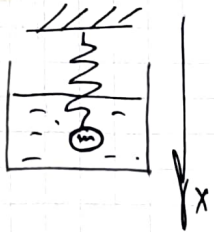


Heures 6

W18.5

m, c
 $-p\dot{x}$



$$m\ddot{x} + p\dot{x} + cx = m\ddot{y}$$

$$\hat{g} = \hat{h} \cdot e^{i\omega t} \Rightarrow (-m\omega^2 + i\omega p + c)\hat{h} = m\ddot{y} e^{i\omega t}$$

$$(-\omega^2 + i\omega \frac{p}{m} + \frac{c}{m})\hat{h} = g e^{i\omega t}$$

$$D(i\omega) = -\omega^2 + i\omega \frac{p}{m} + \frac{c}{m}$$

$$W(i\omega) = \frac{1}{D(i\omega)} = \frac{1}{-\omega^2 + i\omega \frac{p}{m} + \frac{c}{m}} \quad - A\varphi x$$

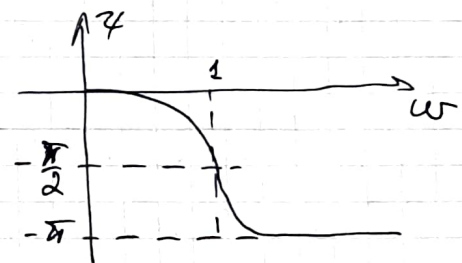
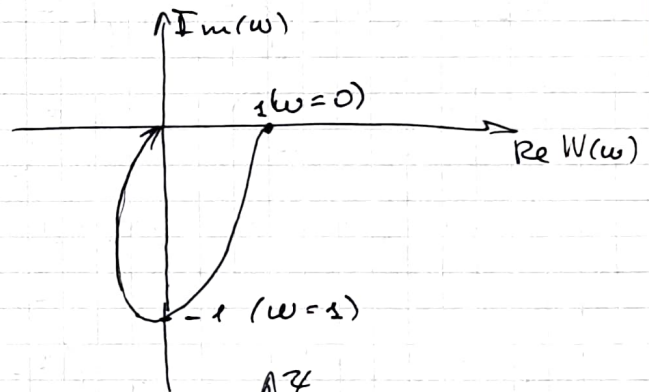
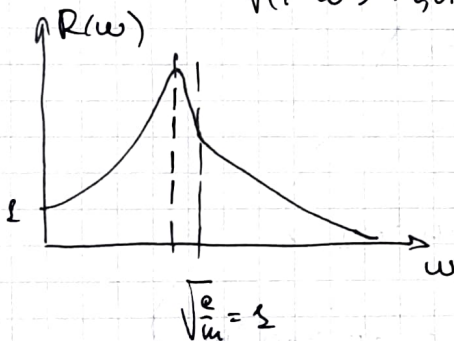
$$R(i\omega) = \frac{1}{\sqrt{(\frac{c}{m} - \omega^2)^2 + (\omega \frac{p}{m})^2}} \quad - A\varphi x$$

$$\varphi = \arg W(i\omega)$$

a) $\frac{c}{m} = 1; \frac{p}{m} = 0,1$

$$D(i\omega) = -\omega^2 + i \cdot 0,1\omega + 1 \Rightarrow W(i\omega) = \frac{1}{1 - \omega^2 + i \cdot 0,1\omega}$$

$$R(i\omega) = \frac{1}{\sqrt{(1 - \omega^2)^2 + 0,01\omega^2}}$$

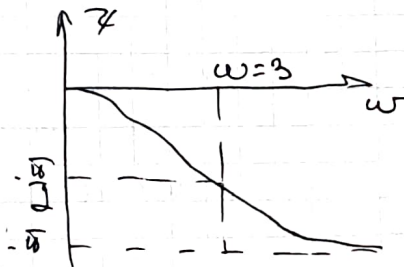
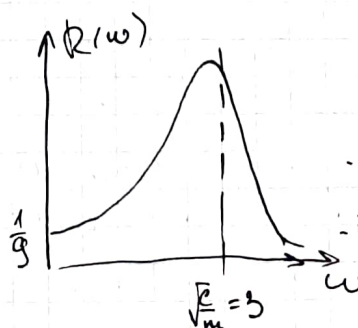
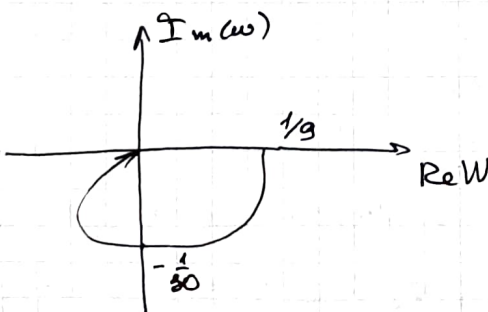


