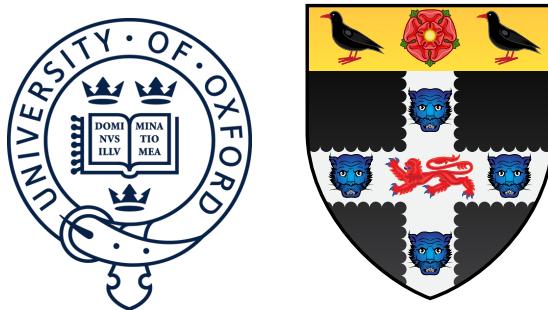


First Measurement of the Solar Neutrino Oscillation Parameters via Boron-8 Solar Neutrinos in SNO+



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A thesis submitted in fulfilment of the requirements for the degree of

Doctor of Philosophy

Trinity Term 2022

To my parents

and

To Oscar Jacobsson:

The best of us

Acknowledgements

And I would like to acknowledge ...

Abstract

Formal 1-page summary of the work completed in the thesis.

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Introduction

Couple of pages outlining document's structure and contents (this is what each of the chapters is here for). Less formal than the abstract, also explaining what the expected audience of this thesis is: who will find this document useful!

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Chapter 1

The Theory of Neutrino Physics

Light

Light

The visible reminder of Invisible Light

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The Rock

T. S. ELIOT

1.1 The Standard Model and Neutrinos

- First up, a very brief summary of what the Standard Model of Particle Physics is, and how it works at a high level (QFT + non-Abelian gauge theories + Brout-Englert-Higgs Mechanism). This gives the highest-level context. 4 5 6 7
- Next: how neutrinos fit into this picture of the SM: the currently-known terms of the SM Lagrangian containing neutrinos. From this, the interactions of neutrinos with the weak force are derived. Experimental evidence supporting this model is given. This gives us the fundamental mechanism by which neutrinos can be detected. This leads to an explanation of neutrino detection modes: inverse-beta 8 9 10 11 12

1 decay, electron-neutrino elastic scattering, quasi-elastic nuclear scattering, deep
2 inelastic scattering, and even coherent neutrino-nuclear scattering.

3 **1.2 Neutrino Oscillations and Neutrino Masses**

- 4 • One major assumption underlying the current SM is that neutrinos are massless
5 — I'll explain why. But, neutrino oscillations have been observed! Give a brief
6 summary of the various places where neutrino oscillations have been observed.
7 This means we need to add two things: a mechanism for neutrinos having a mass,
8 and a mechanism for oscillations given those masses. Starting with the former,
9 I will cover briefly how the see-saw mechanism allows for neutrino masses, as
10 well as the differences between Dirac and Majorana neutrinos. This also has
11 implications for the problem of matter-antimatter asymmetry in the universe.
- 12 • This leads on to a description of neutrino double beta decay: what it is, how it
13 can be searched for, and how a discovery of this decay guarantees that neutrinos
14 have a Majorana mass term. What is the current status of research in this
15 area (briefly)? This provides the necessary context for SNO+ as an experiment
16 designed to search for $0\nu\beta\beta$.
- 17 • Now onto explaining the mechanism for neutrino oscillations. Describe the
18 current phenomenological model we use: the PMNS matrix with the MSW effect
19 in the LMA regime. Experiments that have best-constrained oscillation params:
20 long-baseline; short-baseline; atmospheric; and, of course, solar.

1.3 Solar Neutrino Oscillations

- Given the focus of my thesis on solar neutrino oscillations, give a brief summary of the history of solar neutrino oscillations. Include the added theory necessary to understand solar neutrino oscillation analyses specifically: the Standard Solar Model, and how the "solar oscillation parameters" are the only neutrino oscillation parameters that actually impact solar neutrino analyses. Also cover how, as a sub-dominant effect, day-night asymmetries can exist for solar neutrinos because of matter effects through the Earth. 2
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- Cover briefly how the same solar oscillation parameters can also be measured by reactor anti-neutrino analyses, and therefore how this can provide complementary information to a solar oscillation analysis. 9
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Chapter 2

The SNO+ Detector

The light-soaked days are coming.

JOHN GREEN

2.1 Detector Geometry and Design

The SNO+ detector is a large, multi-purpose neutrino detector built in the SNOLAB underground laboratory near Sudbury, Canada. Its main detector structure is taken from the Nobel prize-winning Sudbury Neutrino Observatory (SNO) [], which can be seen in Fig. 2.1. The bulk of the detector is the main detector medium, which changes depending on the phase of the experiment — more on the specifics of this shortly. This medium is held within a 12 m diameter sphere known as the Acrylic Vessel (AV). The AV floats within a body of ultra-pure water (UPW), beyond which is a stainless steel support structure (PSUP) that holds ~ 9000 Photomultiplier Tubes (PMTs). It is these PMTs that detect the light generated from physics events that occur within the detector medium. The AV is kept in place relative to the PSUP through a series of ‘hold-up’ and ‘hold-down’ tensylon ropes. All of these components are suspended within a large cylindrical cavity also filled with UPW. Directly above the detector is

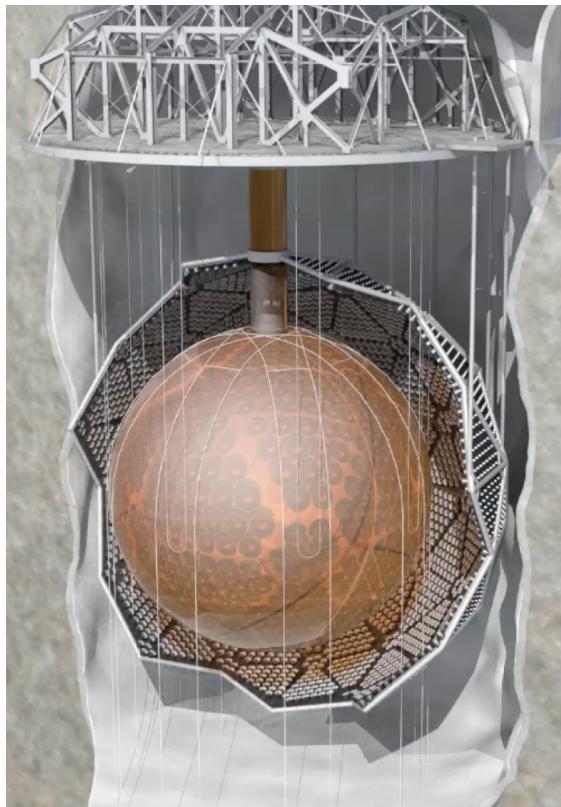


Fig. 2.1 3D model of the SNO+ detector [1].

1 the Deck, within which all the detector electronics are kept. Access within the AV for
 2 calibration tools and filling is possible only through the acrylic ‘neck’ on top of the AV.

3 This choice of design is highly deliberate, with the details are discussed in [1]. The
 4 location 2.2 km underground ensures that there is minimal impact from cosmic rays:
 5 only 3 cosmic ray muon events are expected within the detector an hour [1]. By making
 6 the detector spherical, the high degree of symmetry can easily be taken advantage of
 7 in event reconstruction and analysis. Moreover, light produced throughout most of
 8 the body of the AV will be minimally-impacted by refraction through the acrylic. The
 9 only major exception to this is light emitted within ~ 50 cm of the AV, at which point
 10 total internal reflection becomes possible. In order to make as much emitted light be
 11 able to get detected as possible, all materials within the PSUP were chosen for their
 12 optical transparency (excepting the ropes).

2.2 Experimental Phases**9**

Another major design consideration is that of radioactive backgrounds. Maintaining minimal levels of backgrounds is critical for effective particle physics, otherwise the signal one is searching for would become completely swamped. Materials within the detector were chosen to ensure these background levels would be low enough for the Collaboration’s physics goals to be achieved. Another benefit of the spherical design is its high volume-to-surface area ratio, which means that the relatively-high background levels of the PMT glass are kept far away from the detection medium.

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7**2.2 Experimental Phases**8
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As mentioned earlier, SNO+ was designed to fulfil a number of physics goals over multiple ‘phases’ of the detector’s lifetime. The phases are distinguished by the medium that fills the AV. The first main phase (after a brief ‘air-filled’ phase used only for detector commissioning) was that of the ‘water-fill’, with data taken between May 2017 and July 2019. This was used to perform fundamental optical calibrations of the detector [], measurements of the solar neutrino flux [], observation of neutrino oscillations in reactor anti-neutrinos [], and searches for nucleon decay [].

After this, the detector was filled with 800 tonnes of liquid scintillator known as linear alkylbenzene (LAB), mixed with the fluor PPO. More information on the physics of scintillators can be found in Section 2.3.1. Filling of the LABPPO cocktail had to be paused in March 2020 due to the COVID-19 pandemic, leading to the detector having its bottom half still filled with UPW, and the top half filled with LAB and PPO at 0.5 g/L. This impromptu phase became known as the ‘partial-fill’, and allowed for some creative analyses to be performed: an initial neutrino oscillation analysis from reactor anti-neutrinos [], as well as the first ever observation of directionality in a high light yield scintillator []. Eventually, filling of the detector with liquid scintillator was able to resume, being completed in May 2021. At that point, the concentration of PPO in the

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1 detector was at 0.6 g/L, markedly below the target level of 2.0 g/L. A further ‘PPO
2 top-up’ campaign then proceeded, finishing in April 2022 with a final concentration of
3 2.2 g/L PPO. Thus began the ‘scintillator-fill’ of the experiment, which continues on
4 during the time of writing. The main goals for this phase include a number of solar
5 neutrino analyses (including the one described in Chapter 6), a precision measurement
6 of the neutrino oscillation parameter Δm_{21}^2 using reactor anti-neutrinos [], and further
7 calibrations of the detector and its backgrounds.

8 Finally, in the near future the detector will be loaded with Tellurium, allowing for
9 the flagship analysis of the experiment to begin: neutrinoless double-beta decay. The
10 details of this chemical loading process are described in []. Alongside the Te-loaded
11 liquid scintillator will be a number of other chemicals within the scintillator cocktail
12 that will help ensure optimal optical properties and chemical stability. These include:
13 the surfactant DDA to ensure the solubility and stability of the ‘Te-diol’ within the
14 LAB; the wavelength-shifter BisMSB to absorb light at short wavelengths and re-emit
15 closer to the optimal quantum efficiency of the detector’s PMTs; and the anti-oxidant
16 BHT to prevent any free-radicals within the liquid scintillator from ‘yellowing’ the
17 medium.

18 **2.3 Detecting a Physics Event in SNO+: A Jour- 19 ney**

20 To understand well the SNO+ detector, it is worth thinking about how the information
21 of a physics event, e.g. a solar neutrino interaction, gets observed. This section follows
22 the journey of such an event.

2.3.1 Particle Interactions with Matter

All observable physics events within the detector begin by the generation of some form of ionising radiation: α , β^\pm , γ , p or n . These can be created via numerous processes, both exciting (e.g. $0\nu\beta\beta$ or interactions of neutrinos) and banal (e.g. decay of background radioisotopes): see Section 6.1.2 for some of them. Regardless of their origin, these particles begin propagating through the detector, and interacting with the detector medium. A number of mechanisms then allow for the generation of optical-wavelength light as a result of these interactions.

Cherenkov Light Emission

Whenever a charged particle passes through a dielectric medium, nearby molecules polarise and attempt to align their dipoles in the direction of the charge. This results in a temporary polarisation of the medium as the charge passes though it. However, the molecules can only respond to the charge's movement at the speed of light in the medium, which is necessarily slower than the speed of light in a vacuum by a factor of the medium's refractive index. If the charged particle is able to move at a speed greater than the speed of light in the medium, then the dipoles formed within the medium struggle to respond to the motion. This superluminal motion results in a wake of polarisation in the medium, which propagates outwards from the direction of the charged particle: this is Cherenkov light. This process is much akin to the ‘sonic boom’ that occurs when an object travels at supersonic speeds.

Cherenkov light emanates outwards in a cone along the direction of the charge’s travel; the angle of the cone θ_γ is purely a function of the speed of the charged particle relative to the speed of light, β , and the refractive index of the medium $n(\lambda)$: $\cos \theta_\gamma(\lambda) = \frac{1}{n(\lambda)\beta}$. This formula also demonstrates that there is a minimum speed necessary for Cherenkov light to be generated: $\beta = 1/n(\lambda)$.

1 All detection media are capable of allowing for Cherenkov light to be generated, as
2 long as sufficiently high energy particles can be produced. In the water-fill phase of
3 the detector, Cherenkov light was the only means by which light could be generated.
4 Light from Cherenkov emission can still be created in liquid scintillator, but it tends
5 to be swamped by another form of light generation: scintillation.

6 **Scintillation**

7 Whenever a high-energy particle passes through a medium, interactions between the
8 particle and the medium's molecules lead to an inexorable transfer of energy from the
9 former to the latter. These interactions are numerous, and are a function of the type
10 of particle and its kinetic energy. For example, a 5 MeV electron loses energy from
11 electromagnetic interactions with nearby molecules as it passes through, and scatters
12 after colliding with atomic electrons or nuclei. From the perspective of the medium,
13 its molecules use this new-found energy for a number of activities:

- 14 1. Exciting atomic electrons into various higher-energy states;
- 15 2. Ionising atomic electrons;
- 16 3. Increasing the overall kinetic energy of the molecule.

17 At the macroscopic level, process 3 is simply the conversion of the high energy particle's
18 energy into heating the medium. In fact, within most materials the other processes
19 also end up doing the same.

