CE394M Advanced Analysis in Geotechnical Engineering: Introduction

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Overview

1. Geotechnical modeling
   - Complexity in Geotechnical modeling
   - Classical vs advanced analysis
2. Numerical methods for differential equations
   - Direct method: Matrix analysis of structures
   - Numerical analysis of engineering problems
3. Governing equations in stress-deformation analysis
   - Stress equilibrium
   - Compatibility condition
   - Stress-strain relationship

Geotechnical modeling of the complex world

Fig. London Bridge Station, London, UK

Geotechnical modeling of the complex world

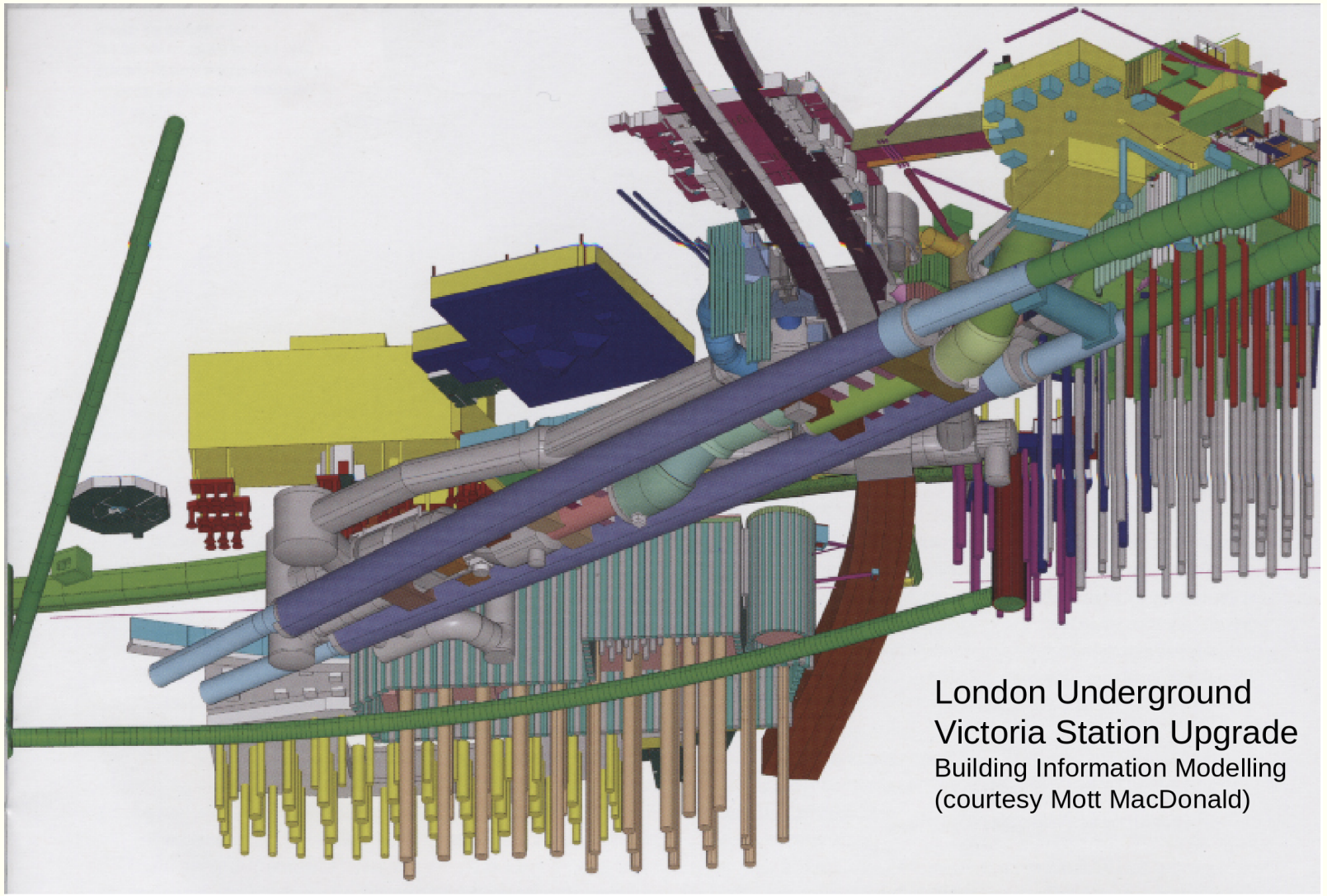
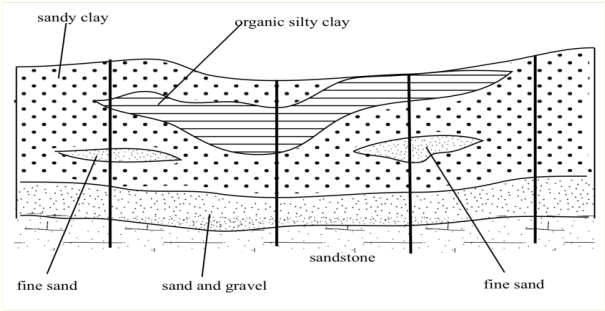
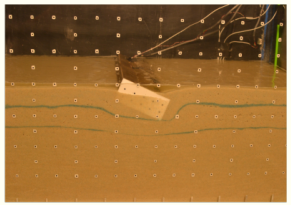
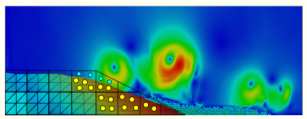


