Date: 1 /

Khrithik S Anand IBMUSCS046 int height (Node *N) seturn O; seturn O; seturn N -> heighty int may (int a , int b.) Achurn (a>b) (a:b) Node * Sight Robots (Node *) Node + T2 = 2 -> Right x -> sight = y y -> left = [2]. y > height = max (height (y >) left),

height (y > sight)), + 1;

n > height = max (height (x -> left),

height (x -> sight)) + 1; sehin a

Khaithih S. Arand papergrid Date: / / 1BM18CSO46 => To rotate of rotate Node * left Rotate (Nodr *x) Node *y = x -> right Node *TL = y -> left y -> height = max (height (x -> left), height (x-) gight))+1; y -> height = max (height (y-> left), height (y-) gight)41; actura y; to get Balance int jetBalance (Node + N) if (N==NVLL) Return O; Seturn heigh (N → 1eft) - heigh (N → sight). = to instakey (insertion)

Rhaidhik S. Anand	
1BM18CSO4,6	papergrid Date: / /
Node & mest (Node +	node, it has
J (100 ada = 2 N/1/1 1	Milabara and Assarba
o elub Chen N	ode (Kcj);
il (ver < node > 1	res) A = The state of the stat
nedc - left	is got (node) left (key).
else if (key 2 node	t = insest (mode -) sight, key),
nade → sigh	F = nees / (non +) sign / reg J,
e se	A. J. C. Trade
setwa nody	+ max (height (node > (eft)
MU (18 -) HE GAT	height (node -> snight)
int balance = getlata	+ max (height (node > left) height (node > snight); nee (node),
if (balance 2) de	key < node > Keft key)
Jehun zigh	+ Rolate thoday
balance C-1 a	t key > node > nept (legs) t Robote (node); d key > node -> sight -> key) Robote (node); key > node -> left -> key)
il (halance > 1 dd	Key Inade > left -> Key)
node -> lelt	= left rotate (node - sleft);
geturn schoo	Rota Sight Rotate (node)
balance < -1	Ad key < node -) right key
0-1-2-02	ht = sight Rotate (node -) Right Rolate (node);
noae = sig	Roberte (node)
2	
setuen node;	
70mg Way	

KloriM.b. S. Anand papergrid 1BM 18CS 046 Date: / / = for deletion Node * a delete Node (Node * root, int they) if (300) == NULL) if (Key < 900t -> key)

200 900t -> telf = delete Node (300t -> lelf hey)

else if (Key > 900tal -> key)

800t -> 919ht = delete Node (900t -> 8ight, key); (900+ -) left == NULL)] (reet -) sight == NULL) Node +temp = root > left 2 root = left 2 root = sight; of (temp == NV LL) free (temp) Nøder-temp - min Value Nøde (soet -) Sight) soot -> key = temp -> key soot -> sight = delete Node (soft-> sight)

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if (goot = = NULL) schuln soot;

soot + height = It max (height (soot > left),

height (soot > shight);

int balance = get halmee (200+); L'halance 21 & d get Balance (2007 > left) >0. 2 étus gight Ratance (2007); L'balance > 111 get Balance (root > left) < 0) schn sight Roxate (soat); getBalance (300t-) sight) <=0)

Setus left Rotate (Root);

(balance <-1 dd get Balance (2001 3 sigth) >0) Root-) right = sight Rolate (soct-);

return 2001;