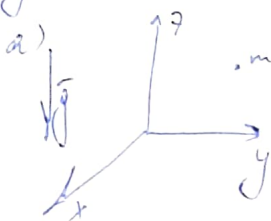


# 

12.4.1



$$\begin{aligned} p_1 &= v \\ p_2 &= y \\ p_3 &= z \end{aligned}$$

$$\Rightarrow H = \frac{p_1^2}{2m} + \frac{p_2^2}{2m} + \frac{p_3^2}{2m} + m g z$$

Угловое Т-Э:  $\frac{\partial S}{\partial t} + \frac{1}{2m} \left( \left( \frac{\partial S}{\partial x} \right)^2 + \left( \frac{\partial S}{\partial y} \right)^2 + \left( \frac{\partial S}{\partial z} \right)^2 \right) + m g z = 0$

Будем искать полный интеграл в виде:

$$S(x, y, z, dx, dy, dz, t) = S_0(t, d) + S_x(x, d) + S_y(y, d) +$$

$$\Rightarrow \frac{\partial S_0}{\partial t} + \frac{1}{2m} \left( \left( \frac{\partial S_x}{\partial x} \right)^2 + \left( \frac{\partial S_y}{\partial y} \right)^2 + \left( \frac{\partial S_z}{\partial z} \right)^2 \right) + m g z = 0 \quad \left( + S_z(z, d) \right)$$

Функции зависят от своих переменных:

$$\begin{cases} \frac{\partial S_x}{\partial x} = dx \\ \frac{\partial S_y}{\partial y} = dy \\ \frac{1}{2m} \left( \frac{\partial S_z}{\partial z} \right)^2 + m g z = dz \\ \frac{\partial S_0}{\partial t} = -dz - \frac{1}{2m} (dx^2 + dy^2) \end{cases}$$

$$S_x = dx \cdot x$$

$$S_y = dy \cdot y$$

$$S_0 = - \left( dz + \frac{dx^2}{2m} + \frac{dy^2}{2m} \right) t$$

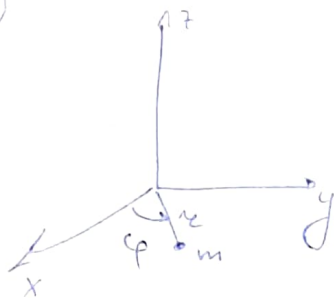
$$S_z = \sqrt{2m} \int \sqrt{dz - m g z} dz = \sqrt{2m} \cdot \left( -\frac{z}{3m g} \right) (dz - m g z)^{3/2}$$

$$S = - \left( dz + \frac{dx^2}{2m} + \frac{dy^2}{2m} \right) t + dx \cdot x + dy \cdot y - \frac{2\sqrt{2m}}{3m g} (dz - m g z)^{3/2}$$

$$\begin{cases} p_x = \frac{\partial S}{\partial dx} = -\frac{dx}{m} t + x \\ p_y = \frac{\partial S}{\partial dy} = -\frac{dy}{m} t + y \\ p_z = \frac{\partial S}{\partial dz} = -t - \frac{\sqrt{2m}}{m g} (dz - m g z)^{1/2} \end{cases}$$

$$\Rightarrow \begin{cases} x(t) = p_x \frac{t}{m} + \frac{dx}{m} t \\ y(t) = p_y \frac{t}{m} + \frac{dy}{m} t \\ z(t) = \frac{dz}{m g} - \frac{g}{2} (p_z + t)^2 \end{cases}$$

5)



$$H = \frac{p_r^2}{2m} + \frac{p_\varphi^2}{2mr^2} + \frac{p_z^2}{2m} + mgyz$$

Углы - Канонические - Импульсы:

$$\frac{\partial S}{\partial t} + \frac{1}{dm} \left[ \left( \frac{\partial S}{\partial r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial S}{\partial \varphi} \right)^2 + \left( \frac{\partial S}{\partial z} \right)^2 \right] + mgyz = 0$$