Fig. London Victoria station upgrade, London, UK

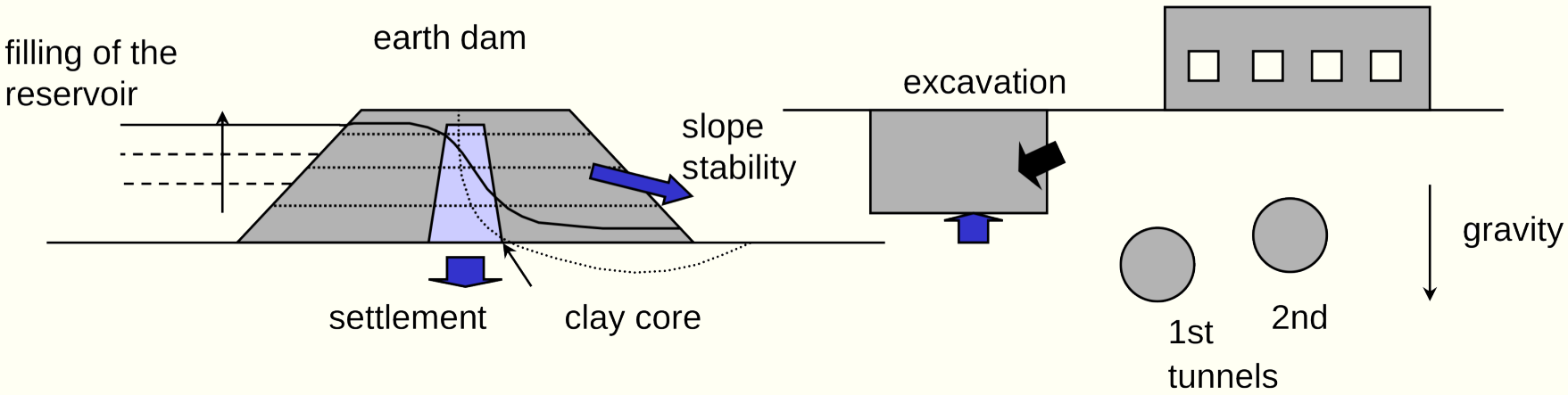
Geotechnical modeling



