

Computer Vision

CVI620

Session 5

Overview

Padding

Shapes

Annotation

Video, FPS

Arithmetic Operation (add)

Agenda

Point Operations Cont.

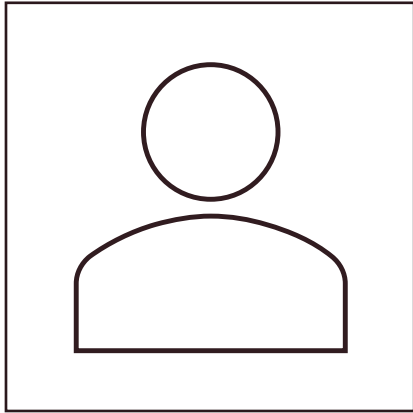
Neighborhood Operations

Upsampling

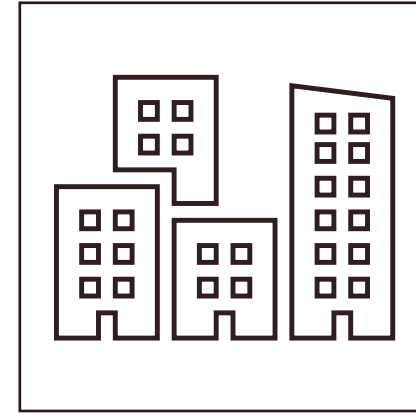
Downsampling



Operations



Point operators



Neighborhood operators

Point Operators

- The value of each pixel in the output depends only on the value of the same pixel in the input (and possibly some global information or some parameters)
- Each pixel is processed independently.
- No influence from neighboring pixels.
- Example:
 - Contrast Adjustment: Stretching or compressing intensity values.
 - Thresholding: Converting grayscale images to binary by setting a threshold.
 - Brightness Adjustment: Adding or subtracting a constant to pixel values.



Addition and Subtraction

- Using arithmetic operations in Numpy does not work when values can go above 255 or lower than 0
- OpenCV's saturated arithmetic ensures that values above 255 are set to 255, and values below 0 are clamped to 0
- Use OpenCV functions instead

```
image = cv2.imread("Lucy.jpg")  
img2 = cv2.add(image, np.ones(image.shape, dtype="uint8") * 50)  
img3 = cv2.subtract(image, np.ones(image.shape, dtype="uint8") * 100)
```

Multiply and Divide

- Make bright colors brighter - use scale > 1

```
img2 = cv2.multiply(image, np.ones(image.shape, dtype="uint8"), scale=1.6)
```

- Make dark colors darker - use scale < 1

```
img2 = cv2.multiply(image, np.ones(image.shape, dtype="uint8"), scale=0.5)
```

Thresholding

- A technique to segment an image by converting it into binary form.
- Separates foreground (object) from background based on intensity values.

```
_, thresholded = cv2.threshold(image, 127, 255, cv2.THRESH_BINARY)
```

- Object detection and segmentation.
- Preprocessing for OCR and feature extraction.

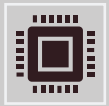
Linear Blend

weighted image addition

Two input images, `img1` and `img2`

- $dst = \alpha \cdot img1 + \beta \cdot img2 + \gamma$
- `img1 = cv2.imread("Trillium.jpg")`
- `img2 = cv2.imread("flower.jpg")`
- `img2 = cv2.resize(img2, (img1.shape[1], img1.shape[0]))`
- `img3 = cv2.addWeighted(img1, 0.6 , img2, 0.4, 0)`

Neighborhood Operators



The value of each pixel in the output depends on the value of the pixel and the value of its neighbors in the input



Example: Smoothing or blurring



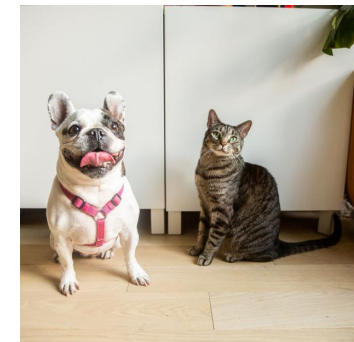
Will continue the discussion in filtering

Resize

- Resizing adjusts the dimensions of an image (width and height) while maintaining its visual content.
- Normalization, Efficiency, Aspect Ratio Preservation

UpScale

DownScale



Resizing Methodology



Either new pixels are created, or some pixels are removed



The key challenge in resizing is determining how to map the pixel values from the original image to the resized image in a way that maintains visual quality.

Interpolation

It is the algorithm of that **matrix operation**

In math: Interpolation means finding a new set of values for a function given a set of prior values for the same function.

