## Seminar 1-2

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1.7 Let  $H_1, H_2, ...$  be be a sequence of finite hypothesis classes from proposition 1.4. To each classifier  $f \in H_k$  we assign weight  $w_f$  from Weighted Halving algorithm.

$$w_f = \frac{1}{k(k+1)|H_k|}$$
 (1)

We decrease weight of each classifier that is mistaken on input  $x_t$  as we did in Weighted Majority algorithm and no classifier is discarded after the mistake.

We define

$$W_t = \sum_{f \in H} w_{f,t} \tag{2}$$

$$F_t = \sum_{\substack{f \in H \\ f(x_t) = y_t}} w_{f,t} \tag{3}$$

where H represents  $H_1 \cup H_2 \cup ...$ . Then the same inequalities hold for the upper bound on  $W_t$  as in Weighted Majority algorithm. After s mistakes we have

$$W_t \le \left(\frac{\beta+1}{2}\right)^s W_1 \tag{4}$$

 $W_1$  is the sum of all weights at the beginning of the algorithm. From the proof of the Weighted Halving algorithm we know that it is equal to 1.

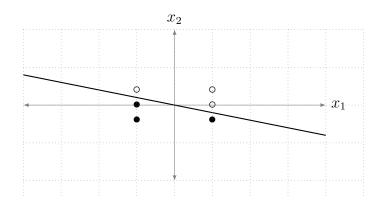
Also, in agnostic setting we have true function  $f^*$  that can make at most  $m^*$  mistakes. Suppose  $f^* \in H_{k^*}$ . Then its weight has been decreased by  $\beta$  at most  $m^*$  times.

$$\frac{\beta^{m*}}{k^*(k^*+1)|H_{k^*}|} \le W_t \tag{5}$$

By taking logarithms from both sides and using bounds from WH and WM algorithms we end up with the bound from the task. Then we assign  $H_k = T_{d,k}$  for all k and  $f^* = T_{d,k^*}$ .

Basically, we operate as in Weighted Majority algorithm with weights from halving variant and partitioning  $H_k$ , so we don't need to know size of a tree in advance.

## **1.8** Let's draw some points from $RN^{-1}(-1)$ and $RN^{-1}(1)$ in $\mathbb{R}^2$ .



We see that line  $x_1 + 2x_2 = 0$  perfectly separates two classes. Let's try to generalize this idea.

Consider strings of length d. We want to find a separating hyperplane of a form  $w_1x_1 + w_2x_2 + \ldots + w_dx_d = 0$ . Let's take  $w = (w_1, \ldots, w_d) = (1, 2, \ldots, 2^{d-1})$  and show why it separates points from different classes. Let  $x = (x_1, x_2, \ldots, x_{l-1}, 1, 0, \ldots, 0) \in RN^{-1}(1), l = 1, \ldots, d$ . Whichever values we set instead of  $x_j$   $j = 1, \ldots, l-1$  dot product with w gives us a positive sign which means x lies above the hyperplane. Because in worst case  $x_j = -1$  for all j the geometric sum with q = 2 equals  $2^l - 1 < 2^l$ . For other combinations of  $x_j$   $2^l$  would be even bigger. So indeed points from the positive class lie above the hyperplane. Symmetrically for the negative class we apply the same idea and all points lie below the hyperplane.

Now let's proof that the Perceptron algorithm makes at least  $\Omega(2^d)$  updates. We know that a vector which is normal to a hyperplane is  $w = (1, 2, \dots, 2^{d-1})$  and we want our algorithm to converge to w. Starting from the zero vector in order to get  $2^{d-1}$  in a last component we must perform at least  $2^{d-1}$  updates, because each coordinate  $|x_i| \leq 1$ , which is exactly  $\Omega(2^d)$ .

**2.9** Let's run SOA and let  $f_1$  to be the classifier we get after Ldim(H) mistakes. Then we predict according to  $f_1$ . If we have a mistake on some new input x, we have two cases. (a) It is a real mistake of classifier  $f_1$ , then it means we've been tricked by Supervisor in a run of SOA. So, we perform another run of SOA, which guarantelly gives us a true classifier  $f_2$ . (b) Or rather Supervisor lies to us on that particular x, then again we end up with the true classifier using prediction strategy of SOA one more time. Anyways, this strategy gives at most 2Ldim(H) + 1 mistakes because we use SOA two times and have one additional mistake.

Remark. If on some step of SOA we receive a non consistent answer with the input we have seen previously, then the algorithm is stopped.