

TEACHING APPROACH: TOP-DOWN (VIA D. PERKINS, BASEBALL ANALOGY)

- ① Start with real, practical examples (teach the whole game)
- ② Learn by doing run/re-implement code
- ③ Deep dive into theory later, as needed -/+ Do personal projects to improve models
- ④ Simplify and remove barriers:
  - fastai library
  - Pytorch
  - Jupyter

Some history:

1943 - McCulloch, Pitts: Artificial Neuron

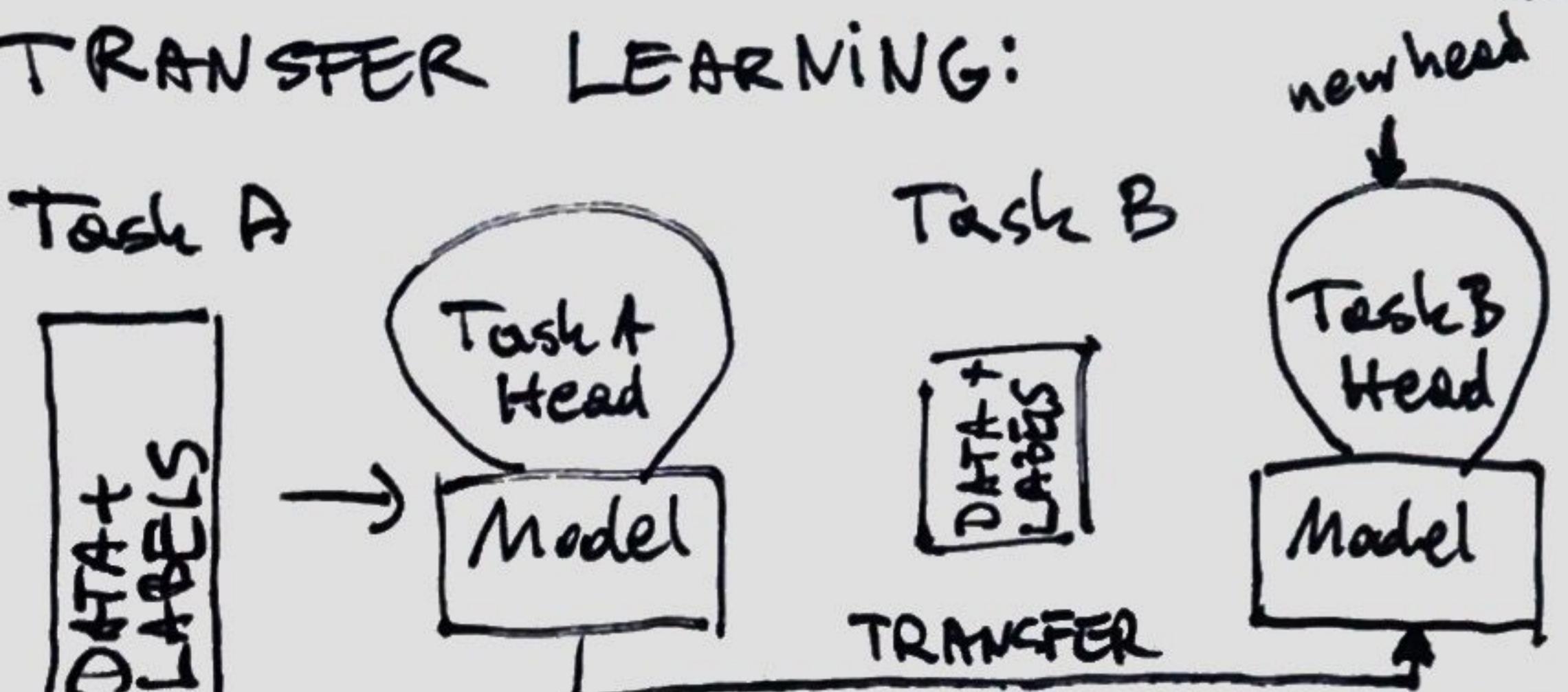
Rosenblatt's device: Mark I Perceptron

Minsky, Papert: Perceptrons - book introducing multiple layer neural networks

1986 - Parallel Distributed Processing - book introducing most of current DL framework

1961/62: Samuel - Artificial Intelligence essay, introducing current ML approach, program beating humans in checkers

TRANSFER LEARNING:



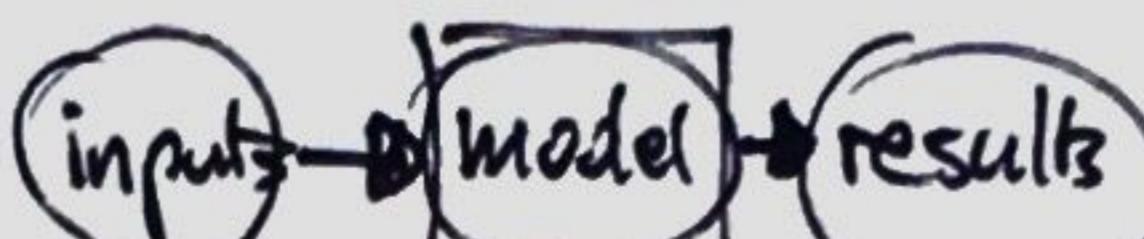
FINE-TUNE: 1) cut pre-trained model's head

2) Add new head specific to new task

3) Train new head only for 1 epochs

4) Fit entire model for more epochs (more tricks here)

ML DURING INFERENCE:



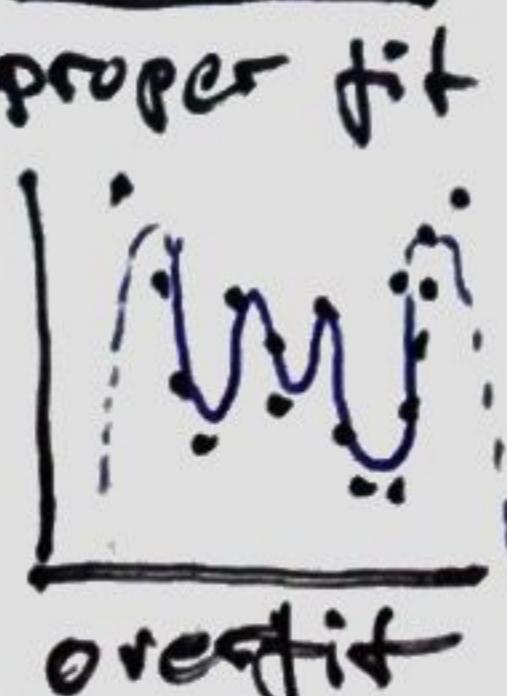
LIMITATIONS OF ML:

- Need data with labels
- Can only learn patterns seen in input data
- Predictions vs recommended actions

WATCH OUT:  
FEEDBACK LOOPS!  
e.g. YouTube recommending viral anti-vax videos

text | tabular | collab  
 from fastai.Vision.all import \* # fastai library  
 path = untar\_data(URLs.PETS)/'images' # download dataset  
 def is\_cat(x): return x[0].isupper() # labelling function  
 dls = ImageDataLoaders.from\_name\_func(  
 path, get\_image\_files(path), valid\_pct=0.2, seed=42,  
 label\_func=is\_cat, item\_tfms=Resize(224))  
 # load data, label, split into train/valid, transform  
 learn = CNN\_learner(dls, resnet34, metrics=error\_rate)  
 # load architecture, pretrained model, define metric  
 learn.fine\_tune(1) # fine-tune ~ fit pretrained model

OVERFITTING! Single most important and challenging issue! Model starts memorizing examples, rather than learning to generalize!