In Computer Vision: A techniques to approximate the color and intensity values of pixels in the resized image.

```
cv2.resize(  
    (src: MatLike, dsize: Size | None, dst: MatLike |  
    None = ..., fx: float = ..., fy: float = ...,  
    interpolation: int = ...) -> MatLike  
)
```

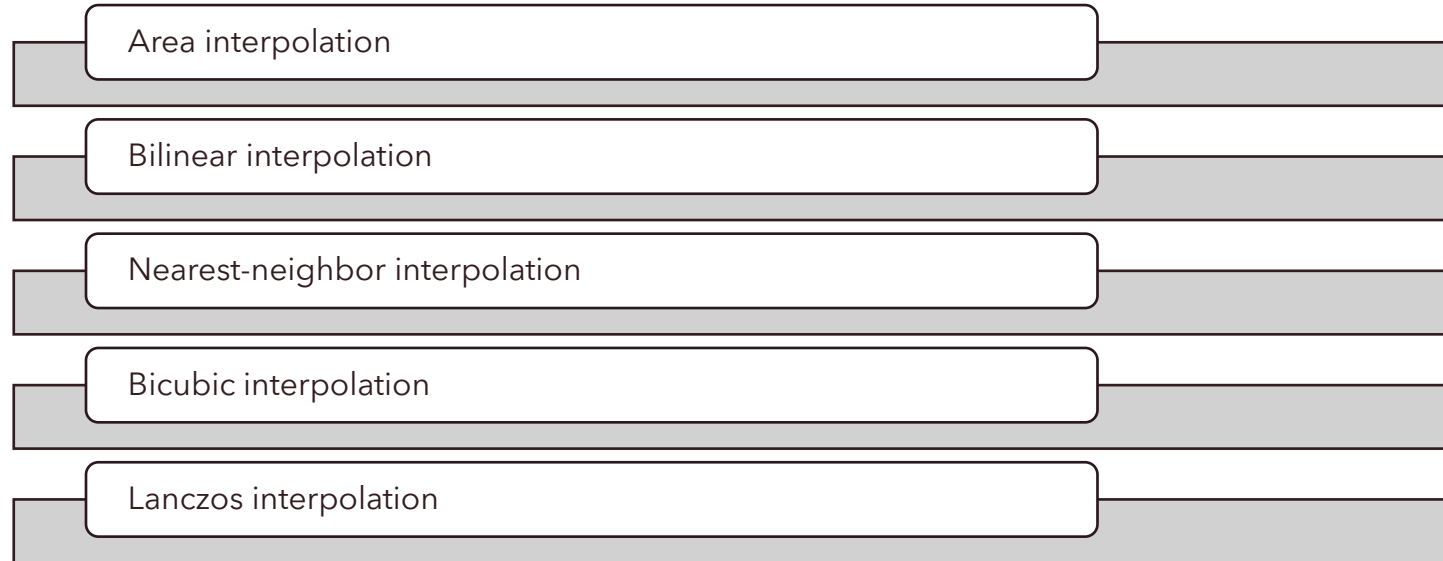
cv2.resize

```
cv2.resize(src, dsize, dst=None, fx=0, fy=0, interpolation=cv2.INTER_LINEAR)
```

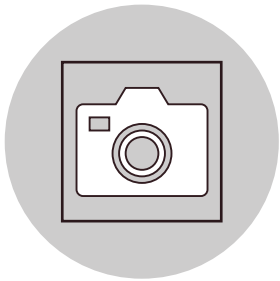
- src: source image to be resized
- dsize: desired size of the destination image – tuple
must be specified if both fx and fy are zero (or not specified). If dsize is set to (0, 0), then fx and fy must be specified to determine the size.
- dst: destination image – usually ignored in Python
- fx, fy: multiplier that scales the width/height of the image
- interpolation: default value is cv2.INTER_LINEAR

Upsampling

Interpolation is used to estimate the color and intensity values of the new pixels based on the existing pixels.



Nearest Neighbor



selects the value of the nearest pixel from the original image and assigns it to the corresponding pixel in the resized image



N is a hyperparameter

Nearest Neighbor

We can apply one of these methods based on **N nearest neighbor**

Averaging

Max
choice

Max

Min

Linear/non-linear function
based on nearest neighbors

(General form of Bilinear
interpolation)

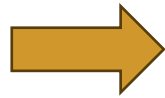
• • •

Nearest Neighbor - Max

Numbers are coordinates
and not pixel values

N=1

	3		
	0,0	0,1	0,2
3	1,0	1,1	1,2
	2,0	2,1	2,2



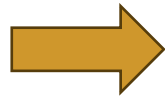
					6
6					

Nearest Neighbor - Max

Numbers are coordinates
and not pixel values

N=1

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



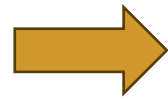
0,0		0,1		0,2	
1,0		1,1		1,2	
2,0		2,1		2,2	

Nearest Neighbor - Max Choice

Numbers are coordinates
and not pixel values

N=1

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



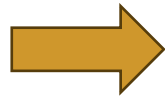
0,0	0,0	0,1		0,2	
0,0	0,0				
1,0		1,1		1,2	
2,0		2,1		2,2	