20 However, for certain special classes of material the excitation and ionisation of
21 electrons can lead to a unique process: scintillation (often generally referred to as
22 'luminescence' or 'fluorescence'). Here we choose to focus on the particular case of
23 organic liquid scintillators, given that this is the type of scintillator which currently fills
24 the SNO+ detector. Certain organic compounds (i.e. molecules built from a skeleton

2.4 Calibrations and Detector Modelling**13**

Fig. 2.2

of carbon atoms) have ‘ π -bonds’ in addition to the single ‘ σ -bond’ that is needed to bond two carbon atoms together. A major example of these π -bonds is in the benzene rings of ‘aromatic’ hydrocarbons, such as LAB and PPO. Fig. 2.2 shows an image of the orbitals for these π -bonds in a benzene ring: note how the electrons that inhabit these particular orbitals become entirely delocalised.

Because of this delocalised structure, excited atomic π -electrons can stay in what is typically the first-excited state for somewhat longer than typical excited states: lifetimes of $\mathcal{O}(10^{-9}\text{ s})$ as opposed to $\mathcal{O}(10^{-12}\text{ s})$. Moreover, decays from this state can emit light typically in the optical-wavelength range. It is this light emission that is called ‘scintillation light’. Ionised electrons can also

- Begin the “journey of a SNO+ Physics Event” — starting by explaining how a high-energy particle interacts with matter to generate Cherenkov and/or scintillation light. In both cases, optical wavelength light gets generated.
- Then, light propagates through the detector, possibly undergoing various physics processes: Rayleigh scattering, absorption, re-emission, refraction, and reflection.
- Light gets detected via the PMTs: explain how.
- Thus begins the DAQ chain. Signals reach the crates of electronics on deck and are processed. A “sufficient signal” leads to the triggering of the detector, which then enables for the saving of the event’s information via the event builder.

2.4 Calibrations and Detector Modelling

- I will now describe how calibrations enable us to use the stored data for actual physics.

- 1 • Detector's state is continuously monitored via a number of systems for data
2 quality purposes, including a human detector 'shifter'. Mention use of run
3 numbers. CHS and CSS ensure only "good" channels used in any analysis.
- 4 • First main set of calibrations are the ECAs and PCAs. These help us convert raw
5 electronic signal information from PMTs into 'calibrated' hit times and charges.
6 PCAs performed via TELLIE and the Laserball.
- 7 • These initial calibrations allow for the first two passes of data processing.
8 SMELLIE data comes from this part of the processing chain.
- 9 • In order to infer properties of an underlying physics event, an accurate model of
10 the detector is needed. This requires two things: a set of calibration tools, and a
11 piece of simulation software. The latter is RAT (explain briefly).
- 12 • Aims of remaining calibration tools are to obtain the optical parameters necessary
13 for accurate modelling. Go through briefly all the calibration tools we have
14 available: SMELLIE, AMELLIE, the Laserball, the AmBe and N16 sources, and
15 in situ backgrounds.
- 16 • Using RAT once calibrated, event reconstruction can become possible. Briefly
17 describe how energy, position, and time reconstruction works. Mention existence
18 of direction fitting!

Chapter 3

1

The SMELLIE Calibration System

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There's a certain Slant of light,

Winter Afternoons —

That oppresses, like the Heft

3

Of Cathedral Tunes —

EMILY DICKINSON

Basic principle for how SMELLIE works: firing collimated laser light into detector to observe scattering events. Analysis will measure and monitor scattering in a detector with changing optics. Ideally, this would be a double differential scattering cross-section measurement as a function of wavelength and scattering angle, measured as a function of time in the detector. Otherwise, one can try and measure some component of this: the cross-section/scattering length versus wavelength and time, or at the very least the relative scattering length versus wavelength and time. Mention the link between cross-section and scattering length.

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3.1 The SMELLIE Hardware

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1 Describe the existing hardware. This includes the path of light into the detector, as
2 well as the path of the trigger signal. Describe also the upgrades made to the hardware:
3 Tony Zummo's fix to the TUBii trigger logic, as well as the addition of the VFA,
4 updated MPU, and modified trigger window. Make sure to motivate why these updates
5 were made.

6 **3.2 Software for SMELLIE Data-taking**

7 Server running on SNODROP; run plan files written in JSON handed to ORCA which
8 then sends relevant commands to SNODROP which fires as appropriate. After events
9 occur, run description file created (used as metadata for analysis).

10 **3.3 Commissioning SMELLIE**

11 Why is commissioning needed? Need to confirm that SMELLIE is working as expected;
12 determine intensity "set-points" for different use cases. No need to describe the Tesseract
13 in detail here - that can be in Jeff L's thesis. But, I do want to show the results of
14 both commissioning campaigns in scintillator-fill, one before the new hardware was
15 added, and one after.

Chapter 4

1

Simulating SMELLIE Events

2

Max Power : *Kids. From now on there are three ways of doing things: the right way, the wrong way, and the Max Power way.*

Bart Simpson : *Isn't that just the wrong way?*

Max Power : *Yes, but faster!*

THE SIMPSONS

Critical to extraction of scattering information from SMELLIE data is an accurate Monte Carlo (MC) simulation of the SMELLIE system. By modelling the laser light emission into the detector correctly, we can simulate how SMELLIE light will be impacted by changing scattering lengths in the detector. Because of the complexity of the optics of the optical fibres used to direct the laser light into the detector, a given SMELLIE event is simulated as a partially-collimated “flash” of visible photons emanating from the emission point of the fibre into the detector. This flash then requires a number of parameters to be correctly described. In particular:

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- **Fibre emission positions** were recorded during the installation of the fibres.

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- **Wavelength and emission timing distributions** of light pulses were taken from measurements of the laser heads by their manufacturers [], or by colleague Jeff Lidgard in the case of the SuperK wavelength distribution [].
- **The “pulse magnitude”**, defined as the mean number of photons simulated per event, is determined on a subrun-by-subrun basis, and is assumed to fluctuate as a Poisson distribution.
- **The beam profiles**, which describe the angular emission distributions of each fibre, is the focus of this chapter. These are necessary because unlike scintillation light, the light emitted from SMELLIE fibres is not isotropic.
- **Nominal fibre emission directions** attempt to define the centre of the beam for a given fibre.

This chapter is split into three sections. Improvements to the existing simulation algorithm for the beam profiles are first made, and then the beam profiles themselves are updated. Finally, comparisons between data and simulation are made after the upgrades to investigate any remaining discrepancies.

4.1 Improving the SMELLIE Generator Algorithm

4.1.1 Previous Attempts at SMELLIE Event Simulation

Before we can determine the beam profiles, we must first decide how to specify them. Previous observations show that different fibres can have notably different beam profiles [2], so we let each fibre’s beam profiles be unique. We assume for now that a given fibre’s beam profile is stable over time, and independent of the wavelength of light fired. A straightforward, naïve approach to parameterising a beam profile would be as follows: specify some nominal fibre direction, corresponding to the direction light

4.1 Improving the SMELLIE Generator Algorithm

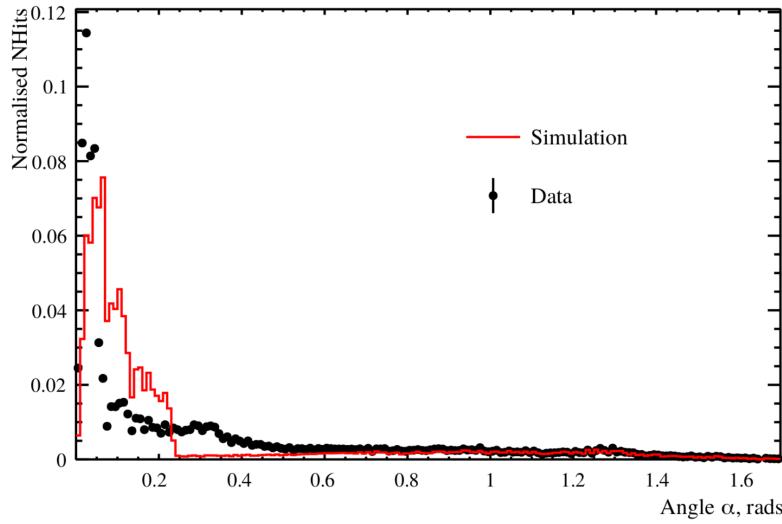


Fig. 4.1 Comparison between a simulation of one of the fibres, made from the 1D beam profile generator (red), with the associated data subrun that was used to create that beam profile (in black). For both MC and data, what is plotted is the PDF of observed PMT hits, as a function of the α angle. Poissonian errors have been added to the data points, but are too small to see. Clearly, this 1D generator does not replicate the observed beam profile correctly. Figure taken from [3].

takes travelling from the fibre to the centre of the “beamspot” observed on the other side of the detector. Then, specify a 1D beam profile, corresponding to the probability density of firing a photon at a given polar angle α relative to the nominal direction. One might even assume this distribution is Gaussian. The distribution in azimuthal direction, ϕ , is assumed to be uniform.

This 1D beam profile approach was used initially for SMELLIE, and remains in use for the other ELLIE sub-systems within SNO+. However, when SMELLIE data was taken in the water-phase of the experiment, simulations using these beam profiles failed to match them well at all - see figure 4.1 for an example. Not only was the distribution in α not Gaussian, a distinct speckle-pattern can be observed within the beamspot that is not uniform in ϕ . This fact led to colleague Esther Turner building a SMELLIE generator that could handle 2D beam profiles: dependent on both α and ϕ . The distribution was stored as a map from each inward-pointing PMT in the detector

¹ to a relative intensity value. This was chosen because the beam profile shapes were
² calibrated from existing SMELLIE data — more on this in section 4.2.

³ This original 2D generator then sampled the beam profile via a rejection sampling
⁴ approach, outlined as follows:

- ⁵ 1. Propose a test direction (α, ϕ) , by generating ϕ uniformly in the interval $[0, 2\pi]$,
⁶ and α according to some pre-determined Gaussian distribution, known as the
⁷ Gaussian envelope.
- ⁸ 2. Given this test direction, calculate where a line following this direction from the
⁹ fibre of interest will hit the PSUP on the other side of the detector. Find the 3
¹⁰ closest PMTs to that point.
- ¹¹ 3. From those PMTs, obtain their relative intensity values from the beam profile
¹² mapping, and perform an interpolation based on how close each PMT is to the
¹³ PSUP intersection point. This gives an interpolated relative intensity value for
¹⁴ this test direction.
- ¹⁵ 4. Because we are sampling using the angular coordinates (α, ϕ) , differential area
¹⁶ elements over this space of directions do not have the same size. We can correct
¹⁷ for this fact by multiplying our interpolated relative intensity by $\sin \alpha$, which
¹⁸ corresponds to the Jacobian of the direction-space.
- ¹⁹ 5. Calculate the value for the Gaussian envelope along this test direction.
- ²⁰ 6. Throw a random number uniformly between 0 and the Gaussian envelope value. If
²¹ the random number is less than the interpolated intensity, then this test direction
²² is accepted, and a photon is generated with that direction. Otherwise, we reject
²³ the direction and try the whole process again.

 4.1 Improving the SMELLIE Generator Algorithm

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This generator certainly works, but has a key problem: efficiency. The 1D generator was able to generate a SMELLIE event (that is, to fully specify the starting parameters of all the photons emitted from a fibre) at a speed of ~ 1 ms. However, the 2D generator specified here could take upwards of ~ 50 s *per event* to generate. Because a typical SMELLIE analysis requires simulating many millions of events, the CPU time taken to perform this quickly became unfeasible. Fixing this generator speed problem was a high priority for the SMELLIE analysis.

4.1.2 The new generator

On careful inspection of the existing 2D generator, the main reason for the slowness of the algorithm is the use of a rejection approach. Even with use of the Gaussian envelope, which was included to help with speed, the vast majority of proposed directions are never selected. Figure 4.2 shows a histogram of number of attempts per event it took for a valid direction to be chosen for a representative SMELLIE simulation. Moreover, the calculations needing to be done for every proposed direction are relatively complex, notably trying to find the 3 nearest PMTs to some point on the PSUP.

A new 2D generator was built with these thoughts in mind. Firstly, the rejection method would no longer be used, given its inefficiency. We would also endeavour to try and “pre-calculate” as much as possible before run-time. Starting with the existing PMT relative intensity maps, we plot these in the 2D direction-space ($1 - \cos \alpha, \phi$): see Figure 4.3a. In a toy-MC simulation, 500,000 directions are then thrown uniformly in this 2D space per fibre. For each direction, the same method of obtaining an interpolated intensity value from the nearest PMTs to the corresponding point on the PSUP as from the original 2D generator was performed, the only difference being that these calculations were done well before any actual SMELLIE simulation. Figure 4.3b shows the interpolated intensities obtained for one fibre.

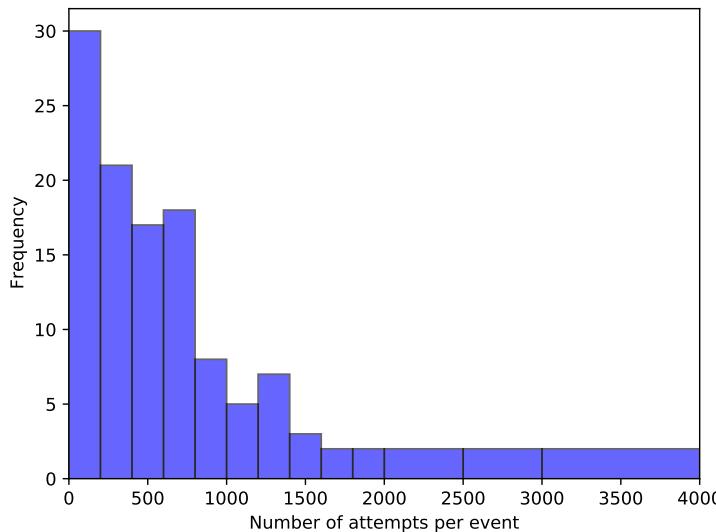


Fig. 4.2 Typical distribution of the number of attempts it takes for the existing 2D generator before the test direction gets accepted, per event.