As a rule, split data into train/validation set, or maybe test set as well:

**TRAINING** **VALID** **TEST**

Train data on this only

Tune model, choose hyperparameters, see performance on chosen metric on valid

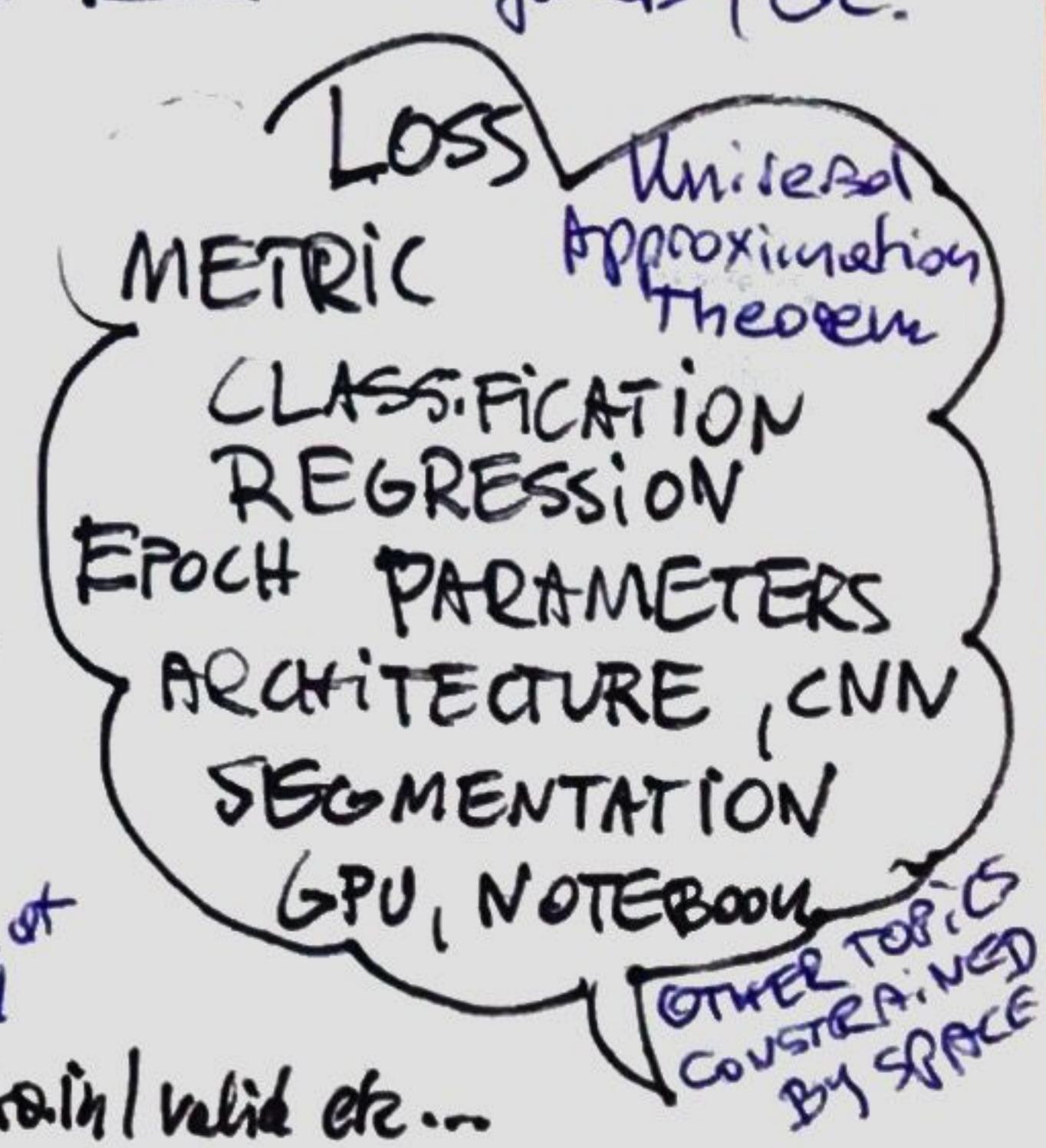
Hide test, use it to estimate performance at the very end

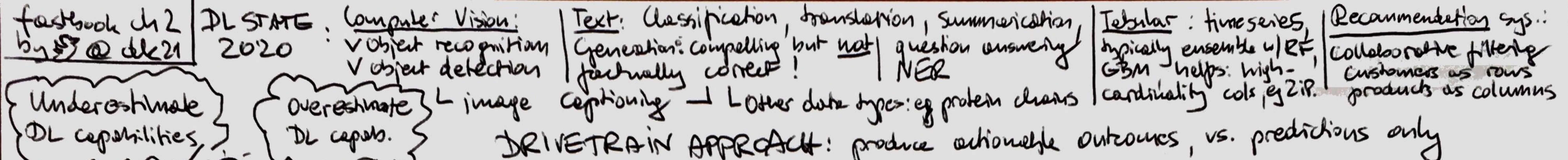
AVOID LEAKAGE! Time series, same subjects in train/valid etc...

Different layers in NN's learn to recognize increasingly complex features.

CNN - Convolutional Neural Network example:

- 
- L1: edges
  - L2: corners, shapes, colors, patterns
  - L3+: higher level components: faces, flowers, etc.