Nearest Neighbor - Max Choice

Numbers are coordinates
and not pixel values

N=1

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



0,0	0,0	0,1	0,1	0,2	0,2
0,0	0,0	0,1	0,1	0,2	0,2
1,0	1,0	1,1	1,1	1,2	1,2
1,0	1,0	1,1	1,1	1,2	1,2
2,0	2,0	2,0	2,0	2,2	2,2
2,0	2,0	2,0	2,0	2,2	2,2

Nearest Neighbor

Default and only option is N=1

```
import cv2

image = cv2.imread('Lenna.png')
resized_image = cv2.resize(image, (image.shape[1]*3, image.shape[0]*3), interpolation=cv2.INTER_NEAREST)

cv2.imwrite('Lenna_Resized_Image.png', resized_image)
cv2.imshow('Lenna_Resized_Image', resized_image)
cv2.waitKey(0)
cv2.destroyAllWindows()
```



Nearest Neighbor - Averaging

Numbers are coordinates
and not pixel values

N=2

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



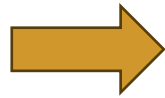
0,0	0,avg(0,1)	0,1		0,2	
1,0		1,1		1,2	
2,0		2,1		2,2	

Nearest Neighbor - Averaging

Numbers are coordinates
and not pixel values

N=2

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



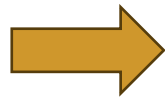
0,0	0,avg(0,1)	0,1	0,avg(1,2)	0,2	0,avg(2,2)
1,0		1,1		1,2	
2,0		2,1		2,2	

Nearest Neighbor - Averaging

Numbers are coordinates
and not pixel values

N=2

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



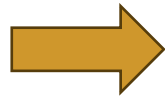
0,0	0,avg(0,1)	0,1	0,avg(1,2)	0,2	0,avg(2,2)
avg(0,1), 0					
1,0		1,1		1,2	
2,0		2,1		2,2	

Nearest Neighbor - Averaging

Numbers are coordinates
and not pixel values

N=2

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



0,0	0,avg(0,1)	0,1	0,avg(1,2)	0,2	0,avg(2,2)
avg(0,1), 0	avg(0,1), avg(0,1)				
1,0		1,1		1,2	
2,0		2,1		2,2	

Nearest Neighbor - Averaging

Numbers are coordinates
and not pixel values

N=2

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



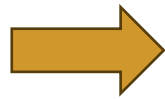
0,0	0,avg(0,1)	0,1	0,avg(1,2)	0,2	0,avg(2,2)
avg(0,1), 0	avg(0,1), avg(0,1)	x			
1,0		1,1		1,2	
2,0		2,1		2,2	

Nearest Neighbor - Averaging

Numbers are coordinates
and not pixel values

N=2

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



0,0	0,avg(0,1)	0,1	0,avg(1,2)	0,2	0,avg(2,2)
avg(0,1), 0	avg(0,1), avg(0,1)	x	x	x	x
1,0	x	1,1	x	1,2	x
x	x	x	x	x	x
2,0	x	2,1	x	2,2	x
x	x	x	x	x	x

Nearest Neighbor - Averaging

Gray-Scale

Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0

$$180 + 255 / 2 = 217.5$$

180	217	255		9	
56		127		255	
0		73		0	

Nearest Neighbor - Averaging

Gray-Scale

Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0

$$255 + 9 / 2 = 132$$

180	217	255	132	9	
56		127		255	
0		73		0	

Nearest Neighbor - Averaging

Gray-Scale

Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0

$$9 + 9 / 2 = 9$$

180	217	255	132	9	9
56		127		255	
0		73		0	

Nearest Neighbor - Averaging

Gray-Scale

Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0

$$180 + 56 / 2 = 118$$

180	217	255	132	9	9
118					
56		127		255	
0		73		0	

Nearest Neighbor - Averaging

Gray-Scale

Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0

$$180 + 56 / 2 = 118$$

180	217	255	132	9	9
118					
56		127		255	
0		73		0	

Nearest Neighbor - Averaging

Gray-Scale
Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0

$$217 + 118 / 2 = 167.5$$

180	217	255	132	9	9
118	167				
56		127		255	
0		73		0	

Nearest Neighbor - Averaging

Gray-Scale

Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0

$$255 + 167 / 2 = 211$$

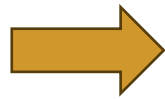
180	217	255	132	9	9
118	167	211			
56		127		255	
0		73		0	

Nearest Neighbor - Averaging

Gray-Scale
Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0



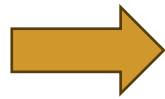
180	217	255	132	9	9
118	167	211	171	90	49
56	111	127	149	255	152
28					
0		73		0	

Nearest Neighbor - Averaging

Gray-Scale
Same concept for colored images

N=2

180	255	9
56	127	255
0	73	0



180	217	255	132	9	9
118	167	211	171	90	49
56	111	127	149	255	152
28	69	98	123	189	170
0	34	73	98	0	85
17	25	49	73	36	60