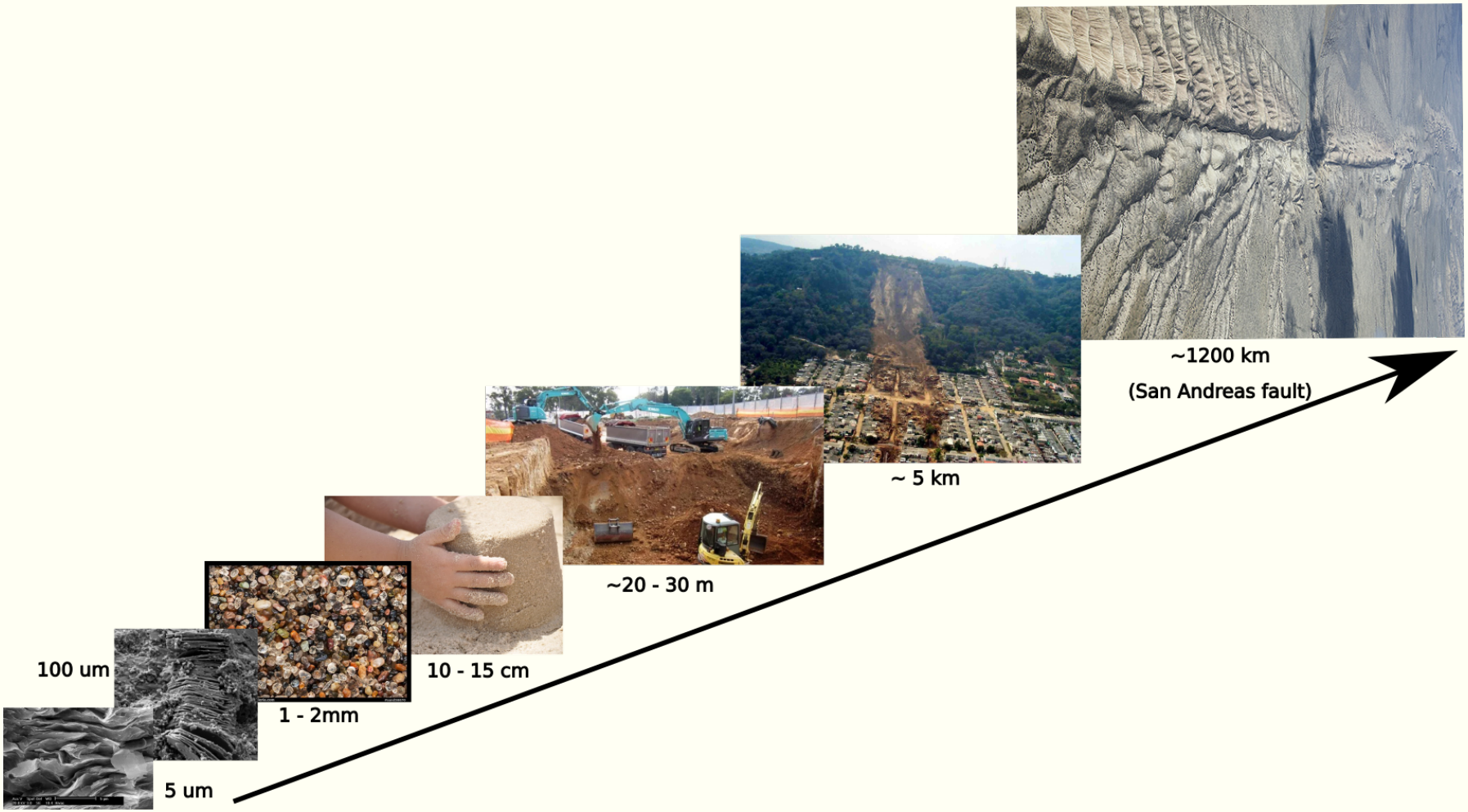




Geotechnical modeling: What should be modeled?



