Fast and user-friendly GLMs with glum 3

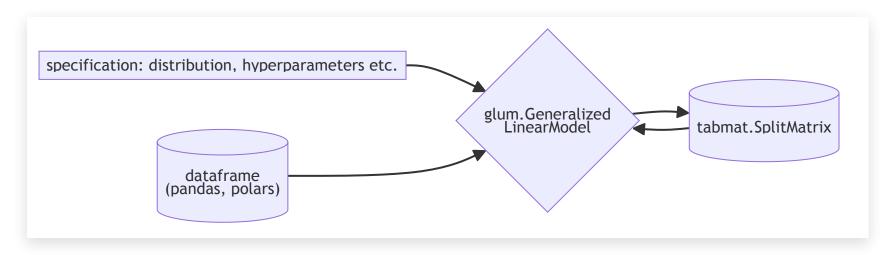
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Glum

- Library for Generalized Linear Models (GLMs).
- Originally built in 2020, when there was no good option to estimate GLMs in Python. Best option was glmnet in R.
- Designed along three principles:
 - Python-first,
 - performant,
 - feature-rich: supporting, among others:
 - L1/L2 regularization,
 - custom regularization matrices (e.g., for spatial smoothing or for penalized splines),
 - o coefficient bounds,
 - efficient cross-validation and regularization path computation,
 - o standard errors, and
 - statistical testing.

Tabmat

• Library with standardized interface for dense, sparse, and categorical matrices.



Plan of the Talk

- Background on GLMs.
- How to compute fast sandwich products with tabmat.
- Formula interface of glum 3.
- Other new features in glum 3.

What is a GLM?

• Exponential Dispersion Model (EDM) with probability density function for observation i:

$$f(y_i \mid \mu_i, \sigma_i^2) = f_0(\sigma_i^2, y_i) \exp\Biggl(rac{ heta_i y_i - b(heta_i)}{\sigma_i^2}\Biggr).$$

- f depends on θ_i only through "exponential tilt."
- Mean is $\mu_i = b'(\theta_i)$ and the variance is $b''(\theta_i)\sigma_i^2$.
- ullet A GLM is an EDM in which a monotone transformation of the mean is a linear function of p predictors,

$$g(\mu_i) = \sum_{j=1}^p x_{ij} eta_j.$$

Matrix operations in GLMs

• β can be estimated by the following equations:

$$\mathbf{X}' \operatorname{diag}(\mathbf{v}(\mu)))(\mathbf{y} - \mu) = 0,$$

- with feature matrix \mathbf{X} , outcome vector \mathbf{y} , and prediction vector μ .
- Derivation: set the score of the log likelihood with respect to β_j to zero and stack results into matrices (see appendix).
- Newton-Raphson requires Fisher information (negative of expected value of Hessian), $\mathbf{X}' \mathrm{diag}(\mathbf{v}) \mathbf{X}$.

Training a GLM quickly

- Various optimizations of solvers in glum:
 - Hyperparameters.
 - Dealing with numerical instabilities, e.g., by standardization.
 - Cythonizing coordinate descent, likelihoods, scores, etc.
- Main speedup is through matrix operations in tabmat:
 - Sandwich products $\mathbf{X}' \mathrm{diag}(\mathbf{v}) \mathbf{X}$ with $n \times p \mathbf{X}$, $n \gg p$.
 - Also matrix-vector products such as $\mathbf{X}\beta$ or cross-products $\mathbf{X}'\mathrm{diag}(\mathbf{v})\mathbf{M}$.
 - A lot of structure can be exploited!

