

## 2. COMPLEX DERIVATIVES AND ANALYTIC FUNCTIONS

We now turn to the fundamental notion of differentiability of complex-valued functions of a complex variable.

It is surprising that while the definition

$$f'(z_0) = \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0}$$

of complex derivatives as limits of difference quotients appears identical to the definition in real-variable calculus, the consequences of complex differentiability are far stronger.

To clearly appreciate the differences, we start by recalling the definition and properties of differentiability in the real sense.

## Component functions

We identify the set  $\mathbb{C}$  of complex numbers with the 2-dimensional plane  $\mathbb{R}^2$  as usual

$$\mathbb{R}^2 \ni (x, y) \longleftrightarrow x + iy \in \mathbb{C}.$$

A complex-valued function

$$f : A \rightarrow \mathbb{C}$$

defined on a subset  $A \subset \mathbb{C}$  of the complex plane then corresponds to a two-component (so vector-valued) function of two real variables:

$$f(x + iy) = u(x, y) + i \cdot v(x, y)$$

where  $u, v : A \rightarrow \mathbb{R}$  are the real-valued component functions,

$$u(x, y) := \operatorname{Re}(f(x + iy))$$

$$v(x, y) := \operatorname{Im}(f(x + iy)).$$

Let us therefore recall notions of calculus in several real variables.

(two, in the case at hand)

# Differentiability in the real sense

Recall:

Def:

Let  $u: A \rightarrow \mathbb{R}$  be a function defined on a subset  $A \subset \mathbb{R}^2$  of the plane, and let  $(x_0, y_0) \in A$  be a point in that subset.

A linear map  $L: \mathbb{R}^2 \rightarrow \mathbb{R}$  is called a **differential** of  $u$  at  $(x_0, y_0)$  if we can write

$$u(x_0 + \xi, y_0 + \eta) = u(x_0, y_0) + L(\xi, \eta) + E(\xi, \eta)$$

⚡: linear approximation of  $u$  locally

where the error term  $E$  is small in the sense that

$$\lim_{(\xi, \eta) \rightarrow (0, 0)} \frac{|E(\xi, \eta)|}{\|(\xi, \eta)\|} = 0.$$

(Euclidean norm of a vector:  $\|(\xi, \eta)\| := \sqrt{\xi^2 + \eta^2}$ )

It is not difficult to check that if  $(x_0, y_0)$  is an interior point of  $A$ , then  $L$  is uniquely determined in the above. We then call it the differential of  $u$  at  $(x_0, y_0)$  and denote it by

$$du(x_0, y_0) = L: \mathbb{R}^2 \rightarrow \mathbb{R}.$$

[differential]

Recall: Linearity of  $L: \mathbb{R}^2 \rightarrow \mathbb{R}^m$   
means that

$$L(\xi_1 + \xi_2, \eta_1 + \eta_2) = L(\xi_1, \eta_1) + L(\xi_2, \eta_2)$$

$$\forall (\xi_1, \eta_1), (\xi_2, \eta_2) \in \mathbb{R}^2$$

and

$$L(\lambda \xi, \lambda \eta) = \lambda \cdot L(\xi, \eta)$$

$$\forall (\xi, \eta) \in \mathbb{R}^2, \lambda \in \mathbb{R}.$$

Fixing choices of bases, linear maps<sup>⊕</sup> can be represented by matrices. (between finite-dim. vector spaces)

Choosing the standard basis of  $\mathbb{R}^2$

$$(e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}) \text{ so that } \begin{bmatrix} \xi \\ \eta \end{bmatrix} = \xi e_1 + \eta e_2$$

and considering limits  $(\xi, \eta) \rightarrow (0, 0)$  along coordinate axes  $(\begin{bmatrix} \xi \\ 0 \end{bmatrix} \xrightarrow{\xi \rightarrow 0} \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ \eta \end{bmatrix} \xrightarrow{\eta \rightarrow 0} \begin{bmatrix} 0 \\ 0 \end{bmatrix})$

one finds the matrix of the differential expressed in terms of partial derivatives:

