

ML/DL for Everyone Season2

with PYTORCH

10-1 Convolution

Code: <https://github.com/deeplearningzerotoall/PyTorch>

Slides: <http://bit.ly/2VrZcWM>

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오늘의 목차

- Convolution?
- Neuron과 Convolution
- Pooling
- 다음시간에는?
- One more Thing!

Convolution?

- 이미지 위에서 stride 값 만큼 filter(kernel)을 이동시키면서 겹쳐지는 부분의 각 원소의 값을 곱해서 모두 더한 값을 출력으로 하는 연산

1	2	3	0	1
0	1	5	1	0
1	0	2	2	1
1	1	2	0	0
1	0	1	1	1

input

1	0	1
0	1	0
1	0	1

filter

8	9	8
8	5	9
6	5	5

output

Convolution?

이미지 위에서 stride 값 만큼 filter(kernel)을 이동시키면서
겹쳐지는 부분의 각 원소의 값을 곱해서 모두 더한 값을 출력으로
하는 연산

1	2	3	0	1
0	1	5	1	0
1	0	2	2	1
1	1	2	0	0
1	0	1	1	1

input

1	0	1
0	1	0
1	0	1

filter

8	9	8
8	5	9
6	5	5

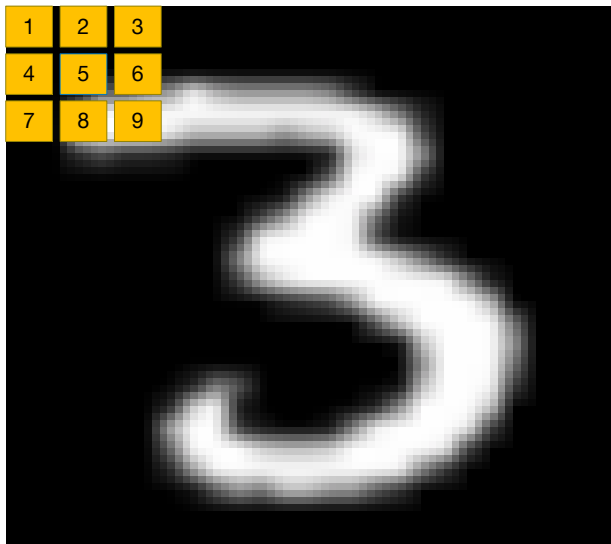
output

1	2	3	1	0	1
0	1	5	0	1	0
1	0	2	1	0	1

8

$$\begin{aligned} &(1 \times 1) + (2 \times 0) + (3 \times 1) + \\ &(0 \times 0) + (1 \times 1) + (5 \times 0) + \\ &(1 \times 1) + (0 \times 0) + (2 \times 1) = 8 \end{aligned}$$

계산해보기



0	0	0
0	0.3	0.5
0	0.8	1

 +

1	2	3
4	5	6
7	8	9

 = 19.9

$$\begin{aligned} & (0 * 1) + (0 * 2) + (0 * 3) + \\ & (0 * 4) + (0.3 * 5) + (0.5 * 6) + \\ & (0 * 7) + (0.8 * 8) + (1 * 9) = 19.9 \end{aligned}$$

Stride and Padding

- stride : filter를 한번에 얼마나 이동 할 것인가
- padding : zero-padding

0	0	0	0	0	0	0
0	1	2	3	0	1	0
0	0	1	5	1	0	0
0	1	0	2	2	1	0
0	1	1	2	0	0	0
0	1	0	1	1	1	0
0	0	0	0	0	0	0

input + padding

Pytorch nn.Conv2d

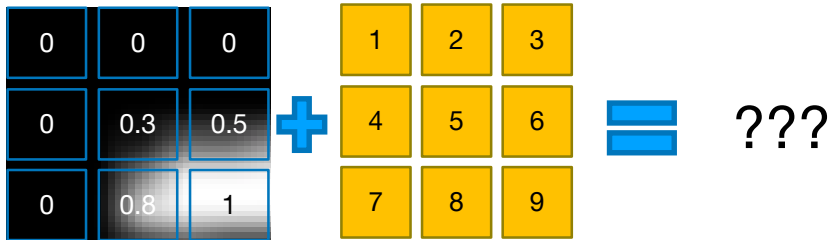
CLASS `torch.nn.Conv2d(in_channels, out_channels, kernel_size, stride=1, padding=0, dilation=1, groups=1, bias=True)`

[\[SOURCE\]](#) 

Applies a 2D convolution over an input signal composed of several input planes.

