Computer Vision

CVI620

Session 4

Overview

Matplotlib

Shallow/Deep Copy

Min Max

ROI, Slicing, Cropping

Split, Merge

Image attributes

Day	Date	Agenda/Topic	Reading(s)	Due
Tue	5/6	- Welcome and course overview - Introduction to Computer Vision and Imaging Systems: What is Computer Vision, Applications in real-world systems, etc Roadmap of the field - Human vision and Cameras - Installing prerequisites and system configurations. VSCode, Python, Virtualenv, NumPy, Pandas, OpenCV, matplotlib, ipykernel, Git.	- Install prerequisites and configurations	
Thu	5/8	 - Digital Cameras and Images - Pixels, resolution, image size and shape - Color models: Binary, Grayscale, RGB, HSV, etc. 		
Tue	5/13	 Introduction to NumPy library and arrays Introduction to matplotlib Introduction to OpenCV: reading, displaying, and saving images. Image Formats: PNG, JPEG (JPG), TIFF, etc. Image Coordinates 	Lab 1	May 13
Thu	5/15	 Basic image operations: slicing, crop, split, merge, min & max Basic image operations: rotate, padding, color model conversion Drawing on images PEP8 standard 	Lab 2	May 15

Agenda

Padding

Drawing on images: line, rectangle, circle

Annotations

Video, FPS



Padding

Preserve Dimensions: Maintain spatial size during convolutions in CNNs

Data Augmentation: Enable cropping, shifting, or rotation without losing content

Standardization: Resize images to uniform dimensions

Object Detection: Keep bounding boxes within image boundaries

Edge Processing: Avoid truncation of features at image borders

Image Alignment: Align images of different sizes for stitching or other operations

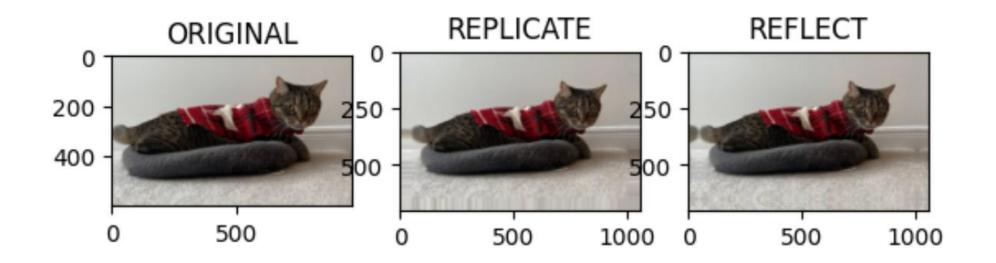
Padding

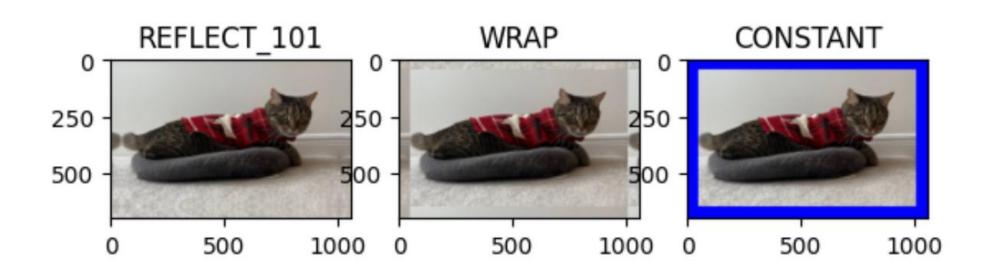
- src: It is the source image
- top: It is the border width in number of pixels in top direction
- bottom: It is the border width in number of pixels in bottom direction
- left: It is the border width in number of pixels in left direction
- right: It is the border width in number of pixels in right direction
- borderType: It depicts what kind of border to be added. It is defined by flags like cv2.BORDER_CONSTANT, cv2.BORDER_REFLECT, etc
- value: It is an optional parameter which depicts color of border if border type is cv2.BORDER_CONSTANT.

BorderType

cv2.BORDER CONSTANT: It adds a constant colored border. The value should be given as a keyword argument cv2.BORDER_REPLICATE: It replicates the last element. Suppose, if image contains letters "abcdefgh" then output will be "aaaaa|abcdefgh|hhhhh". cv2.BORDER REFLECT: The border will be mirror reflection of the border elements not including the border pixel. cv2.BORDER_REFLECT_101 or cv2.BORDER_DEFAULT: It does the same works as reflect but with including the border pixel. cv2.BORDER_WRAP: Wraps around the opposite edge.