Lemma

[jacobian-matrix] If  $u: A \rightarrow \mathbb{R}$  has differential  $L$  at an interior point  $(x_0, y_0)$  of  $A \subset \mathbb{R}^2$ , then  $u$  has both partial derivatives  $\frac{\partial u}{\partial x}(x_0, y_0)$  and  $\frac{\partial u}{\partial y}(x_0, y_0)$  at that point and

$$L = du(x_0, y_0) \longleftrightarrow \begin{bmatrix} \frac{\partial u}{\partial x}(x_0, y_0) & \frac{\partial u}{\partial y}(x_0, y_0) \end{bmatrix} \in \mathbb{R}^{1 \times 2}.$$

(matrix rep. in standard basis)

### Example

The function  $u: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$u(x,y) = x^2 + y^2$$

has, at a point  $(x_0, y_0) \in \mathbb{R}^2$ ,  
the differential

$$L(\xi, \eta) = 2x_0 \xi + 2y_0 \eta$$

since

$$\begin{aligned} E(\xi, \eta) &= u(x_0 + \xi, y_0 + \eta) - u(x_0, y_0) - L(\xi, \eta) \\ &= \underbrace{(x_0 + \xi)^2}_{= x_0^2 + 2x_0\xi + \xi^2} + \underbrace{(y_0 + \eta)^2}_{= y_0^2 + 2y_0\eta + \eta^2} - x_0^2 - y_0^2 - 2x_0\xi - 2y_0\eta \\ &= \xi^2 + \eta^2 \end{aligned}$$

satisfies

$$\lim_{(\xi, \eta) \rightarrow (0,0)} \frac{E(\xi, \eta)}{\|(\xi, \eta)\|} = \lim_{(\xi, \eta) \rightarrow (0,0)} \frac{\xi^2 + \eta^2}{\sqrt{\xi^2 + \eta^2}} = 0.$$

And indeed the matrix of  $L$  (in std basis)

$$\begin{bmatrix} 2x_0 & 2y_0 \end{bmatrix}$$

has components given by the partial derivatives

$$\frac{\partial u}{\partial x} = \frac{\partial}{\partial x}(x^2 + y^2) = 2x, \quad \frac{\partial u}{\partial y} = \frac{\partial}{\partial y}(x^2 + y^2) = 2y$$

at  $(x_0, y_0)$ .

Let us record an easy but important observation:

### Lemma

[differentiable -  
implies - continuous]

If  $u: A \rightarrow \mathbb{R}$  defined on  $A \subset \mathbb{R}^2$  is differentiable at  $(x_0, y_0) \in A$ , then it is also continuous at  $(x_0, y_0)$

Proof: For any linear map  $L: \mathbb{R}^2 \rightarrow \mathbb{R}$  we

have 
$$\lim_{(\xi, \eta) \rightarrow (0,0)} L(\xi, \eta) = 0$$

and for the error term  $E$  we also have

$$\lim_{(\xi, \eta) \rightarrow (0,0)} E(\xi, \eta) = 0$$

(Indeed, from  $\lim_{(\xi, \eta) \rightarrow (0,0)} \frac{|E(\xi, \eta)|}{\|(\xi, \eta)\|} = 0$  it

follows that for any  $\varepsilon > 0$  there exists a  $\delta > 0$  such that

$$|E(\xi, \eta)| < \varepsilon \cdot \|(\xi, \eta)\| \quad \text{when} \quad \|(\xi, \eta)\| < \delta.)$$

Using the linearity of limits, we therefore get

$$\begin{aligned} & \lim_{(\xi, \eta) \rightarrow (0,0)} u(x_0 + \xi, y_0 + \eta) \\ &= \lim_{(\xi, \eta) \rightarrow (0,0)} \left( u(x_0, y_0) + L(\xi, \eta) + E(\xi, \eta) \right) \end{aligned}$$

$$= u(x_0, y_0) + 0 + 0 = u(x_0, y_0),$$

showing that  $u$  is continuous at  $(x_0, y_0)$ .  $\square$

Differentiability of vector-valued functions

$$f: A \rightarrow \mathbb{R}^2$$

simply amounts to the differentiability of each of the component functions.