Following this, the sampled intensities were then binned into a 2D histogram, where the bin value corresponds to the sum of all intensities for all directions found within this bin. Choosing a sensible binning procedure is important: too few bins, and necessary information about the shape of the beam is lost, whilst too many bins can oversample the data and capture statistical artefacts in the sampling process instead of just the beam profile. As a balance, 15 bins were chosen along the ϕ direction, and 60 in $r = 1 - \cos \alpha$. This was chosen to ensure that a reasonable number of PMTs were located within each bin, lessening the impact of any statistical fluctuations. Although the bins in ϕ were chosen to have uniform width, this was decided to be not the case for the other axis, as there is far more important information near $r = 0$ (the beamspot). Instead, the width of the bins in r were calculated so that roughly the same total probability was contained in each r -strip. By consequence, bins near the beamspot typically are of significantly smaller size than ones much further out. This allows us to both capture any rapid changes in intensity near the beamspot, where this

4.1 Improving the SMELLIE Generator Algorithm

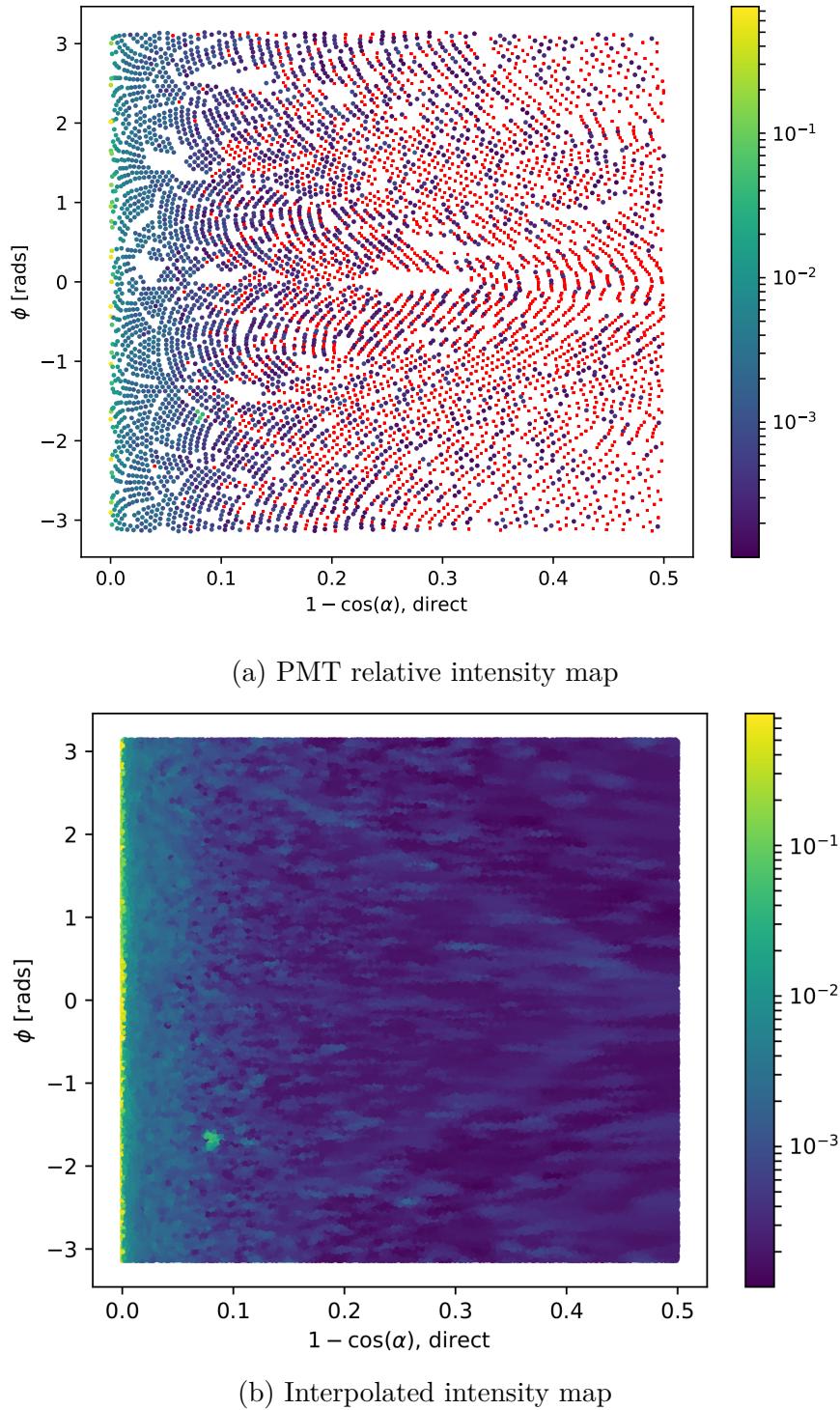


Fig. 4.3 The first step in the new method for preparing the new generator. In (a), the relative intensities used for the existing beam profile of fibre labelled FS055 are shown for each PMT, the position on the plot indicating the location of that PMT in the fibre coordinates. The colour indicates the relative intensity; PMTs marked red have an intensity of zero. Figure (b) shows the result of throwing 500,000 directions uniformly over this 2D space, the intensity of each point given by interpolating the intensities of nearby PMTs.

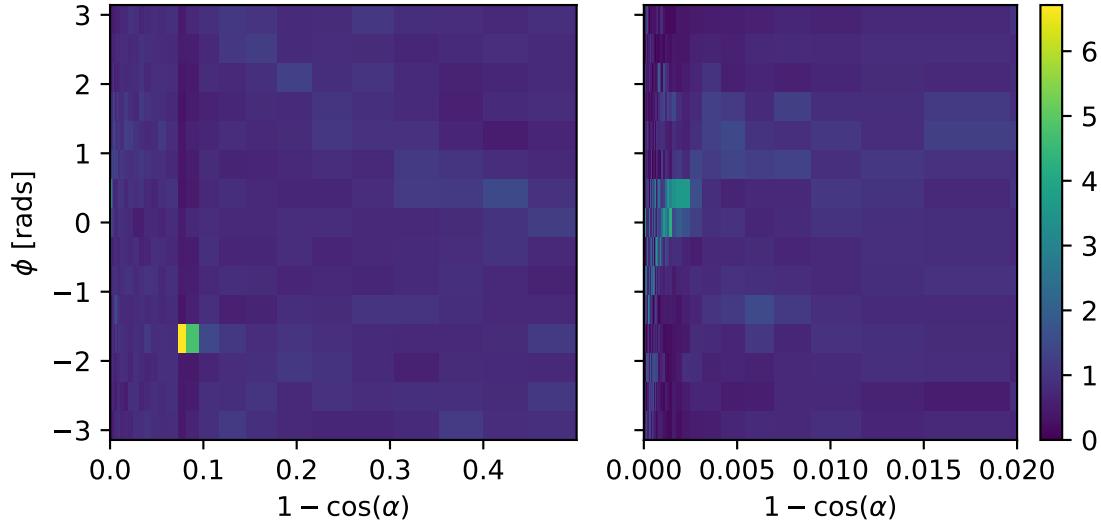


Fig. 4.4 Histogram of interpolated intensities within the 2D direction-space. The left view shows the full histogram; the right is a zoomed-in version near the beamspot. Unlike the binning in ϕ , the bin widths in r are not at all uniform. Instead, they have been determined such that the area summed over a given “strip” of bins of constant r will be the same.

¹ matters greatly, and smooth out the very-low intensities seen at larger polar angles.

² One of these histograms can be seen in Figure 4.4: the large change in bin widths as a
³ function of r is clear. One can also see that near the beamspot notable dependence on
⁴ the intensity as a function of ϕ . The mysterious “spot” at $r = 0.08$, well out of the
⁵ beamspot, is an indication that the underlying beam profile data being used requires
⁶ improvement: more on this in section 4.2.

⁷ The Cumulative Density Function (CDF) of this intensity histogram as a function
⁸ of bin was then produced, where the bins were ordered through a raster-scan: scanning
⁹ first over ϕ , and then r . The CDF was then normalised to 1 so that it was well-defined.

¹⁰ It is this CDF object that is then loaded in and sampled from during event generation.

¹¹ To do this, an “inverse-CDF” approach was used, which has the major benefit over
¹² rejection sampling of always producing a valid direction for every sample made. The
¹³ algorithm works as follows:

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1. Throw a random number uniformly in $[0, 1]$. 1
2. Perform a binary search to find the bin that has the largest CDF value below this random number. 2
3. Look at the bin edges in ϕ of this selected bin: use linear interpolation of the random number to obtain a ϕ value located between these two ϕ -values. 3
4. Look at the selected bin's r -bin edges, and select a value of r by throwing a second random number uniformly between the two edges. Convert this r into a polar angle α . 4
5. The photon's direction is defined by the (α, ϕ) chosen by this process. 5

Because of the relative simplicity of this algorithm compared to the previous 2D generator, the speed improvement was very large: generation now took ~ 1 ms per SMELLIE event, a speed improvement of nearly 50,000. Event generation became as fast as it was when the 1D generator was being used. Furthermore, because of the approach taken, this major speed improvement comes at no sacrifice in accuracy. Figure 4.5 shows a comparison of the average number of photoelectrons (npe) per event per PMT between water-phase SMELLIE data and simulations with both the old and new 2D generator. One can see clearly that both generators are as accurate as one another. Note that this plot uses the updated beam profiles as explained in the next section.

4.2 Improving the beam profiles

Even with the new 2D profile generator, a problem remains: the simulation fails to reasonably recreate data, and much of this appears to be because of the poor beam profile data being used. The curious “spot” for one of the fibres was already noted in

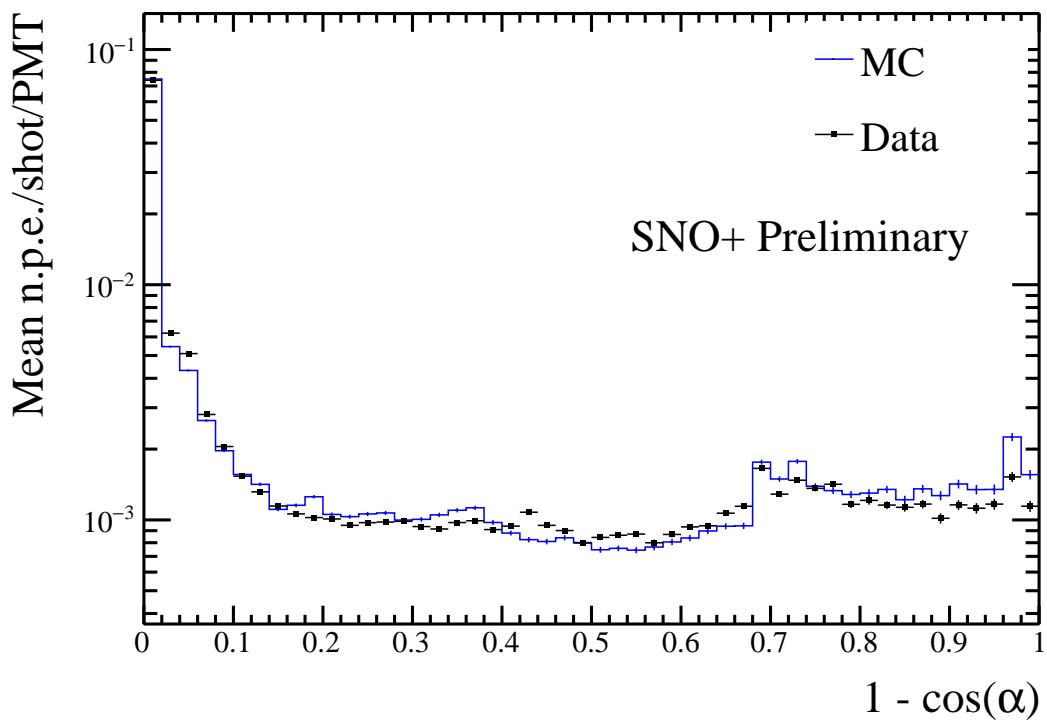


Fig. 4.5 Comparison of water-phase data to MC generated using both the old and new 2D beam profile generator approaches, with the updated beam profiles. Both versions of the generator are consistent with one another, but the new generator is many times faster.

4.2 Improving the beam profiles

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the previous section that doesn't seem to be physical, and more broadly at large angles for all the fibres there are large swathes of PMTs with an intensity of zero, providing little useful information about the beam shape. It was shown in [3] that with the old 2D generator, the systematic uncertainty on the beam profiles was the dominant source of error in the main SMELLIE analysis. To help improve this situation, it was decided to update the existing beam profiles.

These old beam profiles were originally determined by looking at SMELLIE data taken during the water-phase. Specifically, a “medium”-intensity subrun with one of the lasers firing at a wavelength of 495 nm, was chosen for each fibre. “Medium”-intensity corresponds to firing the relevant laser at a set intensity determined during an earlier commissioning process, for which the maximum occupancy of PMT hits at that intensity, i.e. the proportion of hits per event, corresponded to roughly 80%. This value was chosen as it allowed for high statistics in a relatively short run-time, but not so intense that the occupancy of any given PMT in the beamspot was 100%. Because Rayleigh scattering is strongly-dependent on wavelength, the long wavelength of light was chosen so that impacts from this scattering were small in the data.