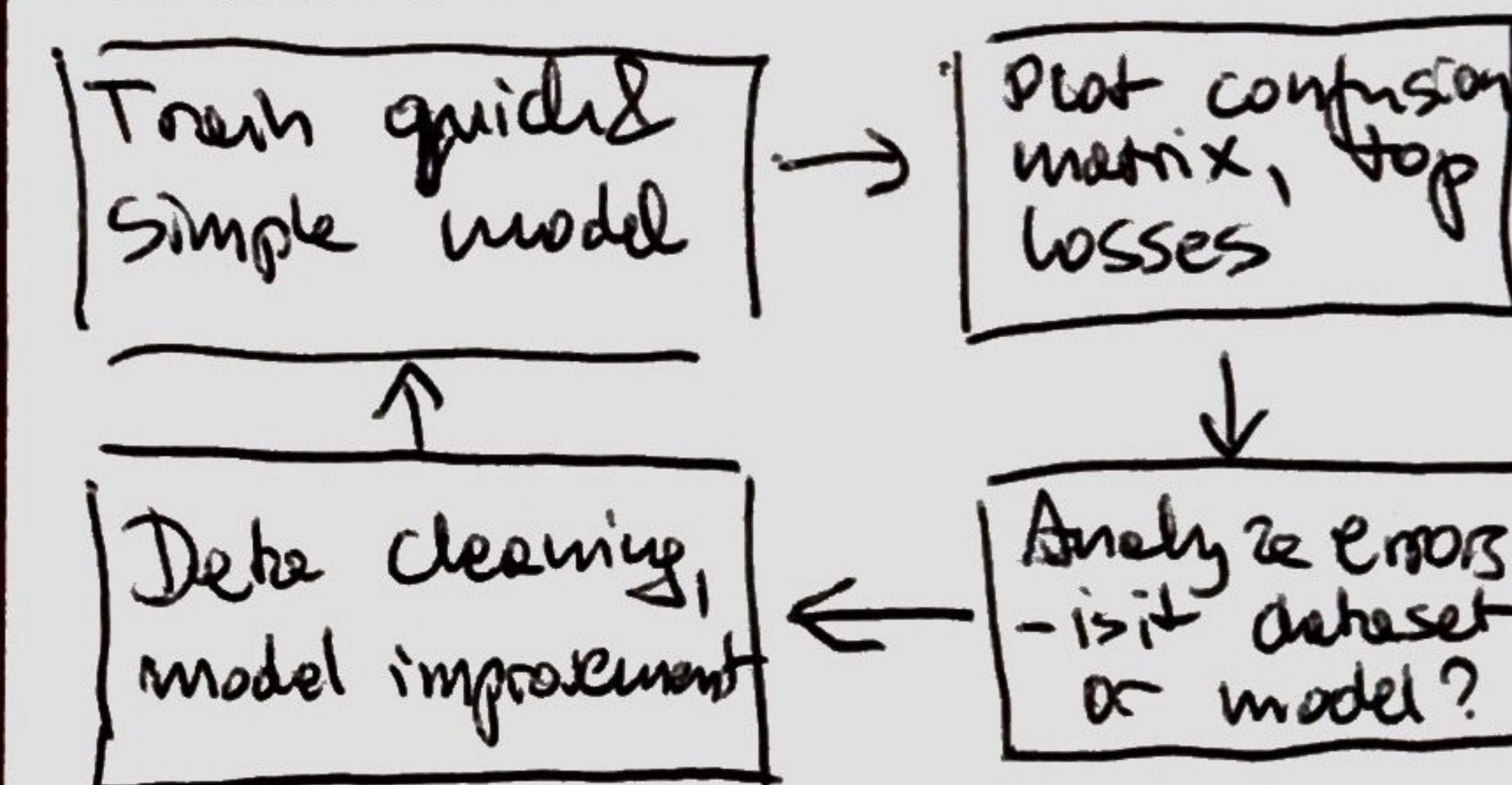




KEEP AN OPEN MIND

- ① Complete lots of small experiments and work on your own project
- ② Consider data availability
- ③ Iterate E2E - all the way to final product
- ④ Start with steps that DL is good at.

WORKFLOW:



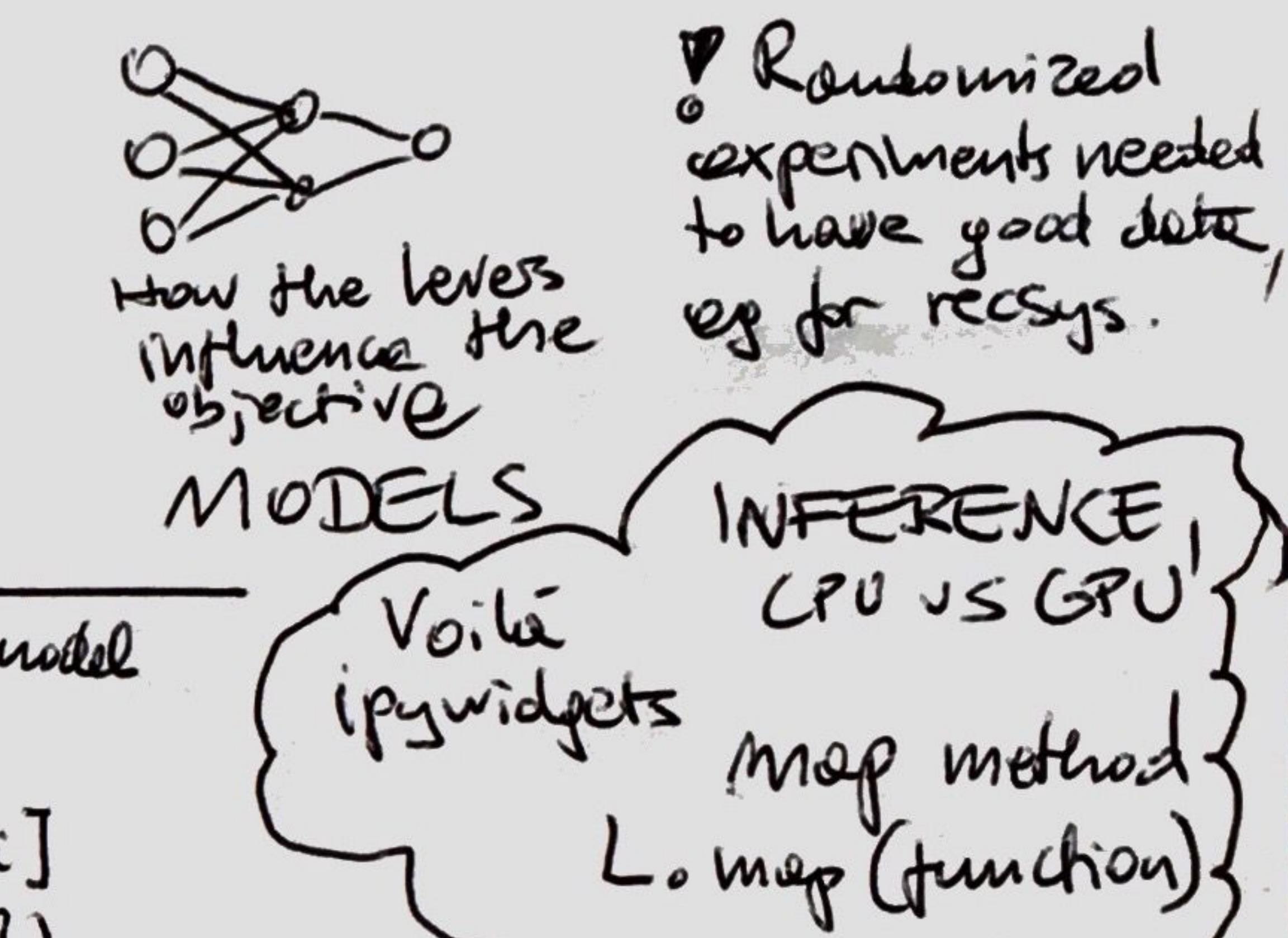
HOW TO AVOID DISASTER?

