GoFa Protocol

⏱ Created	@May 31, 2023 4:35 PM
⊙ Class	Compas
⊙ Type	
📎 Materials	
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Connection

Open Visual Studio > Open Docker >Compose Up (right click in "docker-compose.real-robot.yml)

In the control panel : Home code > RRC Main > In > … > Control > Reset program
Press dead man>press play

Reset Program > PLAY >Send the code from Visual Studio

Message in the screen: T_CTROL RRC Connected

If the program finished we have to restart Docker and in the control panel > Code > Control > Reset Program > Play > Connected
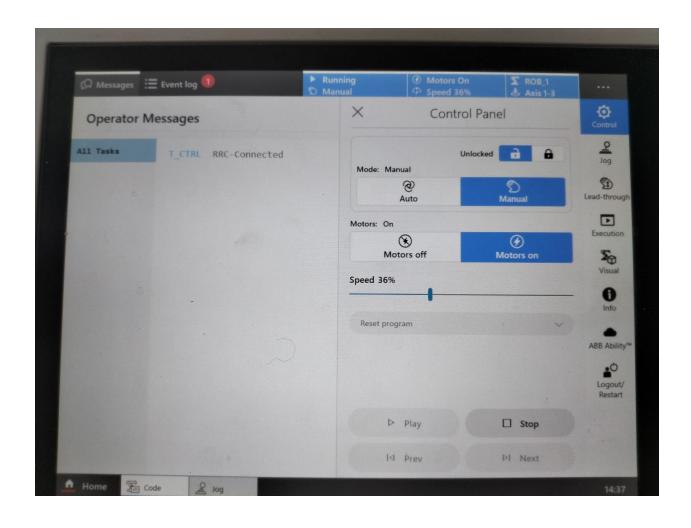
If you stop half way the program you terminate (Visual Studio)

STOP COMPLETE If it didn't finished

- Kill terminal

- Restart DOCKER (start to get it green)

Rotation Converter → https://www.andre-gaschler.com/rotationconverter/