b) $\frac{c}{m} = 9; \frac{p}{m} = 10$

$$\Rightarrow D(i\omega) = -\omega^2 + 10i\omega + 9$$

$$W(i\omega) = \frac{1}{(9 - \omega^2) + 10i\omega}$$

$$R(i\omega) = \frac{1}{\sqrt{(9 - \omega^2)^2 + 100\omega^2}}$$

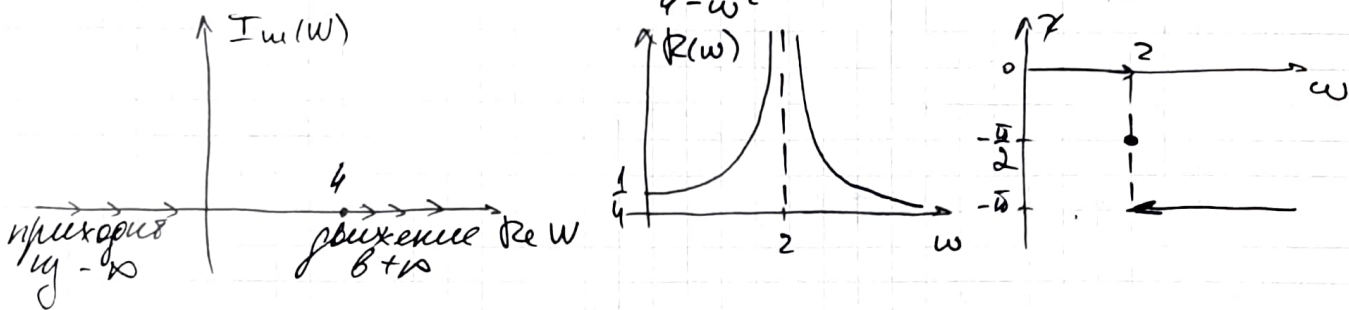


b) $\frac{c}{m} = 4, \beta = 0$

$\Rightarrow D(\omega) = -\omega^2 + 4$

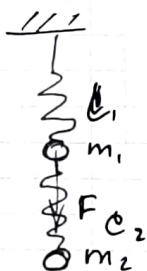
$R(\omega) = \frac{1}{|4 - \omega^2|}$

$W(\omega) = \frac{1}{4 - \omega^2}$



18.25

m_1, m_2
 c_1, c_2
 $F(t) = a \sin t$
 $A_{m1} = a \sin t$



$q = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

$A\ddot{q} + B\dot{q} + Cq = \begin{pmatrix} a \\ 0 \end{pmatrix} \sin t - g \begin{pmatrix} m_1 \\ m_2 \end{pmatrix}$

$T = \frac{m_1 \dot{x}_1^2}{2} + \frac{m_2 \dot{x}_2^2}{2}$

$\Pi = \frac{c_1 x_1^2}{2} + \frac{c_2 (x_1 - x_2)^2}{2} = \frac{(c_1 + c_2)x_1^2}{2} -$

$- c_2 x_1 x_2 + \frac{c_2 x_2^2}{2} = \frac{1}{2} ((c_1 + c_2)x_1^2 - 2c_2 x_1 x_2 + c_2 x_2^2)$

$\Rightarrow A = \begin{pmatrix} m_1 & 0 \\ 0 & m_2 \end{pmatrix} \quad C = \begin{pmatrix} c_1 + c_2 & -c_2 \\ -c_2 & c_2 \end{pmatrix}$

$D(\omega) = C - \omega^2 A = \begin{pmatrix} (c_1 + c_2) - \omega^2 m_1 & -c_2 \\ -c_2 & c_2 - \omega^2 m_2 \end{pmatrix}$

$W = D^{-1}(\omega) = \frac{1}{\det D(\omega)} \begin{pmatrix} c_2 - \omega^2 m_2 & c_2 \\ c_2 & (c_1 + c_2) - \omega^2 m_1 \end{pmatrix} =$

$= \frac{1}{(c_2 - \omega^2 m_2)(c_1 + c_2 - \omega^2 m_1) - c_2^2} \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$

$q = \pi \sin t - g C^{-1} \begin{pmatrix} \omega_1 \\ \omega_2 \end{pmatrix}$

$D(\omega) \cdot h \cdot \sin t = \begin{pmatrix} a \\ 0 \end{pmatrix} \sin t \Rightarrow h = W(\omega) \cdot \begin{pmatrix} a \\ 0 \end{pmatrix}$