- Out of domain data: training vs production
- Domain shift: data changes over time
- Anticipate unforeseen consequences and feedback loops. What if this went really well?

1) Manual process  
- Run model in parallel  
- Humans check cell predictions

2) Limited scope deployment  
- Careful human supervision  
- Time or geography limited

3) Gradual expansion  
- Good reporting systems needed!  
- Consider what could go wrong!



```

class DataLoaders(LightningDataModule):
    def __init__(self, *loaders):
        self.loaders = loaders
    def __getitem__(self, i):
        return self.loaders[i]
    train, valid = add_props(lambda i, self: self[i])
bears = DataBlock( # template for creating data loaders (DB)
    blocks=(ImageBlock, CategoryBlock), # type of independent/dependent variable
    get_items=get_image_files, # function takes a path and returns images in that path
    splitter=RandomSplitter(valid_pct=0.3, seed=42), # split train/valid, fix seed
    get_y=parent_label # label images
    item_tfms=Resize(128)) # item_tfms run on CPU, eg. image resizing
dls = bears.dataloaders(path) # provide source of data to (DB) - here path with images
RESIZE OPTIONS: crop, squish, pad, RandomResizedCrop & recommended
  
```

DATA AUGMENTATION: create random variation in the input data, standard set provided in aug-transforms, can be done on GPU in batch:

```

bears = bears.new(item_tfms=RandomResizedCrop(128, min_scale=0.5), batch_tfms=aug_transforms,
                  learn.export(): saves both model and parameters. load_learner(path/'export.pkl') = loads model()
  
```

! TIP: Start writing, blog!  
Write for people one step behind you.

LastNode Ch.3  
notes by @dk21

**ETHICS:** the study of right & wrong, how we define & recognize them, understand the connection between action & consequences

**DATA ETHICS:** complicated, context dependent → learn through examples, like a ~~muscle~~ muscle → develop & practice it!

## BUGS, REOURSE, ACCOUNTABILITY

- (Ex) Buggy algorithm cut healthcare benefits, impacting a vulnerable group
- ▷ Finger-pointing vs taking accountability bureaucracy as a way to evade responsibility
- ▷ Data often contains errors → mechanisms for audit and correction are crucial
- (Ex) Police maintaining database of gang members with no mechanism to correct obvious errors
- (Ex) US credit report system - very difficult to correct errors

## FEEDBACK LOOPS

- (Ex) Conspiracy theories videos tend to get recommended more on YT | FB  
People watching them tend to watch more online videos  
YT | FB recommendation algorithms suggest more similar videos

## WHY YOU SHOULD CARE?

- Ex. IBM products used in Nazi concentration camps - would you be ok to contribute to killing people?

Ex. VW emission scandal - engineers jailed!

- ML can create feedback loops & amplify bias
- People more likely to assume algorithms are objective and error-free
- Often used at scale, with no appeals process implied
- Considering this will make you a better practitioner!

## BIAS IDENTIFYING & ADDRESSING ETHICAL ISSUES

- BIAS** Historical biases - people, processes, society are biased -  
Faking real world data includes these biases
- MEPICAL - doctor prescriptions differ for white vs black patients
- SALES - different prices by race
- (Ex) Searching google for a name that is historically black, you get ads for background checks (suggesting a criminal record)

- ▷ Systematic imbalance in the make-up of popular datasets, e.g. ImageNet, word embeddings

- (Ex) Translating doctor ~ man, nurse ~ women.

- Measurement bias** - measuring wrong thing, in the wrong way, incorporating it into model incorrectly

- (Ex) Factors predictive of stroke

- prior stroke
- cardiovascular disease
- accidental injury
- colonoscopy
- 

these are correlated with people actually going to a doctor, being able to afford it, vs having a stroke

- Aggregation bias** - eg diabetes treatment

based on linear, univariate models, small studies on homogeneous groups, when reality is non-linear, e.g. diff. complications, symptoms across ethnicities

- ① Analyze a project you're working on
  - Should we even be doing this?
  - What bias is in the data?
  - Can the code and data be audited?
  - What are error rates for different sub-groups?
  - What is the accuracy of a simple, rule based alternative?
  - What processes are in place to handle appeals or mistakes?
  - How diverse is the team that built it?

## Processes to implement

- Ex. Regular ethical risk sweeps (pen testing)
  - include perspectives of a variety of stakeholders
  - what could bad actors do?
  - who will be directly and indirectly affected?
  - apply ethical lenses: which option

- [RIGHTS] best reflects the rights of all stakeholders
- [JUSTICE] treat people equally or proportionately?
- [UTILITARIAN] will produce most good & least harm?
- [COMMON GOOD] best serves community as a whole, not just some members

- [VIRTUE] leads me to act as the sort of person I want to be

## The power of diversity

- ▷ Similar backgrounds = similar blindspots!  
⇒ innovation, more risks/solutions considered

- (Ex) FB lack of action during Rohingya genocide, vs quick action to address GDPR

- Advocacy is important - support the regulations that you a data scientist - believe we need!

# Fundamental Tools and Concepts for Deep Learning

`new_list = [f(o) for o in a_list if o > 0]`  
 list comprehension → to do for each element, filter

TENSOR shape - length of each axis  
 rank - number of axes = `len(shape)`

Measuring distance in space:

Mean absolute distance (L1 norm)  
 → absolute differences

Root mean squared error (RMSE, L2)  
 → mean of square diff, then root norm

Numpy ARRAY: multidimensional table of data, with all items of the same type, any type. With array of arrays, arrays underneath may have different sizes → "agged array". Operations on regular arrays written in optimized C - much faster than Python.

PyTorch TENSOR - like a numpy array, but has to use simple basic numeric type for all components. Can run on GPU.