Scales of modeling in geotechnical engineering



Soil behavior

Advanced analysis in geotechnical engineering

Geotechnical design:

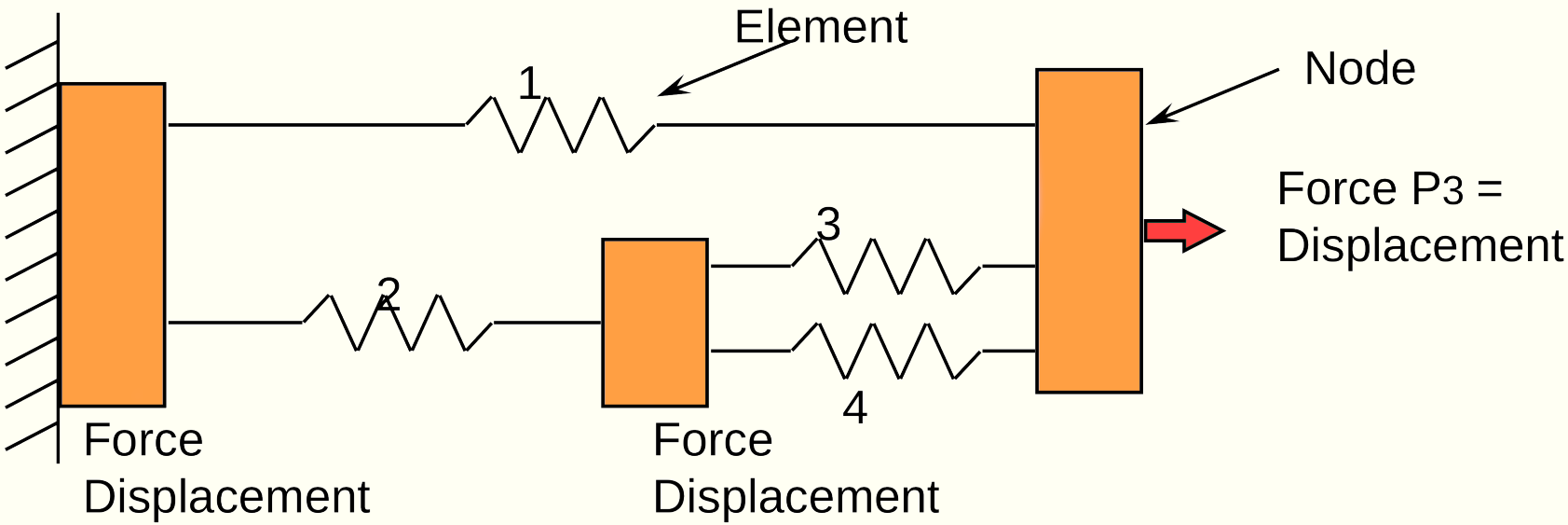
Analysis:

Classical vs advanced analysis

Classical approach:

Advanced analysis:

Matrix analysis of structures



- What are the known variables?
- What are the unknowns?
- What do we know?