Будем искать решение уравнения в виде:

$$S = S_0(t, d) + S_r(r, d) + S_\varphi(\varphi, d) + S_z(z, d)$$

$$\frac{\partial S_0}{\partial t} + \frac{1}{dm} \left[ \left( \frac{\partial S_r}{\partial r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial S_\varphi}{\partial \varphi} \right)^2 + \left( \frac{\partial S_z}{\partial z} \right)^2 \right] + mgyz = 0$$

$$\Rightarrow \begin{cases} \frac{1}{2m} \left( \frac{\partial S_z}{\partial z} \right)^2 + mgyz = dz \\ \frac{\partial S_\varphi}{\partial \varphi} = d\varphi \\ \left( \frac{\partial S_r}{\partial r} \right)^2 + \frac{d\varphi}{r^2} = dr \\ \frac{\partial S_0}{\partial t} = -dz = \frac{dr}{dm} \end{cases} \Rightarrow \begin{cases} S_\varphi = d_\varphi \cdot \varphi \\ S_0 = - \left( dz + \frac{1}{dm} dr \right) t \\ S_z = \sqrt{2m} \int \sqrt{dz - mgyz} dz = \\ = \frac{2\sqrt{2m}}{3mgy} (dz - mgyz)^{3/2} \\ S_r = \int \frac{\sqrt{dr^2 - d_\varphi^2}}{r} dr \end{cases}$$

$$\Rightarrow \text{Итак получим: } S = - \left( dz + \frac{dr}{dm} \right) t + d_\varphi \varphi - \frac{2\sqrt{2m}}{3mgy} (dz - mgyz)^{3/2} + \int \frac{\sqrt{dr^2 - d_\varphi^2}}{r} dr$$

$$p_r = \frac{\partial S}{\partial dr} = - \frac{t}{dm} + \int \frac{r}{2\sqrt{dr^2 - d_\varphi^2}} dr = - \frac{t}{dm} + \frac{\sqrt{dr^2 - d_\varphi^2}}{2dr}$$

$$\left( p_r + \frac{t}{dm} \right)^2 \cdot 4dr = r^2 \frac{d\varphi^2}{dr} \Rightarrow r = \sqrt{4dr \left( p_r + \frac{t}{dm} \right)^2 + \frac{d_\varphi^2}{dr}}$$

$$p_z = \frac{\partial S}{\partial dz} = \frac{\sqrt{2m}}{mgy} (dz - mgyz)^{1/2} \Rightarrow z = + \frac{dz}{mgy} - \frac{1}{g} \left( p_z + \frac{t}{dm} \right)^2$$

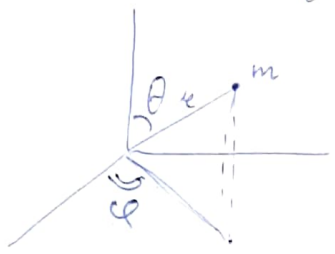
$$p_\varphi = \frac{\partial S}{\partial d_\varphi} = \varphi + \int \frac{1}{r} - \frac{d_\varphi}{\sqrt{dr^2 - d_\varphi^2}} dr = \varphi - d_\varphi \int \frac{1}{r^2} \frac{dr}{\sqrt{dr - \frac{d_\varphi^2}{r^2}}} = \\ = \varphi + d_\varphi \int \frac{d(1/r)}{\sqrt{dr - \frac{d_\varphi^2}{r^2}}} = \varphi + \int \frac{d(\frac{1}{r})}{\sqrt{dr - (\frac{d_\varphi}{r})^2}} = \varphi - \arccos \left( \frac{d_\varphi}{r\sqrt{dr}} \right)$$