BROADCASTING - critical efficient code!

PyTorch, when performing operation between tensors of different ranks, will automatically expand tensor with smaller rank to have the same size as the one with larger rank.

PyTorch VIEW change the shape of a tensor without changing contents, -1 parameter: make this axis as big as necessary to fit all data

② - PyTorch matrix multiplication  
 $\text{batch} @ \text{weights} + \text{bias} \Rightarrow \text{fundamental operation MNN}$   
 $w * x + b$   
 weights } parameters      Universal Approximation Theorem: this can represent any function

```
def train_model(model, epochs):
    for i in range(epochs):
        train_epoch(model)
        print(validate_epoch(model))
```

```
def train_epoch(model):
    for xb, yb in dl:
        calc_grad(xb, yb, model)
        opt.step()
        opt.zero_grad()
```

class BasicOptim:

```
def __init__(self, params, lr):
    self.params = self.params
    self.lr = lr
```

```
def step(self, *args, **kwargs):
    for p in self.params:

```

p.data -= p.grad.data \* lr

# we use .data so PyTorch won't take gradient  
# of this step

```
def zero_grad(self, *args, **kwargs):
    for p in self.params:
        p.grad = None
```

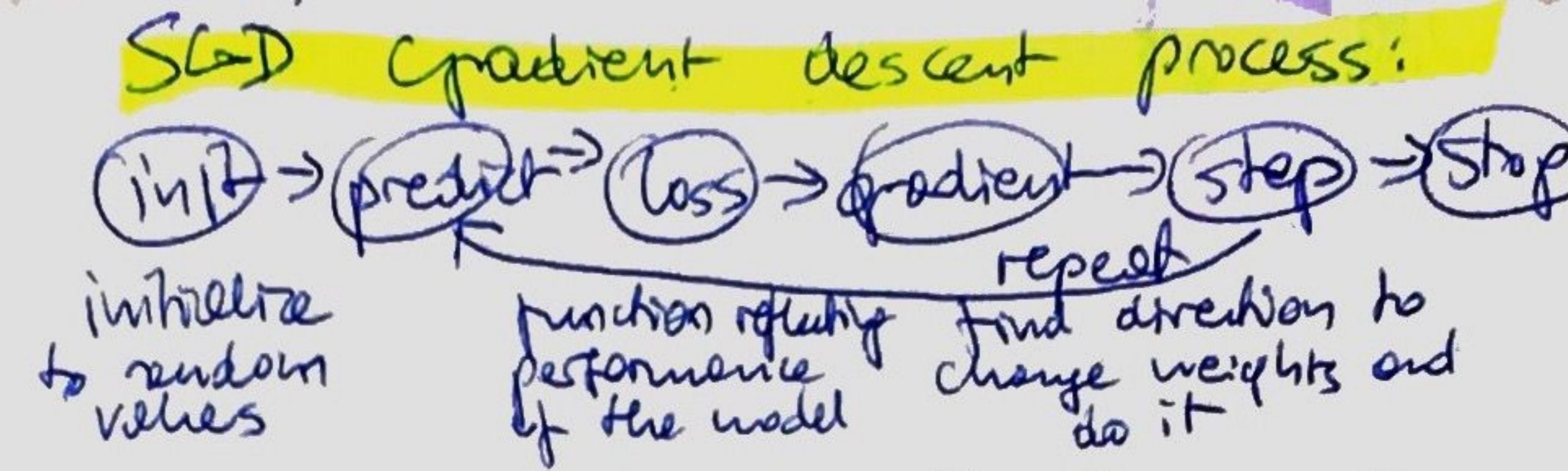
```
def calc_grad(xb, yb, model):
    preds = model(xb)
    loss = mnist_loss(preds, yb)
    loss.backward()
```

```
def linear(xb): return xb @ weights + bias
    => linear1 = nn.Linear(28*28, 1)
```

```
def mnist_loss(predictions, targets):
    predictions = predictions.sigmoid()
    return torch.where(targets == 1, 1 - predictions,
                      predictions).mean()
```

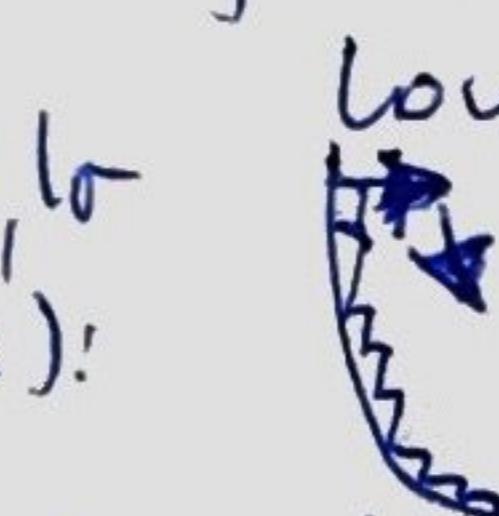
```
def init_params(size, std=1):
    return (torch.randn(size) * std).requires_grad_()
```

```
def simple_net(xb):
    res = xb @ w1 + b1
    res = res.max(tensor(0.0))
    res = res @ w2 + b2
    return res
```



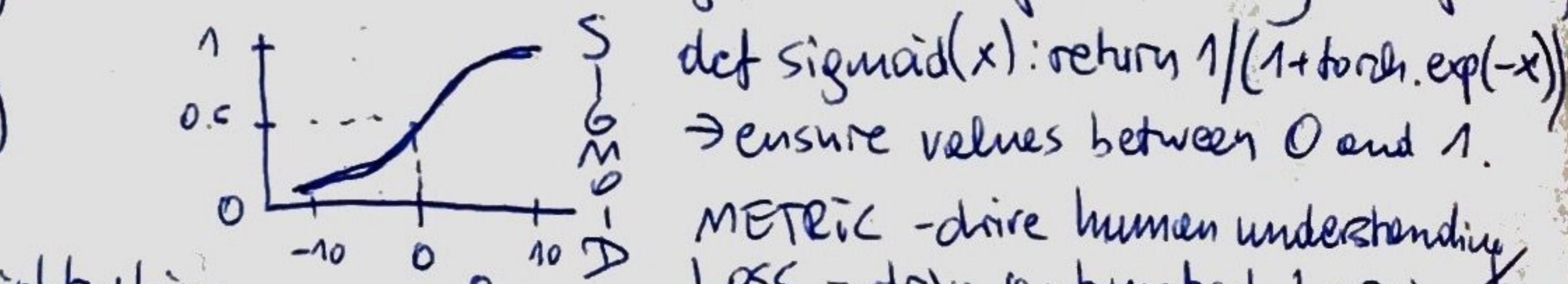
Derivative of a function tells us how much a change in parameters will change results (rise/run)

GRADIENT! value of loss function's derivative at the point we're predicting /  $\frac{df(x)}{dx}$ : return  $x^2$   
 PyTorch can do it for us!



long time! explode vs converge! A LEARNING RATE  
 Multiply the gradient by a small learning rate to decide how much to change parameters.