Specifically, if

$$f(x,y) = (u(x,y), v(x,y))$$

then  $f$  has a differential

at  $(x_0, y_0) \in A$  if

$$u(x_0 + \xi, y_0 + \eta) = u(x_0, y_0) + L^{(u)}(\xi, \eta) + E^{(u)}(\xi, \eta),$$

$$v(x_0 + \xi, y_0 + \eta) = v(x_0, y_0) + L^{(v)}(\xi, \eta) + E^{(v)}(\xi, \eta),$$

where

$$\lim_{(\xi, \eta) \rightarrow (0,0)} \frac{|E^{(u)}(\xi, \eta)|}{\|(\xi, \eta)\|} = 0, \quad \lim_{(\xi, \eta) \rightarrow (0,0)} \frac{|E^{(v)}(\xi, \eta)|}{\|(\xi, \eta)\|} = 0.$$

The clearest form is obtained by collecting the differentials and error terms in vectors as

$$L(\xi, \eta) = (L^{(u)}(\xi, \eta), L^{(v)}(\xi, \eta)) \in \mathbb{R}^2$$

$$E(\xi, \eta) = (E^{(u)}(\xi, \eta), E^{(v)}(\xi, \eta)) \in \mathbb{R}^2,$$

so that  $L: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a linear map, and the local linear approximation

reads

$$f(x_0 + \xi, y_0 + \eta) = f(x_0, y_0) + L(\xi, \eta) + E(\xi, \eta)$$

with the error term satisfying

$$\lim_{(\xi, \eta) \rightarrow (0, 0)} \frac{\|E(\xi, \eta)\|}{\|(\xi, \eta)\|} = 0.$$

The matrix representation of the differential

$$df(x_0, y_0) = L$$

is again expressible in terms of the partial derivatives (of the component functions):

### Lemma

[jacobian - matrix] If  $f: A \rightarrow \mathbb{R}^2$  is written in terms of its component functions  $u, v: A \rightarrow \mathbb{R}$ , and  $f$  has a differential  $L: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  at an interior point  $(x_0, y_0)$  of  $A$ , then both partial derivatives of both component functions exist at  $(x_0, y_0)$  and the matrix of the differential reads

$$L = df(x_0, y_0) \leftrightarrow \begin{bmatrix} \frac{\partial u}{\partial x}(x_0, y_0) & \frac{\partial u}{\partial y}(x_0, y_0) \\ \frac{\partial v}{\partial x}(x_0, y_0) & \frac{\partial v}{\partial y}(x_0, y_0) \end{bmatrix} \in \mathbb{R}^{2 \times 2}.$$

(matrix in standard basis of  $\mathbb{R}^2$ )



### Example

The function  $z \mapsto \bar{z}$  ( $\mathbb{C} \rightarrow \mathbb{C}$ ) corresponds to the vector-valued function

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$f(x, y) = (x, -y)$$

of two real variables, whose component functions are given by

$$u(x, y) = x \quad v(x, y) = -y.$$

Clearly this  $f$  is differentiable in the real sense at any  $(x_0, y_0) \in \mathbb{R}^2$ , and its differential (at any point) is the linear map determined by the

$$\text{matrix} \quad \begin{bmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

(Just note that the existence of partial derivatives is not sufficient for differentiability — but once one writes things out, the error term in this example is identically zero, so differentiability has been justified, "clearly".)

$$\text{i.e.} \quad L(\xi, \eta) = (\xi, -\eta) \quad \forall (\xi, \eta) \in \mathbb{R}^2.$$

## Complex derivatives

Let us then turn our attention to derivatives in the complex sense.

Def

[complex-derivative]

A complex-valued function  $f: A \rightarrow \mathbb{C}$  defined on a subset  $A \subset \mathbb{C}$  of the complex plane has (complex) derivative

$$f'(z_0) = \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0}$$

at an interior point  $z_0$  of  $A$  if the limit above exists in  $\mathbb{C}$ .

Remark:

Another equivalent way to write the derivative is obtained by setting  $h = z - z_0$  above:

$$f'(z_0) = \lim_{h \rightarrow 0} \frac{f(z_0 + h) - f(z_0)}{h}.$$

⚠ The limit that defines the complex derivative must exist when  $h$  tends to 0 from any direction in the complex plane.

### Example

Consider the function  $f: \mathbb{C} \rightarrow \mathbb{C}$   
 $f(z) = z^2$ .

