

# Quiz 1

Introduction to AI and Problem Solving via Search

All Questions are compulsory

\* Required

Enter your Name and Roll Number \*

Your answer

The first test proposed to evaluate artificial intelligence was \*

1 point

- ☐ McCarthy test
- ☐ Reasoning test
- ☐ Turing test
- ☐ Theorem test

The traditional AI was focused on \*

1 point

- ☐ Inference
- ☐ Probability
- ☐ Statistics
- ☐ Model building



A rational agent is the one \*

1 point

- ☐ who acts optimally to solve a problem
- ☐ who acts to achieve best solution of a problem
- ☐ who acts and adapts to solve a problem
- ☐ who acts to find goals for a problem

The complete history of everything that an agent has perceived is known as \*

1 point

- ☐ percept knowledge
- ☐ percept base
- ☐ percept brain
- ☐ percept sequence

An assembly line is the example of \*

1 point

- ☐ Episodic environment
- ☐ Deterministic environment
- ☐ Partially observable environment
- ☐ Sequential environment



Which of the following AI agent conquered the game of chess \*

1 point

- ☐ Deepblue
- ☐ Deepmind
- ☐ Deepgreen
- ☐ Deeplearner

Amalgamation of human psychology with AI is called \*

1 point

- ☐ Deeplearning
- ☐ Cognitive science
- ☐ Brain modeling
- ☐ Neural computation

Suppose in an iterative deepening search (IDS), in place of increasing the depth by 1 at each step, the depth is increased by 3 at each step then the resultant algorithm will be \*

1 point

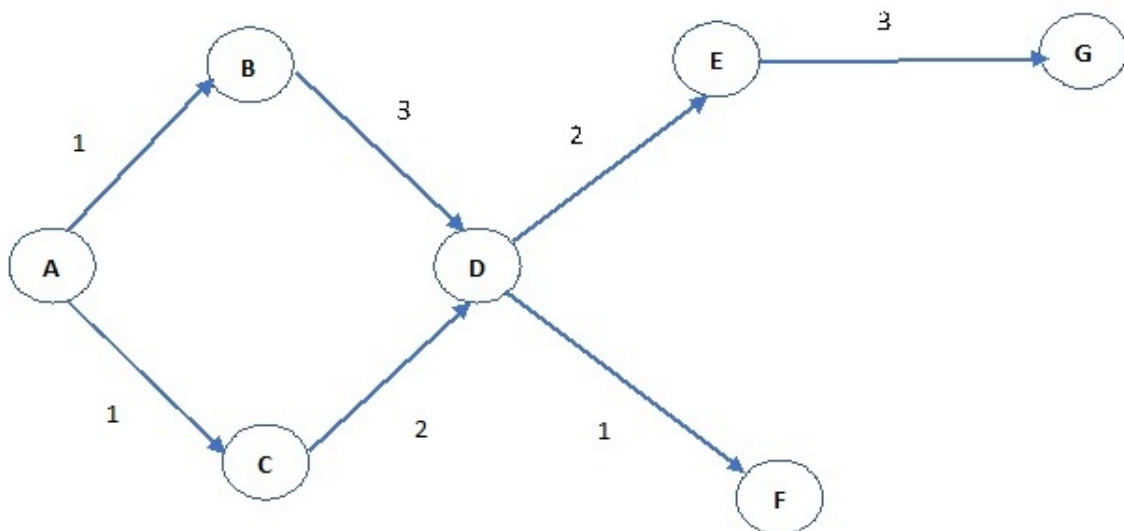
- ☐ Optimal and complete
- ☐ Optimal but not complete
- ☐ Complete but not optimal
- ☐ Same performance as original IDS



Suppose there is only single goal state and the cost at each step is  $c$  ( $c > 0$ ), 1 point  
then which of the following algorithm can be used to solve the problem for a given initial state  $s$  \*

- ☐ Depth first search
- ☐ Breadth first search
- ☐ Uniform cost search
- ☐ Iterative deepening search

For the given directed graph, find the sequence of nodes explored using 2 points  
uniform cost algorithm from state A to state G. The number on the edges represent cost, \*



- ☐ ABDEG
- ☐ Option 2
- ☐ ABCDDFEG
- ☐ ABCDDFEFEG



For two given heuristics  $h_1$  and  $h_2$ , which one of the following is not admissible? \*

