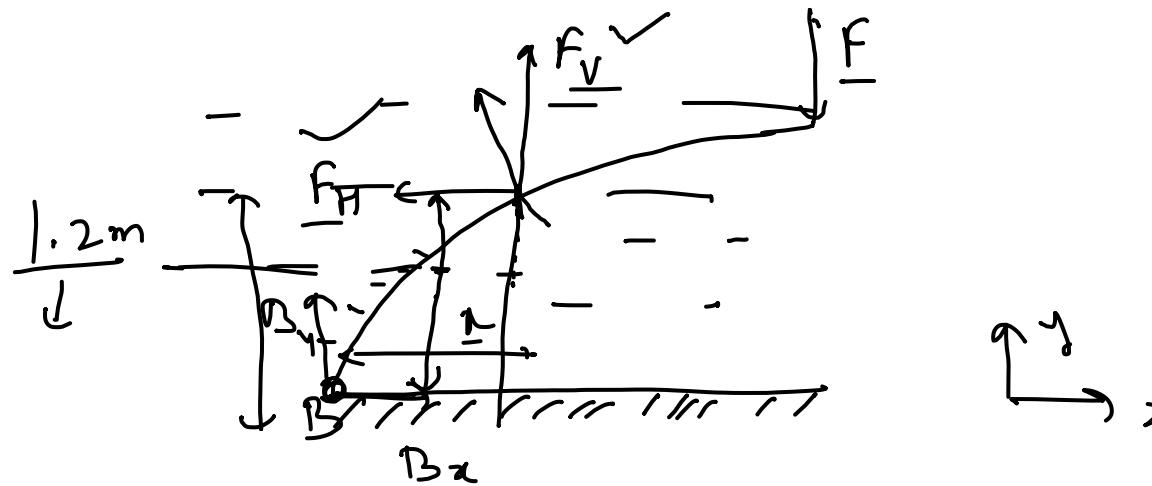


Quiz 1 - Solution

Que 1

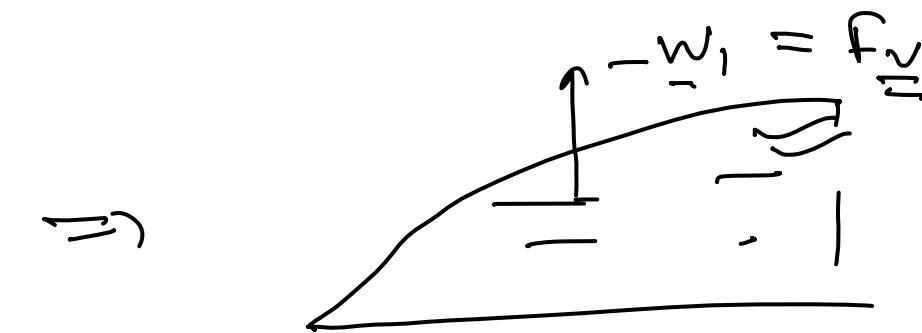
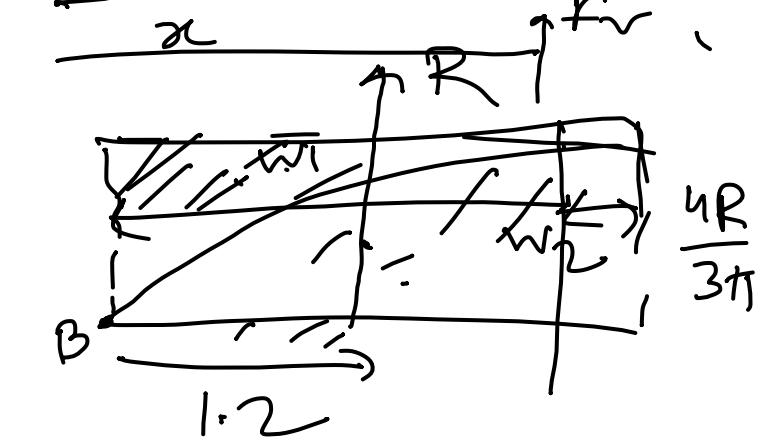
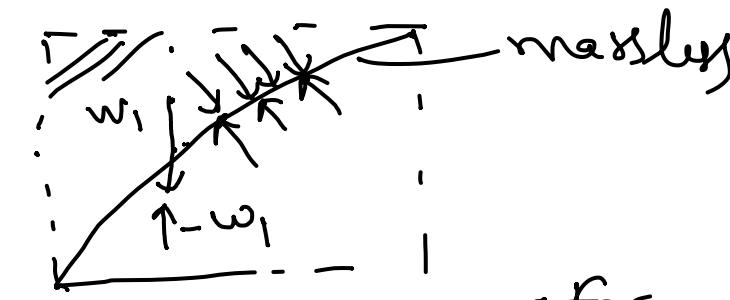