It has a derivative at any  $z_0 \in \mathbb{C}$ :

$$\begin{aligned}\frac{f(z_0+h) - f(z_0)}{h} &= \frac{(z_0+h)^2 - z_0^2}{h} \\ &= \frac{\cancel{z_0^2} + 2h \cdot z_0 + h^2 - \cancel{z_0^2}}{h} \\ &= 2z_0 + h \xrightarrow{h \rightarrow 0} 2z_0.\end{aligned}$$

So  $f'(z_0) = 2z_0$ .

### Example

Consider the function  $f: \mathbb{C} \rightarrow \mathbb{C}$   
 $f(z) = \bar{z}$ .

This function does not have a (complex) derivative at any point  $z_0 \in \mathbb{C}$ :

Approaching  $z_0 = x_0 + iy_0$  ( $x_0, y_0 \in \mathbb{R}$ ) from a "real" direction ( $h = \xi \in \mathbb{R}$ ) we find a limit of difference quotients

$$\begin{aligned} \frac{f(z_0 + \xi) - f(z_0)}{\xi} &= \frac{(x_0 + \xi - iy_0) - (x_0 - iy_0)}{\xi} \\ &= \frac{\xi}{\xi} = 1 \xrightarrow[\xi \rightarrow 0]{} 1 \end{aligned}$$

whereas from an "imaginary" direction ( $h = i\eta$ ,  $\eta \in \mathbb{R}$ ) we find

$$\begin{aligned} \frac{f(z_0 + i\eta) - f(z_0)}{i\eta} &= \frac{(x_0 - i(y_0 + \eta)) - (x_0 - iy_0)}{i\eta} \\ &= \frac{-i\eta}{i\eta} = -1 \xrightarrow[\eta \rightarrow 0]{} -1. \end{aligned}$$

The different directional limits show that  $\lim_{h \rightarrow 0} \frac{f(z_0 + h) - f(z_0)}{h}$  does not exist.



The previous example shows that differentiability in the real sense is not sufficient to guarantee the existence of a complex derivative. ( $z \mapsto \bar{z}$  is differentiable in the real sense but does not have a complex derivative anywhere)

The following shows that differentiability in the real sense is, however, a necessary condition for the existence of a complex derivative.

# Cauchy - Riemann equations

## Theorem

[complex-derivative  $\implies$  implies-differentiable]

If a function  $f: A \rightarrow \mathbb{C}$  defined on  $A \subset \mathbb{C}$  has a complex derivative  $f'(z_0)$  at an interior point  $z_0 = x_0 + iy_0$  then  $f$  viewed as a vector-valued function of two real variables is differentiable at  $(x_0, y_0)$  and the partial derivatives of its component functions  $u(x, y) = \operatorname{Re}(f(x + iy))$  and  $v(x, y) = \operatorname{Im}(f(x + iy))$  satisfy the

Cauchy - Riemann equations

$$\begin{cases} \frac{\partial u}{\partial x}(x_0, y_0) = \frac{\partial v}{\partial y}(x_0, y_0) \\ \frac{\partial v}{\partial x}(x_0, y_0) = -\frac{\partial u}{\partial y}(x_0, y_0) \end{cases}$$

Proof: Suppose that

$$f'(z_0) = \lim_{h \rightarrow 0} \frac{f(z_0+h) - f(z_0)}{h}$$

exists. Write  $f'(z_0) = a + ib$

with  $a, b \in \mathbb{R}$ . Also write

$h = \xi + i\eta$  with  $\xi, \eta \in \mathbb{R}$  and

consider the error term

$$E(\xi, \eta) = f(z_0 + \xi + i\eta) - f(z_0) - (\xi + i\eta)f'(z_0).$$

We then find

$$\begin{aligned} & \lim_{(\xi, \eta) \rightarrow (0,0)} \frac{\|E(\xi, \eta)\|}{\|(\xi, \eta)\|} \\ &= \lim_{(\xi, \eta) \rightarrow (0,0)} \frac{|f(z_0 + \xi + i\eta) - f(z_0) - (\xi + i\eta)f'(z_0)|}{|\xi + i\eta|} \\ &= \lim_{(\xi, \eta) \rightarrow (0,0)} \left| \frac{f(z_0 + \xi + i\eta) - f(z_0)}{\xi + i\eta} - f'(z_0) \right| = 0 \end{aligned}$$

using the existence of the complex derivative.