LOSS FUNCTION: represents how good is the performance of our model. Needs to react to small changes in weights (accuracy isn't good!).



def sigmoid(x): return 1/(1+torch.exp(-x))  
 → ensure values between 0 and 1.  
 METRIC - drive human understanding  
 LOSS - drive automated learning.

To step: change the weights/biases - we need to calculate loss on 1 or more data items. 1 is not enough - not much info, not optimized. Whole dataset would be too slow → MINI-BATCH  
 # items = batch size (! important decision)  
 We need to vary examples during training - randomly shuffle dataset on every epoch.

DATA LOADER: takes Python collection, turns it into iterator over batches:  
 $\text{dl} = \text{DataLoader}(\text{collection}, \text{batch\_size}=8, \text{shuffle}=\text{True})$   
 DATA SET: collection with tuples of independent and dependent variables. Simplest PyTorch dataset  
 $\text{dataset} = \text{list}(\text{zip}(\text{x-train}, \text{y-train}))$

## Fastbook ch.5 DEEP DIVE INTO MECHANICS OF DL

### PRESIZING

item\_tfms = Resize(460),  
batch\_tfms = aug\_transforms(size=224, min-scale=0.75)

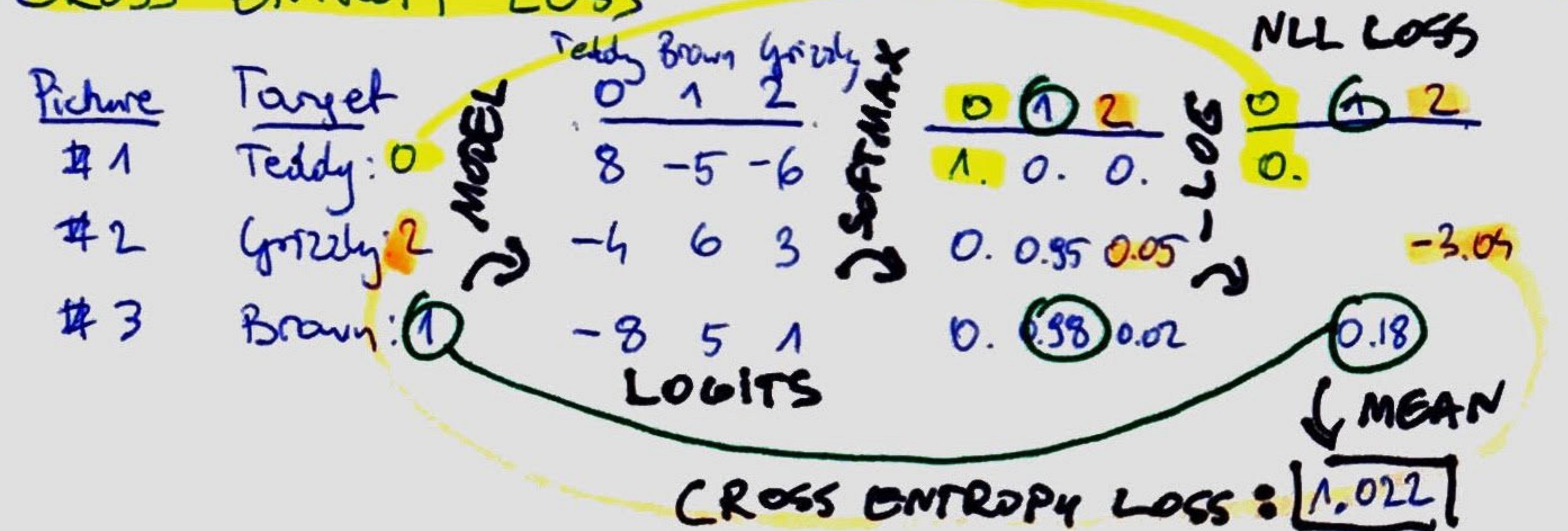
① Resize images to relatively large dimension (vs target training dimension)

② Compose all common aug operations (incl. resize to target size) into 1, and perform the combined operation on the GPU once at the end of processing  
 → avoids data losses during augmentation  
 → speeds up the process!

### CHECKING AND DEBUGGING DATA BLOCK

Show-batch → inspect data, DataBlock.summary(path)

### CROSS ENTROPY LOSS



⇒ take the softmax, then negative log likelihood of that

softmax: ensure final activations are between 0-1, and sum=1

def softmax(x): return exp(x)/exp(x).sum(dim=1,

- if one activation is slightly higher keepdim=True  
 then others, exp will amplify this - softmax really wants to pick one class - good if each image has definitive label
- may not be good at inference - will boast probs of example relative to other choices, independent of overall confidence - binary output columns, with sigmoid activation may be better?

Log likelihood: pick loss from column with correct label only, take -log of that to transform 0-1 scale to 0->inf scale