Matrix analysis of structures: Equilibrium

- $P_1 =$
- $P_2 =$
- $P_3 =$

Matrix analysis of structures: Compatibility

Matrix analysis of structures: Compatibility

v = internal spring distortion d = nodal displacement

- $v_1 =$
- $v_2 =$
- $v_3 =$
- $v_4 =$

Matrix analysis of structures: Physical condition

Force-distance relationship: spring constant

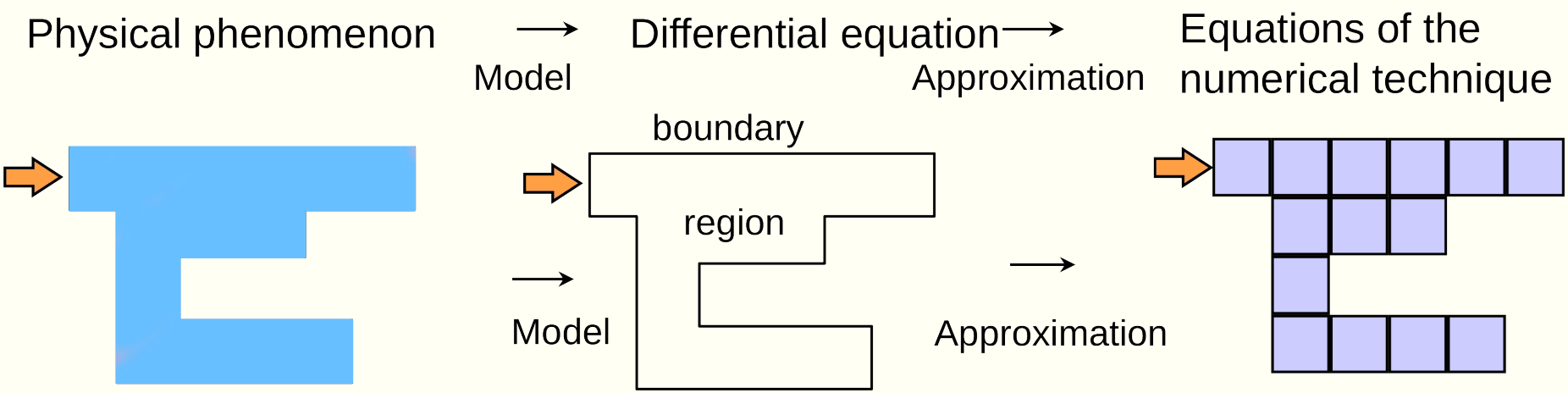
spring #	1	2	3	4
stiffness ($F.L^{-1}$)	3	2	1	2