$$\cos(\varphi - p_\varphi) = \frac{d_\varphi}{r\sqrt{dr}}$$

224.9

$$\Pi(r) = -\frac{\mu_1}{r} + \frac{\mu_2}{r^2}$$

$$c_\varphi = \text{const} \\ \frac{dc_\varphi}{dt} = 0$$



$$L = \frac{mvr^2}{2} - \Pi(r)$$

$$V^2 = V_r^2 + V_\theta^2 + V_\varphi^2$$

$$V_r = \dot{r} \quad V_\theta = r\dot{\theta} \quad V_\varphi = r\sin\theta\dot{\varphi}$$

$$L = \frac{m}{2} [\dot{r}^2 + r^2\dot{\theta}^2 + r^2\sin^2\theta\dot{\varphi}^2] - \Pi(r)$$

$$\begin{cases} p_r = \frac{\partial L}{\partial \dot{r}} = m\dot{r} \\ p_\theta = \frac{\partial L}{\partial \dot{\theta}} = mr^2\dot{\theta} \\ p_\varphi = \frac{\partial L}{\partial \dot{\varphi}} = mr^2\sin^2\theta\dot{\varphi} \end{cases} \Rightarrow H = \vec{p} \cdot \vec{\dot{q}} - L(\vec{q}, \vec{\dot{q}}, t) = \frac{p_r^2}{2m} + \frac{p_\theta^2}{2mr^2} + \frac{p_\varphi^2}{2mr^2\sin^2\theta} - \left(\frac{\mu_1}{r} + \frac{\mu_2}{r^2}\right)$$

Уг. е. Г-л:  $\frac{\partial S}{\partial t} + \frac{1}{2m} \left[ \left(\frac{\partial S}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial S}{\partial \theta}\right)^2 + \frac{1}{r^2\sin^2\theta} \left(\frac{\partial S}{\partial \varphi}\right)^2 \right] - \frac{\mu_1}{r} + \frac{\mu_2}{r^2} = 0$

Разделяем переменные:  $S = S_0(t, d) + S_r(r, d) + S_\theta(\theta, d) + S_\varphi(\varphi, d)$

$$\frac{\partial S_0}{\partial t} + \frac{1}{2m} \left[ \left(\frac{\partial S_r}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial S_\theta}{\partial \theta}\right)^2 + \frac{1}{r^2\sin^2\theta} \left(\frac{\partial S_\varphi}{\partial \varphi}\right)^2 \right] - \frac{\mu_1}{r} + \frac{\mu_2}{r^2} = 0$$

Угловой момент, т.е.  $\frac{\partial S_\varphi}{\partial \varphi} = d_\varphi = 0 \Rightarrow$   
 $\Rightarrow \frac{\partial S_0}{\partial t} + \frac{1}{2m} \left[ \left(\frac{\partial S_r}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial S_\theta}{\partial \theta}\right)^2 \right] - \frac{\mu_1}{r} + \frac{\mu_2}{r^2} = 0$

$$\begin{cases} \frac{\partial S_0}{\partial \theta} = d_\theta \\ \frac{1}{2m} \left[ \left(\frac{\partial S_r}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial S_\theta}{\partial \theta}\right)^2 \right] - \frac{\mu_1}{r} + \frac{\mu_2}{r^2} = d_r \\ \frac{\partial S_0}{\partial t} = -d_r \end{cases} \Rightarrow \begin{aligned} S_0 &= d_\theta \theta \\ S_r &= -d_r t \\ S_\theta &= \int \sqrt{2m(d_r + \frac{\mu_1}{r} - \frac{\mu_2}{r^2}) - \frac{d_\theta^2}{r^2}} dr \\ S &= -d_r t + d_\theta \theta + \int \sqrt{2m(d_r + \frac{\mu_1}{r} - \frac{\mu_2}{r^2}) - \frac{d_\theta^2}{r^2}} dr \end{aligned}$$

Углы  $\varphi = p_\varphi$

$$p_r = \frac{\partial S}{\partial d_r} = -t + \int \frac{m}{\sqrt{2m(d_r + \frac{\mu_1}{r} - \frac{\mu_2}{r^2}) - \frac{d_\theta^2}{r^2}}} dr$$