1 point

- ☐  $\max(h_1, h_2)$
- ☐  $\min(h_1, h_2)$
- ☐  $(h_1 + h_2)/2$
- ☐ All are admissible

Suppose you know that the value of a particular state in MiniMax tree lies between  $x$  and  $y$  ( $x < y$ ). How can you use this information to optimize alpha-beta pruning \*

1 point

- ☐  $\alpha = x, \beta = y$
- ☐  $\alpha = y, \beta = x$
- ☐ Mark value of all states as  $(x + y)/2$
- ☐ This information cannot be used

There is a perfect evaluation function available at each node such that there is no search required in Minimax algorithm \*

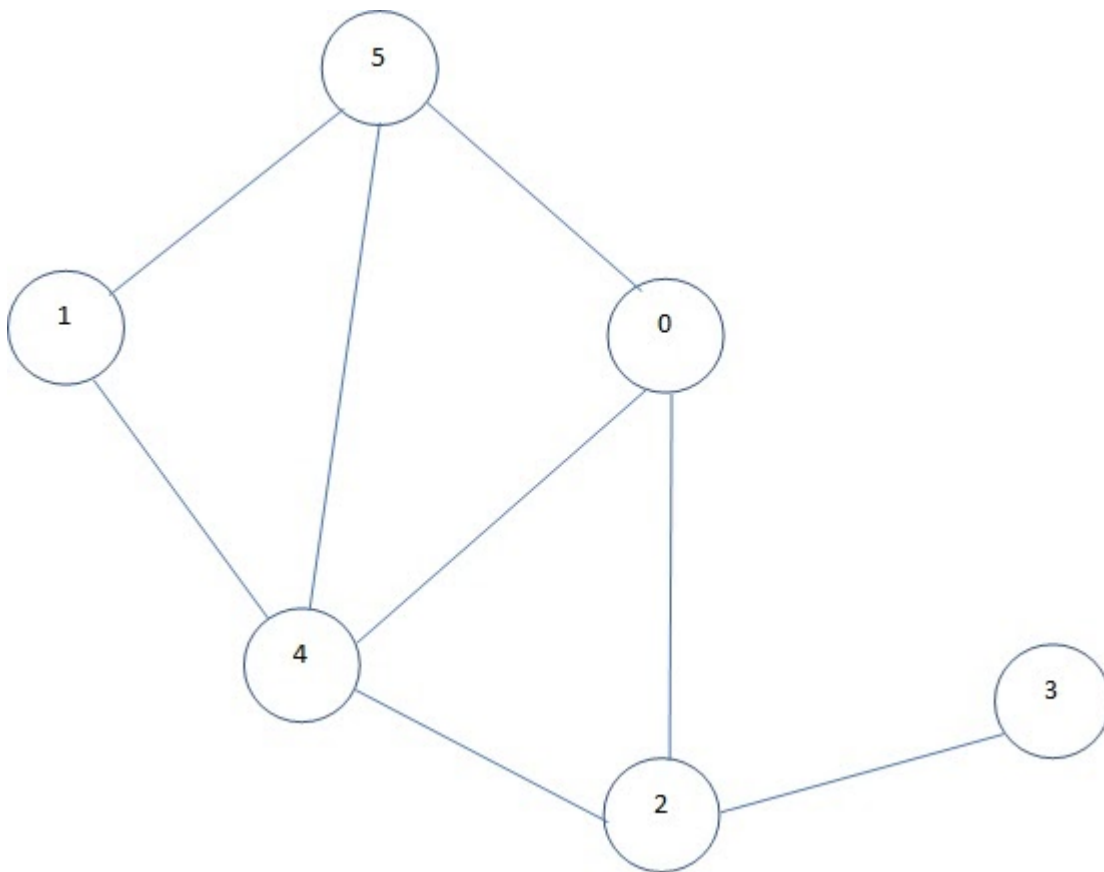
1 point

- ☐ True
- ☐ False



You are given the following constraint graph and your task is to assign the value to each variable. A wise person comes to help you to give you value of a variable. Which variable will you choose? \*

1 point



- ☐ 5
- ☐ 2
- ☐ 0
- ☐ 4



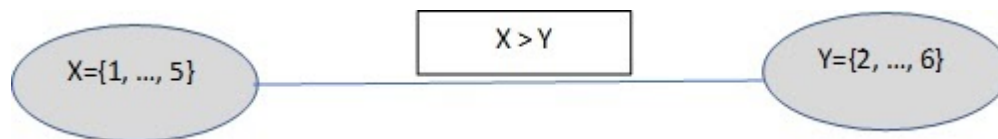
What is the worst case complexity of CSP with  $n$  variables where each variable can take  $d$  values? \*