Matrix analysis of structures: Direct Method

Combine all the equations: $\mathbf{P} =$
where $\mathbf{K} =$

Matrix analysis of structures

Numerical analysis of engineering problems



Boundary value problems

Differential equations coupled with boundary conditions

- Steady state (time-independent)

- Transient (time-dependent)

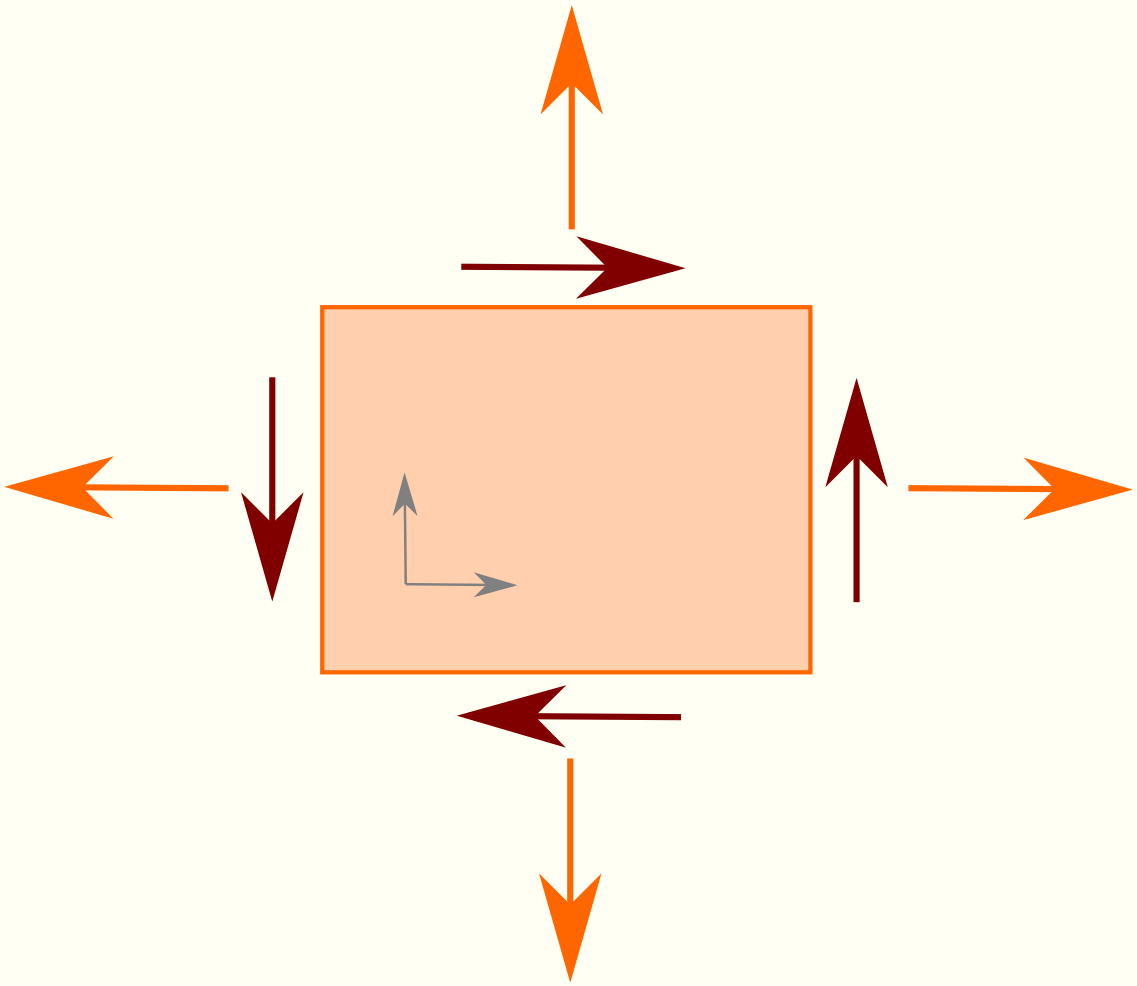
Numerical solutions to differential equations