The mapping

$$(\xi, \eta) \mapsto L(\xi, \eta) = (a\xi - b\eta, a\eta + b\xi)$$

is real-linear and from the above we see that it is the differential  $df(x_0, y_0)$ .

this pair corresponds to the complex number  $(\xi + i\eta) \cdot f'(z_0) = (\xi + i\eta)(a + ib)$

In matrix form, this differential  $L$  reads

$$L \longleftrightarrow \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

so comparing with the matrix of partial derivatives

$$\begin{bmatrix} \frac{\partial u}{\partial x}(x_0, y_0) & \frac{\partial u}{\partial y}(x_0, y_0) \\ \frac{\partial v}{\partial x}(x_0, y_0) & \frac{\partial v}{\partial y}(x_0, y_0) \end{bmatrix}$$

(which by a previous lemma also represents  $L = df(x_0, y_0)$ ) we find

$$\frac{\partial u}{\partial x}(x_0, y_0) = a = \frac{\partial v}{\partial y}(x_0, y_0)$$

$$\frac{\partial v}{\partial x}(x_0, y_0) = b = -\frac{\partial u}{\partial y}(x_0, y_0),$$

which are the asserted Cauchy-Riemann equations.

□



💡 From the proof we observe:

If the complex derivative  $f'(z_0)$  exists, then the differential

$$df(x_0, y_0) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

is not merely  $\mathbb{R}$ -linear but also a  $\mathbb{C}$ -linear map

$$\xi + i\eta \mapsto (a + ib)(\xi + i\eta)$$

once we identify the plane  $\mathbb{R}^2$  with  $\mathbb{C}$  as usual:

$$\mathbb{R}^2 \ni (\xi, \eta) \longleftrightarrow \xi + i\eta \in \mathbb{C}.$$

The Cauchy-Riemann equations are exactly the additional requirement to promote the  $\mathbb{R}$ -linearity of the differential to  $\mathbb{C}$ -linearity.

Geometric interpretation:

Write the complex derivative in polar form,  $f'(z_0) = \rho \cdot e^{i\phi}$ , where  $\rho = |f'(z_0)| \geq 0$ ,  $\phi = \arg(f'(z_0)) \pmod{2\pi}$ .

Then the differential  $df(z_0)$  is the  $\mathbb{C}$ -linear map  $\xi + i\eta \mapsto \rho \cdot e^{i\phi} \cdot (\xi + i\eta)$  which performs a rotation by angle  $\phi$  and dilatation by factor  $\rho$ .

### Example

We saw that  $f(z) = z^2$  defines a function  $f: \mathbb{C} \rightarrow \mathbb{C}$  which has a complex derivative  $f'(z_0) = 2z_0$  at  $z_0 \in \mathbb{C}$ .

Writing

$f(x+iy) = (x+iy)^2 = x^2 - y^2 + 2ixy$   
we find that the component functions of  $f$  are given by

$$u(x,y) = x^2 - y^2, \quad v(x,y) = 2xy.$$

Now also a direct calculation of the partial derivatives

$$\frac{\partial u}{\partial x} = 2x$$

$$\frac{\partial v}{\partial y} = 2x$$

$$\frac{\partial v}{\partial x} = 2y$$

$$-\frac{\partial u}{\partial y} = 2y$$

shows that the Cauchy-Riemann equations hold for  $f$  everywhere.

The previous result showed that the existence of a complex derivative implied differentiability and Cauchy-Riemann equations. Also the converse holds:

### Theorem

If  $f : A \rightarrow \mathbb{C}$  defined on  $A \subset \mathbb{C}$  is differentiable at an interior point  $(x_0, y_0)$  and if the Cauchy-Riemann equations hold at  $(x_0, y_0)$  for its component functions

$$u(x, y) = \operatorname{Re}(f(x+iy)), \quad v(x, y) = \operatorname{Im}(f(x+iy))$$

then  $f$  has a complex derivative at  $z_0 = x_0 + iy_0$  given by any of the following expressions:

$$f'(z_0) = \frac{\partial u}{\partial x}(x_0, y_0) + i \frac{\partial v}{\partial x}(x_0, y_0)$$

$$= \frac{\partial v}{\partial y}(x_0, y_0) - i \frac{\partial u}{\partial y}(x_0, y_0)$$

$$= \frac{\partial u}{\partial x}(x_0, y_0) - i \frac{\partial u}{\partial y}(x_0, y_0)$$

$$= \frac{\partial v}{\partial y}(x_0, y_0) + i \frac{\partial v}{\partial x}(x_0, y_0).$$

### Sketch of proof:

The equality of the 4 different expressions follows directly from the Cauchy-Riemann equations.

