

ESO 204A: Fluid Mechanics and Rate Processes

Revisiting Kinematics

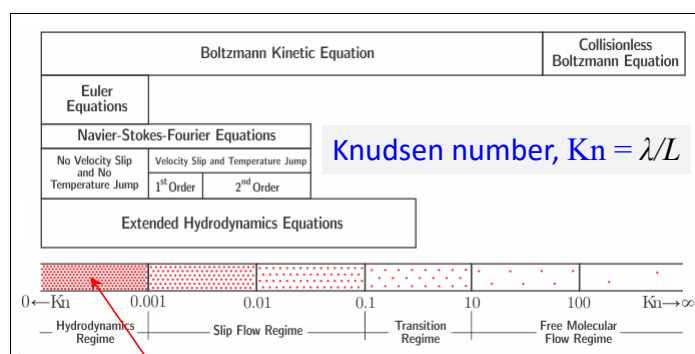
Lagrangian and Eulerian Descriptions

Anything else (on kinematics) you want to discuss

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Knudsen number and continuum limit

Continuum hypotheses is applicable when length-scale of interest (L) \gg molecular length-scale (mean free path, λ)



We are interested in this regime

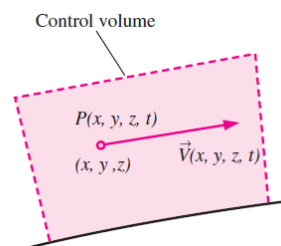
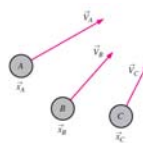
Lagrangian (particle)

- We model the fluid as a bunch of particles; many many particles in our case (due to continuum assumption)
- Describe fluid motion by stating the **instantaneous position and velocity** of each particle

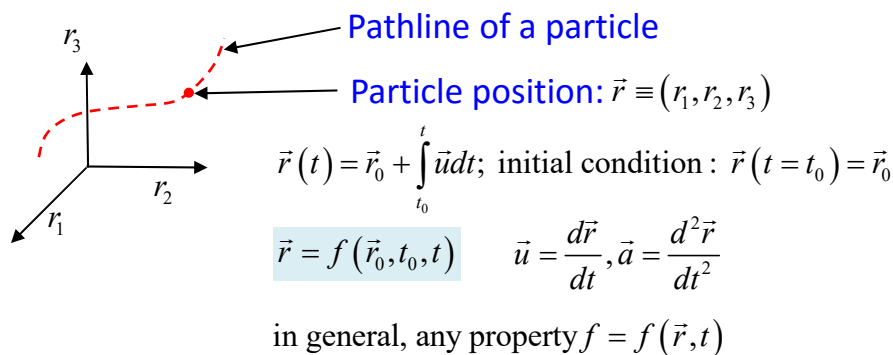


Eulerian (field)

- We define (many many) points in space
- Fluid particles arrive at a point, occupy the **position and velocity of that point**
- Eulerian concept is applicable as long as continuum concept is valid, Lagrangian is far more general

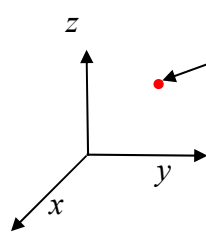


Lagrangian description



In Lagrangian description, position of a particle is **NOT an independent variable** and is a function of the independent variable: **time**. Particles are identified based on the **initial condition**

Eulerian description



Point in space

At continuum scale, the point is always occupied by **some (not same)** fluid particle

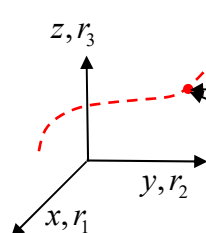
Point coordinate: $\vec{x} \equiv (x, y, z)$

in general, any property $f = f(\vec{x}, t)$

Physically, the above property is the property of the fluid particle occupying the point

In Eulerian description, **point coordinate and time** (x, y, z, t) are the **independent variables**

Combining everything



Pathline of a particle

Particle position: $\vec{r} \equiv (r_1, r_2, r_3)$

Point coordinate: $\vec{x} \equiv (x, y, z)$

$$\vec{r} \equiv \vec{x}$$

therefore, $f(\vec{r}, t) = f(\vec{x}, t)$ Using same 'clock'

$$\begin{aligned} \frac{df(\vec{x}, t)}{dt} &= \frac{df(\vec{r}, t)}{dt} = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial r_1} \frac{dr_1}{dt} + \frac{\partial f}{\partial r_2} \frac{dr_2}{dt} + \frac{\partial f}{\partial r_3} \frac{dr_3}{dt} \\ &= \frac{\partial f}{\partial t} + (\vec{u} \cdot \nabla) f \end{aligned}$$

Material derivative in Eulerian sense

Total (not partial) time derivative in Lagrangian sense

Quiz:

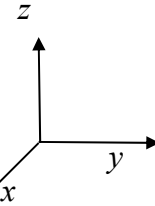
Given $u = \frac{dx}{dt}; v = \frac{dy}{dt};$ (x, y) indicates

1. Position of a fluid particle (Lagrangian)
2. Location of a point in space (Eulerian)

Whenever you see x, y, z as a function of t , we mean **Lagrangian** frame (particle position)

(u, v) indicates:

1. Velocity of a fluid particle (Lagrangian)
2. Velocity at a point in space (Eulerian)
3. Both of the above

**Example:**

Find the velocity **field** from the Lagrangian description:

$$x = x_0 \exp(-kt) + y_0 [1 - \exp(-2kt)]; y = y_0 \exp(-kt)$$

$$u = \frac{dx}{dt}; v = \frac{dy}{dt} \quad u = -kx_0 e^{-kt} + 2ky_0 e^{-2kt}; v = ky_0 e^{-kt}$$

Velocity components of a **specific particle** at time t

Initial condition of the **particle**: $\vec{x}(t=0) = (x_0, y_0)$

To get the velocity in

Eulerian sense u, v should be free of x_0, y_0

$$u = -kx + ky(e^{-kt} + e^{-3kt}); v = ky \quad \text{Velocity both in Eulerian and Lagrangian frames}$$

Closure

1. Keywords: **Particle, Field**
2. Think about the independent variables
3. All the lines (stream, streak etc.) are simply **geometric entity**
4. Streaklines, pathlines are drawn by taking particle information from Lagrangian descriptions
5. Streamline is described using velocity field data from Eulerian frame