$\Rightarrow h = \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} \begin{pmatrix} a \\ 0 \end{pmatrix}$

\Rightarrow резонанс $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} \begin{pmatrix} a \\ 0 \end{pmatrix} \sin t$

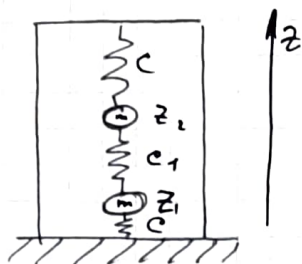
\Rightarrow чтобы амплитуда колеб. m , была $= 0$, нужно, чтобы $w_{11} = 0$

$\Rightarrow \frac{c_2 - \omega^2 m_2}{(c_2 - \omega^2 m_2)(c_1 + c_2 - \omega^2 m_1) - c_2^2} = 0$

$\Rightarrow c_2 - m_2 \omega^2 = 0 \quad \omega = p$
 $\Rightarrow \boxed{c_2 - m_2 p^2 = 0} \rightarrow \underline{0.16}$

18.29

m, c_1, c
 $z = A_0 \sin \omega t$



$f = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$

$T = \frac{m\dot{z}_1^2}{2} + \frac{m\dot{z}_2^2}{2} \Rightarrow A = \begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix} \quad C = \begin{pmatrix} c+c_1 & -c_1 \\ -c_1 & c+c_1 \end{pmatrix}$

$A\ddot{q} + Cq = -gm \begin{pmatrix} 1 \\ 1 \end{pmatrix} + m\ddot{z} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ *Подставляем $z = A_0 \sin \omega t$*
 $\Rightarrow A\ddot{q} + Cq = -gm \begin{pmatrix} 1 \\ 1 \end{pmatrix} + A_0 \omega^2 m \sin \omega t \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

Найдем решение в виде: $q = \frac{gm}{c} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + h \sin \omega t$
 $\Rightarrow (-\omega^2 A + C)h \sin \omega t = -A_0 m \omega^2 \sin \omega t \begin{pmatrix} 1 \\ 1 \end{pmatrix}$
 $\rightarrow h = -m \omega^2 A_0 (C - \omega^2 A)^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$(C - \omega^2 A) = D(\omega) = \begin{pmatrix} c+c_1 - \omega^2 m & -c_1 \\ -c_1 & c+c_1 - \omega^2 m \end{pmatrix}$

$W = D^{-1}(\omega) = \frac{1}{(c+c_1 - \omega^2 m)^2 - c_1^2} \begin{pmatrix} c+c_1 - \omega^2 m & c_1 \\ c_1 & c+c_1 - \omega^2 m \end{pmatrix}$

$\Rightarrow h = \frac{-m \omega^2 A_0}{(c+c_1 - \omega^2 m)^2 - c_1^2} \begin{pmatrix} c+c_1 - \omega^2 m + c_1 \\ c+c_1 - \omega^2 m - c_1 \end{pmatrix} = \frac{-m \omega^2 A_0}{(c - \omega^2 m)} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \textcircled{=}$

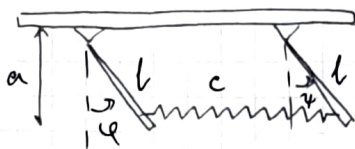
~~$c^2 + c c_1 - c \omega^2 m + c_1 c + c_1^2 - c_1 \omega^2 m + c \omega^2 m + c_1 \omega^2 m + \omega^2 m^2 - c_1^2$~~
 $= \frac{c^2 + 2c c_1 + \omega^2 m^2}{\omega^2 m (\omega^2 m - c)} \begin{pmatrix} c+c_1 - \omega^2 m \\ c+c_1 - \omega^2 m \end{pmatrix}$
 ~~$c^2 + c c_1 - \omega^2 m c + c_1 c + c_1^2 - c_1 \omega^2 m - c \omega^2 m - c \omega^2 m + \omega^2 m^2 - c_1^2$~~
 $= c^2 + 2c c_1 - 2\omega^2 m c - 2c_1 \omega^2 m + \omega^2 m^2$

$\textcircled{=} \frac{-m \omega^2 A_0 (c + 2c_1 - \omega^2 m)}{(c+c_1 - \omega^2 m)^2 - c_1^2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{-m \omega^2 A_0}{(c - \omega^2 m)} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$\Rightarrow \boxed{\omega = \sqrt{\frac{c}{m}}} \rightarrow \text{Отб}$