Найдем  $r(t)$ :

$$p_\theta = \frac{\partial S}{\partial d_\theta} = \theta + \int \frac{-d_\theta/r^2}{\sqrt{2m(d_r + \frac{\mu_1}{r} - \frac{\mu_2}{r^2}) - \frac{d_\theta^2}{r^2}}} dr = \theta + \int \frac{d}{\sqrt{2m(d_r + \frac{\mu_1}{r} - \frac{\mu_2}{r^2}) - \frac{d_\theta^2}{r^2}}} dr$$

$$= \left| \begin{aligned} u &= \frac{1}{r} \\ a &= 2m\mu_2 + d_\theta^2 \\ b &= 2m\mu_1 \\ c &= 2md_r \end{aligned} \right| = \theta + d_\theta \int \frac{du}{\sqrt{c + bu - au^2}} = \theta + d_\theta \int \frac{du}{\sqrt{c - a(u^2 - \frac{b}{a}u + \frac{c}{a}) + \frac{b^2}{4a}}} =$$

$$= \theta + da \int \frac{du}{\sqrt{\left(\frac{b^2}{4a^2} - a\left(u - \frac{b}{2a}\right)\right)^2}} = \theta + \frac{da}{\sqrt{a}} \int \frac{d(u - \frac{b}{2a})}{\sqrt{\frac{b^2 + 4ac}{4a^2} - \left(u - \frac{b}{2a}\right)^2}} =$$

$$= \theta - \frac{da}{\sqrt{a}} \arccos \left[ \frac{u - \frac{b}{2a}}{\frac{\sqrt{b^2 + 4ac}}{2a}} \right]$$

$$\frac{u \cdot 2a - b}{\sqrt{b^2 + 4ac}} = \cos \left/ \frac{\sqrt{a}}{da} (\theta - \theta_0) \right)$$

$$\frac{1}{r} = u = \frac{b}{2a} + \frac{\sqrt{b^2 + 4ac}}{2a} \cos \left/ \frac{\sqrt{a}}{da} (\theta - \theta_0) \right)$$

$$r(\theta) = \frac{2a/b}{1 + \sqrt{1 + \frac{4ac}{b^2}} \cos \left/ \frac{\sqrt{a}}{da} (\theta - \theta_0) \right)}$$

Пересоберём:

$$p = \frac{2a}{b} = \frac{2m\mu_2 + da^2}{m\mu_1}$$

$$e = \sqrt{1 + \frac{4ac}{b^2}} = \sqrt{1 + 2m dr \frac{m\mu_2 + da^2}{(m\mu_1)^2}}$$

$$w = \frac{\sqrt{a}}{da} = \sqrt{1 + \frac{2m\mu_2}{da^2}}$$

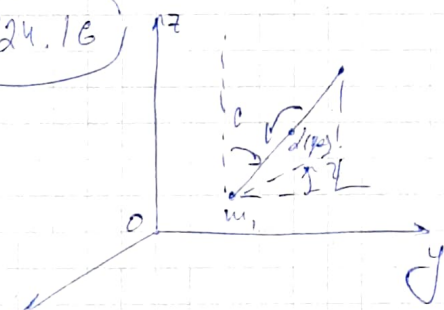
$$\theta_0 = \theta_2$$

$$u(\theta) = \frac{p}{1 + e \cos(w(\theta - \theta_0))}$$

$$\frac{p_{n+1}}{m} = \int \frac{dr}{\sqrt{2m(dr + \frac{\mu_1}{r} - \frac{\mu_2}{r^2}) \cdot \frac{da^2}{r^2}}}$$

из этого  
можно  
выразить  $r(r)$

124.16



Углы  $\varphi, \psi, \theta$ :

