```
view_frames Result

Recorded at time: 1754079347.911
```

world

Broadcaster: /Unity_ROS_message_Rx
Average rate: 18.820 Hz
Most recent transform: 1754079347.783 (0.129 sec old)
Buffer length: 4.889 sec

Broadcaster: /tf_node
Average rate: 18.820 Hz
Most recent transform: 1754079347.783 (0.129 sec old)
Buffer length: 4.889 sec

OurCar/INS

odom

Broadcaster: /tf_nominal_center
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1754079347.911 sec old)
Buffer length: 0.000 sec

Broadcaster: /tf_node
Average rate: 18.820 Hz
Most recent transform: 1754079347.783 (0.129 sec old)
Buffer length: 4.889 sec

OurCar/Center

base_link

Broadcaster: /tf_sensors
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1754079347.911 sec old)
Buffer length: 0.000 sec

OurCar/Sensors/SensorBase

Broadcaster: /tf_depth_camera
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1754079347.911 sec old)
Buffer length: 0.000 sec

Broadcaster: /tf_segmentation_camera
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1754079347.911 sec old)
Buffer length: 0.000 sec

Broadcaster: /tf_RGB_camera_left
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1754079347.911 sec old)
Buffer length: 0.000 sec

Broadcaster: /tf_RGB_camera_right
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1754079347.911 sec old)
Buffer length: 0.000 sec

OurCar/Sensors/DepthCamera

OurCar/Sensors/SegCamera

OurCar/Sensors/RGBCameraLeft

OurCar/Sensors/RGBCameraRight