Area Interpolation

Numbers are coordinates
and not pixel values

Divide and fill

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2

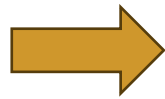


0,0	0,0				
0,0	0,0				

Area Interpolation

Numbers are coordinates
and not pixel values

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2



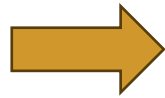
0,0	0,0	0,1	0,1	0,2	0,2
0,0	0,0	0,1	0,1	0,2	0,2
1,0	1,0	1,1	1,1	1,2	1,2
1,0	1,0	1,1	1,1	1,2	1,2
2,0	2,0	2,0	2,0	2,2	2,2
2,0	2,0	2,0	2,0	2,2	2,2

Area Interpolation

Gray-Scale

Same concept for colored images

180	255	9
56	127	255
0	73	0



180	180	255	255	9	9
180	180	255	255	9	9
56	56	127	127	255	255
56	56	127	127	255	255
0	0	73	73	0	0
0	0	73	73	0	0

Area Interpolation

```
import cv2

image = cv2.imread('Lenna.png')
resized_image = cv2.resize(image, (image.shape[0]*3, image.shape[1]*3), interpolation=cv2.INTER_AREA)

cv2.imwrite('Lenna_Resized_Image_Averaging.png', resized_image)
cv2.imshow('Lenna_Resized_Image_Averaging', resized_image)
cv2.waitKey(0)
cv2.destroyAllWindows()
```



Algorithm

- How would you Python code the area interpolation method if you did not have OpenCV?

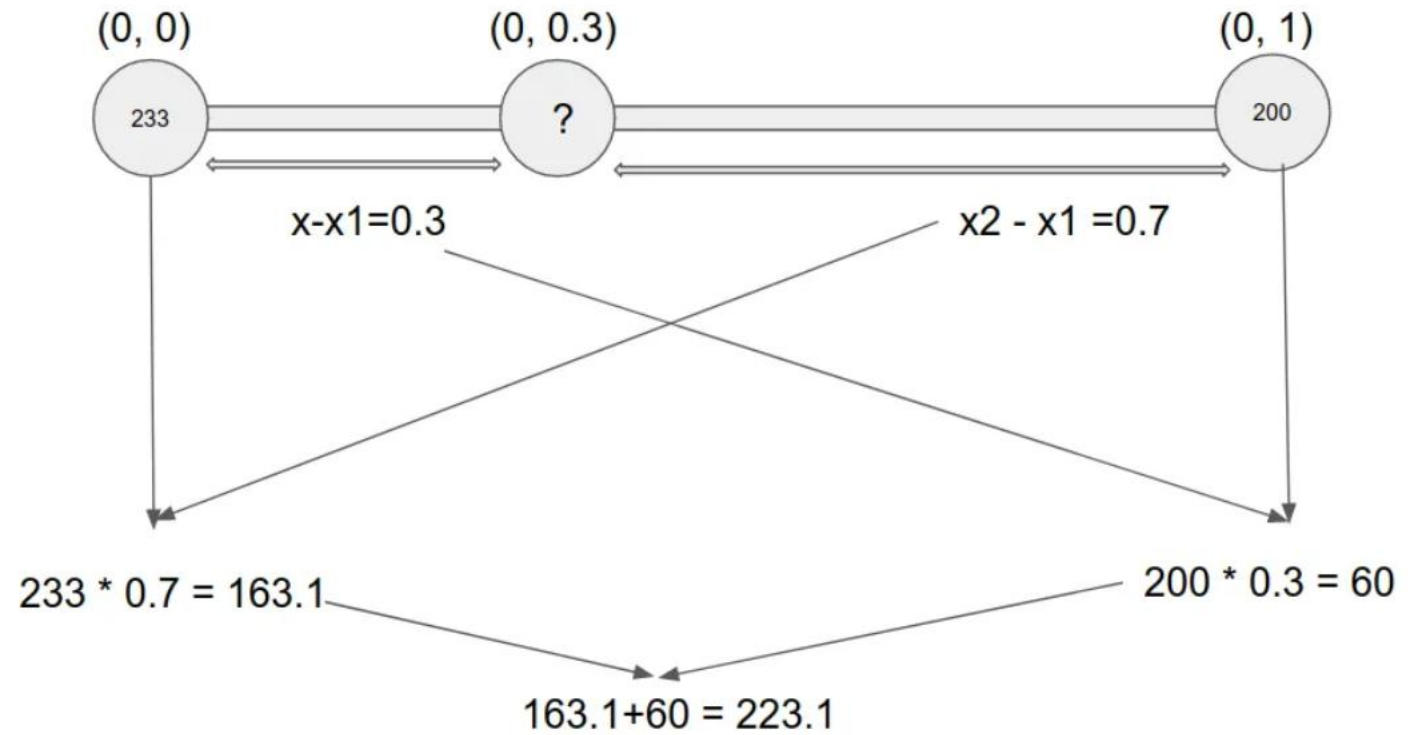
Algorithm

```
half_upsclaed_img[0:height:2, :, :] = resized_img[:, :, :]  
half_upsclaed_img[1:height:2, :, :] = resized_img[:, :, :]  
  
upsclaed_img[:, 0:width:2, :] = half_upsclaed_img[:, :, :]  
upsclaed_img[:, 1:width:2, :] = half_upsclaed_img[:, :, :]
```