$\mu = \frac{m_1 m_2}{m_1 + m_2}$  - приведённая масса

$$H = \frac{1}{2(m_1 + m_2)} (p_x^2 + p_y^2 + p_z^2) +$$

$$+ \frac{1}{2\mu} \left[ p_r^2 + \frac{1}{r^2} p_\theta^2 + \frac{1}{r^2 \sin^2 \theta} p_\varphi^2 \right] - \frac{\gamma_{m_1 m_2}}{r}$$

$$\frac{\partial S}{\partial t} + \frac{1}{2(m_1 + m_2)} \left[ \left( \frac{\partial S}{\partial x} \right)^2 + \left( \frac{\partial S}{\partial y} \right)^2 + \left( \frac{\partial S}{\partial z} \right)^2 \right] + \frac{1}{2\mu} \left[ \left( \frac{\partial S}{\partial r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial S}{\partial \theta} \right)^2 + \frac{1}{r^2 \sin^2 \theta} \left( \frac{\partial S}{\partial \varphi} \right)^2 \right] - \frac{\gamma_{m_1 m_2}}{r} = 0.$$

Разложим в ряд Тейлора:



$$S = S_0(t, d) + S_x(x, d) + S_y(y, d) + S_z(z, d) + S_\phi(\phi, d) + S_\theta(\theta, d) + S_\gamma(\gamma, d)$$

$$\frac{\partial S_0}{\partial t} + \frac{1}{2(m_1+m_2)} \left[ \left( \frac{\partial S_x}{\partial x} \right)^2 + \left( \frac{\partial S_y}{\partial y} \right)^2 + \left( \frac{\partial S_z}{\partial z} \right)^2 \right] + \frac{1}{2\mu} \left[ \left( \frac{\partial S_\phi}{\partial \phi} \right)^2 + \frac{1}{r^2} \left( \frac{\partial S_\theta}{\partial \theta} \right)^2 + \frac{1}{r^2 \sin^2 \theta} \left( \frac{\partial S_\gamma}{\partial \gamma} \right)^2 \right] - \frac{g_{m_1, m_2}}{r} = 0$$

$$\left\{ \begin{array}{l} \frac{\partial S_x}{\partial x} = d_x \\ \frac{\partial S_y}{\partial y} = d_y \\ \frac{\partial S_z}{\partial z} = d_z \\ \frac{\partial S_\phi}{\partial \phi} = d_\phi \\ \frac{\partial S_\theta}{\partial \theta} = d_\theta \\ \frac{1}{2\mu} \left[ \left( \frac{\partial S_\theta}{\partial \theta} \right)^2 + \frac{d_\gamma^2}{\sin^2 \theta} \right] = d_\theta \\ \frac{1}{2\mu} \left[ \left( \frac{\partial S_\gamma}{\partial \gamma} \right)^2 + \frac{d_\theta^2}{\sin^2 \theta} \right] - \frac{g_{m_1, m_2}}{r} = d_\gamma \\ \frac{\partial S_0}{\partial t} = - \frac{d_x^2 + d_y^2 + d_z^2}{2(m_1+m_2)} - d_\phi \end{array} \right.$$

$$\Rightarrow \left\{ \begin{array}{l} S_x = d_x x \\ S_y = d_y y \\ S_z = d_z z \\ S_\phi = d_\phi \phi \\ S_\theta = \int \sqrt{d_\theta^2 - \frac{d_\gamma^2}{\sin^2 \theta}} d\theta \\ S_r = \int \sqrt{2\mu dr + \frac{2\mu g_{m_1, m_2}}{r} - \frac{d_\theta^2}{r^2}} dr \\ S_0 = - \left( \frac{d_x^2 + d_y^2 + d_z^2}{2(m_1+m_2)} + d_\phi \right) t \end{array} \right.$$