The proof is otherwise very similar to the converse proven before.  $\square$

⚠ To conclude the existence of the complex derivative at a point, the hypothesis (in the theorem above) about differentiability at that point cannot be relaxed to the mere existence of partial derivatives (even if they would satisfy the Cauchy-Riemann equations).

For a counterexample, see the exercises.

### Example

Recall that the complex exponential function was defined by

$$\exp : \mathbb{C} \rightarrow \mathbb{C}$$

$$\exp(x+iy) = \underbrace{e^x \cdot \cos(y)}_{=u(x,y)} + i \underbrace{e^x \cdot \sin(y)}_{=v(x,y)}.$$

Claim The function  $z \mapsto \exp(z) = e^z$  is  
[ complex differentiable at every  $z_0 \in \mathbb{C}$   
and its derivative is  $\exp'(z_0) = \exp(z_0)$ . ]

To check this, observe first that the component functions  $u, v$  have continuous partial derivatives everywhere, so  $\exp$  is differentiable everywhere (see calculus courses).

By the previous theorem, then, it suffices to verify the Cauchy-Riemann equations. For this, calculate

$$\frac{\partial u}{\partial x} = e^x \cdot \cos(y), \quad \frac{\partial v}{\partial y} = e^x \cdot \cos(y)$$

$$\frac{\partial v}{\partial x} = e^x \cdot \sin(y), \quad \frac{\partial u}{\partial y} = -e^x \cdot \sin(y).$$

□

## Analyticity (= holomorphicity)

The existence of the (complex) derivative at a single point does not yet have drastic implications.

A more fruitful starting point is :

### Def

[analytic-function]

A function  $f: U \rightarrow \mathbb{C}$  defined on an open set  $U \subset \mathbb{C}$  is analytic if it has a complex derivative at every point  $z \in U$ .

(We say that  $f$  is analytic at  $z_0$  if for some  $\varepsilon > 0$  it has a complex derivative at every point  $z \in B(z_0; \varepsilon)$  of the  $\varepsilon$ -radius disk centered at  $z_0$ .)

### Example

The complex exponential function

$$\exp: \mathbb{C} \rightarrow \mathbb{C}$$

is analytic in the whole complex plane  $\mathbb{C}$  (by the previous example).

Example:

Consider the function defined by the formula  $f(z) = |z|^2$ .

It's component functions are

$$u(x,y) = \operatorname{Re}(|x+iy|^2) = x^2 + y^2 \quad \text{and}$$

$$v(x,y) = \operatorname{Im}(|x+iy|^2) = 0.$$

The partial derivatives are

$$\frac{\partial u}{\partial x} = 2x$$

$$\frac{\partial v}{\partial y} = 0$$

$$\frac{\partial v}{\partial x} = 0$$

$$\frac{\partial u}{\partial y} = 2y.$$

The continuity of the partial derivatives implies differentiability.

Cauchy - Riemann equations hold at the point  $(x,y) = (0,0)$  but nowhere else. The function  $f(z) = |z|^2$  is not analytic anywhere (although at  $z=0$  it has complex derivative  $f'(0) = 0$ ).

We can combine some earlier observations to obtain the first important properties of analytic functions:

### Lemma

[analytic-  
implies-  
continuous]

Every analytic function  $f: U \rightarrow \mathbb{C}$  is continuous.

Proof: Analyticity implies, by definition, the existence of a complex derivative at any point  $z \in U$ , which by an earlier lemma implies differentiability at  $z$ , which by another earlier lemma implies continuity at  $z$ .  $\square$

### Theorem

[cauchy-riemann]

A function  $f: U \rightarrow \mathbb{C}$  on an open set  $U \subset \mathbb{C}$  is analytic if and only if its component functions  $u = \operatorname{Re}(f)$ ,  $v = \operatorname{Im}(f)$  are differentiable at every  $z \in U$  and their partial derivatives satisfy the Cauchy-Riemann equations.

Proof This follows from the definition of analyticity and an earlier lemma.  $\square$