Bilinear Interpolation

$$I_{new} = \frac{x_2 - x}{x_2 - x_1} * I_1 + \frac{x - x_1}{x_2 - x_1} * I_2$$

where $x_1 \geq x \geq x_2$

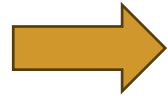


$I_1=233, I_2=200$ and $I_{new}=223.1$

Bilinear Interpolation

Initialization and filling pixels are hyperparameters

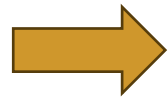
10	20
30	40



10			20
30			40

Bilinear Interpolation

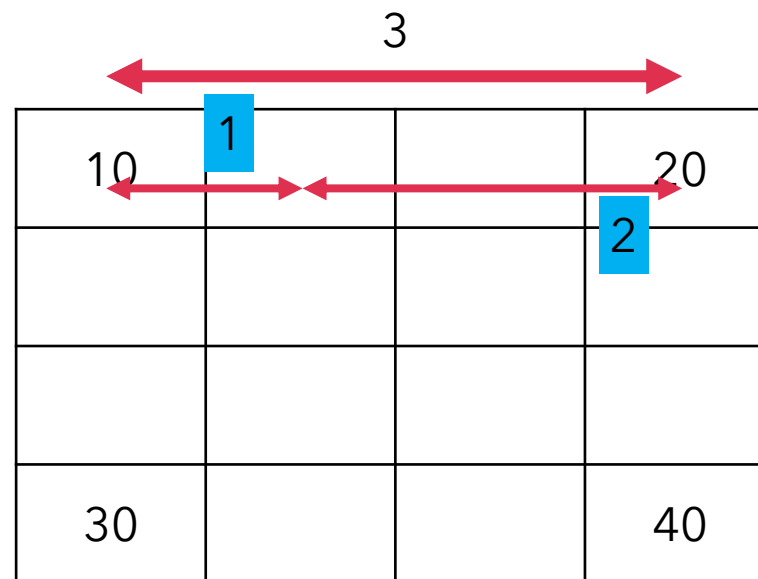
10	20
30	40



	(0,0)	(0,1)	(0,2)	(0,3)
(0,0)	10			20
(0,1)				
(0,2)				
(0,3)	30			40

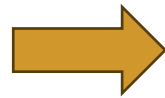
Bilinear Interpolation

10	20
30	40



Bilinear Interpolation

10	20
30	40

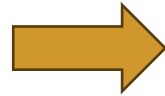


<div>4</div>			
10	affect=2/3	affect=1/3	20
30			40

Bilinear Interpolation

$$\text{round} [(2/3 * 10) + (1/3 * 20)] = \text{round} [(6.6 + 6.6) / 2] = 13$$

10	20
30	40



10	13		20
30			40

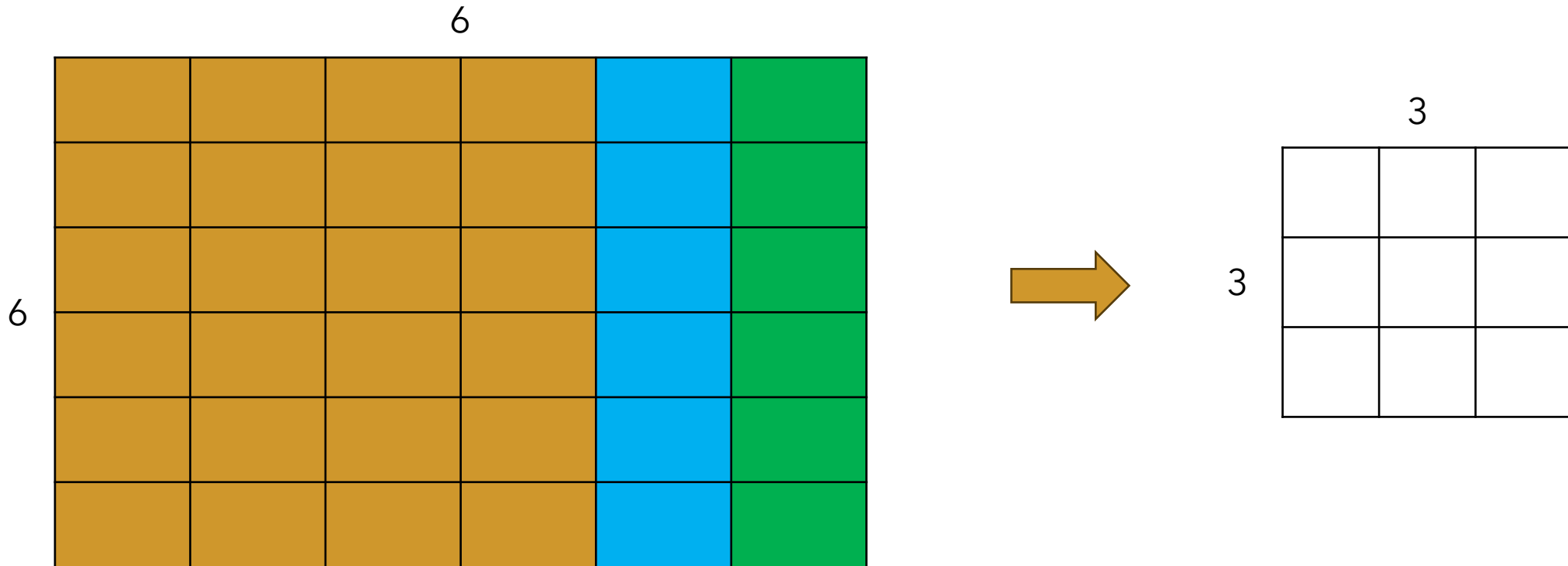
Enumerator	
INTER_NEAREST Python: cv.INTER_NEAREST	nearest neighbor interpolation
INTER_LINEAR Python: cv.INTER_LINEAR	bilinear interpolation
INTER_CUBIC Python: cv.INTER_CUBIC	bicubic interpolation
INTER_AREA Python: cv.INTER_AREA	resampling using pixel area relation. It may be a preferred method for image decimation, as it gives moire'-free results. But when the image is zoomed, it is similar to the INTER_NEAREST method.
INTER_LANCZOS4 Python: cv.INTER_LANCZOS4	Lanczos interpolation over 8x8 neighborhood
INTER_LINEAR_EXACT Python: cv.INTER_LINEAR_EXACT	Bit exact bilinear interpolation
INTER_NEAREST_EXACT Python: cv.INTER_NEAREST_EXACT	Bit exact nearest neighbor interpolation. This will produce same results as the nearest neighbor method in PIL, scikit-image or Matlab.
INTER_MAX Python: cv.INTER_MAX	mask for interpolation codes
WARP_FILL_OUTLIERS Python: cv.WARP_FILL_OUTLIERS	flag, fills all of the destination image pixels. If some of them correspond to outliers in the source image, they are set to zero
WARP_INVERSE_MAP Python: cv.WARP_INVERSE_MAP	flag, inverse transformation For example, linearPolar or logPolar transforms: <ul style="list-style-type: none"> flag is not set: $dst(\rho, \phi) = src(x, y)$ flag is set: $dst(x, y) = src(\rho, \phi)$