$$\Rightarrow S = - \left( \frac{d_x^2 + d_y^2 + d_z^2}{2(m_1+m_2)} + d_\phi \right) t + d_x x + d_y y + d_z z + d_\phi \phi + \int \sqrt{d_\theta^2 - \frac{d_\gamma^2}{\sin^2 \theta}} d\theta + \int \sqrt{2\mu dr + \frac{2\mu g_{m_1, m_2}}{r} - \frac{d_\theta^2}{r^2}} dr$$

$$p_x = \frac{\partial S}{\partial d_x} = - \frac{d_x}{m_1+m_2} t + x$$

$$p_y = \frac{\partial S}{\partial d_y} = - \frac{d_y}{m_1+m_2} t + y$$

$$p_z = \frac{\partial S}{\partial d_z} = - \frac{d_z}{m_1+m_2} t + z$$

$$p_\phi = \frac{\partial S}{\partial d_\phi} = - t + \phi + \int \frac{A dr}{\sqrt{2\mu dr + \frac{2\mu g_{m_1, m_2}}{r} - \frac{d_\theta^2}{r^2}}}$$

$$p_\theta = \frac{\partial S}{\partial d_\theta} = \int \frac{d\theta}{2\sqrt{d_\theta^2 - \frac{d_\gamma^2}{\sin^2 \theta}}} - \frac{1}{2} \int \frac{dr}{r^2 \sqrt{2\mu dr + \frac{2\mu g_{m_1, m_2}}{r} - \frac{d_\theta^2}{r^2}}}$$

$$p_\gamma = \frac{\partial S}{\partial d_\gamma} = \gamma - \int \frac{d\gamma}{\sin^2 \theta \sqrt{d_\theta^2 - \frac{d_\gamma^2}{\sin^2 \theta}}}$$

12433

$$H = p_1 q_2 + p_2 q_1$$

преобразование:

$$\begin{cases} q_1 = \tilde{q}_1 + \tilde{q}_2 \\ q_2 = \tilde{p}_1 - \tilde{p}_2 \\ p_1 = \tilde{p}_1 + \tilde{p}_2 \\ p_2 = \tilde{q}_2 - \tilde{q}_1 \end{cases} \Rightarrow \begin{cases} \tilde{p}_1 = \frac{1}{2}(p_1 + q_2) \\ \tilde{p}_2 = \frac{1}{2}(p_1 - q_2) \\ \tilde{q}_1 = \frac{1}{2}(q_1 - p_2) \\ \tilde{q}_2 = \frac{1}{2}(q_1 + p_2) \end{cases}$$

Докажем каноничность преобразования:

$$\tilde{p}_1 \delta \tilde{q}_1 + \tilde{p}_2 \delta \tilde{q}_2 = c p_1 \delta \tilde{q}_1 + c p_2 \delta \tilde{q}_2 - \delta F$$

$$\frac{1}{4}(p_1 + q_2)(\delta q_1 - \delta p_2) + \frac{1}{4}(p_1 - q_2)(\delta q_1 + \delta p_2) = c p_1 \delta q_1 + c p_2 \delta q_2 - \delta F$$

$$\begin{cases} \delta q_1: & \frac{p_1}{2} = c p_1 - \frac{\delta F}{\delta q_1} \\ \delta q_2: & 0 = c p_2 - \frac{\delta F}{\delta q_2} \\ \delta p_1: & 0 = -\frac{\delta F}{\delta p_1} \\ \delta p_2: & -\frac{q_2}{2} = -\frac{\delta F}{\delta p_2} \end{cases} \Rightarrow \begin{cases} \frac{\delta F}{\delta q_1} = (c - \frac{1}{2})p_1 \\ \frac{\delta F}{\delta q_2} = c p_2 \\ \frac{\delta F}{\delta p_1} = 0 \\ \frac{\delta F}{\delta p_2} = \frac{q_2}{2} \end{cases} \Rightarrow \text{при } c = \frac{1}{2} \\ \delta F = \frac{p_2 q_2}{2}, \\ \text{уравн. теор.} \\ \Rightarrow \text{преобр. каноническое.}$$

