ESO204A, Fluid Mechanics and rate Processes

Dimensional Analysis: application to model testing

Chapter 5 of F M White Chapter 7 of Fox McDonald

A running car experiences fluid resistance known as 'drag force' $F = f(L, u, \rho, \mu)$

We are interested to measure the drag on a similar to estimate the drag on the prototype

$$\frac{F}{\rho u^2 L^2} = \psi \left(\frac{\mu}{\rho u L} \right) \qquad C_D = \psi \left(\frac{1}{\text{Re}} \right)$$

To conduct useful model test, we need to match **Re**, which may need model testing at high-speed

Our crude experiment indicated C_D = constant!!

We can explain this result from the dimensional $\frac{F}{\rho u^2 L^2} = \psi \left(\frac{\mu}{\rho u L}\right)$ $C_D = \psi \left(\frac{1}{\mathrm{Re}}\right)$

 $C_D = \frac{\text{drag}}{\text{inertia}}$

 $\frac{1}{Re} = \frac{\text{viscous}}{\text{inertia}}$

- o Dim. analysis indicates three forces
- o Dim. analysis scales other forces w. r. t. inertia

Drag force has two sources: viscous + pressure (or 'form' drag)

Form drag becomes more important at high velocity

High Re ≡ viscous << inertia

$$\frac{F}{\rho u^2 L^2} = \psi \left(\frac{\mu}{\rho u L} \right)$$

$$C_D = \psi \left(\frac{1}{\text{Re}} \right)$$

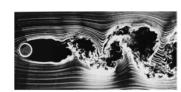
$$C_D = \frac{\text{drag}}{\text{inertia}}$$

$$\frac{1}{\text{Re}} = \frac{\text{viscous}}{\text{inertia}}$$

Form drag dominates



Re = 0.1



Re = 10,000

Flow over cylinders at varying Re

High Re case
$$F = f(L, u, \rho)$$
 Dropping μ

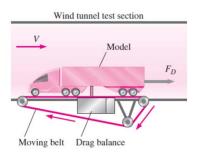
Conduct dimensional analysis $\pi_1 = \frac{F}{\rho u^2 L^2}$

$$\Rightarrow \psi \left(\frac{F}{\rho u^2 L^2} \right) = 0 \quad \Rightarrow \frac{F}{\rho u^2 L^2} = C_D = \text{constant}$$

Above relation usually holds for $Re \sim 10^3$ or more

The model study can be conducted up to the point where $C_{\rm D}$ reaches the Re-independent value

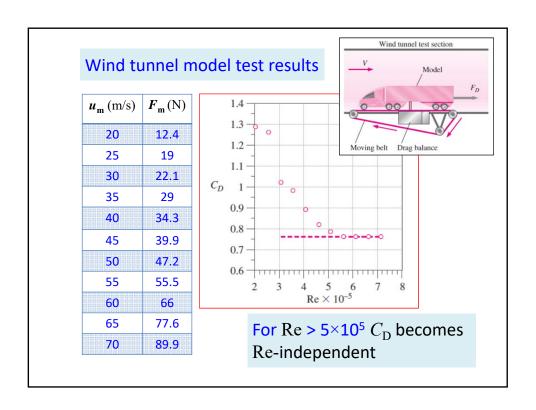
Example: model testing of a truck

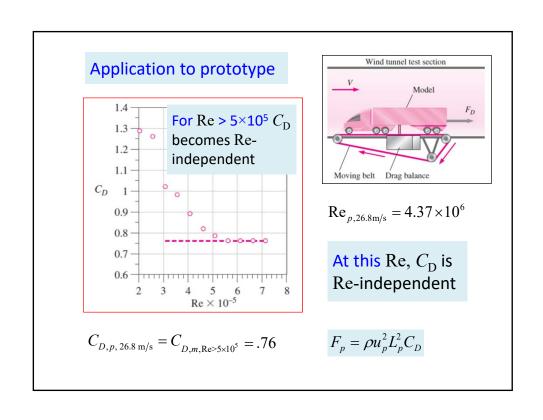


	Model	Prototype
L	.991m	15.9m
и	70m/s max	26.8 m/s (100km/hr)

For Re matching $(uL)_m = (uL)_p$ $u_m = 429 \text{ m/s}$

The model speed is in compressible regime and also cannot be attained in the present wind-tunnel





$$F = f(L, u, \rho, \mu) \quad \frac{F}{\rho u^2 L^2} = \psi \left(\frac{\mu}{\rho u L}\right) \qquad C_D = \psi \left(\frac{1}{\text{Re}}\right)$$
$$C_D = \frac{\text{drag}}{\text{inertia}} \qquad \frac{1}{\text{Re}} = \frac{\text{viscous}}{\text{inertia}}$$

Low Re case \Rightarrow small inertia \Rightarrow drag \sim viscous

As discussed before, drag force has two components: pressure (form) and viscous

For low Re, viscous part dominates

Low Re case
$$F = f(L, u, \mu)$$
 Dropping ρ

Conduct dimensional analysis $\pi_1 = \frac{F}{\mu u L}$

$$\Rightarrow \psi \left(\frac{F}{\mu u L} \right) = 0 \Rightarrow \frac{F}{\mu u L} = \text{constant} \Rightarrow \frac{F}{\rho u^2 L^2} = \frac{\text{constant.} \mu u L}{\rho u^2 L^2}$$

$$\Rightarrow C_D = \frac{\text{constant}}{\text{Re}}$$

Above relation holds for Re <1 (creeping flow or Stoke's flow) and is very useful for viscosity measurement, microflows, biological systems

Low Re

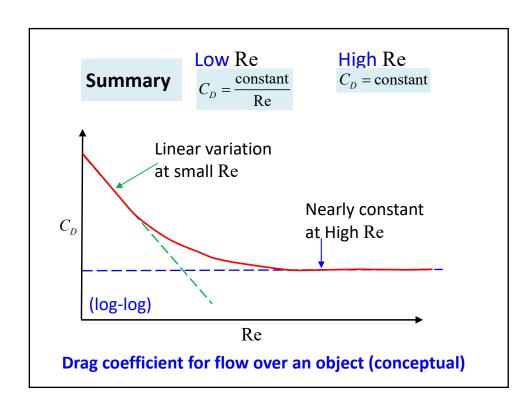
High Re

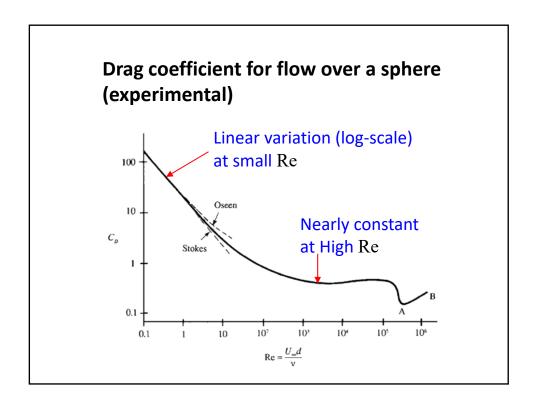
Drag = constant. μuL

Drag = constant. $\rho u^2 L^2$

At high speed drag is proportional to u^2 while at low speed drag is proportional to u

In a highly viscous (low Re) environment, it is very difficult to start/maintain motion





Example: terminal speed of a falling object

Terminal speed: steady speed of the falling object when drag = weight $Drag = constant.L^3$

Low Re

High Re

Drag = constant. μuL

Drag = constant. $\rho u^2 L^2$

 $u \propto L^2$

 $u \propto \sqrt{L}$

Terminal speed varies differently with lengthscale for smaller and larger objects

