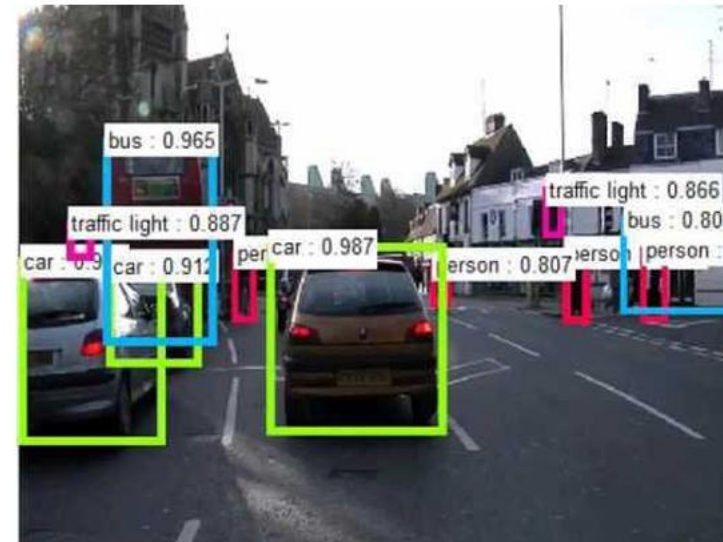
cv2.COLOR_BGR2RGB - Convert to RGB

cv2.COLOR_BGR2HSV - Convert to HSV

```
b, g, r = cv2.split(image) # Blue, Green, Red channels
```

```
merged_image = cv2.merge([b, g, r])
```

Drawing Shapes



Line

- draw a straight line on an image

```
cv2.line(image, pt1, pt2, color, thickness)
```

image: Input image where the line will be drawn

pt1: starting point (x1, y1) (W, H)

pt2: ending point (x2, y2)

color: line color in BGR format (e.g., (255, 0, 0) for blue)

thickness: line thickness (integer)

```
1 import cv2
2 import numpy as np
3
4 #blank image
5 image = np.zeros((400, 400, 3), dtype=np.uint8)
6
7 cv2.line(image, (50, 50), (350, 350), (255, 255, 255), thickness=3)
8
9 cv2.imshow("line example", image)
10 cv2.waitKey(0)
11 cv2.destroyAllWindows()
```

Rectangle

- Draw rectangle on an image

```
cv2.rectangle(image, pt1, pt2, color, thickness)
```

image: Input image where the rectangle will be drawn.

pt1: Top-left corner (x1, y1).

pt2: Bottom-right corner (x2, y2).

color: Rectangle color in BGR format (e.g., (0, 255, 0) for green).

thickness: Border thickness (integer). Use -1 to fill the rectangle.

```
5 image = np.zeros((400, 400, 3), dtype=np.uint8)
6
7 cv2.rectangle(image, (50, 50), (350, 300), (0, 255, 0), thickness=5)
8
9 cv2.imshow("Rectangle Example", image)
10 cv2.waitKey(0)
11 cv2.destroyAllWindows()
```

Circle

- Draw circle

```
cv2.circle(image, center, radius, color, thickness)
```

image: input image where the circle will be drawn

center: center of the circle (x, y)

radius: radius of the circle (integer)

color: circle color in BGR format (e.g., (0, 0, 255) for red)

thickness: circle thickness (integer). Use -1 for a filled circle

```
7 cv2.circle(image, (200, 200), 100, (0, 0, 255), thickness=5)
```

More shapes

- `cv2.line()`
- `cv2.rectangle()`
- `cv2.circle()`
- `cv2.ellipse()`
- `cv2.polylines()`
- `cv2.fillPoly()`
- `cv2.putText()`
- `cv2.arrowedLine()`
- `cv2.drawMarker()`