SNO+ PMTs are unable to distinguish the exact number of photoelectrons being generated. One is typically only able to know if a PMT has been triggered at all, by any number of photoelectrons. As a result, the occupancy of a PMT over a number of SMELLIE events, o , is a biased estimator of the mean number of photoelectrons generated, μ . Assuming the number of photoelectrons generated in a given event follows Poisson statistics, the probability of generating k photoelectrons is:

$$P(k|\mu) = \frac{\mu^k e^{-\mu}}{k!}. \quad (4.1)$$

The probability of observing a “hit” in a given PMT corresponds to generating at least one photoelectron:

$$P(\text{hit}|\mu) = P(k \geq 1|\mu) = 1 - P(k = 0|\mu) = 1 - e^{-\mu}, \quad (4.2)$$

which implies after rearrangement that one can determine the mean number of photoelectrons per event from the occupancy by:

$$\mu = \ln(1 - o). \quad (4.3)$$

This is the reason why we want to avoid PMTs with occupancies of 100%: they preclude one's ability to convert into a value for μ by looking at occupancy alone. We call this conversion from occupancy into npe the “multi-hit correction”. The impact of this correction is typically small for most PMTs, but can become very significant in a fibre's beamspot.

Once the npe mapping from data was obtained, a correction was then made for the detector's optics: even ignoring a fibre's beam profile, we still expect certain PMTs to be illuminated more than others because of e.g. reflections off the AV, or the solid angle subtended by the PMT bucket opening. For each fibre, a simulation was made where the beam profile was set as isotropic, and the corresponding npe mapping obtained: this map held information about the detector optics only. The beam profile mapping was then derived by simply dividing each fibre's npe mapping from data to its associated isotropic MC npe map. It is these maps that were first used in section 4.1.2.

4.2.1 Combining beam profile datasets

Fortunately, much more SMELLIE data was taken during the water-phase than was used for the original beam-profiling analysis. This additional data can be combined with that which was already used to far better constrain the beam profiles. In particular, given the existing assumption that scattering effects are minimal above wavelengths

4.2 Improving the beam profiles

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Run Number	Run Type	Comments
114,018	All PQ lasers; SuperK laser in 400–500 nm range	Only PQ495 laser and SuperK at 495 nm is used
114,023	SuperK laser in 500–600 nm range	Part 1 of this wavelength range; crash occurred on last subrun, so that subrun is ignored
114,034	SuperK laser in 500–600 nm range	Part 2 of this wavelength range

Table 4.1 Water-phase runs used for new beam profiling.

of ~ 490 nm, all data taken with wavelengths above this can also be used. The specific runs (and associated comments about their specifics) are described in Table 4.1. Because high-intensity runs require a different analysis approach (PMTs with high occupancies must use charge, not occupancy, to estimate npe), for this analysis we only considered subruns that used low or medium intensity set-points.

For each subrun j of data per fibre, we look only at PMT hits for each PMT i that has been identified as “good” for that subrun¹, $i \in G_j$. G_j here represents the set of good PMTs in subrun j . In particular, a “good” PMT must have valid electronic and timing calibrations, be at high voltage and masked into the detector’s trigger system for that subrun. In addition, an angular cut of $\alpha < 60^\circ$ was made to remove PMTs that are well outside any reasonable beam direction. To isolates the hits arriving directly from the fibre without reflecting, scattering, or being noise, a time cut was also made. Because what matters is the time relative to emission from the fibre, and the expected time-of-flight from fibre to different PMTs varies, a quantity known as the time residual was used. Starting with the calibrated hit time of a given PMT relative to the event’s trigger time, t_{hit} , the expected time-of-flight t_{TOF} from the fibre to the PMT was subtracted, estimated with the collaboration’s “Light Path Calculator”. Then, the emission time was also subtracted, t_{emm} , estimated by looking at the second-earliest value of $t_{hit} - t_{TOF}$ within the fibre’s central beamspot, defined as the PMTs for which

¹Strictly speaking, a PMT’s “goodness” is only determined on a run-by-run, not a subrun-by-subrun level, but this has no impact on the analysis.

¹ $\alpha < 3^\circ$. It was found that a “loose” time residual cut of $t_{res} \in [-10, +12]\text{ns}$ was
² sufficient to remove the vast majority of non-direct light with little signal sacrifice. In
³ the situation where a subrun with intensity was very small, it would not regularly have
⁴ at least two hits in the beamspot, and so the time residuals calculated would not be
⁵ valid for many events. To avoid this situation, a cut was made on any subruns with
⁶ mean intensities below 9 within their beamspot. This value was chosen as it would
⁷ mean a 2σ fluctuation downwards of $2 \cdot \sqrt{9} = 2 \cdot 3 = 6 \text{ npe}$ would still have more than
⁸ the 2 hits necessary for timing reconstruction. One fibre, FS207, has no data subruns
⁹ that satisfy this condition, and as such will have to be dealt with separately. For the
¹⁰ time being, this fibre was ignored.

¹¹ Extracting the underlying beam profiles from these data required some careful
¹² thought, especially because different subruns could have different intensities. Consider-
¹³ ing a PMT i in subrun j , the mean number of photoelectrons generated per event in
¹⁴ that PMT for that subrun, μ_{ij} can be decomposed as follows:

$$\mu_{ij} = I_j k_i = I_j b_i f_i. \quad (4.4)$$

¹⁵ I_j is the intensity of the subrun, i.e. the mean number of photons generated from the
¹⁶ fibre in that subrun per event. k_i is the probability that a given photon generated at
¹⁷ the fibre source ends up generating a photoelectron in PMT i . This itself can be further
¹⁸ split into two components: b_i , the probability that a given photon at the fibre source
¹⁹ points in the direction of PMT i ; and f_i , the probability that a given correctly-pointed
²⁰ photon actually makes it to the PMT and successfully generates a photoelectron. It is
²¹ b_i that is the actual beam profile we would like to measure.
²²

²³ Letting p_{ij} be the probability of observing a hit for a given event on a given
²⁴ PMT, the probability of observing m_{ij} hits out of N_j events in the subrun will be

4.2 Improving the beam profiles**31**

binomially-distributed:

$$P(m_{ij}|\mu_{ij}) = L(\mu_{ij}|m_{ij}) = \binom{N_j}{m_{ij}} p_{ij}^{m_{ij}} (1-p_{ij})^{N_j-m_{ij}} = \binom{N_j}{m_{ij}} (1-e^{-\mu_{ij}})^{m_{ij}} e^{-\mu_{ij}(N_j-m_{ij})}. \quad (4.5)$$

Here we have used equation 4.2, and noted that this probability distribution in m can be re-framed as a likelihood function for the parameter μ_{ij} . Considering only a single subrun of data, the maximum likelihood estimate of the parameter μ_{ij} can be shown to be:

$$\langle \mu_{ij} \rangle = -\ln \left(1 - \frac{m_{ij}}{N_j} \right) = \ln (1 - o_{ij}) \quad (m_{ij} \neq N_j), \quad (4.6)$$

where o_{ij} is just the occupancy of PMT i in subrun j . This is just the multi-hit correction formula seen in equation 4.3, which makes sense.

When looking at multiple subruns for the same fibre, the total likelihood function for a given PMT when considering all the data for a given fibre will be the product of the likelihoods from each dataset,

$$L(\{I_j\}, k_i | \{m_{ij}\}) = \prod_j L(I_j, k_i | m_{ij}) = \prod_j \binom{N_j}{m_{ij}} (1 - e^{-I_j k_i})^{m_{ij}} e^{-I_j k_i (N_j - m_{ij})}. \quad (4.7)$$

This leads to a log-likelihood distribution of

$$\mathcal{L}(\{I_j\}, k_i | \{m_{ij}\}) = \sum_j \left[\ln \left(\binom{N_j}{m_{ij}} C_{m_{ij}} \right) + m_{ij} \ln \left(1 - e^{-I_j k_i} \right) - I_j k_i (N_j - m_{ij}) \right]. \quad (4.8)$$

Formally, one could combine the likelihoods of all the PMTs together, and by looking at the maximum likelihood estimates for each of the parameters measure the parameter values this way. However, the set of equations one obtains through this approach quickly become analytically intractable, because the PMTs are coupled by the intensity values I_j . Even a direct numerical approach would be liable to fail: for a given fibre

¹ there can be dozens of subruns, and many thousands of PMTs of relevance, so the
² dimensionality of the system of equations would be far too large.

³ Because of this, a different approach was taken. It is expected that in a subrun the
⁴ total npe, summed over all good PMTs, should be proportional to the intensity value
⁵ I_j . One must be careful about this construction — different subruns can have different
⁶ sets of good PMTs, so two subruns with identical I_j values could have a larger summed
⁷ npe merely because more PMTs were good in that subrun. To counter-act this effect,
⁸ only PMTs that were classified as good in *all* subruns being analysed for that fibre
⁹ would be used for the npe summation. In other words, we use data from PMT i for
¹⁰ summing only if:

$$\text{11} \quad i \in \mathcal{I} = \bigcap_j G_j. \quad (4.9)$$

¹² We can then define the summed npe for a given subrun as $S_j = \sum_{i \in \mathcal{I}} \text{npe}_{ij}$, and assert
¹³ that $I_j = cS_j$. By finding a value proportional to I_j , there is now enough information
¹⁴ to maximise the log-likelihood $\mathcal{L}(k_i | \{m_{ij}\}, \{I_j\})$ with respect to k_i for each PMT
¹⁵ independently, and hence obtain estimates for these k_i parameters.

¹⁶ Of course, what is actually wanted are the underlying b_i values, not k_i . This is
¹⁷ where isotropic simulations come in. For each run of data used, a matching isotropic
¹⁸ MC was produced. As an example, a simulation for run 114,023 contained 200,000
¹⁹ events for each fibre using an isotropic beam profile, over the full wavelength range
²⁰ considered in this run, 500–600 nm, using the same run conditions as in data (which
²¹ PMTs were at high voltage, etc.).

²² For each isotropic MC run, both I_j^{MC} and k_i^{MC} were calculated via the method
²³ described above. Because the simulations were isotropic, the underlying value for b_i
²⁴ was constant across all the PMTs, and so $ak_i^{MC} = f_i$. By doing some rearranging of

4.2 Improving the beam profiles

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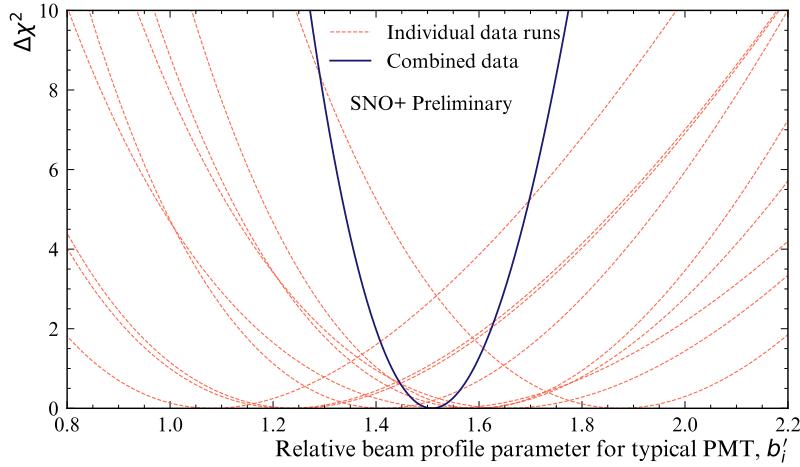


Fig. 4.6 Plot of $\Delta\chi^2 \simeq X_i$, twice the negative log-likelihood ratio, for both single subruns of a typical PMT, and when all relevant subruns are combined.

equation 4.4, we find that:

$$\mu_{ij} = I_j b_i f_i = c S_j b_i a k_i^{MC} = (acb_i) S_j k_i^{MC}. \quad (4.10)$$

As a result of this, given the set $\{S_j\}$ and k_i^{MC} , one can maximise the log-likelihood \mathcal{L} with respect to $b'_i = acb_i$ numerically, to obtain the maximum likelihood estimate of b'_i . Because a and c were global constants of proportionality, they would become irrelevant as soon as the beam profile was normalised in the CDF-creation process outlined in 4.1.2.

Figure 4.6 shows the shape of this log-likelihood distribution for a particular PMT when considering fibre FS007's beam profile. One can see how individual subruns provide much more information when combined than if one looked at a single subrun alone.

Another benefit of using this log-likelihood approach is that the resulting distribution's shape can be used for uncertainty estimation. In almost all cases, Wilks Theorem [4] allows us to produce 1σ confidence intervals about the maximum likelihood

estimate for b'_i , $\langle b'_i \rangle$, because

$$X(b'_i) = -2 [\mathcal{L}(b'_i) - \mathcal{L}(\langle b'_i \rangle)]$$

¹ approximates a χ^2 -distribution. As a result, the error bounds on our parameter estimate
² are given by when $X = 1$. The fact that the shape of X can be well-approximated by
³ a quadratic in the region near $X = 0$ indicates the validity of Wilks' Theorem being
⁴ used here.