Downsampling

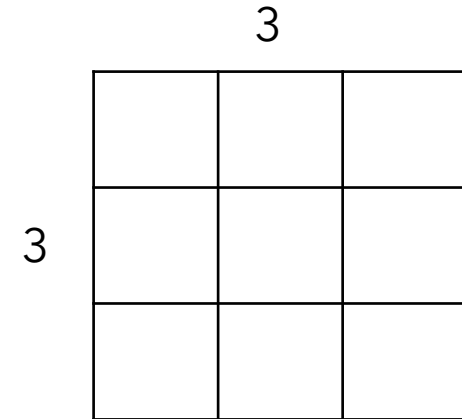
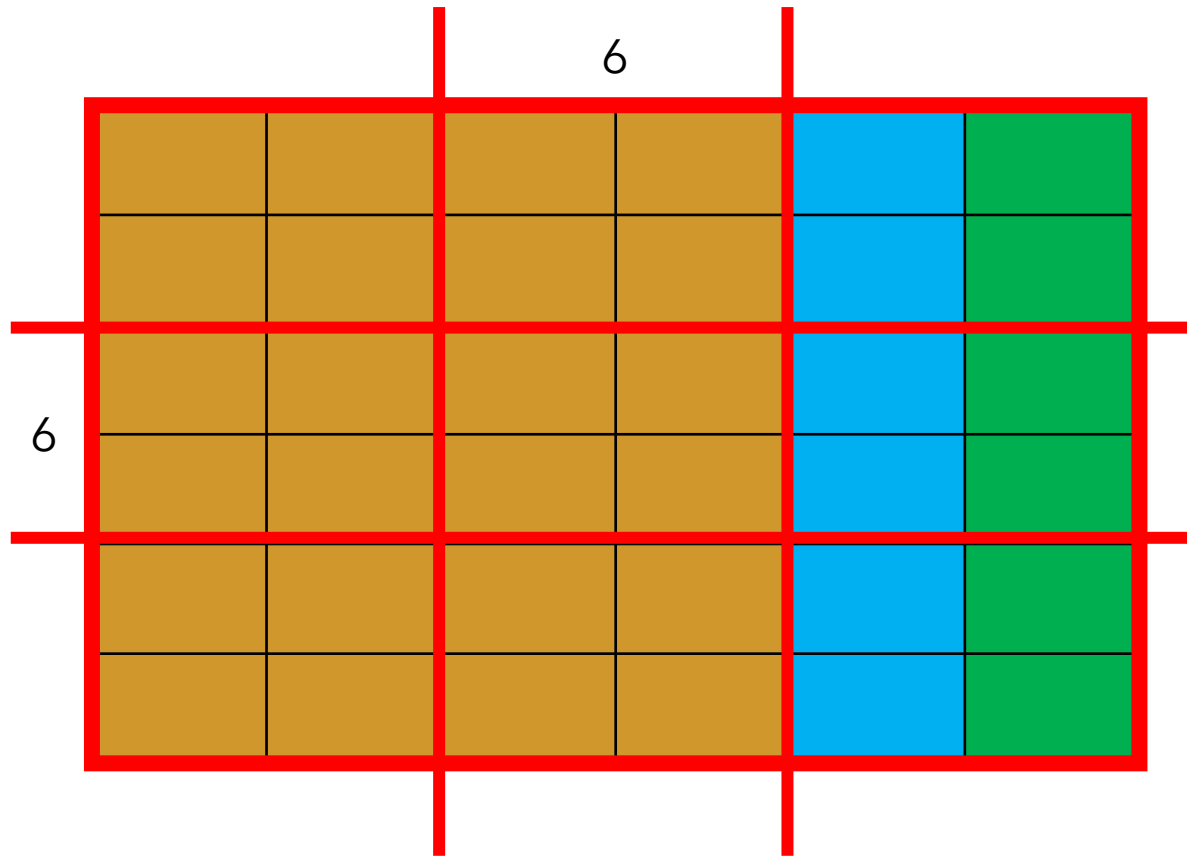
Interpolation is used to estimate the color and intensity values of