1 point

- ☐  $O(nd)$
- ☐  $O(n)$
- ☐  $O(n^2 d)$
- ☐  $O(d^n)$

For the following CSP, which of the following statement is true? \*

1 point

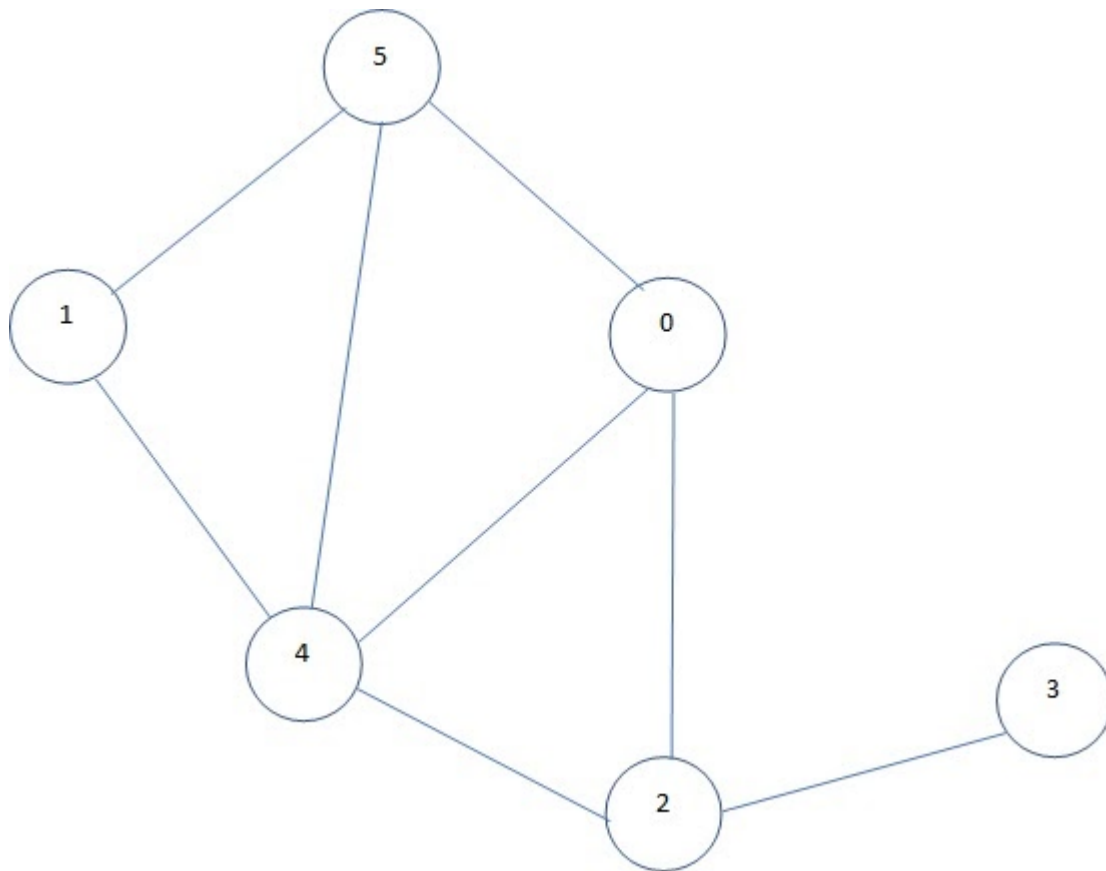


- ☐ The arc is consistent in both direction
- ☐ The arc is not consistent in both direction
- ☐ The arc  $(x,y)$  is consistent but arc  $(y,x)$  is not
- ☐ The arc  $(y,x)$  is consistent but arc  $(x,y)$  not



For the following constraint graph, you need to solve the CSP using minimum remaining value heuristic. Each node can take the value from the set { a, b, c} and nodes connected by an edge needs to have different values. For node tie breaking, a small numbered node is preferred over high numbered node. For the value tie breaking, a is assigned before b and c, b is assigned before c. [Note you can write your answers as, for example, 0=a, 1=a and so on in the given space.] \*

3 points



Your answer

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