

ESO204A, Fluid Mechanics and rate Processes

## Momentum Conservation principle differential formulation

Derivation of Navier-Stokes Equation

Chapter 4 of F M White  
Chapter 5 of Fox McDonald

**Continuity:**  $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0$

**RTT:**  $\frac{dB_{\text{sys}}}{dt} = \int_{\text{CV}} \left[ \frac{\partial (\rho \beta)}{\partial t} + \nabla \cdot (\rho \beta \vec{u}) \right] dV$

$$\begin{aligned} \frac{\partial (\rho \beta)}{\partial t} + \nabla \cdot (\rho \beta \vec{u}) &= \left( \beta \frac{\partial \rho}{\partial t} + \rho \frac{\partial \beta}{\partial t} \right) + \left[ \beta \nabla \cdot (\rho \vec{u}) + \rho (\vec{u} \cdot \nabla) \beta \right] \\ &= \beta \left[ \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) \right] + \rho \left[ \frac{\partial \beta}{\partial t} + (\vec{u} \cdot \nabla) \beta \right] \end{aligned}$$

**RTT:**  $\frac{dB_{\text{sys}}}{dt} = \int_{\text{CV}} \rho \left[ \frac{\partial \beta}{\partial t} + (\vec{u} \cdot \nabla) \beta \right] dV$

**Momentum conservation:**  $\frac{d(m\vec{u})}{dt} = \vec{F} = \vec{F}_B + \vec{F}_S$

**RTT:**  $\frac{dB_{\text{sys}}}{dt} = \int_{\text{CV}} \rho \left[ \frac{\partial \beta}{\partial t} + (\vec{u} \cdot \nabla) \beta \right] dV$

using  $B_{\text{sys}} = m\vec{u}$  we have  $\beta = \vec{u}$  and  $\frac{dB_{\text{sys}}}{dt} = \vec{F}_B + \vec{F}_S$

$$\vec{F}_B + \vec{F}_S = \int_{\text{CV}} \rho \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} \right] dV$$

$$\int_{\text{CV}} \rho \vec{g} dV + \vec{F}_S = \int_{\text{CV}} \rho \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} \right] dV$$

**Surface forces are related to normal and shear stresses**

### Stress in a fluid:

**Normal stress**

$$\sigma_{xx} = \lim_{\delta A_x \rightarrow 0} \frac{\delta F_x}{\delta A_x}$$

**Shear**

$$\sigma_{xy} = \lim_{\delta A_x \rightarrow 0} \frac{\delta F_y}{\delta A_x}$$

$$\sigma_{xz} = \lim_{\delta A_x \rightarrow 0} \frac{\delta F_z}{\delta A_x}$$

Surface normal  
direction

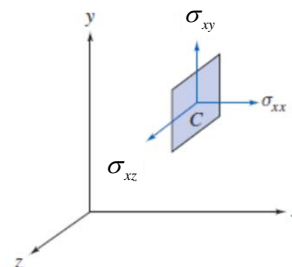
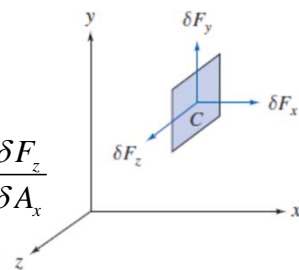
Force  
direction

$\sigma_{ij}$ : Surface normal direction:  $i$

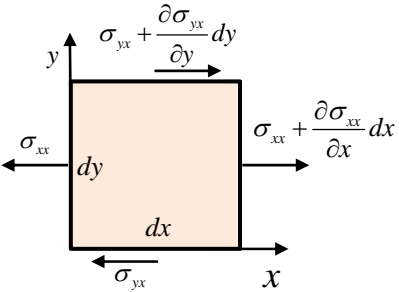
Force direction:  $j$  **or**

Surface normal direction:  $-i$

Force direction:  $-j$



### Surface force component in x-direction:

$$\begin{aligned}
 dF_{sx} &= \left( \sigma_{xx} + \frac{\partial \sigma_{xx}}{\partial x} dx \right) dy - \sigma_{xx} dy \\
 &+ \left( \sigma_{yx} + \frac{\partial \sigma_{yx}}{\partial y} dy \right) dx - \sigma_{yx} dx \\
 &= \left( \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{yx}}{\partial y} \right) dV \\
 F_{sx} &= \int_{CV} \left( \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{yx}}{\partial y} \right) dV
 \end{aligned}$$


**Recall:** 
$$\int_{CV} \rho \vec{g} dV + \vec{F}_s = \int_{CV} \rho \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} \right] dV$$