Sandwich product with one-hot-encoded (OHE) categoricals

```
import numpy as np
import pandas as pd
import tabmat as tm
from scipy import sparse
rng = np.random.default rng()
cat = pd.Categorical(rng.integers(low=0, high=200, size=100 000))
X = pd.get dummies(cat)
X.head()
      0
                           3
                                  4
                                        5
                                               6
                                                             8
                                                                    9
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```

5 rows × 200 columns

Naive implementation

```
d = rng.uniform(size=len(cat))
%%timeit
X = pd.get_dummies(cat, dtype="float64").to_numpy()
X.T * d[np.newaxis, :] @ X

130 ms ± 13.3 ms per loop (mean ± std. dev. of 7 runs, 10 loops each)
```

Implementing the dense sandwich product in C++ and other speedups

```
%%timeit

X_dense = tm.DenseMatrix(pd.get_dummies(cat, dtype="float64").to_numpy())

X_dense.sandwich(d)
```

29.8 ms \pm 395 μ s per loop (mean \pm std. dev. of 7 runs, 10 loops each)

Specialized sandwich product for OHE categoricals

```
%*timeit

X_cat = tm.CategoricalMatrix(cat)
X_cat.sandwich(d)
```

92.8 μ s \pm 1.21 μ s per loop (mean \pm std. dev. of 7 runs, 10,000 loops each)

Speeding up sandwich products for OHE categoricals (pseudocode)

- i, j 'th element of sandwich product is sum_k X[k, i] d[k] X[k, j].
- If i != j, sum_k X[k, i] d[k] X[k, j] = 0 because OHE matrices have only one nonzero entry per row.
- For i == j, sandwich(X, d)[i, i] = sum_k X[k, i] d[k], because OHE matrices consist only of zeroes and ones and 1*1=1.
- So sandwich(X, d) = diag(X.T @ d).
- No need to expand the categorical to X. Instead, keep categorical codes in cat, initialize the sandwich matrix with shape (p, p) as zeroes, and compute:

```
for k in range(n):
    i = cat[k]
    sandwich(X, d)[i, i] += d[k]
```

Combining categorical, dense, and sparse matrices

```
dns = rng.normal(size=(100 000, 100))
sps = sparse.random(100 000, 100, density=0.01, random state=rng)
sm = tm.SplitMatrix(
    [tm.CategoricalMatrix(cat), tm.DenseMatrix(dns), tm.SparseMatrix(sps)]
sm.sandwich(d)
 array([[2.62108688e+02, 0.00000000e+00, ..., 7.60231539e-01,
          1.53523965e+00],
         [0.00000000e+00, 2.70724717e+02, ..., 1.49602246e-01,
          1.42353807e+001.
         . . . ,
         [7.60231539e-01, 1.49602246e-01, ..., 1.66799521e+02,
          1.26643752e+001.
         [1.53523965e+00, 1.42353807e+00, ..., 1.26643752e+00,
          1.84677336e+0211)
```

Usually, a tm.SplitMatrix will be initialized via tm.from_(pandas|polars|formula).

GLM building

- Compared to other machine learning algorithms, GLM's require substantial manual preprocessing to get X.
- Manual preprocessing has pros and cons.

Pros	Cons
Modeller learns about main effects in the data.	Time-intensive.
Interpretable, since all effects and interactions were explicitly modelled.	To achieve high predictive performance, complicated transformations and interactions are often needed, harming interpretability.

- Time-tested idea to make GLM model building less time-intensive is to specify models via Wilkinson (1973) formulas: a domain-specific language that captures the essence of a model specification.
- Glum 3 introduces Wilkinson formulas, based on formulaic.

Formulas

```
import formulaic
import glum
from vega datasets import data
cars = data.cars().dropna()
formula = (
    "Miles_per_Gallon ~ {np.log(2.20462 * Weight_in_lbs)} "
    "+ bs(Horsepower, 3) + C(Cylinders) * Origin"
model = glum.GeneralizedLinearRegressor(
    formula=formula, drop first=True, fit intercept=False, family="gamma", alpha=0
model.fit(cars[:380])
model.predict(cars[380:])
```

```
array([18.22549226, 19.73007056, 27.66390534, 17.8747613 , 32.21080938, 27.41974637, 29.19519495, 28.93554487, 28.86996769, 27.100013 , 28.86903563, 28.99728628])
```

Efficient interactions

- tm.from_formula has various speedups for interactions:
 - Sparsity preserving: interaction of sparse and dense columns will always be sparse.
 - Interactions between categoricals are internally represented by one new categorical column.
- Take the following input:

Encoding categorical interactions outside of glum

The following crashes on my computer:

```
X = formulaic.model_matrix("c1 : c2", data=df)
big_model_ext = glum.GeneralizedLinearRegressor(alpha=1).fit(X=X, y=df["y"])

The Kernel crashed while executing code in the current cell or a previou s cell.