PyTorch: nn.CrossEntropyLoss ⇒ nn.LogSoftmax + nn.NLLLoss

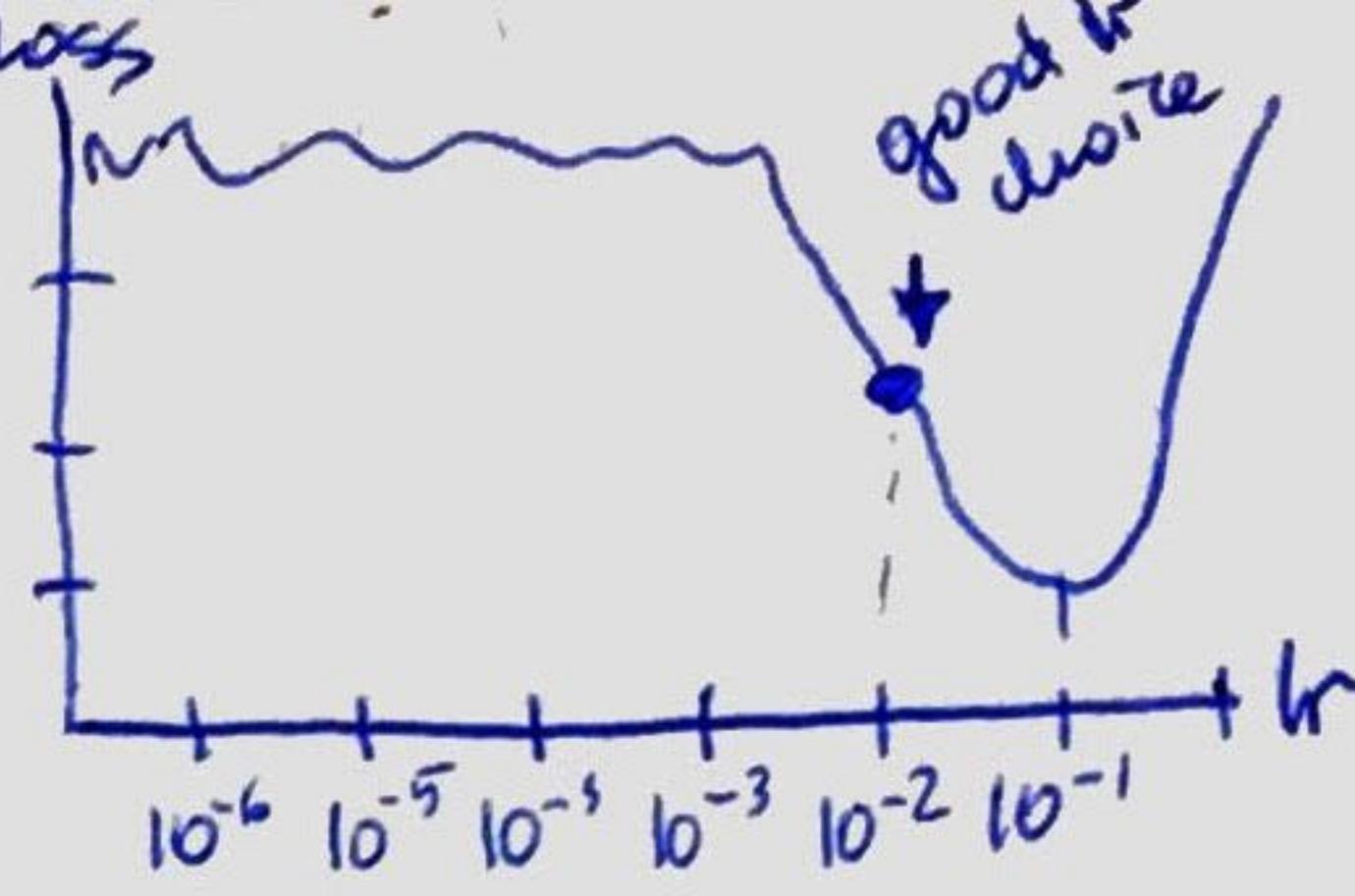
G = Learn Use eg in Regex! → RegexLabeller

this adds

RandomResizedCrop

### Learning Rate Finder (Leslie Smith)

- start with a very small learning rate
- use that for 1 mini-batch, find the loss
- increase the lr gradually, e.g. double, per mini-batch, track the loss again
- keep doing this until the loss gets worse
- good choices: a) divide minimum loss lr by 10, or b) last point where the loss is clearly decreasing (steepest point)



### Unfreezing and transfer learning

- remove pretrained model's classification head
- replace it with classif. head for new task
- this will have random weights initially, so we freeze pretrained layers and only train new head
- later, we unfreeze, check lr-finder again



### Discriminative learning rates

: pass slice (0,1, lr2) in `fit`

→ train first layers with smaller lr, last layer with higher lr, range between - multiplicatively equidistant lr's.

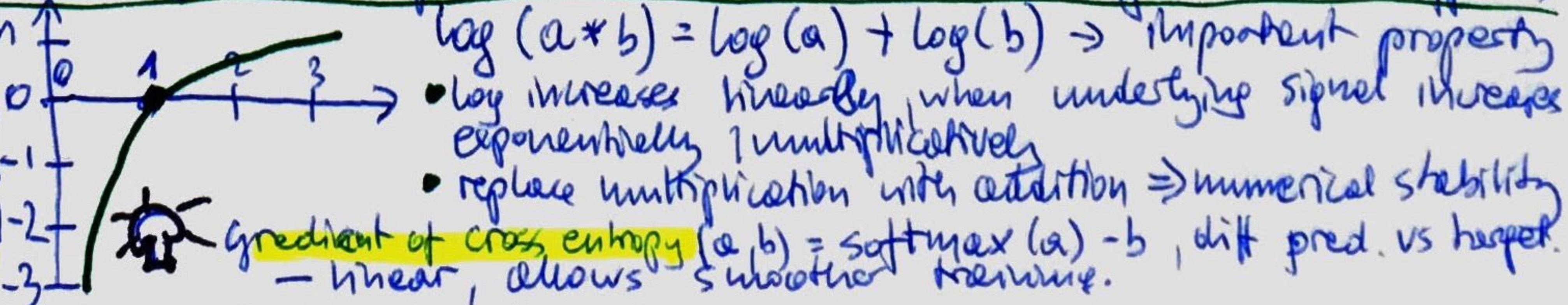
### Selecting the number of epochs

- 1) Choose based on time available
- 2) Observe training/validation losses and val. metrics
- 3) Make decisions on metrics, not losses! - Initially, validation loss will get worse, because lr becomes overconfident, it's still ok if the metrics improve. Only later, model will start to memorize.

Early stopping - save model after each epoch, select the one with best metric

This is NOT GOOD with 1cycle training - epochs in the middle have higher lr, so unlikely to find best result. Better - If we overfit - refresh model from scratch with the number of epochs where we had best results.

Deeper Architectures: rule of thumb - more layers → more accurate model, but also risk of overfitting, longer to train, not always better!  
 We can speed this up with mixed precision training: learner.to\_fp16()



Factbook ch.6 | multi-one-hot encoding  
notes by @dk21 | [0 1 0 0 1 0 1 0 0]

**Multi-label classification:** more than one type of object in an image - more common in practice to have some images with zero or more than 1 category match.

Use DataBlock API to construct DataLoaders object from Pandas df:

- start by creating and testing Datasets
- create DataLoaders after that's working

```
dblock = DataBlock(get_x=lambda r: r['frame'],
                    get_y=lambda r: r['labels'])
```

dsets = dblock.datasets(df)

dsets.train[0], len(dsets.train), len(dsets.valid)

! Lambda functions (defined inline) are good for iterating, but not compatible with serialization!