Method 1 → more detail

$$F_H = \rho g h_{cc} A_{\text{Project}}$$

$$\frac{w_1}{w_2}$$

$\underline{\underline{f}_V}$ How to find f_V and its line of action

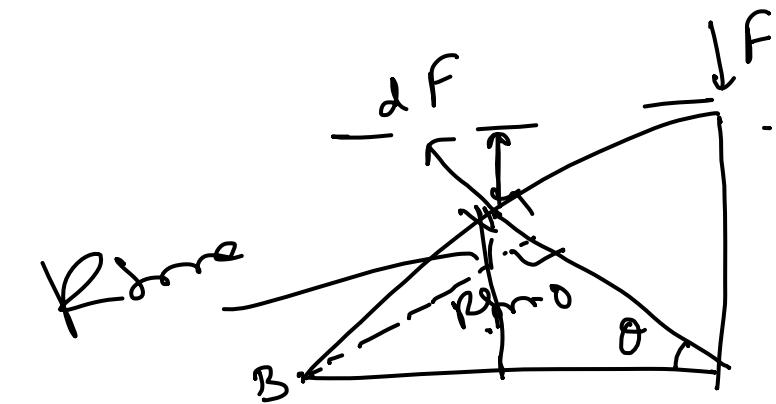


$$\begin{aligned}\vec{R} &= \vec{w}_1 + \vec{w}_2 \\ \vec{w}_1 &= \vec{R} - \vec{w}_2\end{aligned}$$

$$\underline{\underline{f}_V} = \vec{R} - \vec{w}_2 = (\underline{\underline{w}_1 + w_2}) - \vec{w}_2 \quad (i)$$

$$\begin{aligned}\text{moment of } (-f_V) &= \text{moment } (\underline{\underline{w}_1 + w_2}) - \text{moment } \vec{w}_2 \\ |f_V| \cdot x &= \end{aligned}$$

Method 2



$$dF = p dA$$

$$dF_x = p dA \cos \theta$$

$$dF_y = p dA \sin \theta$$

$$p = \rho g h$$

$$h = R(p - S_{mo})$$

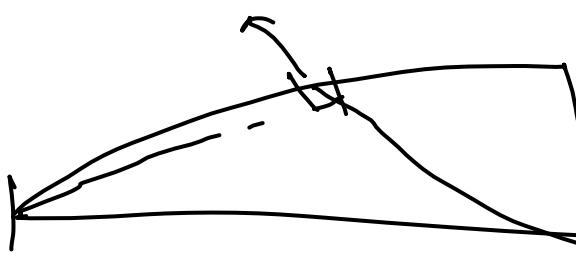
$$f_n = \int p dA \cos \theta$$

$$f_v = \int p dA \sin \theta$$

$$f_R = \sqrt{f_n^2 + f_v^2}$$

$$\tan \theta = \frac{f_v}{f_n}$$

Method 3



$$dM_B = \int p dA R_{Bmo} = F \cdot 2\pi r$$

Non-dimensional analysis of equation of motion

of-the-order

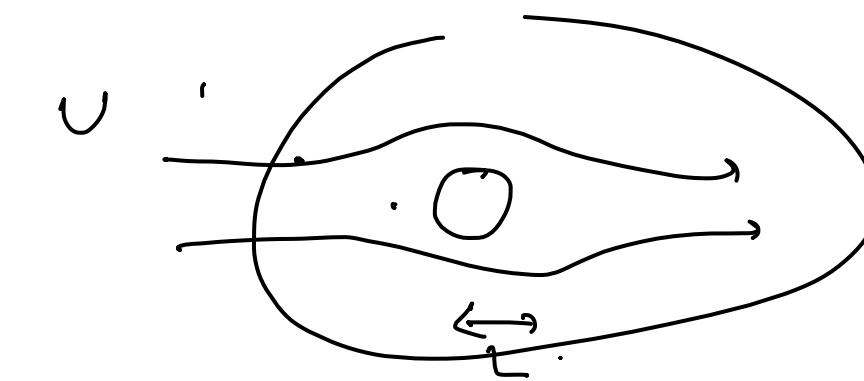
- Incompressible flow

continuity

eqn motion - (ns)