the new pixels based on the existing pixels.



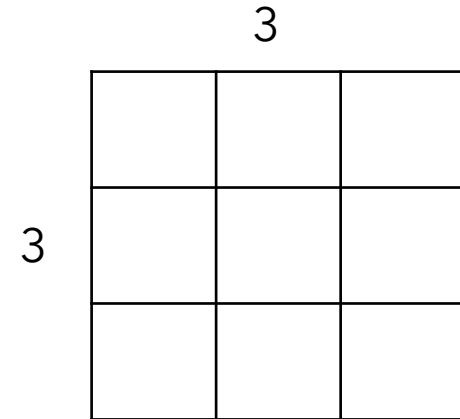
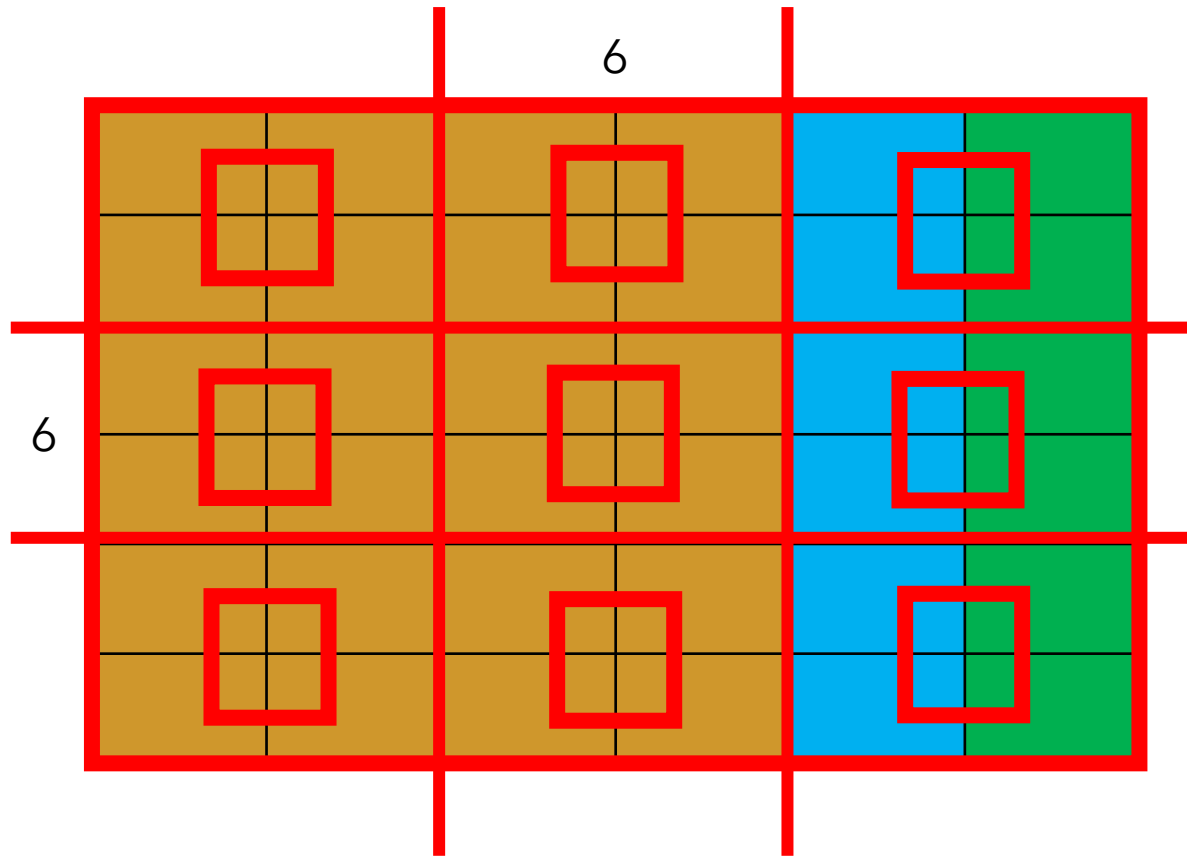
Nearest Neighbor - Max Choice



