

Kevin Kellar

COMPUTER SCIENCE UNDERGRADUATE (GRADUATING SPRING 2021)

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Objective

Seeking embedded software engineering roles targeting performance and safety critical applications

Education

California Polytechnic University

B.S. IN COMPUTER SCIENCE

San Luis Obispo, CA

Fall 2017 - Present

- Major GPA: **3.9** — Cal Poly Cumulative GPA: **3.9** — Expected graduation **Spring 2021**
- Exceeded in **Algorithms, Operating Systems, Computer Architecture, and Microcontrollers**

Work Experience

Zipline International

EMBEDDED SOFTWARE ENGINEERING INTERN

South San Francisco, CA

March-September 2020

Apple: Special Projects Group

SOFTWARE ENGINEERING INTERN

Santa Clara, CA

Summer 2019

Dynamic Robotics Laboratory (II)

RESEARCH EXPERIENCE FOR UNDERGRADUATES (REU)

Oregon State University

Summer 2018

- Developed **Cassie Trajectory Editor**, a tool to manipulate walking gaits for the bipedal robot Cassie
- Wrote C in Ubuntu Linux to link with C++ libraries such as **MuJoCo Physics Simulator** and **GLFW**
- Self-taught **Matplotlib** in Python for visualizing subtle differences robot trajectories and solver outputs

Dynamic Robotics Laboratory (I)

HIGH SCHOOL RESEARCH ASSISTANT

Oregon State University

Summer 2017

Skills

- C** Fluent. Extensive work with **POSIX-style systems programming** as well as **MCU-style** low-level development
- Test** Built systems/embedded software using **C test-driven development**, mock objects, cmocka, and GTest
- MCU** Developed **analog acquisition drivers** for Microchip SAME70 and TI MSP423, and drivers for hardware timers
- RTOS** Implemented application tasks on the preemptive **Micrium μ C/OS-II** as well as an internal RTOS for Apple
- Bus** Wrote MSP423 **I2C, UART and SPI drivers** & work with CAN/CANOpen protocols for communication
- Build** Experience with **Bazel Build**, GNU Make, SCons and CMake for building and testing projects with many targets
- Python** Extensive work with **Matplotlib/Pandas** to prove functionality, using batch processing and summary plots
- C++** Limited experience with **C++ style OOP**, smart pointers, and data structures, as well as **OpenGL and GTest**
- Unix** Comfortable with bash scripting programs sed/grep, primarily for **integration testing** systems-level software
- SSH** Built a **home file server**: experience with ssh server setup, ssh tunneling, and RSA key setup
- Android** Published **two Android applications** to the **Google Play Store**, using Android Studio, **Java**, and XML
- Git** Developed **dozens of public and GitHub projects**, including rebase conflict resolution and code reviews
- Chinese** Early-intermediate level conversational competency in **Mandarin**, experience with many sentence structures

Honors & Awards

COMPETITIONS

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| 2019 | 2nd Prize: Roborodentia: Cal Poly's Autonomous Robotics Competition | Cal Poly, SLO |
| 2018 | 1st Prize: Roborodentia: Cal Poly's Autonomous Robotics Competition | Cal Poly, SLO |
| 2018 | 2nd Prize: Winter SLOHacks: Developed a networked Android application | Cal Poly, SLO |