In the simplest case, the output value of the layer with input size (N, C_{in}, H, W) and output $(N, C_{out}, H_{out}, W_{out})$ can be precisely described as:

$$\text{out}(N_i, C_{out_j}) = \text{bias}(C_{out_j}) + \sum_{k=0}^{C_{in}-1} \text{weight}(C_{out_j}, k) \star \text{input}(N_i, k)$$



ex) 입력 채널 1 / 출력채널 1 / 커널 크기 3x3

`conv = nn.Conv2d(1,1,3)`

입력의 형태

- input type : torch.Tensor
- input shape : (N x C x H x W)

(batch_size, channel, height, width)

직접 해볼까요?

Convolution의 output 크기

$$Output\ size = \frac{input\ size - filter\ size + (2 * padding)}{Stride} + 1$$

예제 1)

input image size : 227 x 227

filter size = 11x11

stride = 4

padding = 0

output image size = ?

예제 2)

input image size : 64 x 64

filter size = 7x7

stride = 2

padding = 0

output image size = ?

예제 3)

input image size : 32 x 32

filter size = 5x5

stride = 1

padding = 2

output image size = ?

예제 4)

input image size : 32 x 64

filter size = 5x5

stride = 1

padding = 0

output image size = ?

예제 5)

input image size : 64 x 32

filter size = 3x3

stride = 1

padding = 1

output image size = ?

Neuron과 Convolution

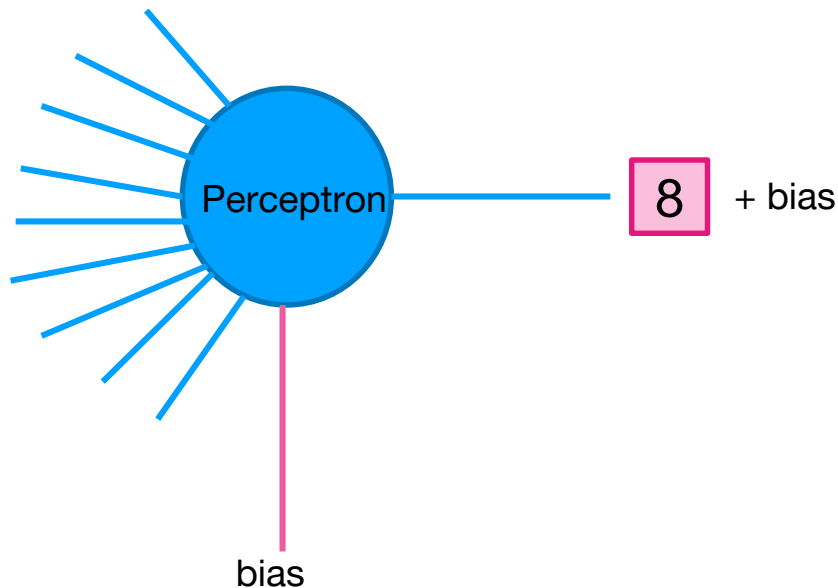
- Perceptron과 Convolution

Convolution filter(=kernel)

1	0	1
0	1	0
1	0	1

1	2	3
0	1	5
1	0	2

1	2	3	0	1
0	1	5	1	0
1	0	2	2	1
1	1	2	0	0
1	0	1	1	1



직접 해볼까요?

- `nn.Conv2d`에 입력
- filter size 변경 (size = 1x1, 3x3, 5x5)
- bias
- stride
- padding

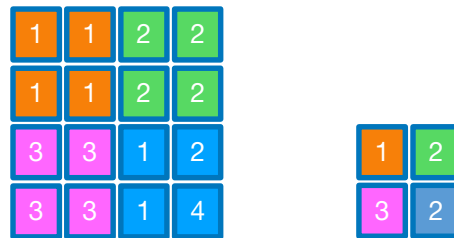
Pooling

- Max Pooling



max pooling

- Average Pooling



Average pooling

MaxPool2d

MaxPool2d [🔗](#)

```
CLASS torch.nn.MaxPool2d(kernel_size, stride=None, padding=0, dilation=1, return_indices=False,  
                           ceil_mode=False)
```

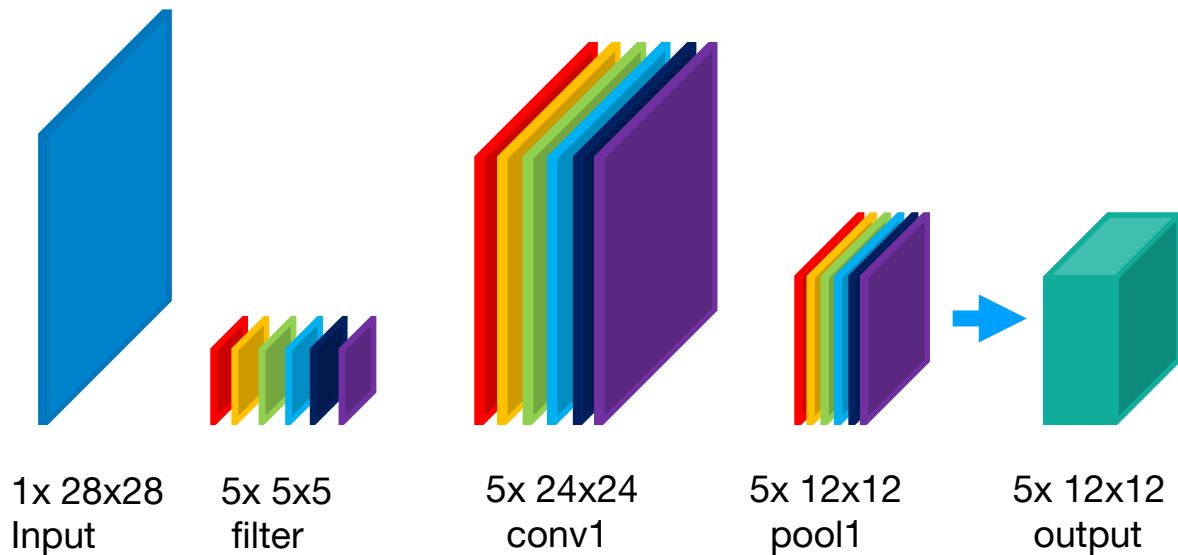
[\[SOURCE\]](#)

Applies a 2D max pooling over an input signal composed of several input planes.

In the simplest case, the output value of the layer with input size (N, C, H, W) , output (N, C, H_{out}, W_{out}) and `kernel_size` (kH, kW) can be precisely described as:

$$\begin{aligned} out(N_i, C_j, h, w) = & \max_{m=0, \dots, kH-1} \max_{n=0, \dots, kW-1} \\ & input(N_i, C_j, stride[0] \times h + m, stride[1] \times w + n) \end{aligned}$$

CNN implementation



```
input = torch.Tensor(1,1,28,28)
```

```
conv1=nn.Conv2d(1,5,5)
```

```
pool = nn.MaxPool2d(2)
```

```
out = conv1(input)
```

```
out2 =pool(out)
```

```
out.size()
```

```
out2.size()
```

직접 해볼까요?

What's Next?

- 오늘은 Convolution 연산과 Pooling 연산을 배우고 직접 활용해봤습니다.
- 다음시간에는 MNIST dataset에 CNN을 적용해보도록 하겠습니다.

One More Thing!

Conv2d

CLASS `torch.nn.Conv2d(in_channels, out_channels, kernel_size, stride=1, padding=0, dilation=1, groups=1, bias=True)`

[SOURCE]

Applies a 2D convolution over an input signal composed of several input planes.