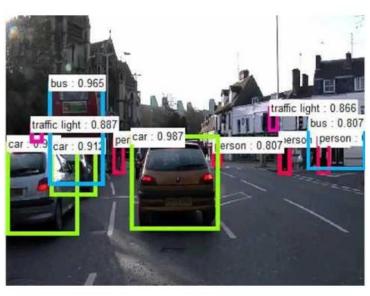
```
import cv2
import matplotlib.pyplot as plt
BLUE = [255,0,0]
bsz = 50
img1 = cv2.imread('Lucy.jpg')
replicate = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REPLICATE)
reflect = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REFLECT)
reflect101 = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REFLECT_101)
wrap = cv2.copyMakeBorder(img1,bsz,bsz,bsz,cv2.BORDER_WRAP)
constant= cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_CONSTANT,value=BLUE)
plt.subplot(231), plt.imshow(cv2.cvtColor(img1,cv2.COLOR_BGR2RGB)), plt.title('ORIGIN
plt.subplot(232), plt.imshow(cv2.cvtColor(replicate,cv2.COLOR_BGR2RGB)), plt.title('
plt.subplot(233), plt.imshow(cv2.cvtColor(reflect,cv2.COLOR_BGR2RGB)), plt.title('REF
plt.subplot(234), plt.imshow(cv2.cvtColor(reflect101,cv2.COLOR_BGR2RGB)), plt.title(
plt.subplot(235), plt.imshow(cv2.cvtColor(wrap,cv2.COLOR_BGR2RGB)), plt.title('WRAP'
plt.subplot(236), plt.imshow(cv2.cvtColor(constant,cv2.COLOR_BGR2RGB)), plt.title('CO
plt.show()
```





Drawing Shapes





Line

draw a straight line on an image

cv2.line(image, pt1, pt2, color, thickness)

- image: Input image where the line will be drawn
- pt1: starting point (x1, y1) (W, H)
- pt2: ending point (x2, y2)
- color: line color in BGR format (e.g., (255, 0, 0) for blue)
- thickness: line thickness (integer)

```
import cv2
import numpy as np

#blank image
image = np.zeros((400, 400, 3), dtype=np.uint8)

cv2.line(image, (50, 50), (350, 350), (255, 255, 255), thickness=3)

cv2.imshow("line example", image)

cv2.waitKey(0)

cv2.destroyAllWindows()
```

Rectangle

• Draw rectangle on an image

cv2.rectangle(image, pt1, pt2, color, thickness)

- image: Input image where the rectangle will be drawn.
- pt1: Top-left corner (x1, y1).
- pt2: Bottom-right corner (x2, y2).
- color: Rectangle color in BGR format (e.g., (0, 255, 0) for green).
- thickness: Border thickness (integer). Use -1 to fill the rectangle.

```
5  image = np.zeros((400, 400, 3), dtype=np.uint8)
6
7  cv2.rectangle(image, (50, 50), (350, 300), (0, 255, 0), thickness=5)
8
9  cv2.imshow("Rectangle Example", image)
10  cv2.waitKey(0)
11  cv2.destroyAllWindows()
```

Circle

• Draw circle

cv2.circle(image, center, radius, color, thickness)

image: input image where the circle will be drawn

center: center of the circle (x, y)

radius: radius of the circle (integer)

color: circle color in BGR format (e.g., (0, 0, 255) for red)

thickness: circle thickness (integer). Use -1 for a filled circle

Text

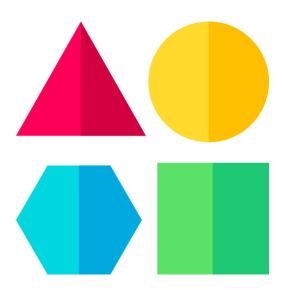
Add text on an image

cv2.putText(image, text, org, font, font_scale, color, thickness, line_type)

- image: Input image where text will be added.
- text: The string to display.
- org: Bottom-left corner of the text (x, y).
- font: Font type (e.g., cv2.FONT_HERSHEY_SIMPLEX).
- font_scale: Scale factor for font size.
- color: Text color in BGR format (e.g., (255, 255, 255) for white).
- thickness: Thickness of the text stroke.
- line_type: Type of line for the text (e.g., cv2.LINE_AA).

More shapes

- cv2.line()
- cv2.rectangle()
- cv2.circle()
- cv2.ellipse()
- cv2.polylines()
- cv2.fillPoly()
- cv2.putText()
- cv2.arrowedLine()
- cv2.drawMarker()



Video

- Videos are sequences of images
- A class to capture video streams from:
 - Webcam
 - Video files (e.g., .mp4, .avi)
 - IP cameras or other sources.
- object being created
- waitKey for speed

```
cap = cv2.VideoCapture(0)

# 0 for the default webcam

# Path to a video file for playback
# 1, 2, ... for external cameras
# IP
```

```
1 ret, frame = cap.read()
2 # ret: Boolean, True if frame is read successfully
3 # frame: Captured image array
4 cap.release()
5 cv2.destroyAllWindows()
```

FPS

```
import cv2
desired fps = 10
video_path = ""
cap = cv2.VideoCapture(video_path)
original_fps = int(cap.get(cv2.CAP_PROP_FPS))
frame_interval = int(original_fps / desired_fps)
frame_count = 0
while True:
   ret, frame = cap.read()
   if not ret:
        break
    # Skip frames to match the desired FPS
   if frame_count % frame_interval == 0:
        cv2.imshow("Frame", frame)
        if cv2.waitKey(1) & 0xFF == ord('q'):
            break
   frame_count += 1
cap.release()
cv2.destroyAllWindows()
```