⁵ Only a couple of exceptions to this approach of parameter estimation are possible.
⁶ In the case where $m_{ij} = N_j$, i.e. a PMT has 100% occupancy, no maximum likelihood
⁷ estimate exists: we need not worry about this, as subruns where this occurs have not
⁸ been used. On the other end, however, there are some PMTs for certain fibres where
⁹ after all subruns of data have been included, there remains no hits. In this scenario,
¹⁰ one can show that the log-likelihood becomes linear in the beam profile parameter:

$$\mathcal{L}(b'_i | \{m_{ij} = 0\}) = b'_i k_i^{MC} \cdot \sum_j [I_j N_j]. \quad (4.11)$$

¹¹ This scenario is very much reminiscent of rare-decay searches, and a similar approach
¹² can be used. A 1σ upper limit on the possible value for b'_i can be analytically-calculated
¹³ to be:

$$b'_{i,ulim} = -\frac{k_i^{MC} \sum_j [I_j N_j]}{\ln [1 - \text{erf}(1/\sqrt{2})]}, \quad (4.12)$$

¹⁴ where $\text{erf}(x)$ is the error function.

¹⁷ 4.2.2 Results & Discussion

¹⁸ Figure 4.7 shows the impact of using additional subruns of data on a typical beam
¹⁹ profile. One can clearly see the great reduction in the number of PMTs with no hits

4.2 Improving the beam profiles

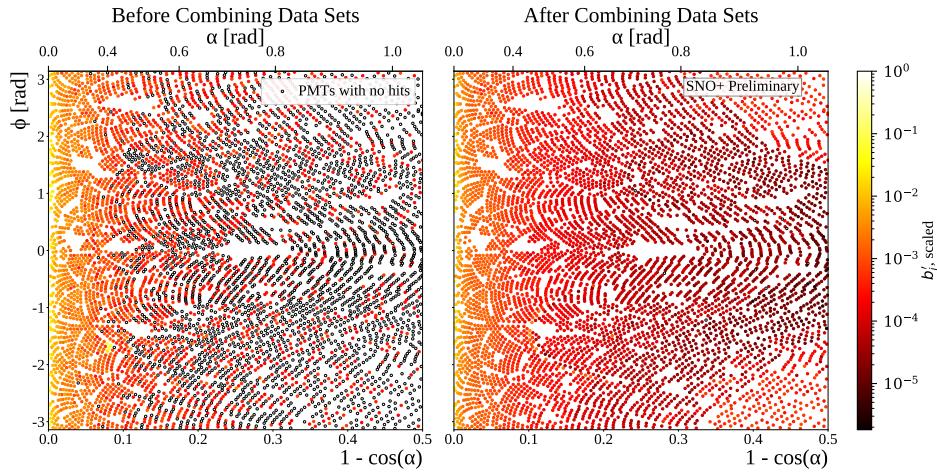


Fig. 4.7 Comparison between old and updated beam profiles for fibre FS055, after combining multiple data sets. Once again, the relative intensities (b'_i) for each PMT are given by the colour of each point, the position of each plotted in the 2D (r, ϕ) -space. The relative intensities have been both scaled here so that the largest value equals 1. Hollowed-out points are PMTs that, even after all relevant subruns have been combined, have no PMT hits.

in data. That many more data sets were included allowed for the major increase in dynamic range available for measuring these b'_i values. One can also note that by including additional data the curious spot that was seen in the old beam profile our at $r \approx 0.08$ has gone, further indicating that it was an artefact of that single data set.

Further details can be gathered from the interpolated intensity maps, one of which can be seen in figure 4.8. There are two curious stand-out features that can be seen here: firstly, there are multiple distinct parabolic arcs. These correspond to the shadows of the ropes that hold up/down the AV. More precisely, they are the mismodelling of those shadows — if the shadows were in the right place in the isotropic MC, then they would correctly cancel out any decreased intensity seen in the data of shadowed PMTs. These shadows could be mismodelled either because the positions of the ropes in the MC are in the wrong place, or the fibre's emission position is wrong. Note that any mismodelling of the fibre's nominal emission direction has no impact on this shadowing problem, as changing that direction merely causes a change of basis in the (r, ϕ) -space.

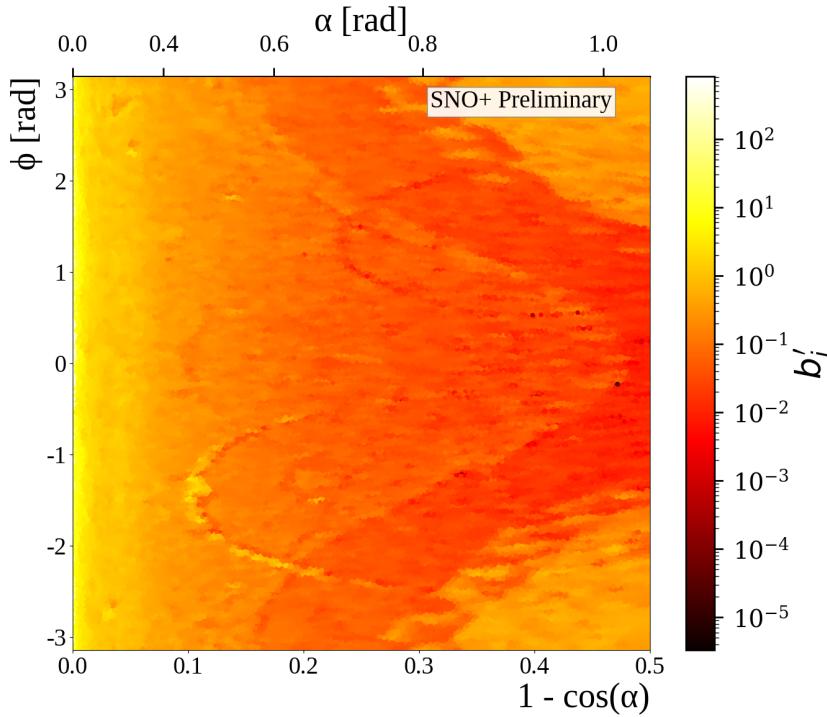


Fig. 4.8 Interpolated intensity map for the new updated beam profile of fibre FS055. The misalignment of rope shadows and AV effects, can both be seen.

¹ The latter possibility of incorrect fibre positions are more likely, and in fact these arcs
² in the beam profiles could be used as an effective way to correct for this problem.

³ The second distinctive feature of this intensity map is the large band of lower
⁴ intensity varying between $r \approx 0.2 - 0.5$, followed by larger intensity out at large
⁵ r values. This feature comes from light reflecting off the AV surface, or internally-
⁶ reflecting. The reason for this band's functional dependence on ϕ is that this particular
⁷ fibre, FS055, has a nominal fibre direction $\sim 10^\circ$ from pointing radially-towards the
⁸ detector's centre. This feature appears in the updated beam profiles of all fibres, but
⁹ its shape depends on the particular fibre's direction — for fibres pointing directly
¹⁰ towards the detector's centre, there is little ϕ -dependence observed. Like the ropes,
¹¹ this feature must come from some form of mismodelling of the optics of the AV. A
¹² de-facto shadowing of PMTs in line with tangents from the AV surface which intersect

4.2 Improving the beam profiles

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the fibre position is to be expected. One also expects PMTs at polar angles larger than
1 this to have their observed intensities boosted from reflected light off the AV. However,
2 the discontinuities seen in the beam profiles indicate that for whatever reason this
3 effect has been over-emphasised in the simulation.
4

There is a further phenomenon that can be seen, by comparing beam profile values
5 obtained from a single subrun to the updated combined beam profile. This can be
6 done by calculating the residuals corresponding to the single subrun, relative to the
7 combined data set. The residual is negative if the combined data sets have a b'_i below
8 the equivalent for a given single subrun; that is, the combined model underestimates
9 this subrun for that PMT.
10

This information was plotted for two different subruns from the same fibre, seen in
11 figure 4.9. One subrun was the same one used by Esther Turner for the original 2D
12 beam profiling, with a wavelength of 495 nm; the latter was at the longer wavelength of
13 595 nm. For both subruns, most PMTs are seen to have intensities well-modelled by the
14 combined model. However, there appears to be a significant amount of mismodelling
15 within the beamspot. There also appears to be some systematic shift between data
16 and model at somewhat larger polar angles. Moreover, this mismodelling seems not to
17 be merely random, but a function of wavelength: at shorter wavelengths the beamspot
18 tends towards being overestimated and then underestimated at larger values of α . At
19 longer wavelengths, the beamspot becomes underestimated, with larger angles getting
20 overestimated. This indicates that there appears to be a wavelength-dependence on the
21 beam profiles, contradicting one of the main assumptions which we used to combine
22 the water-phase data in the first place! All three of these features — rope shadows,
23 AV reflections, and wavelength dependence — add systematic uncertainty to the beam
24 profiles, beyond the statistical uncertainty as measured by the width of the likelihood
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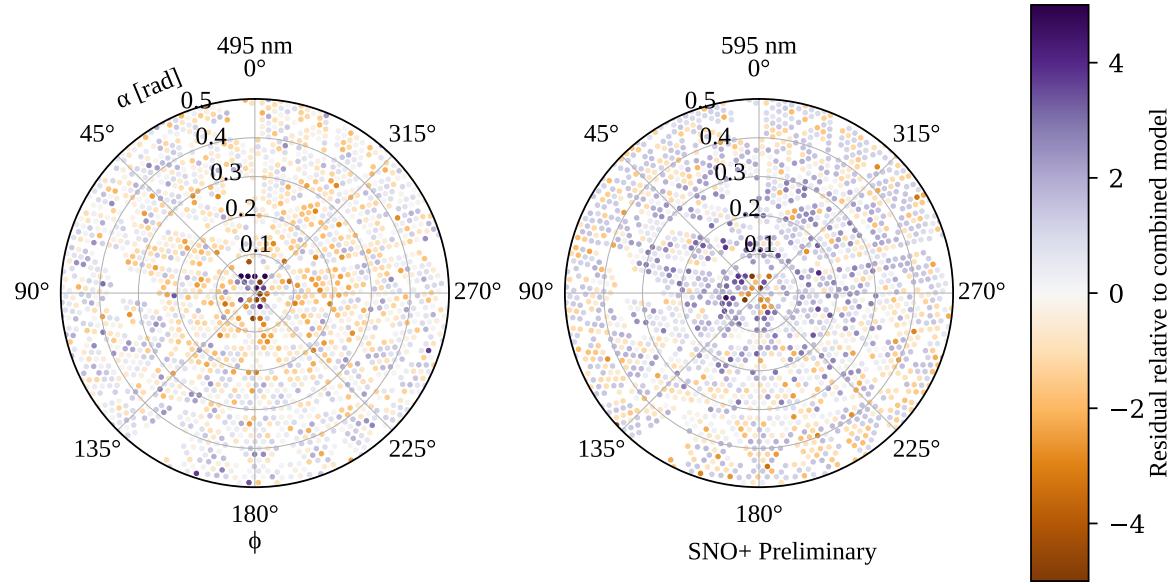


Fig. 4.9 Residuals from subruns at two different wavelengths, both compared to the combined beam profile model for fibre FS055. A negative sign, and hence bluer colours, indicate that the combined model underestimates the observed intensity for that particular subrun. Values with a magnitude beyond 5 are shown capped at this maximal value for the purposes of this plot. These PMTs are plotted in the polar fibre coordinates (α, ϕ) .

¹ distribution. Certainly if one wanted to further improve the uncertainties in the beam
² profiles, tackling these challenges would be key.

³ 4.3 Comparisons between Data and Simulation

⁴ This focuses on disagreements noticed between data and MC even after the new
⁵ generator and beam profiles have been used. Important to mention that none of
⁶ these are necessarily game-ending, they are just systematics that may or may not be
⁷ substantial in a given analysis with SMELLIE. Main classes of discrepancies noticed:

4.3.1 Forward Hemisphere Discrepancies

The continued disagreement between data and MC when it comes to measured npe in various parts of the "forward" hemisphere. This includes the central beamspot, the TIR region, rope shadows, and a noticeable wavelength-dependence.

4.3.2 Emission Time Discrepancies

For certain lasers, a strong mismatch in the observed hit time residuals for prompt light. Also, a mysterious +18 ns bump seen for the PQ495 laser, and a trigger jitter in the SuperK laser.

4.3.3 Backward Hemisphere Discrepancies

The observed distribution of hits vs time and angle in MC does not match data in a number of ways for PMTs near the fibre emission point. Includes the outer-water scattering length, rope reflections, and investigations into whether certain modifications to the optics could plausibly fix things (so far, no).

Chapter 5

Analysis of SMELLIE Data in the Scintillator Phase

This chapter contains two sets of analyses: measurements of the extinction lengths of the scintillator as a function of wavelength and time, as well as monitoring the Rayleigh scattering length over time.

5.1 Extinction Length Analysis

- Motivation for this analysis given by a discrepancy between MC and data in the number of photons observed at different PPO concentrations was found. Explain multiple ways that this could happen, one being via scattering or absorption. A "straightforward" way of testing this hypothesis is via measuring the extinction length using SMELLIE, as we don't need to distinguish between scattering and scintillator absorption/reemission.
- Theory for how to measure in-situ extinction length of scintillator for a given wavelength, via a data-to-data comparison. Make clear the assumptions being

made for this analysis (e.g. external water scattering cross-section and beam profile unchanged between water->scintillator phases).

- Note any corrections that have to be made to account for differences between water and scintillator phases, notably the change in refractive index moving the beamspot.
- Show approach going to be used with water- and scint-phase MC. Demonstrate that it works over a variety of extinction lengths. Can any limitations be seen?
- Description of actual data sets used - water-phase data set, scintillator data sets. Obtain results.
- Explain possible origins of uncertainty, both statistical and systematic.
- Compare to RAT model(s), other measurements made. Differences? What conclusions can be made?

5.2 Scattering Analysis

- Comparison to MC is necessary in scattering analysis, compared to merely being needed as a correction factor. This is because of the angular dependence of scattering. As a result, we can be far more susceptible to systematics from poor modelling!
- As a warning, show how Krish's/Esther's approach to the SMELLIE scattering analysis suffers majorly from these systematic effects. Motivates the need for either reduced systematics, or an alternative analysis approach that is more robust to them!

5.2 Scattering Analysis**43**

- Propose the new analysis approach: looking at light in the "bad lightpath" PMT region (define what this is). Show how simulations indicate this should be a region with a very high purity of scattered light, and (assuming all else being equal) robust to beam profile uncertainties. 1
2
3
4
- Problem of systematics now pushed onto the calculation of an average absolute emission intensity. Show how various methods don't work particularly well. Look at "beamspot but excepting the central bit": if that works well, then we can continue! Otherwise, we'll have to live with measuring relative scattering lengths instead of absolute amounts, using the outer water back-scattering as a measure of the relative emission intensity. 5
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- Actually do the proposed analysis on data, versus time and wavelength. Do the results seem consistent between fibres? Are they sensible values? 11
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Chapter 6

1

Solar Oscillation Analysis

2

Driving out into the Sun

Let the ultraviolet cover me up

Looking for a Creation Myth

Ended up with a pair of black lips

3

This is the End

PHOEBE BRIDGERS

Measuring the “solar” neutrino oscillation parameters Δm_{21}^2 and θ_{12} is one of the principal aims of the SNO+ detector during the scintillator-phase. There are, in fact, two complementary methods of measuring these parameters: the oscillations of anti-neutrinos from terrestrial nuclear reactors, and the oscillations of neutrinos from the Sun.

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This chapter focuses on the latter approach, using ${}^8\text{B}$ neutrinos coming from the Sun to measure the solar oscillation parameters. An initial background-free study was performed by Javi Caravaca [], which demonstrated that it was indeed possible to make such a measurement in the detector. The work in this chapter builds on substantially from that analysis. This chapter also draws on the associated reactor anti-neutrino

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¹ analysis built by Iwan Morton-Blake []], and more broadly from the general techniques
² used in the $0\nu\beta\beta$ analysis of Tereza Kroupova [] and Jack Dunger [].

³ This chapter begins by explaining how it is possible to measure the solar oscillation
⁴ parameters via ^8B events. Then, the framework used to perform the analysis is then
⁵ explained: that of a *Bayesian Analysis using Markov Chain Monte Carlo techniques*.
⁶ After the method has been described, the dataset upon which the analysis is performed
⁷ is then introduced. The results and associated validation are then given. Given these
⁸ results, a projection is then made for the expected sensitivity to θ_{12} as a function of
⁹ livetime.

¹⁰ **6.1 Analysis Methodology**

¹¹ **6.1.1 Observational Principle**

¹² How can we measure neutrino oscillation parameters via solar neutrinos in the SNO+
¹³ detector? As discussed in Chapter 1, it is possible to detect all flavours of neutrino
¹⁴ through elastic scattering with electrons in the detector. If this interaction was purely
¹⁵ neutral-current, then there would be no way of telling the flavour-state of an interacting
¹⁶ neutrino. However, electron neutrinos are able to interact through an additional
¹⁷ charged-current mode. This modifies the cross-section for electron neutrinos, and
¹⁸ means that as the survival probability for electron neutrinos generated from the Sun,
¹⁹ P_{ee} , is modified, the interaction probability of neutrinos with the detector will also.

²⁰ Of course, we do not directly measure neutrino energies in the detector — only
²¹ the associated scattered electron. If there were no correlation between the observed
²² electron energy and its associated neutrino, then the only effect of neutrino oscillations
²³ would be to change the overall observed rate of events due to this process. There
²⁴ would be no change in the shape of the event's energy spectrum, even though neutrino

6.1 Analysis Methodology

47

Fig. 6.1

Fig. 6.2

oscillations are a function of neutrino energy. Fortunately, there is some dependence 1
of the neutrino's energy on that of the scattered electron. This dependence can be 2
seen in Fig. 6.1 for ${}^8\text{B}$ electron neutrinos interacting in SNO+. As can be seen, the 3
dependence is weak, and comes mostly from basic energy conservation: If one observes 4
a 10 MeV electron event in the detector, it can't reasonably have come from a 5 MeV 5
neutrino. 6

In Fig. 6.2 we can see the impact each physical process has on the energy spectrum 7
that we eventually observe. We start with a broad energy distribution of ${}^8\text{B}$ electron 8
neutrinos generated in the Sun. These neutrinos then oscillate their flavour state as 9
they propagate to the detector, in an energy-dependent manner. When a (tiny) fraction 10
of these neutrinos interact with the electrons in our detector, there is both an energy- 11
and flavour-dependence on the cross-section. The scattered electrons gain a kinetic 12
energy with some mild dependence on the inciting neutrino's energy, which is then 13
measured by the detector to within some energy resolution. 14

Let us now consider the dependence of P_{ee} on the individual neutrino oscillation 15
parameters. Recall from Eq. ?? that, after considering matter-induced oscillations 16
due to neutrinos passing through the Sun and possibly the Earth, $P_{ee} =$ 17
 $P_{ee}(\tan 2\theta_{12}^M, \sin \theta_{13}^M, \Delta m_{21,M}^2) = P_{ee}(\theta_{12}, \theta_{13}, \Delta m_{12}^2, \Delta m_{13}^2)$. Fig. 6.3 shows the dependence 18
of each of these four oscillation parameters on $P_{ee}(E)$. We can see that in reality 19
only the two parameters Δm_{21}^2 and θ_{12} have a substantial impact on $P_{ee}(E)$ and hence 20
the observed electron energy spectrum. Because of this, for this analysis we will only 21

Fig. 6.3

Fig. 6.4

¹ ever vary these two oscillation parameters, and keep θ_{13} and Δm_{13}^2 at their current
² global fit values¹ of $\sin^2 \theta_{13} = 0.0222$ and $\Delta m_{13}^2 = +2.515 \times 10^{-3} \text{ eV}^2$ [].

³ 6.1.2 Background Processes

⁴ Sadly, elastically-scattered electrons from ${}^8\text{B}$ neutrinos are not the only events we
⁵ see in the SNO+ detector during the scintillator phase. There are a number of
⁶ background processes that our signal must compete against. Below a reconstructed
⁷ energy of $\sim 2 \text{ MeV}$, it is known that various backgrounds completely swamp any
⁸ possible ${}^8\text{B}$ signal, and so for this analysis we only consider processes that can generate
⁹ reconstructed energies of at least $E_{\min} = 2 \text{ MeV}$. The following subsections explain
¹⁰ each of these backgrounds, as well as methods that have been used to mitigate them
¹¹ as much as possible.

¹² Internal Uranium- and Thorium-Chain Backgrounds

¹³ Although every effort has been made to make the scintillator cocktail that fills SNO+
¹⁴ to be as radio-pure as possible, there inevitably remain trace amounts of the radioactive
¹⁵ isotopes that derive from the decay chains of the ${}^{238}\text{U}$ and ${}^{232}\text{Th}$ isotopes. Fig. 6.4
¹⁶ shows these two decay chains. Fortunately, only a fraction of the radioactive isotopes
¹⁷ in these chains actually are capable of generating events in the detector with energies
¹⁸ above E_{\min} : these have been highlighted in Fig. 6.4 in gold.

¹We use the global fit results excluding Super-Kamiokande’s atmospheric data, and assuming normal ordering of the neutrino mass hierarchy. This choice has a tiny impact on the magnitudes of these two fixed parameters, the main impact being the sign of Δm_{13}^2 .

Of particular note are the decays of ^{212}Bi and ^{214}Bi . Both are capable of either α - or β -decays to Tl or Po isotopes, respectively. For the former, it is the subsequent β -decay of the Tl that can have a reconstructed energy above E_{\min} . For the latter, the Bi decay is the part of the pair of decays that can lie above E_{\min} . Although the α -decays here certainly have Q-values well above 2 MeV, the liquid scintillator quenches the observed energy well below E_{\min} . The so-called “Bi–Po” decays are particularly special because the lifetimes of ^{212}Po and ^{214}Po are 300 ns and 164 μs , respectively, which are short enough to allow for highly-effective coincidence tagging.

There are two classes of Bi–Po event in the detector: “out-of-window” events for which the Bi and Po occur in separate event windows, and “in-window” events whereby the Bi and Po occur within the same event window. These lead to two distinct strategies for tagging these kinds of events. For out-of-window Bi–Pos, we look for a delayed coincidence of two events. Using the tagging algorithm suggested in [] as a starting point, the chosen procedure was as follows. There must be two events that trigger the detector within 4 μs of one another, and both have a valid `scintFit` position reconstruction within 2 m of one another. The delayed candidate event must also have at least 100 cleaned PMT hits. This very broad coincidence tagging procedure was designed to ensure that the cut was as *efficient* in tagging (and hence, rejecting) Bi–Pos as possible, whilst negligibly impacting the solar signal. This is in contrast to the cuts chosen by Rafael Hunt-Stokes in [], which try and obtain a highly *pure* sample of Bi–Po tags.

Of course, the above delayed coincidence procedure cannot catch any of the in-window Bi–Po events. For these, we use a different approach. Because two decays happened in the same event window, we expect to see two distinct peaks in the event’s time residual spectrum. In order to look for this event topology, a likelihood-ratio classifier was run over events, first developed by Eric Marzec [] and re-coordinated for

Fig. 6.5

the 2.2 g l^{-1} LABPPO scintillator optics by Ziping Ye []. This classifier calculates the likelihood ratio between the null hypothesis of a $0\nu\beta\beta$ event (a proxy in this analysis for single-site events such as our ^8B signal) and the alternative hypothesis of an in-window Bi–Po event. The more negative the value of the result, `alphabeta212`, the greater the evidence there is for rejecting the null hypothesis of a single-site event. Events with $\text{alphabeta212} < 0$ were then rejected.

Combining both out-of-window and in-window Bi–Po tagging, the impact on $^{212}\text{Bi–Po}$, $^{214}\text{Bi–Po}$, and $^8\text{B } \nu_e$ events can be seen in Fig. 6.5. We consider here only events that pass all other cuts used in this analysis: see section ?? for the specifics of the cuts used. Because of the different lifetimes of the decays, $^{214}\text{Bi–Po}$ decays predominantly fall out-of-window whilst $^{212}\text{Bi–Po}$ events are typically in-window. This explains why the out-of-window tagging is substantially better at cutting $^{214}\text{Bi–Po}$ decays, whereas the in-window tagging far better tags $^{212}\text{Bi–Po}$ decays. Overall, within the analysis region of interest (ROI), the two combined cuts are able to tag TODO% of $^{214}\text{Bi–Po}$ triggered events, TODO% of $^{212}\text{Bi–Po}$ triggered events, whilst retaining TODO% of $^8\text{B } \nu_e$ signal events.

17 (α, n) Reactions

The impact of ^{238}U - and ^{232}Th -chain isotopes does not simply end at their direct decays. It is possible for the α s generated during these decays to undergo their own interactions with nuclei in the detector. Within the organic scintillator of SNO+, the dominant interaction of this type is when an α collides with a ^{13}C nucleus, emitting a neutron: $\alpha + ^{13}\text{C} \longrightarrow ^{16}\text{O} + \text{n}$. This is known as an (α, n) reaction.

The topology of this reaction in the detector is a delayed coincidence, as shown in Fig. 6.6. For the prompt signal, there is the light emitted from the α just before,

Fig. 6.6

Fig. 6.7

and the n just after the (α, n) . The neutron then thermalises and gets captured by another nucleus — usually hydrogen in SNO+ — which creates an excited state that then eventually decays, creating a γ that creates the delayed signal in the detector [].

As can be seen in Fig. 6.7, (α, n) interactions can lead to events reconstructed at a wide variety of energies, which could be an issue for this analysis. However, because they are delayed coincidence events with a typical decay time of ~ 100 ns, the aforementioned out-of-window Bi–Po tagging algorithm also efficiently tags (α, n) events. Looking again at Fig. 6.7, simply by using the out-of-window Bi–Po tagger without any further modifications TODO% of events in the ROI are cut.

External Backgrounds

All materials within the SNO+ detector are radioactive, not just the liquid scintillator cocktail. This includes the acrylic, ropes, external water, and PMTs. These components have had their radiopurity “assayed” (that is, measured) throughout the detector’s lifetime, often back to the construction of the original SNO detector itself. The materials other than the liquid scintillator are known to have far higher background levels, especially in the important ^{238}U - and ^{232}Th -chain backgrounds []. To distinguish between the inherent backgrounds within the scintillator, and the backgrounds from materials at larger radii, we use the terminology “internal” and “external”, respectively.

Although there are numerous external backgrounds, with a suitably accurate and precise position reconstruction algorithm they can be suitably handled. The simplest approach is with a so-called “fiducial volume” (FV) cut: just throw out all events that reconstruct beyond some radius. The only external background events that will

Fig. 6.8

reach within the FV are those that have reconstructed very poorly, or have some long-distance radiation that manages to deposit radiation close to the centre of the AV. Because α and β radiation can only travel short distances through the detector, it is only γ radiation that can realistically travel far enough into the detector to be able to reconstruct anywhere near the centre. Moreover, the intensity of this γ radiation attenuates exponentially towards the centre of the detector, meaning only a tiny fraction of the total number of external events reconstruct within a 3.5 m FV, say.

This strong radial-dependence can be seen in Fig. 6.8.

What this figure also demonstrates is that our solar signal has a completely different radial dependence to these backgrounds. As a result, if one considers not just the energy of events but also their reconstructed radius, then it is possible to get an additional handle on the external backgrounds. The FV cut can then be pushed further out to larger radii, allowing one to gain more signal statistics.

Work by Tereza Kroupova [] allows for additional means of distinguishing external backgrounds from the solar signal. The underlying assumption in the reconstruction of SNO+ events is that there was an electron at a single point, which is entirely valid for ^{8}B elastic scattering events. However, external backgrounds can fail this assumption in two ways. Firstly, these radioactive decays often generate γ radiation in addition to the main α/β particle, which creates a multi-site event. Because the `scintFit` position reconstruction algorithm is not prepared for a distribution of energy depositions in the scintillator, the t_{res} distribution will broaden. This allows an event classifier to be built that distinguishes between the t_{res} distributions of single-site events and externals, known as the “external background timing classifier”. Secondly, because external backgrounds that do reconstruct close to the centre of the detector typically have a γ that travelled a long distance towards the centre of the detector, we expect the earliest

Fig. 6.9

light that hits the PMTs to arrive most often along the direction of the reconstructed position vector. A distribution of PMT hits for a given event as a function of their angular distribution relative to the direction of position reconstruction can be built, and compared to the expected distributions for single-site and external background events. This is known as the “external background topological classifier”. Much like the classifier described in Section 6.1.2, the single-site events used for comparison were $0\nu\beta\beta$ events, but these have a similar single-site structure to the solar signal of interest in this analysis.

Fig. 6.9 shows the correlation between the two classifier results for both a typical external background, and $^8\text{B} \nu_e$ events.

Cosmogenic Isotopes

The final source of background events are radioactive isotopes that form via collisions of cosmic rays with atomic nuclei, known as cosmogenic isotopes. Most of these isotopes are short-lived [], with lifetimes $\mathcal{O}(1\text{ s})$. Fortunately, the depth of SNO+ means that our rate of cosmic ray muons interacting with the detector is only 3 an hour []. Because the rate is so low relative to other experiments, relatively straightforward approaches to tagging and removing cosmic ray muons and their cosmogenic followers can be utilised without substantial loss of livetime. Events are tagged as a cosmic ray muon if they create a sufficient number of hits in the outward-looking PMTs above background levels, as well as many hits within the detector itself. The details of this tagging for the scintillator-fill were put in place by Lorna Nolan [], modifying the existing algorithms used in the water-phase [] and in SNO []. After a tagged cosmic muon event, all events for the next 20s are then vetoed as a means of rejecting followers. This simple cut is enough to remove the vast majority of expected cosmogenic events

in the scintillator-phase. The expected impact on loss of livetime, and hence quantity of signal events, is 3 lots of 20 s vetoes an hour, that is to say 1/60th of the signal is lost via this cut.

There is one cosmogenic isotope with a long-enough half-life that even the 20 s muon follower veto is not sufficient to remove all events. This is ¹¹C, which β^+ -decays to stable ¹¹B with a half-life of 20.4 min. The maximum possible energy deposited in this decay is 1.982 MeV [], just below E_{\min} , so only a small fraction of ¹¹C events end up in the ROI: the ones with very high energies that get their energy reconstruction falsely-inflated by some amount. As a result, this background is expected to be very much sub-dominant to all other backgrounds in this analysis. Because this background is important to consider for some other analyses, a triple-coincidence tagging algorithm is being built by Katharine Dixon [], but not used for this analysis currently.

6.1.3 The Log-likelihood Test Statistic

At the highest level, this analysis involves taking the data observed in the scintillator-fill after applying a certain set of cuts, along with simulated PDFs for all processes believed to build up the observed data with those same cuts applied, and then attempting to fit the combined energy and radial distributions of the MC to that of the data. Given a set of PDFs, to try and match the distribution of observables in data we can modify a number of parameters. These consist of the normalisations of each PDF (i.e. the total number of events observed due to that process), and any systematic parameters that could modify the shapes of these distributions. For this analysis, the neutrino oscillation parameters act as *de facto* systematic parameters, as they modify the shape of the ⁸B PDFs. Of course, unlike usual systematics the oscillation parameters are what we are actively trying to measure, instead of being a nuisance.

In order to perform a fit to data in this way, we must first answer a set of questions:

-
- | | |
|--|-------------|
| 1. Which signal and background processes must we consider? | 1 |
| 2. In addition to their normalisations, are there any further parameters necessary to specify the distributions of the PDFs for each of the processes? Systematics and oscillation parameters are good examples. | 2
3
4 |
| 3. What is our test statistic? | 5 |
| 4. What algorithm do we use to try and find the best-fit result? | 6 |
| 5. How do we measure uncertainties on these best-fit values for each parameter? | 7 |

In section 6.1.2, question 1 was answered for this analysis. We now give the answer to question 3; all other questions on this list will be answered shortly. 8
9

The test statistic used for this analysis is the *binned extended log-likelihood*. Once the data and MC PDFs have been binned in both the observables of interest, it is assumed that the expected number of events in a given bin j is governed by a Poisson distribution: 10
11
12
13

$$P_j(n_j|\lambda_j) = \frac{\lambda_j^{n_j} e^{-\lambda_j}}{n_j!}, \quad (6.1) \quad 14$$

where $P_j(n_j|\lambda_j)$ is the probability of observing n_j events in bin j , given an expectation of λ_j events in total from signal and background processes in that bin. This λ_j can be decomposed into each of the expected rates for each process, i : 15
16
17

$$\lambda_j = \sum_{i=1}^{N_{\text{PDFs}}} \mathcal{N}_i P_{ij}(\boldsymbol{\theta}), \quad (6.2) \quad 18$$

where N_{PDF} is the number of PDFs being considered in the analysis, \mathcal{N}_i is the normalisation parameter of the i^{th} PDF, and $P_{ij}(\boldsymbol{\theta})$ is the probability of observing an event of process type j in bin i , assuming a set of non-normalisation parameters $\boldsymbol{\theta}$. By combining the probabilities of all the bins together, the total probability for a given 19
20
21
22

1 set of processes assuming these parameters to give rise to the data seen is:

$$2 P(\mathbf{n}|\mathcal{N}, \boldsymbol{\theta}) = L(\mathcal{N}, \boldsymbol{\theta}|\mathbf{n}) = \prod_{j=1}^{N_{\text{bins}}} \frac{\left[\sum_{i=1}^{N_{\text{PDFs}}} \mathcal{N}_i P_{ij}(\boldsymbol{\theta}) \right]^{n_j} e^{-\sum_{i=1}^{N_{\text{PDFs}}} \mathcal{N}_i P_{ij}(\boldsymbol{\theta})}}{n_j!}, \quad (6.3)$$

4 where N_{bins} is the total number of bins being considered in the analysis. This probability
 5 can be re-framed as the likelihood of the vectors of parameters \mathcal{N} and $\boldsymbol{\theta}$ given
 6 the vector of number of events in each bin, \mathbf{n} : $L(\mathcal{N}, \boldsymbol{\theta}|\mathbf{n})$. It is rare to see the
 7 likelihood as-is, instead, for computational purposes the log-likelihood is used instead,
 8 $\mathcal{L}(\mathcal{N}, \boldsymbol{\theta}|\mathbf{n}) := \ln L(\mathcal{N}, \boldsymbol{\theta}|\mathbf{n})$. We can then get to the formula actually used for this
 9 analysis:

$$10 \mathcal{L}(\mathcal{N}, \boldsymbol{\theta}|\mathbf{n}) = - \sum_{i=1}^{N_{\text{PDFs}}} \mathcal{N}_i + \sum_{j=1}^{N_{\text{bins}}} n_j \ln \left(\sum_{i=1}^{N_{\text{PDFs}}} \mathcal{N}_i P_{ij}(\boldsymbol{\theta}) \right). \quad (6.4)$$

12 6.1.4 The Bayesian Statistical Approach

13 There are two main schools of statistical inference, “Frequentist” and “Bayesian”. In
 14 the former, probabilities describe the fraction of times a situation can be found within
 15 the whole ensemble of possible worlds. For the latter, we care not about an ensemble
 16 of worlds but instead our degree of belief in this current one. We update our beliefs as
 17 we acquire knowledge of the world through Bayes’ Theorem:

$$18 P(\boldsymbol{\mu}|\mathbf{x}) = \frac{\mathcal{L}(\boldsymbol{\mu}|\mathbf{x}) P(\boldsymbol{\mu})}{P(\mathbf{x})}. \quad (6.5)$$

19 Here, $\boldsymbol{\mu}$ is the set of parameters that model our system, $P(\boldsymbol{\mu})$ is our *prior* (pre-existing)
 20 distribution for those model parameters, and \mathbf{x} is the data taken in our experiment. The
 21 updated, *posterior* distribution $P(\boldsymbol{\mu}|\mathbf{x})$ is then the prior multiplied by the likelihood
 22 of parameters $\boldsymbol{\mu}$ given observations \mathbf{x} , $L(\boldsymbol{\mu}|\mathbf{x})$, and divided by the total probability
 23 $P(\mathbf{x})$ of observing \mathbf{x} under any circumstance.

Both approaches to statistics are widely-used in statistical analysis, in both particle physics and beyond. The Bayesian approach was used for this analysis, as it was believed that this helps keep transparent what assumptions are being made in the analysis.

Now, if one is able to determine the overall posterior distribution, then it is possible to derive best-fit values with uncertainties for all parameters in the fit. This is done by “marginalising” the posterior distribution, i.e. integrating over all parameters other than the one of interest. A sensible best-fit value is then the modal marginalised posterior density, the highest value in the marginalised distribution. The uncertainty on this value is derived from the spread of the marginalised posterior, by the calculation of the 1σ Credible Interval (CI): this is the set of values for a given parameter which has a total posterior probability of 68.3%, and contain the best-fit value. There are in fact an infinite number of CIs that satisfy this property; for this analysis, the values are chosen in decreasing order of marginalised posterior probability density.

6.1.5 Markov Chain Monte Carlo

Of course, all of this assumes that one can accurately determine the posterior density distribution. Whilst the likelihood and prior distribution are straightforward enough to calculate, often-times $P(\mathbf{x})$ (which acts as a normalisation) is very challenging to determine. This is because calculating this normalisation involves integrating the likelihood over all the parameter space, and if there are a large number of parameters this can become enormously numerically complex. An alternative approach is needed!

That alternative comes in the form of *Markov Chain Monte Carlo*, MCMC. A Markov Chain is any mathematical system for which the next state of the system is dependent only on its current state; the system is in some sense “memoryless”. For a large class of Markov Chains — those that are “ergodic” and “aperiodic” — one can

¹ prove that regardless of the initial position on the chain, the probability distribution
² converges to the same distribution π . MCMC uses such a Markov Chain which attempts
³ to converge towards the posterior density distribution in particular. In MCMC, after
⁴ choosing the initial position in the parameter space, successive states are chosen at
⁵ random with a probability dependent only on the properties of the current position
⁶ in parameter space and the proposed position. The convergence property of Markov
⁷ Chains means that the set of steps made in the parameter space after some initial
⁸ number of steps will have a distribution that converges to that of the posterior density
⁹ distribution.

¹⁰ There are a number of MCMC algorithms, and the particular one used in this
¹¹ analysis is that of the *Random-Walk Metropolis-Hastings Algorithm*. In this algorithm,
¹² after the initial position in the parameter space μ , a new step is proposed some distance
¹³ from the current one, μ' . This step is chosen at random from a multivariate Gaussian
¹⁴ distribution centred on the current position, with widths in each dimension of the
¹⁵ parameter space chosen beforehand as constants for tuning the MCMC process. This
¹⁶ choosing of a new proposed step at random is what gives the algorithm its Monte Carlo
¹⁷ and Random Walk titles. Once a new step is proposed, it is accepted as the new step
¹⁸ with a probability $S(\mu'|\mu)$ according to the condition of *detailed balance*:

$$\begin{aligned} S(\mu'|\mu) &= \min\left(1, \frac{P(\mu'|\mathbf{x}) R(\mu|\mu')}{P(\mu|\mathbf{x}) R(\mu'|\mu)}\right) = \min\left(1, \frac{L(\mu'|\mathbf{x}) P(\mu') R(\mu|\mu')}{L(\mu|\mathbf{x}) P(\mu) R(\mu'|\mu)}\right) \\ &= \min\left(1, \frac{R(\mu|\mu')}{R(\mu'|\mu)} \exp\left[\mathcal{L}(\mu'|\mathbf{x}) - \mathcal{L}(\mu|\mathbf{x}) + \ln \frac{P(\mu')}{P(\mu)}\right]\right). \end{aligned} \quad (6.6)$$

²² $R(\mu'|\mu)$ is the probability density that position μ' is proposed as a step from position μ ,
²³ and vice versa for $R(\mu|\mu')$. In most cases, because of the use of the same multivariate
²⁴ Gaussian in choosing proposals, $\frac{R(\mu|\mu')}{R(\mu'|\mu)} = 1$ simply. This component only becomes

important at the edges of the parameter space, preventing the sampling probability
1 being incorrectly impacted if a proposed step goes outside the allowed parameter space.
2

It is the detailed balance condition that ensures convergence of the MCMC algorithm
3 to specifically the posterior density distribution. Crucially, because it is only dependent
4 on the ratio of posterior densities, the hard-to-calculate normalisation $P(\boldsymbol{x})$ in both
5 posterior density terms cancels out, meaning one only needs to calculate the likelihood
6 and priors for each step, as well as $\frac{R(\boldsymbol{\mu}|\boldsymbol{\mu}')}{R(\boldsymbol{\mu}'|\boldsymbol{\mu})}$.
7

The specific implementation of MCMC used for this analysis is that of **OXO**, a C++
8 analysis framework first developed by Jack Dunger []. **OXO** is able to run the Metropolis-
9 Hastings algorithm on multidimensional binned data, using the log-likelihood defined
10 in 6.1.3. This framework also allows one to include systematic parameters that can
11 float within the fit, and define non-uniform priors for normalisations and systematics
12 that have constraints: the details of this will be discussed shortly.
13

6.1.6 Choosing Priors

For this analysis, the suggestions made by Biller & Oser in [] about choosing prior
15 distributions are followed: for parameters that do not have some pre-existing constraint,
16 a flat prior is used. A nice consequence of this choice is that $\ln \frac{P(\boldsymbol{\mu}')}{P(\boldsymbol{\mu})} = 0$, so the actual
17 value of the prior for these variables never needs to be calculated when running the
18 MCMC algorithm. For the bulk of this analysis, uniform priors are assumed on the
19 neutrino oscillation parameters Δm_{21}^2 and θ_{12} , as the magnitudes of these parameters
20 are now well-established. There is no major reason to prefer a flat prior in θ_{12} as
21 opposed to $\tan^2\theta_{12}$ or $\sin^2\theta_{12}$; we will see the impact of these different choices of prior
22 in section ??.

For parameters with existing asymmetric constraints $\beta_{-\sigma_-}^{+\sigma_+}$, this analysis uses an
24 asymmetric Gaussian prior, equivalent to the logarithm of the prior being an asymmetric
25

¹ quadratic:

$$\ln P(\mu) = \mathcal{A} - \begin{cases} \frac{(\mu-\beta)^2}{2\sigma_+^2} & \text{if } \mu \geq \beta, \\ \frac{(\mu-\beta)^2}{2\sigma_-^2} & \text{if } \mu < \beta. \end{cases} \quad (6.7)$$

³ Here, \mathcal{A} is the logarithm of the prior's normalisation constant, and cancels out in the
⁴ detailed balance condition. For parameters with symmetric constraints, $\sigma_+ = \sigma_-$, then
⁵ $\ln P(\mu)$ reduces to a quadratic with maximum at $\mu = \beta$.

⁶ 6.1.7 Including Systematics in the Fit

⁷ One important implementation detail is how systematics are applied within the MCMC
⁸ fitting process. Once systematics are added to the fit, at every step the binned PDFs
⁹ for all the processes considered in the fit must get modified appropriately, which
¹⁰ can become extremely computationally-intensive if not approached carefully. The
¹¹ strategy used in the **OXO** framework starts by thinking of the contents of a binned
¹² PDF as a vector of bin probabilities, $\mathbf{p} = (p_1, p_2, \dots, p_{N_{\text{bins}}})^T$. Then, we can think of a
¹³ systematic acting on the PDF as a linear transformation, and hence a matrix S acting
¹⁴ on this vector: $\mathbf{p}' = S\mathbf{p}$. We only need to calculate this matrix once for a given set
¹⁵ of systematic parameter values, and can then use the same matrix on all the PDFs
¹⁶ in the fit. Furthermore, when multiple systematics are applied, the matrix for each
¹⁷ systematic can then be combined via matrix multiplication into one single “detector
¹⁸ response” matrix. **OXO** uses the **Armadillo** [] linear algebra package for efficient matrix
¹⁹ manipulation.

²⁰ There is a problem that can arise when considering the impact of systematics
²¹ near the edge of the analysis ROI. Many systematics such as shifts, scalings, and
²² convolutions use information about the contents of nearby bins to determine the
²³ contents of a particular bin. However, for bins near the edge some of that information

Fig. 6.10

does not exist — it has been lost to the cuts that define the ROI. This can lead to a bias in the generation of the modified PDFs, and therefore also the posterior distribution.

As an example, consider the impact of an energy scale systematic on the energy distribution of ^{234m}Pa events in the detector, shown in Fig. 6.10. Because the events seen for this process in the ROI are merely the high-energy tail, any systematic energy scaling $E'_{\text{reco}} := \beta E_{\text{reco}}$ should have a large impact on the number of events observed at the low end of the ROI. However, given that the information about data below E_{\min} is lost to the ROI cuts, any energy scaling of $\beta > 1$ will not be applied correctly at all.

The solution to this problem is defining a “buffer region” of bins on either side of the ROI, which allow for tracking of events in and out of the ROI due to systematics, but aren’t considered when calculating the likelihood. This is also shown in Fig. 6.10. After the scaling systematic is applied, although incorrect bin values are found in the buffer region, this is fine because we are no longer calculating the likelihood with those bins. Note that because of this modification, the normalisation parameters we put into the model no longer represent the expected number of events in the ROI. Instead, they represent the number of events expected in both the ROI and buffer region, before any systematics have been applied.

6.1.8 Including Oscillations in the Fit

Within the analysis MCMC code, the process of neutrino oscillations are thought of as a *de facto* systematic that acts only on the ^8B ν_e and ν_x signal spectra. Three parameters relevant to the signal are floated within the MCMC fit: Δm_{21}^2 , θ_{12} , and $\Phi_{^8\text{B}}$, the unoscillated ^8B flux relative to the expected rate. For the two signal PDFs, a third “bookkeeping” dimension is added on top of reconstructed energy and radius:

the true neutrino energy, E_ν . This is necessary for correctly applying oscillations, as the oscillation probability is a function of the neutrino’s energy, not the scattered electron’s. Before the fit, these 3D PDFs are given normalisations corresponding to the expectation of the number of events for each type, ν_e and ν_x , after cuts but before oscillations have been applied. Strictly speaking there should be zero ν_x events before neutrino oscillations: the pre-oscillation rate used here is the post-cut number of events expected if 100% of the neutrinos oscillated to the ν_x type.

During the MCMC fit, for a given set of parameters $\boldsymbol{\theta} = (\Delta m_{21}^2, \theta_{12}, \Phi_{8B})$ the following is performed to oscillate the signal PDFs. Firstly, the normalisations are scaled by the factor Φ_{8B} . Then, for each E_ν bin the survival probability $P_{ee}(E_\nu, \Delta m_{21}^2, \theta_{12})$ is calculated. Each bin then has their probability scaled by either P_{ee} or $1 - P_{ee}$, for ν_e and ν_x respectively. Of course, within the structure of the **OXO** framework these bin-by-bin scaling aren’t immediately applied, but instead a matrix describing the impact of oscillations on each of the PDFs is made. Because the oscillation transformation is purely a bin-by-bin scaling, the resulting matrices are diagonal, with diagonal elements $\Phi_{8B} \cdot P_{ee}(E_\nu, \Delta m_{21}^2, \theta_{12})$ or $\Phi_{8B} \cdot (1 - P_{ee}(E_\nu, \Delta m_{21}^2, \theta_{12}))$ for ν_e and ν_x respectively. After the oscillation matrix along with all other systematic matrices are applied to the signal PDFs, the PDFs are then marginalised over the E_ν dimension so that the signal PDFs match the dimensionality of all other processes.

Calculations of the survival probability are handled with **PSelmaa**, an algorithm written by Nuno Barros for the SNO 3-phase Analysis []. This considers not only the neutrino oscillations through the vacuum of space between the Sun and Earth, but also the impact of matter effects in both the Sun and Earth. This can usually be a very computationally-intensive process, but **PSelmaa** takes advantage of the assumption that the solar oscillation parameters are in the so-called “Large Mixing Angle” regime, making the calculation much faster. As seen in section ??, previous solar oscillation

experiments demonstrate that this assumption is reasonable. For this analysis, the standard MSW effect is assumed with neutrinos obeying the Normal Hierarchy, with the Sun following the B16_GS98 metallicity model [1] and the PREM model being used for the Earth [2].

One final thing `PSelmaa` needs to know to calculate survival probabilities is the distribution of solar zenith angles during the data-taking. The solar zenith θ_z is the angle between the two following vectors: one going from the centre of the Earth through the centre of the SNO+ detector, and another starting from the detector's centre and pointing towards the Sun. As an example, if the Sun were ever to be directly overhead the detector, both vectors would be along direction \hat{z} in detector coordinates, leading to a solar zenith angle of $\theta_z = 0$. The position of the SNO+ detector on Earth, as well as the times at which the detector was live, determine the solar zenith angle distribution. If not accounted for, this can lead to a bias in the result of the analysis, as a preponderance of livetime taken at night (say) would lead to a larger fraction of solar neutrinos having to pass through the bulk of the Earth to get to the detector, and hence the impact of the MSW effect would be greater.

Even after using the Large Mixing Angle approximation, having to call `PSelmaa` numerous times for every step in the MCMC algorithm would lead to exorbitant run times for the fitting. Therefore, a further approximation is made. Before running the MCMC fit, `PSelmaa` is used to calculate P_{ee} over the necessary 3D space of parameters. To get a fine scan of this space, 101 E_ν values from 1 MeV to 20 MeV, 101 Δm_{21}^2 values from $3 \times 10^{-6} \text{ eV}^2$ to $1 \times 10^{-3} \text{ eV}^2$, and 151 values for θ_{12} from 5° to 65° were looked over. This 3D grid of $101 \cdot 101 \cdot 151$ P_{ee} values is then written to disk, and loaded into memory for use during the fit as a lookup table. At run-time, as the Metropolis-Hastings algorithm samples this 3D space the survival probability is estimated through

¹ a trilinear interpolation of the 3D grid loaded in: a version of linear interpolation for
² three dimensions [].

³ 6.2 Analysis on Scintillator-Phase data

- ⁴ • Description of dataset chosen for analysis: 2.2 g/L scintillator-phase data that
⁵ satisfies the “gold” list of run selection requirements, between 1st June 2022 and
⁶ March 2023. Starting date chosen to ensure radon levels have stabilised within
⁷ the centre of the detector.
- ⁸ • Describe finalised choice of binning for PDFs and data.
- ⁹ • List final set of cuts chosen for analysis, along with any explanations for cuts
¹⁰ that haven’t already been motivated earlier (e.g. data cleaning).
- ¹¹ • Impact of cuts on data and MC. Show tables (the full details maybe in an
¹² appendix) indicating this.
- ¹³ • Describe the constraints chosen to apply to the fit, and why they can be justified.
- ¹⁴ • Describe the systematics to be added to the fit (just energy scale for now, maybe
¹⁵ also energy smearing?). Mention other systematics that could be of relevance,
¹⁶ and then discuss how they should be handled: either scanned over, or have its
¹⁷ sub-dominance in this statistics-limited analysis be demonstrated.
- ¹⁸ • Running & validation of MCMC fitting. Show plots of parameter values versus
¹⁹ step, to demonstrate that the step sizes have been tuned sufficiently. Show
²⁰ auto-correlation plots, to motivate a sensible “burn-in” size. Show posterior
²¹ density plots for each nuisance parameter, to check that they all look sensible and
²² have sufficient statistics. Show plot of correlation coefficients between parameters,
²³ and look at any correlations that are particularly interesting.

6.3 Sensitivity Projections**65**

- Look at the data versus MC plot in energy, radius, and both. Is there a good fit to data? Any clear disagreements? 1
2
- Show 2D contour plot for oscillation parameter posterior density. Note salient features. Show 1D posterior densities for each oscillation parameter. Derive measurement result for θ_{12} . 3
4
5
- Show impact of modifying certain constraints on the final results of the measurement of θ_{12} . 6
7
- Discussion of systematics post-fit — is energy scaling reasonable? Perform a scan over energy smearing, and check impact of possible radial scale systematic. 8
9

6.3 Sensitivity Projections

10

- Using the same production MC, generate PDFs with the expected normalisations for longer periods of livetime: 1, 3, and 5 years. This still assumes a scintillator-fill with identical detector conditions on average, so not considering the impact of BisMSB loading at any point. 11
12
13
14
- Describe any further constraints to be assumed on top of the existing analysis of data: expected improved constraints on various backgrounds, as well as a possible energy-scale calibration constraint from the AmBe source, for example. 15
16
17
- Run MCMC fits to these Asimov PDFs for each livetime scenario. Describe results in terms of the improvement to the sensitivity to θ_{12} as a function of livetime. 18
19
20
- Also consider scenario of lower backgrounds! How does that impact the result? 21

6.4 Conclusions and Suggestions for Further Work

- Say what has been achieved with the analysis in this chapter! Both in terms of actual measurement of θ_{12} , but also expected sensitivities in the future.
- Give suggestions for further work that could be done on this analysis beyond the addition of further livetime:
 - Various computational improvements to allow for faster MCMC run-times, including the calculation of the systematic matrices, and possible use of GPUs to parallelise some parts of the computation.
 - Inclusion of additional solar neutrino components at lower energy into the fit, e.g. Be7. Maybe the addition of lower energies also helps to naturally constrain backgrounds within the fit?
 - Looking at the impact of various advanced background-rejection procedures, such as event directionality or topology. How much do they help with the sensitivity?
 - Looking at the impact of splitting data into day and night parts, to try and provide further constraints on any matter effects. Not expected to be significant, so was ignored for this analysis so far.
 - Performing a combined fit with the reactor anti-neutrino oscillation analysis, which allows for the handling of correlated uncertainties, such as detector response systematics.

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