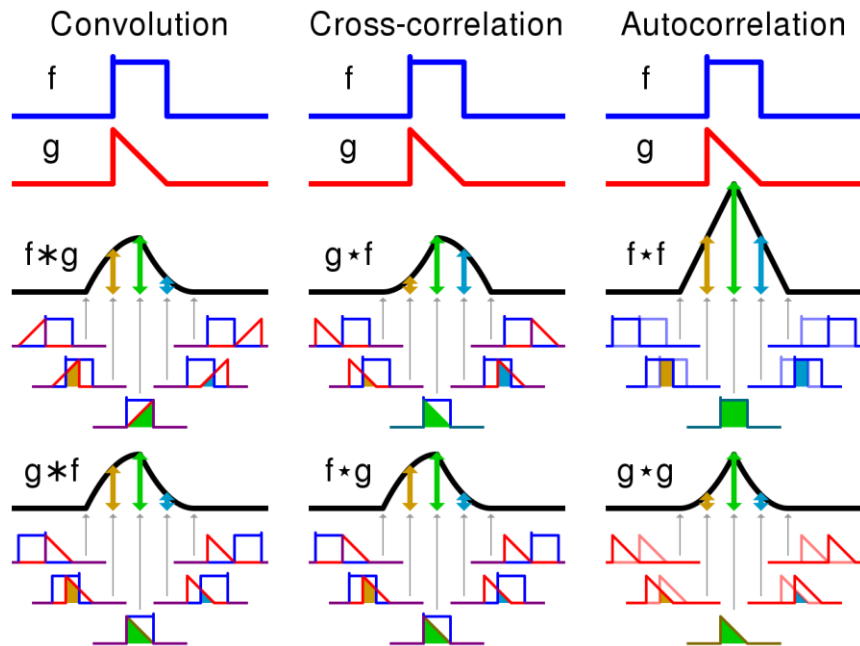
In the simplest case, the output value of the layer with input size (N, C_{in}, H, W) and output $(N, C_{\text{out}}, H_{\text{out}}, W_{\text{out}})$ can be precisely described as:

$$\text{out}(N_i, C_{\text{out}_j}) = \text{bias}(C_{\text{out}_j}) + \sum_{k=0}^{C_{\text{in}}-1} \text{weight}(C_{\text{out}_j}, k) \star \text{input}(N_i, k)$$

where \star is the valid 2D **cross-correlation operator**, N is a batch size, C denotes a number of channels, H is a height of input planes in pixels, and W is width in pixels.

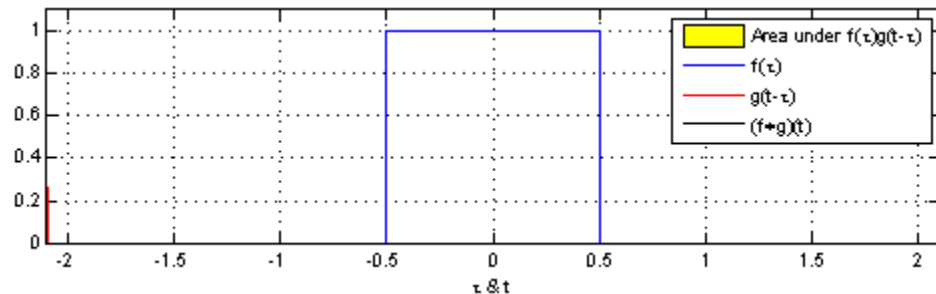
- `stride` controls the stride for the cross-correlation, a single number or a tuple.
- `padding` controls the amount of implicit zero-paddings on both sides for `padding` number of points for each dimension.
- `dilation` controls the spacing between the kernel points; also known as the à trous algorithm. It is harder to describe, but this [link](#) has a nice visualization of what `dilation` does.
- `groups` controls the connections between inputs and outputs. `in_channels` and `out_channels` must both be divisible by `groups`. For example,
 - At `groups=1`, all inputs are convolved to all outputs.
 - At `groups=2`, the operation becomes equivalent to having two conv layers side by side, each seeing half the input channels, and producing half the output channels, and both subsequently concatenated.
 - At `groups= in_channels`, each input channel is convolved with its own set of filters, of size: $\left\lfloor \frac{C_{\text{out}}}{C_{\text{in}}} \right\rfloor$.

What is Convolution?



$$(f * g)(t) \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} f(\tau)g(t - \tau) d\tau$$

$$= \int_{-\infty}^{\infty} f(t - \tau)g(\tau) d\tau.$$



Cross-correlation

- Cross-correlation과 Convolution의 차이를 간단히 말하면...?

- 뒤집고 계산하면 => (Convolution)

- 안 뒤집고 계산하면 => (Cross-Correlation)

- 안 뒤집고 계산해서 Cross-Correlation!

