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<b>Experiment No.</b>	6

<b>AIM:</b>	Greedy Approach- Single Source Shortest path-Dijkstra's Algorithm
<b>Program 1</b>	
<b>PROBLEM STATEMENT :</b>	Implement Dijkstra's Algorithm using C programming
<b>ALGORITHM:</b>	<p>Dijkstra algorithm is also called single source shortest path algorithm. It is based on greedy technique. The algorithm maintains a list visited[ ] of vertices, whose shortest distance from the source is already known.</p> <ol style="list-style-type: none"> <li>1. Create cost matrix C[ ][ ] from adjacency matrix adj[ ][ ]. C[i][j] is the cost of going from vertex i to vertex j. If there is no edge between vertices i and j then C[i][j] is infinity.</li> <li>2. Array visited[ ] is initialized to zero.  for(i=0;i&lt;n;i++)  visited[i]=0;</li> <li>3. If the vertex 0 is the source vertex then visited[0] is marked as 1.</li> <li>4. Create the distance matrix, by storing the cost of vertices from vertex no. 0 to n-1 from the source vertex 0.  for(i=1;i&lt;n;i++)  distance[i]=cost[0][i];  Initially, distance of source vertex is taken as 0. i.e. distance[0]=0;</li> <li>5. for(i=1;i&lt;n;i++) <ul style="list-style-type: none"> <li>– Choose a vertex w, such that distance[w] is minimum and visited[w] is 0. Mark visited[w] as 1.</li> <li>– Recalculate the shortest distance of remaining vertices from the source.</li> <li>– Only, the vertices not marked as 1 in array visited[ ] should be considered for recalculation of distance. i.e. for each vertex v  if(visited[v]==0)  distance[v]=min(distance[v],  distance[w]+cost[w][v])</li> </ul> </li> </ol>

**PROGRAM:**

```
#include<stdio.h>
#include<conio.h>
#define INFINITY 9999
#define MAX 10

void dijkstra(int G[MAX][MAX],int n,int startnode);

int main()
{
    int G[MAX][MAX],i,j,n,u;
    printf("Enter no. of vertices:");
    scanf("%d",&n);
    printf("\nEnter the adjacency matrix:\n");
    for(i=0;i<n;i++)
        for(j=0;j<n;j++)
            scanf("%d",&G[i][j]);
    printf("\nEnter the starting node:");
    scanf("%d",&u);
    dijkstra(G,n,u);
    return 0;
}

void dijkstra(int G[MAX][MAX],int n,int startnode)
{
    int cost[MAX][MAX],distance[MAX],pred[MAX];
    int visited[MAX],count,mindistance,nextnode,i,j;
    //pred[] stores the predecessor of each node
    //count gives the number of nodes seen so far
    //create the cost matrix

    for(i=0;i<n;i++)
        for(j=0;j<n;j++)
            if(G[i][j]==0)
                cost[i][j]=INFINITY;
            else
                cost[i][j]=G[i][j];
    //initialize pred[],distance[] and visited[]
    for(i=0;i<n;i++)
    {
```

```

distance[i]=cost[startnode][i];
pred[i]=startnode;
visited[i]=0;
}
distance[startnode]=0;
visited[startnode]=1;
count=1;
while(count<n-1)
{
mindistance=INFINITY;
//nextnode gives the node at minimum distance
for(i=0;i<n;i++)
if(distance[i]<mindistance&&!visited[i])
{
mindistance=distance[i];
nextnode=i;
}
//check if a better path exists through nextnode
visited[nextnode]=1;
for(i=0;i<n;i++)
if(!visited[i])
if(mindistance+cost[nextnode][i]<distance[i])
{
distance[i]=mindistance+cost[nextnode][i];
pred[i]=nextnode;
}
count++;
}

//print the path and distance of each node
for(i=0;i<n;i++)
if(i!=startnode)
{
printf("\nDistance of node%d=%d",i,distance[i]);
printf("\nPath=%d",i);
j=i;
do
{
j=pred[j];
printf("<-%d",j);

```

```
}while(j!=startnode);  
}  
}
```

**RESULT:**

```
Enter no. of vertices:5  
  
Enter the adjacency matrix:  
0 10 0 30 100  
10 0 50 0 0  
0 50 0 20 10  
30 0 20 0 60  
100 0 10 60 0  
  
Enter the starting node:0  
  
Distance of node1=10  
Path=1<-0  
Distance of node2=50  
Path=2<-3<-0  
Distance of node3=30  
Path=3<-0  
Distance of node4=60  
Path=4<-2<-3<-0  
  
...Program finished with exit code 0  
Press ENTER to exit console.
```

**OBSERVATION:**

- The program contains two nested loops each of which has a complexity of  $O(n)$ .  $n$  is number of vertices. So the complexity of algorithm is  $O(n^2)$ . Space complexity of Dijkstra's algorithm is  $O(n^2)$ . where  $n$  denotes the number of vertices (or nodes) in the graph.

**CONCLUSION:**

In this experiment, we implemented Dijkstra's Algorithm to find the shortest path.

