

```
def __init__(self, vertices):
```

self,  $V$  = vertices

```
self.graph = [[0 for column in range(vertices)]
               for row in range(vertices)]
```

```
def print_solution(self, dist):
```

```
print("Vertex \t Distance from source")
```

for node in range (self.v):

```
print(node, "vt", dist[node])
```

```
def min_distance (self, dist, spSet):
```

$$\min = 9999$$

```
for v in range(self.V):
```

```
if dist[v] < min and set[v] == False:
```

$$\text{min} = \text{dist}[v]$$
$$\text{min\_index} = v$$

return min\_index

```
def add_edge(self, src, dst, weight):
```

```
self.graph[src][dest] = self.graph[dest][src] = weight
```

```
def dijkstra (self, src):
```

$$\text{dist} = [\text{qqqq}]^T * \text{self.V}$$
$$\text{dist}[\text{src}] = 0$$

```
sptSet = [False] * self.V
```

for car in range(self.v):

$$v = \text{self.min-distance}(\text{dist}, \text{sptSet})$$
$$\text{sptSet}^0[v] = \text{True}$$

for  $V_{in}$  range (self.  $V$ ):

```

if self.graph[v][v] > 0 and sptSet[v] == False and

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$$\text{dist}[v] > \text{dist}[u] + \text{self.graph}[u][v]:$$
$$\rightarrow \text{dist}[v] = \text{dist}[u] + \text{self.graph}[u][v]$$

```
self.print_solution(cost)
```

```
g = Graph(int(input("Enter number of nodes in the topology:")))
c = int(input("Enter number of edges:"))
```

```
for i in range(c)
    src, dest, cost = [int(_) for _ in input("Enter [SRC][DEST]
                                         [WEIGHT]: ").split(' ')]
    g.add_edge(src, dest, cost)
```

```
src = int(input("Enter [SRC] to find cost:"))
```

```
g.dijkstra(src)
```