**x-mom Eq.** 
$$\int_{CV} \rho g_x dV + F_{sx} = \int_{CV} \rho \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} \right]_x dV$$

$$F_{sx} = \int_{CV} \left( \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{yx}}{\partial y} \right) dV$$

$$\int_{CV} \rho g_x dV + \int_{CV} \left( \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{yx}}{\partial y} \right) dV = \int_{CV} \rho \left[ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} \right]_x dV$$

Since the above relation is true for arbitrary CV

$$\rho \left[ \frac{\partial u}{\partial t} + (\vec{u} \cdot \nabla) u \right] = \rho g_x + \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{yx}}{\partial y}$$

## Newton's law of viscosity

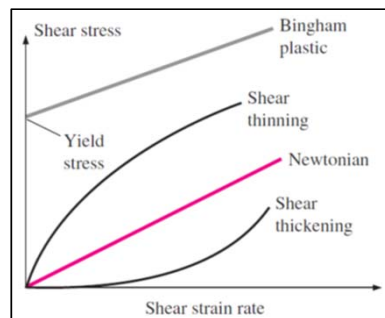
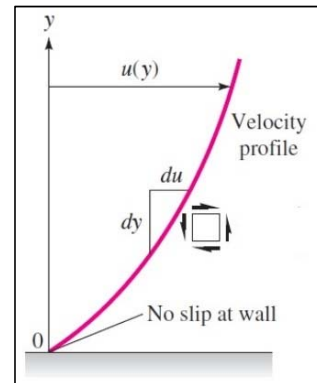
stress  $\propto$  strain-rate  $\sigma_{yx} = \mu \frac{\partial u}{\partial y}$

$\mu$ : viscosity

Fluid following above relation:

**Newtonian fluid**

Ex: air (most gases), water



**Non-Newtonian fluid**  
examples: ketchup,  
blood, toothpaste

## Generalized form of Newton's law for incompressible flow (Stokes)

$$\sigma_{yx} = \mu \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \quad \sigma_{xx} = -p + 2\mu \frac{\partial u}{\partial x}$$

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{yx}}{\partial y} = \frac{\partial}{\partial x} \left( -p + 2\mu \frac{\partial u}{\partial x} \right) + \mu \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) = 0, \text{ incompressible}$$

$$= -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 u}{\partial x^2} + \mu \frac{\partial^2 u}{\partial y^2} + \cancel{\mu \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)}$$

$$= -\frac{\partial p}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

x-mom. Eq. for Newtonian fluid, 2-D  
incompressible flow

$$\rho \left[ \frac{\partial u}{\partial t} + (\vec{u} \cdot \nabla) u \right] = \rho g_x - \frac{\partial p}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial t} + (\vec{u} \cdot \nabla) u = g_x - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right); \nu = \mu / \rho$$

$\mu$  : viscosity (dynamic viscosity), Pa-s

$\nu$  : kinematic viscosity, m<sup>2</sup>/s

In 3-D

$$\begin{aligned} \frac{\partial u}{\partial t} + (\vec{u} \cdot \nabla) u &= g_x - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) \\ &= g_x - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \nabla^2 u \end{aligned}$$

Similarly y- and z-direction mom. Eq.

$$\frac{\partial v}{\partial t} + (\vec{u} \cdot \nabla) v = g_y - \frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \nabla^2 v \quad \frac{\partial w}{\partial t} + (\vec{u} \cdot \nabla) w = g_z - \frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \nabla^2 w$$

Momentum Eq. in vector form  
(incompressible, Newtonian)

$$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = \vec{g} - \frac{1}{\rho} \nabla p + \nu \nabla^2 \vec{u}$$

Above Eq. is known as **Navier-Stokes Equation**  
(Navier 1825, Stokes 1850)

Inviscid form: 
$$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = \vec{g} - \frac{1}{\rho} \nabla p$$

Known as **Euler Equation** (Euler, 1757)

**Applications:** Geophysical flows, aerodynamics,  
flows far away from walls



Bernoulli  
1700-1782



Euler  
1707-1783



Navier  
1785-1836



Stokes  
1819-1903

$$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = \vec{g} - \frac{1}{\rho} \nabla p + \nu \nabla^2 \vec{u} \quad \vec{u} \cdot \nabla \equiv u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}$$

3-D, N-S eq., scalar form, Cartesian coordinate:

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = g_x - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = g_y - \frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right)$$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = g_z - \frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right)$$

Incompressible continuity: 
$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$