N 18.37

l, m, c, a
 $A \sin pt$



$$A\ddot{q} + c\dot{q} = Q(t)$$

$$q = u\theta$$

$$u^T A u \ddot{\theta} + c u \dot{\theta} = Q(t)$$

$$\ddot{\theta} + \Lambda \theta = u^T Q(t)$$

$$T = \frac{ml^2 \dot{\varphi}^2}{2} + \frac{ml^2 \dot{\psi}^2}{2}$$

$$\Pi = \frac{ca^2}{2} (\sin \varphi - \sin \psi)^2 + \frac{mgl}{2} (1 - \cos \varphi + 1 - \cos \psi) =$$

$$= \frac{ca^2}{2} (\varphi - \psi)^2 + \frac{mgl}{2} \left(\frac{\varphi^2}{2} + \frac{\psi^2}{2} \right)$$

$$A = \begin{pmatrix} \frac{ml^2}{3} & 0 \\ 0 & \frac{ml^2}{3} \end{pmatrix} \quad C = \begin{pmatrix} \frac{mgl}{2} + ca^2 & -ca^2 \\ -ca^2 & \frac{mgl}{2} + ca^2 \end{pmatrix}$$

$|C - \Lambda A| = 0$ Приходим к уравнению симметричному $\Rightarrow \bar{u}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}; \bar{u}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

$$\Rightarrow \omega_1 = \sqrt{\frac{3g}{2l}} \quad \lambda_1 = \frac{3g}{2l}; \quad \lambda_2 = \frac{3g}{2l} + \frac{6ca^2}{ml^2} \Rightarrow \omega_2 = \sqrt{\lambda_2}$$

$$u_1^T A u_1 = \frac{2}{3} ml^2 = u_2^T A u_2$$

$$u = \sqrt{\frac{3}{2}} \frac{1}{\sqrt{ml^2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

Рассмотрим силу инерции, действ. на груз стержня:

$y^e = -m\ddot{x} = m A_0 \omega^2 \sin \omega t \Rightarrow y_{\text{ин. макс}} \Rightarrow Q_1^e = l y^e = m c A_0 \omega^2 \sin \omega t$
 $Q_2^e = 0$

$$Q = m c A_0 \omega^2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \sin \omega t$$

$$u^T Q = \sqrt{\frac{3}{2}} \frac{m c A_0 \omega^2}{\sqrt{ml^2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \sin \omega t = \begin{pmatrix} \sqrt{\frac{3}{2}} A_0 \omega^2 \sqrt{m} \sin \omega t \\ 0 \end{pmatrix}$$

$$\Rightarrow \text{Получаем упр-е на } \theta_1: \ddot{\theta}_1 + \frac{3g}{2l} \theta_1 = \sqrt{\frac{3m}{2}} A_0 \omega^2 \sin \omega t$$

$$\text{Ищем реш-е в виде: } \theta_1 = d \sin \omega t \Rightarrow -d \omega^2 + \frac{3g}{2l} d = \sqrt{\frac{3m}{2}} A_0 \omega^2$$

$$\Rightarrow d = \sqrt{\frac{3m}{2}} \frac{2l A_0 \omega^2}{3g - 2l \omega^2} \Rightarrow \theta^{\text{привнес}} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sqrt{\frac{3m}{2}} \frac{2l A_0 \omega^2}{3g - 2l \omega^2} \sin \omega t$$

$$\text{Пропишем обратный переход: } \begin{pmatrix} \varphi \\ \psi \end{pmatrix} = u \theta = \sqrt{\frac{3}{2m}} \cdot \frac{1}{2} \sqrt{\frac{3m}{2}} \frac{2l A_0 \omega^2}{3g - 2l \omega^2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} =$$

$$= \frac{3 A_0 \omega^2}{3g - 2l \omega^2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \sin \omega t$$

$$\omega = p \Rightarrow \begin{pmatrix} \varphi \\ \psi \end{pmatrix}^{\text{привнес}} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \frac{3 A_0 p^2}{3g - 2l p^2} \sin p t$$

⇒ Общее решение имеет вид:

$$\begin{pmatrix} \varphi \\ \gamma \end{pmatrix}^{\text{общ.}} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} c_1 \sin(\omega_1 t + d_1) \\ c_2 \sin(\omega_2 t + d_2) \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} \varphi \\ \gamma \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} c_1 \sin(\omega_1 t + d_1) \\ c_2 \sin(\omega_2 t + d_2) \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} \frac{3A_0 p^2}{3g - 2lp^2} \sin p t$$

$$\omega_1^2 = \frac{3g}{2l}; \quad \omega_2^2 = \frac{3g}{2l} + \frac{6ca^2}{ml^2}$$