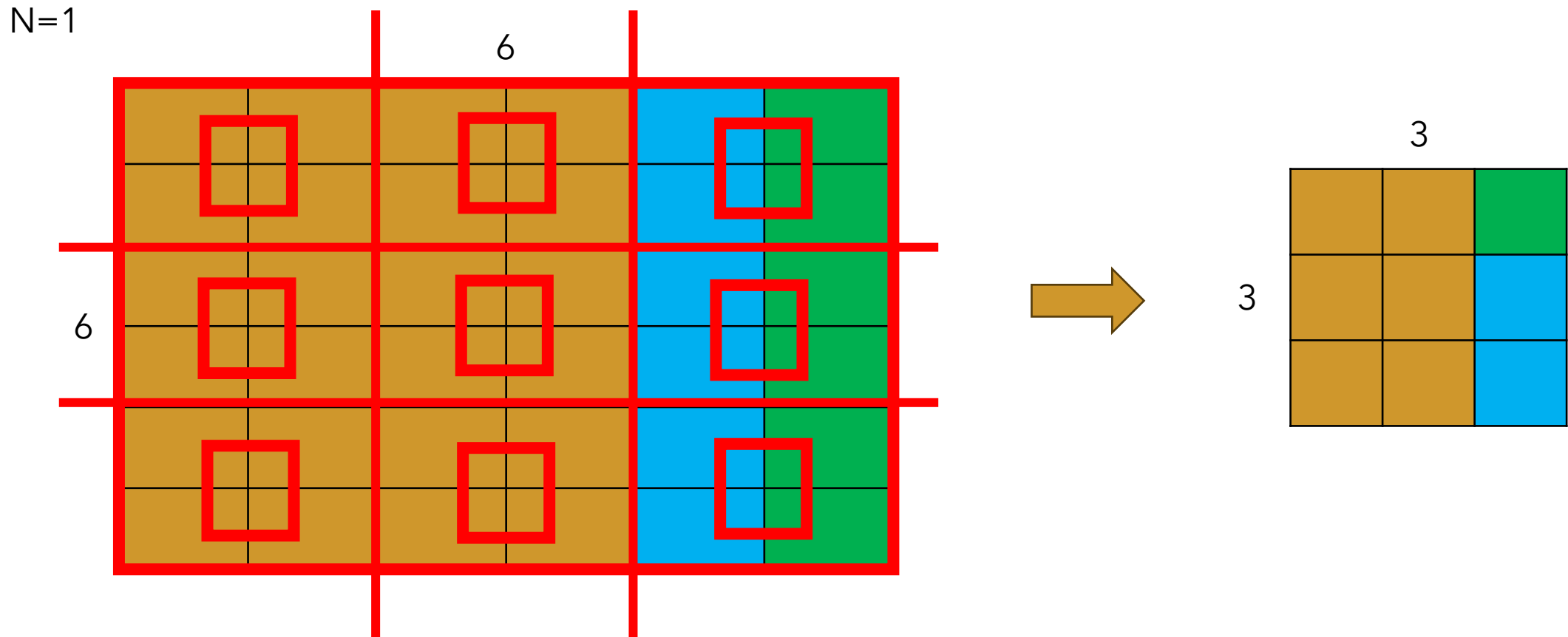
Nearest Neighbor - Max Choice



Nearest Neighbor - Max Choice



Nearest Neighbor - Max Choice



Bilinear Filtering