Governing equations in stress-deformation analysis

In stress-deformation analysis, we need to consider:

Governing equations in stress-deformation analysis

The governing differential equation for equilibrium expresses:



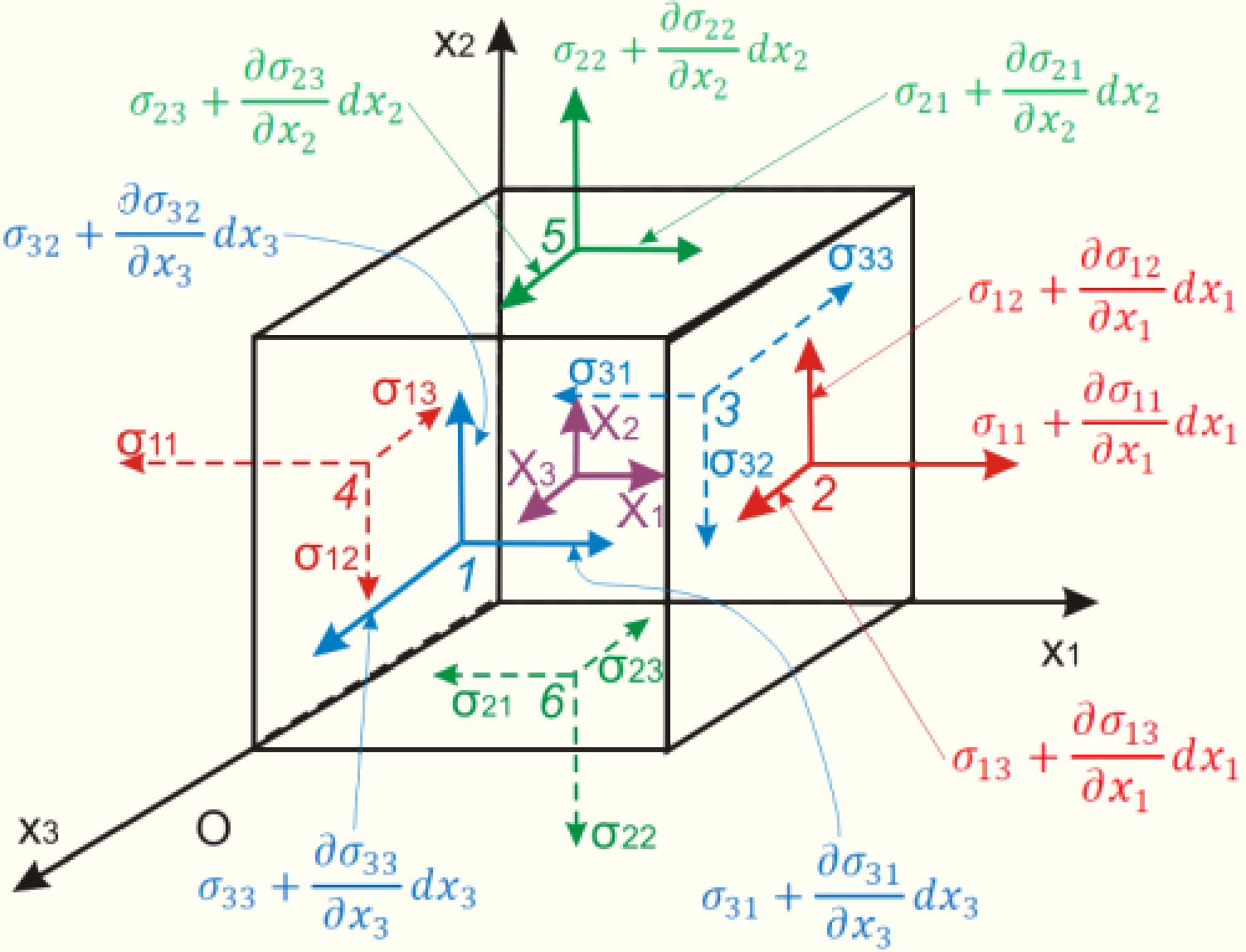
Equilibrium equations

Summing all this in the x-direction gives:

Cleaning up terms that cancel, and dividing through by *dxdy* gives

And summing forces in the y-direction leads to:

Equilibrium in 3D



Equilibrium in 3D

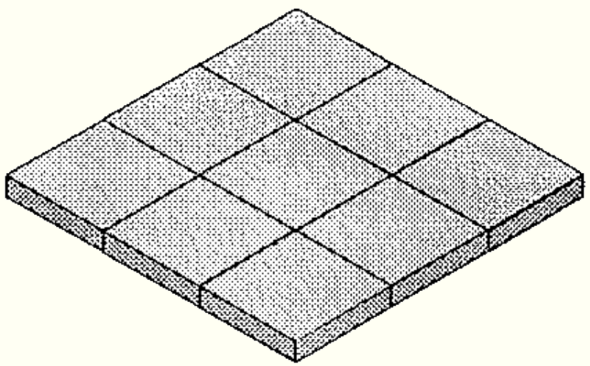
The governing differential equation for equilibrium expresses $\sum \mathbf{F} = m\mathbf{a}$ in terms of derivatives of the stress tensor as:

Stress equilibrium

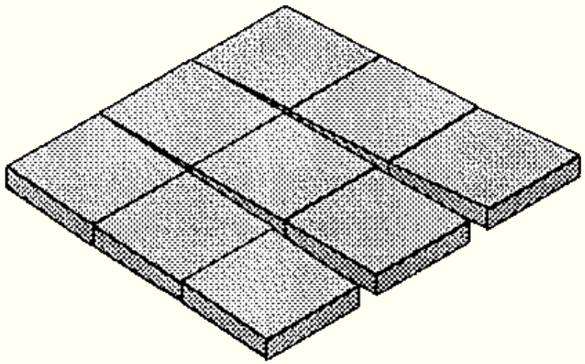
If the object is in equilibrium, then

Stresses in Voigt notation:
Equilibrium equation:
Then:

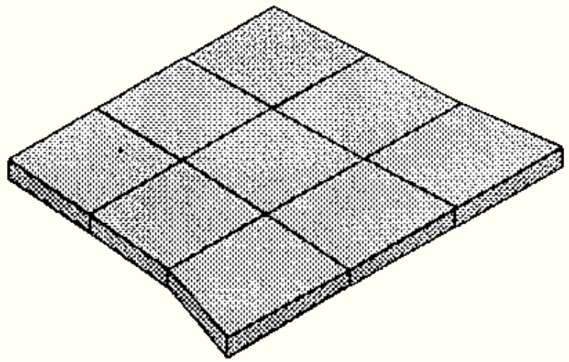
Governing equations: Compatibility



(a) original



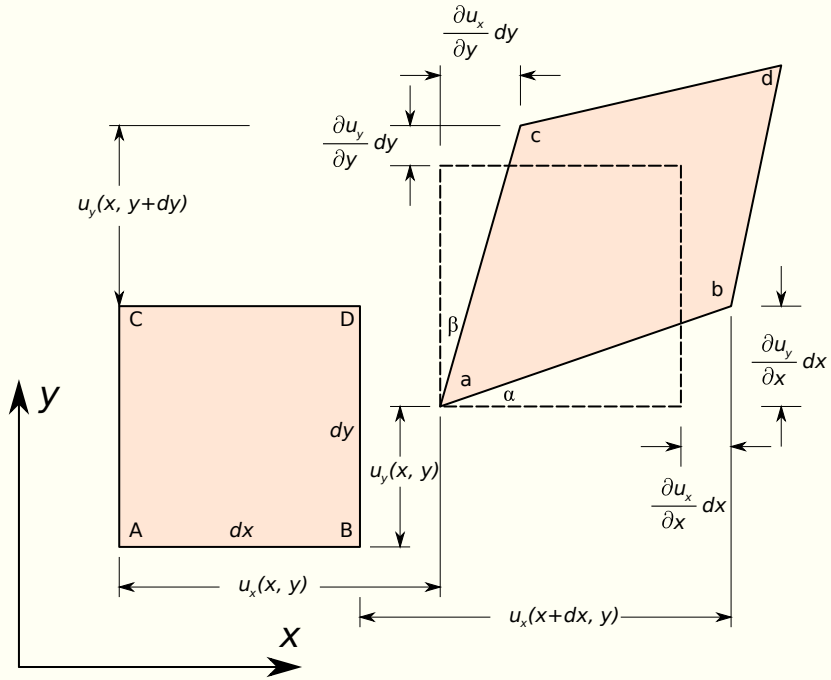
(b) non-compatible



(c) compatible

Governing equations: Displacement - strain relationship

Displacement - strain relationship:



Equilibrium and compatibility conditions

Combining the Equilibrium and Compatibility conditions gives:

- Unknowns:
- Equations:

Governing equations: Stress-strain relationship

Stress - strain relationship:

$$\begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{zz} \\ \sigma_{xy} \\ \sigma_{yz} \\ \sigma_{zx} \end{bmatrix} = \begin{bmatrix} D_{xxxx} & D_{xxyy} & D_{xxzz} & D_{xxxy} & D_{xxyz} & D_{xxzx} \\ D_{yyxx} & D_{yyyy} & D_{yyzz} & D_{yyxy} & D_{yyyz} & D_{yyzx} \\ D_{zzxx} & D_{zzyy} & D_{zzzz} & D_{zzxy} & D_{zzyz} & D_{zzzx} \\ D_{xyxx} & D_{xyyy} & D_{xyzz} & D_{xyxy} & D_{xyyz} & D_{xyzx} \\ D_{yzxx} & D_{yzyy} & D_{yzzz} & D_{yzxy} & D_{yzyz} & D_{yzzx} \\ D_{zxxx} & D_{zxyy} & D_{zxzz} & D_{zxxy} & D_{zxyz} & D_{zxzx} \end{bmatrix} \begin{bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \varepsilon_{zz} \\ \varepsilon_{xy} \\ \varepsilon_{yz} \\ \varepsilon_{zx} \end{bmatrix}$$

Governing equations in stress-deformation analysis

What are the variables used in the governing equations?

Advanced analysis involves: