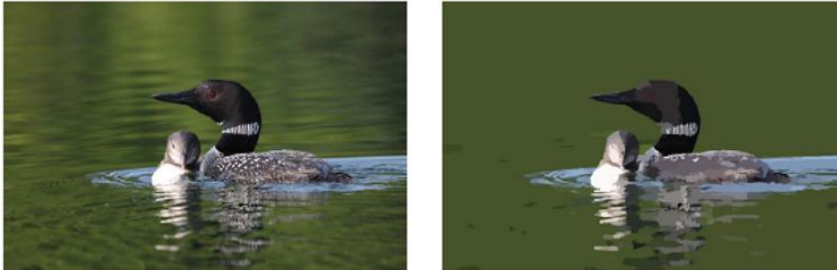


FL #6

1. Cluster the RGB image using k-means method. (Use kmeans() functions in sklearn module)



2. Design the Harris corner detector.

a) Obtain the feature possibility map using Harris corner detector.

b) Obtain the local maximum key points.