$$\Rightarrow \tilde{H} = \frac{1}{2} H = \frac{1}{2} [\tilde{p}_1^2 - \tilde{p}_2^2 + \tilde{q}_1^2 - \tilde{q}_2^2]$$

$$\text{Уф.-е Т-Я: } \frac{\partial \tilde{S}}{\partial t} + \frac{1}{2} \left[ \left( \frac{\partial \tilde{S}}{\partial \tilde{q}_1} \right)^2 - \left( \frac{\partial \tilde{S}}{\partial \tilde{q}_2} \right)^2 + \tilde{q}_1^2 - \tilde{q}_2^2 \right] = 0$$

Введем переменные:  $\tilde{S} = \tilde{S}_0(t, d) + \tilde{S}_1(\tilde{q}_1, t) + \tilde{S}_2(\tilde{q}_2, t)$

$$\frac{\partial \tilde{S}_0}{\partial t} + \frac{1}{2} \left[ \left( \frac{\partial \tilde{S}_1}{\partial \tilde{q}_1} \right)^2 - \tilde{q}_1^2 \right] - \frac{1}{2} \left[ \left( \frac{\partial \tilde{S}_2}{\partial \tilde{q}_2} \right)^2 - \tilde{q}_2^2 \right] = 0$$

$$\begin{cases} \frac{1}{2} \left[ \left( \frac{\partial \tilde{S}_1}{\partial \tilde{q}_1} \right)^2 - \tilde{q}_1^2 \right] = d_1 \\ \frac{1}{2} \left[ \left( \frac{\partial \tilde{S}_2}{\partial \tilde{q}_2} \right)^2 - \tilde{q}_2^2 \right] = d_2 \\ \frac{\partial \tilde{S}_0}{\partial t} = d_2 - d_1 \end{cases} \Rightarrow \begin{cases} \tilde{S}_1 = \int \sqrt{2d_1 + \tilde{q}_1^2} d\tilde{q}_1 \\ \tilde{S}_2 = \int \sqrt{2d_2 + \tilde{q}_2^2} d\tilde{q}_2 \\ \tilde{S}_0 = (d_2 - d_1)t \end{cases}$$

$$\Rightarrow p_1 = \frac{\partial \tilde{S}}{\partial d_1} = -t + \int \frac{d\tilde{q}_1}{\sqrt{2d_1 + \tilde{q}_1^2}} = -t + \text{arctanh} \left( \frac{\tilde{q}_1}{\sqrt{2d_1}} \right)$$

$$\tilde{q}_1 = \sqrt{2d_1} \tanh(p_1 + t)$$

$$p_2 = \frac{\partial \tilde{S}}{\partial d_2} = -t - \int \frac{d\tilde{q}_2}{\sqrt{2d_2 + \tilde{q}_2^2}} = -t - \text{arctanh} \left( \frac{\tilde{q}_2}{\sqrt{2d_2}} \right)$$

$$\tilde{q}_2 = \sqrt{2d_2} \tanh(p_2 + t)$$

$$\tilde{H} = \frac{1}{2} (\tilde{p}_1^2 - \tilde{p}_2^2 + \tilde{q}_2^2 - \tilde{q}_1^2)$$

$$\left\{ \begin{array}{l} \tilde{q}_1 = \frac{\partial \tilde{H}}{\partial \tilde{p}_1} = \tilde{p}_1 \\ \tilde{q}_2 = \frac{\partial \tilde{H}}{\partial \tilde{p}_2} = -\tilde{p}_2 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} \tilde{p}_1 = c_1 \operatorname{ch}(p_1 + t) \\ \tilde{p}_2 = -c_2 \operatorname{ch}(p_2 + t) \\ \tilde{q}_1 = c_1 \operatorname{sh}(p_1 + t) \\ \tilde{q}_2 = c_2 \operatorname{sh}(p_2 + t) \end{array} \right.$$