Please review the code in the cell(s) to identify a possible cause of the failure.

Click <a href='https://aka.ms/vscodeJupyterKernelCrash'>here</a> for mor e info.

View Jupyter <a href='command:jupyter.viewOutput'>log</a> for further de tails.
```

Encoding categorical interactions internally

Letting glum create the model matrix:

```
big_model = glum.GeneralizedLinearRegressor(formula="y \sim c1 : c2", alpha=1).fit(df big_model.coef_table()
```

```
intercept
                  4.999537e-01
c1[0]:c2[0]
               1.205366e-07
c1[1]:c2[0]
                  5.852428e-07
c1[2]:c2[0]
                 -1.144714e-09
c1[3]:c2[0]
                 -1.398972e-07
c1[195]:c2[199] 8.068055e-07
c1[196]:c2[199]
               -1.201487e-06
c1[197]:c2[199]
               -1.315570e-06
c1[198]:c2[199] 2.831186e-07
c1[199]:c2[199] -5.820133e-07
Name: coef, Length: 40001, dtype: float64
```

Other usability improvements in glum 3

- Missings in categorical can be custom-handled, e.g., as "y \sim C(x1, missing method='zero') + C(x2, missing method='convert')".
- Term names:
 - A term is all columns in the "expanded" matrix pertaining to a single feature prior to expansion (e.g., before OHE).
 - Wald tests can test terms such as "model.wald_test(cars, terms= ["bs(Horsepower, 3)"], r=[0])".
- Wald tests can also be specified with formulas, e.g., model.wald_test(cars, terms="`bs(Horsepower, 3)[1]` = 2 * `bs(Horsepower, 3)[2]`").
- Freely customizable interaction separators and categorical formats.

Want to contribute?

- Try out glum/tabmat for yourself.
- Report bugs through our issue tracker.
- Reach out if you want to contribute a pull request.



Questions?

Appendix

Deriving the score equations of a GLM

One can show that the mean of an EDM is $\mu_i = b'(\theta_i)$ and that the variance is $b''(\theta_i)\sigma_i^2$. Define unit variance $v_i = b''(\theta_i)$.

Log likelihood with respect to θ_i is

$$rac{ heta_i y_i - b(heta_i)}{\sigma_i^2} + ext{constant.}$$

Score of the log likelihood with respect to one β_j for one observation is:

$$egin{aligned} &rac{1}{\sigma_i^2}(y_i-b'(heta_i))rac{\partial heta_i}{\partial\mu_i}rac{\partial\mu_i}{\partialeta_j}\ &=rac{1}{\sigma_i^2}(y_i-\mu_i)rac{1}{v_i}rac{x_{ij}}{g'(\mu_i)}. \end{aligned}$$

Setting to zero and stacking the data into matrices,

$$\mathbf{X}' \operatorname{diag}(\mathbf{v})(\mathbf{y} - \mu) = 0,$$

with
$$\frac{1}{v_i(\mu_i)q'(\mu_i)\sigma_i^2}$$
 in **v**.

Benchmarking the sparse sandwich product

Slower than equivalent code for tm.DenseMatrix because pd.get_dummies appears to slow down when sparse argument is set.

```
%%timeit

X_sparse = tm.SparseMatrix(pd.get_dummies(cat, dtype="float64", sparse=True))
X_sparse.sandwich(d)

118 ms ± 1.14 ms per loop (mean ± std. dev. of 7 runs, 10 loops each)
```

Compare only the tabmat parts:

```
%%timeit
X_sparse.sandwich(d)

275 µs ± 3.7 µs per loop (mean ± std. dev. of 7 runs, 1,000 loops each)

%%timeit
X_dense.sandwich(d)

19.9 ms ± 567 µs per loop (mean ± std. dev. of 7 runs, 100 loops each)
```