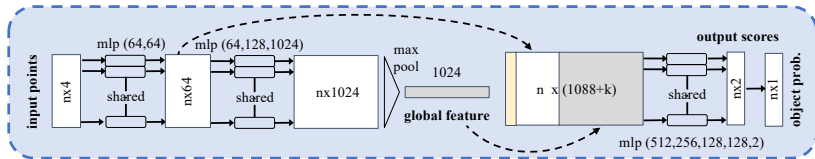
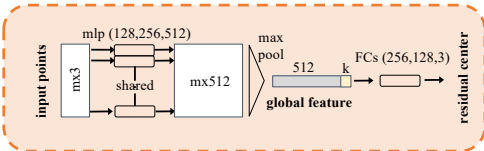


v1 3D Instance Segmentation PointNet



T-Net for estimating residual center



v1 Amodal 3D Box Estimation PointNet