Враменистый репер:

$$\left\{ \begin{array}{l} q_1 = c_1 \operatorname{sh}(p_1 + t) + c_2 \operatorname{sh}(p_2 + t) \\ q_2 = c_1 \operatorname{ch}(p_1 + t) + c_2 \operatorname{ch}(p_2 + t) \\ p_1 = c_1 \operatorname{ch}(p_1 + t) - c_2 \operatorname{ch}(p_2 + t) \\ p_2 = -c_1 \operatorname{sh}(p_1 + t) + c_2 \operatorname{sh}(p_2 + t) \end{array} \right.$$

(24.42)  $H = p_1^2 + q_1^2 + \frac{p_2^2 + p_3^2}{q_2^2 + q_3^2}$

$$y_f = c \quad T = S: \quad \frac{\partial S}{\partial t} + \left( \frac{\partial S}{\partial q_1} \right)^2 + q_1^2 + \frac{\left( \frac{\partial S}{\partial q_2} \right)^2 + \left( \frac{\partial S}{\partial q_3} \right)^2}{q_2^2 + q_3^2} = 0.$$

Разрешение уравнения:

$$S = S_0(t, d) + S_1(q_1, d) + S_2(q_2, d) + S_3(q_3, d)$$

$$\frac{\partial S_0}{\partial t} + \frac{\left( \frac{\partial S_1}{\partial q_1} \right)^2 + q_1^2 + \left( \frac{\partial S_2}{\partial q_2} \right)^2 + \left( \frac{\partial S_3}{\partial q_3} \right)^2}{q_2^2 + q_3^2} = 0$$

$$\frac{\partial S_0}{\partial t} = -h$$

$$\left( \frac{\partial S_1}{\partial q_1} \right)^2 + q_1^2 = d_1$$

$$\left( \frac{\partial S_2}{\partial q_2} \right)^2 - (h - d_1) q_2^2 + \left( \frac{\partial S_3}{\partial q_3} \right)^2 - (h - d_1) q_3^2 = 0.$$

$$S_0 = -ht$$

$$S_1 = \int \sqrt{d_1 - q_1^2} dq_1$$

$$\left( \frac{\partial S_2}{\partial q_2} \right)^2 - (h - d_1) q_2^2 = d_{23}$$

$$\left( \frac{\partial S_3}{\partial q_3} \right)^2 - (h - d_1) q_3^2 = -d_{23}$$

$$S_0 = -ht$$

$$S_1 = \int \sqrt{d_1 - q_1^2} dq_1$$

$$S_2 = \int \sqrt{(h - d_1) q_2^2 + d_{23}} dq_2$$

$$S_3 = \int \sqrt{(h - d_1) q_3^2 - d_{23}} dq_3$$

$$S = -ht + \int \sqrt{d_1 - q_1^2} dq_1 + \int \sqrt{(h - d_1) q_2^2 + d_{23}} dq_2 + \int \sqrt{(h - d_1) q_3^2 - d_{23}} dq_3$$



$$\Rightarrow 2p_1 = 2 \frac{\partial S}{\partial d_1} = \int \frac{dq_1}{\sqrt{d_1 - q_1^2}} - \int \frac{q_2^2 dq_2}{\sqrt{(h-d_1)q_2^2 + d_{23}}} - \int \frac{q_3^2 dq_3}{\sqrt{(h-d_1)q_3^2 - d_{23}}}$$

$$2p_{23} = 2 \frac{\partial S}{\partial d_{23}} = \int \frac{dq_2}{\sqrt{(h-d_1)q_2^2 + d_{23}}} - \int \frac{dq_3}{\sqrt{(h-d_1)q_3^2 - d_{23}}}$$

$$2(p_1 + p_{23}) = \int \frac{q_1^2 dq_1}{\sqrt{(h-d_1)q_1^2 + d_{23}}} + \int \frac{q_3^2 dq_3}{\sqrt{(h-d_1)q_3^2 - d_{23}}}$$