Kevin Kellar

4438 NW Boxwood Drive, Corvallis OR. 97330

② kkevlar | □ 541-224-6877 | ≥ kellar@calpoly.edu | in kellar-kevin

Objective_

Seeking embedded software engineering roles targeting performance and safety critical applications

Education_

California Polytechnic University

B.S. IN COMPUTER SCIENCE

San Luis Obispo, CA

- Fall 2017 Present
- Major GPA: **3.9** Cal Poly Cumulative GPA: **3.9** Expected graduation **Spring 2021**
- Exceeded in Algorithms, Operating Systems, Computer Architecture, and Microcontrollers

Work Experience.

Zipline International

South San Francisco, CA

March-October 2020

EMBEDDED SOFTWARE ENGINEERING INTERN

- Began each embedded software project with an architecture document to consider multiple solutions, ask for team member buy-in, and brainstorm testing criteria
- Tested embedded software projects with unit test driver development, acceptance testing at desk, and log data analysis notebooks
- Developed functionality for two batteries to safely take turns using a shared Delta-Q battery charger using a
- Improved timing logic for the vehicle nodes' electrical telemetry task to measure at predictable, consistent and verifiable intervals
- Implemented an analog driver for the same 70 using the MCU's manual, a semaphore to internally pend for results, and a mutex for safe ownership of the driver

Apple: Special Projects Group

Santa Clara, CA

SOFTWARE ENGINEERING INTERN

Summer 2019

- Designed a **failure analysis tool** to detect dead software nodes, and summarize findings in a markdown report
- Thirteen weeks of **systems programming** experience targeting real time **embedded** operating system
- Extensive work with test driven development, using **cmocka** and **bazel build system** to build and test targets

Dynamic Robotics Laboratory

Oregon State University Summer 2017 & Summer 2018

RESEARCH EXPERIENCE FOR UNDERGRADUATES (REU)

• Designed Cassie Trajectory Editor, a tool to manipulate walking gaits for the bipedal robot Cassie

• Wrote C in Ubuntu Linux to link with C++ libraries such as MuJoCo Physics Simulator and GLFW

Skills

C Fluent. Extensive work with **POSIX systems programming** as well as **MCU-style** driver & task development

Test Built systems/embedded software using **C test-driven development**, mock objects, cmocka, and GTest

MCU Developed **analog acquisition drivers** for Microchip SAME70 and TI MSP423, and drivers for hardware timers **RTOS** Implemented application tasks on the preemptive Micrium μC/OS-II as well as an internal RTOS for Apple

Bus Wrote MSP423 I2C, UART and SPI drivers & work with CAN/CANOpen protocols for communication

Debug Strong w/ embedded tools find sneaky defects: GDB, Valgrind, Clang Sanitizers, and the Ozone debugger

Build Experience with **Bazel Build**, GNU Make, SCons and CMake for building and testing projects with many targets

Unity Published an Virtual Reality chemical modeling simulation using **Steam's OpenVR Plugin** and C# scripting

Python Extensive work with **Matplotlib**/Pandas to prove functionality, using batch processing and summary plots **C++** Limited experience with **C++ style OOP**, smart pointers, and data structures, as well as **OpenGL and GTest**

Unix Comfortable with bash scripting programs sed/grep, primarily for **integration testing** systems-level software

SSH Built a **home file server**: experience with ssh server setup, ssh tunneling, and RSA key setup

App Published **two Android applications** to the **Google Play Store**, using Android Studio, **Java**, and XML

Chinese Early-intermediate level conversational competency in **Mandarin**, experience with many sentence structures **Git** Developed **dozens of public and GitHub projects**, including rebase conflict resolution and code reviews

Honors & Awards _____

COMPETITIONS

2019	2nd Prize : Roborodentia: Cal Poly's Autonomous Robotics Competition	Cal Poly, SLO
2018	1st Prize : Roborodentia: Cal Poly's Autonomous Robotics Competition	Cal Poly, SLO
2018	2nd Prize : Winter SLOHacks: Developed a networked Android application	Cal Poly, SLO