$$\nabla \cdot V = 0$$

$$P \left[\frac{dV}{dt} \right] = [\rho g] [\nabla P] + [\mu \nabla^2 V]$$



inviscid flow \rightarrow Euler eqn \rightarrow

creeping flow $\rightarrow \underline{\underline{V}} \rightarrow 0$

$$x = \underline{\underline{(0, L)}}$$

$$\frac{x}{L} = (0, 1)$$

scale $V = U =$ velocity far away from surface

scale $x, y, z = L \equiv$ some dimension of surface

$$V^* = \frac{V}{U}, \quad U^* = \frac{U}{U}, \quad \omega^* = \frac{\omega}{U}, \quad w^* = \frac{w}{U}, \quad x^* = \frac{x}{L}, \quad y^* = \frac{y}{L}, \quad z^* = \frac{z}{L}$$

$$P^* = \frac{P - \rho g z}{\rho U^2}$$

$P U^2$ - inertial stress

$$\frac{P U^2}{A} = \text{momentum flux} = \frac{1}{A} \frac{dP_1}{dx} = \underline{\underline{C}_M}$$

$$\nabla = \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) = \frac{1}{L} \left(\frac{\partial}{\partial x^*} \hat{i} + \frac{\partial}{\partial y^*} \hat{j} + \frac{\partial}{\partial z^*} \hat{k} \right) = \frac{1}{L} \nabla^*$$

$$\nabla \cdot V = 0 \Rightarrow \frac{1}{L} \nabla^* \cdot V^* = 0 \Rightarrow \boxed{\nabla^* \cdot V^* = 0}$$

eqn of motion

$$\rho \left[\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right] = \rho g - \nabla p + \mu \nabla^2 v$$

$$t^* = \frac{t}{L/U}$$

$$\rho \left[\frac{u}{L} \frac{\partial v^*}{\partial t^*} + u^* \frac{v}{U} \frac{\partial v^*}{\partial x^*} + \frac{u^* U}{L} \frac{\partial v^*}{\partial y^*} + \frac{w^* U}{L} \frac{\partial v^*}{\partial z^*} \right] = \rho g - \nabla^* \left(p^* \rho U^2 + \rho g z^* L \right) + \mu \frac{\nabla^{*2}}{L^2} U^2 v^*$$

$$\nabla^* =$$

$$\nabla \cdot \nabla = \frac{\partial^2}{L^2} \nabla^2$$

$$\left(\rho \frac{U^2}{L} \right) \left[\frac{\partial v^*}{\partial t^*} + u^* \frac{\partial v^*}{\partial x^*} + u^* \frac{\partial v^*}{\partial y^*} + u^* \frac{\partial v^*}{\partial z^*} \right] = \cancel{\rho g} - \frac{\rho U^2}{L} \nabla^* p^* - \cancel{\rho g} + \frac{U \mu}{L} \nabla^{*2} v^*$$

$$\boxed{\frac{dv^*}{dt^*} = -\nabla^* p^* + \left(\frac{\mu}{\rho L U} \right) \nabla^{*2} v^*}$$

$$\boxed{\frac{dv^*}{dt^*} = -\nabla^* p^* + \frac{1}{Re} \nabla^{*2} v^*}$$

Non-dimensional eqn of motion

$\rightarrow Re \rightarrow \infty \rightarrow$ inviscid condition \Rightarrow Euler eqn

$$\begin{aligned} & \rightarrow Re \rightarrow 0 \rightarrow Re \left(\frac{dv^*}{dt^*} \right) \rightarrow 0 \Rightarrow 0 = -\nabla^* p^* + \frac{1}{Re} \nabla^{*2} v^* \\ & \hookrightarrow v \rightarrow 0 \text{ (creeping flow)} \end{aligned}$$