Need verbose functions to export Learner after training.

```
def get_x(r): return path/'train'/r['frame']
```

```
def get_y(r): return r['labels'].split(' ')
```

def splitter(df):

```
train = df.index[df['is_valid']].tolist()
```

```
valid = df.index[df['is_valid']].tolist()
```

return train, valid

```
dblock = DataBlock(blocks=(ImageBlock, MultiCategoryBlock))
```

splitter = splitter,

get\_x = get\_x,

get\_y = get\_y,

item\_tfms = RandomResizedCrop(128, min\_scale=0.35)

dl = dblock.dataloaders(df)

dl.show\_batch(rows=1, ncols=3)

! Pass y-range to learner to force outputs into range: def sigmoid\_range(x, lo, hi): return torch.sigmoid(x)\*(hi-lo)+lo

## BINARY CROSS ENTROPY (BCE)

def binary\_cross\_entropy(inputs, targets):

inputs = inputs.sigmoid()

return -torch.where(targets == 1, inputs, 1 - inputs).log().mean()

Picture	Target	Logits	Sigmoid	Loss
#1	Teddy Brown Grizzly	8 -5 -6	1 0.01 0	0. 0.01 D.
#2	1 0 0	-4 6 3	0.02 1 0.95	0.02 0. 3.05
#3	0 1 0	-8 5 1	0 0.99 0.73	0.001 0.3)

positive targets:  $-\log(\text{sigmoid})$

neg. targets:  $-\log(1 - \text{sigmoid})$

BCE Loss = 0.3777

PyTorch: nn.BCELoss (without sigmoid) or nn.BCEWithLogitsLoss

(with sigmoid)

loss\_func = nn.BCEWithLogitsLoss()

loss = loss\_func(activs, targets)

accuracy - single label | accuracy - multi-label

def accuracy(inp, targ, axis=-1):  
pred = inp.argmax(dim=axis)  
return (pred == targ).float().mean()

def acc\_multi(inp, targ, thresh=0.5,  
sigmoid=True):  
if sigmoid: inp = inp.sigmoid()  
return ((inp > thresh) == targ.bool()).float().mean()

PARTIAL example (Python):

acc\_0.2 = partial(acc\_multi, thresh=0.2)

## REGRESSION

Example - image regression, key point detection:

bini = DataBlock(in test set this will also apply)

blocks = (ImageBlock, PointsBlock), augmentation no

get\_items = get\_image\_files,

get\_y = get\_chr,

splitter = FuncSplitter(lambda o: o.parent.name == 'B'),

batch\_tfms = [x any-transforms(size=(240, 320)),

NormalizeFromStats(\*image-net-stats)]

learn = nn.Learner(dls, resnet15, y\_range=(-1, 1))

dls.loss\_func

→ MSELoss()

→ right function for regression!

Flexible API + Transfer learning  
= POWER!

Rather than focusing on domains, focus on:

Independent Dependent  
Var Var

Image	Text (caption)
Text	Image (from opt.)
Image + Text + Behavior	Product - Purchase-prob.

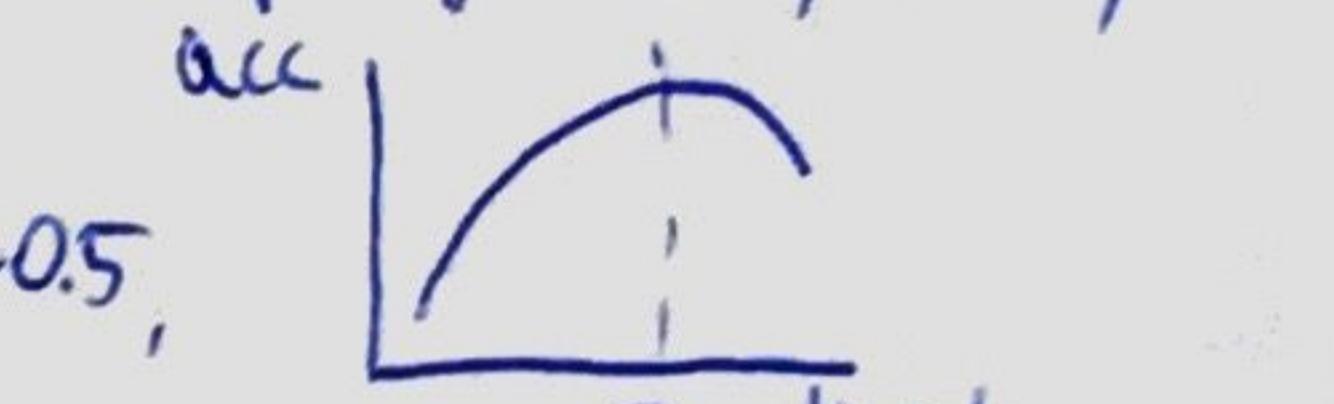
+ Loss function!

Finding the best threshold:

xs = torch.linspace(0.05, 0.95, 25)

accs = [acc\_multi(pred, targ, thresh=i, sigmoid=False)  
for i in xs]

plt.plot(xs, accs);



Ok to choose hyperparam based on valid set, if the function looks smooth

## Fastbook ch. 7 | Training a SOTA model

- ① If your dataset is big, experiment on a subset of it
  - iterate at faster speed
  - the more experiments you can do, the better
  - subset should be representative → generalize

(Ex) Imagenette: 10 classes from Imagenet

## Normalization $\Rightarrow \text{mean} = 0, \text{std} = 1$

- helps the model train
- especially important when using pretrained models - distributed with stats used for normalization, use them for inference or transfer learning

check:  $x, y = dls.one\_batch()$

•  $x.\text{mean}(\text{dim}=[0, 2, 3]), x.\text{std}(\text{dim}=[0, 2, 3])$

(average over all axes except channel=1)

fastai: add Normalize transform in batch\_tfms

def get\_dls(bs, size):

dblock = DataBlock(blocks=(ImageBlock, CategoryBlock),

get\_items = get\_image\_files,

get\_y = parent\_label,

item\_tfms = Resize(460),

batch\_tfms = [\*aug\_transforms(size=size,  
min\_scale=0.75),

normalize.from\_stats(\*imagenet\_stats)])

return dblock.dataloaders(path, bs=bs)

## Progressive resizing

Gradually using larger & larger images as we do finetune after resizing

Works also as data augmentation

dls = get\_dls(128, 128)

# create learner, fit one-cycle

learn, dls = get\_dls(64, 224)

# learn.fine\_tune(epocs, lr)

May hurt performance  
in finetune learning if  
pretrained model/dataset  
are similar to our dataset.

## Test Time Augmentation (TTA)

During inference or validation, creating multiple versions of each image using data augmentation, and then taking the average or maximum of the predictions.

- (the default in fastai is center-cropping, for validation = largest square centered)
- problematic if relevant objects near edges
- squish/stretch may be difficult to train
- TTA solves these problems

preds, targs = learn.tta() # default is unaugmented center crop + 4 randomly augmented images, applied on valid dset.

## Mixup

For each image img

- 1) select another dataset image at random
  - 2) pick a weight at random
  - 3) take a weighted average of the img image and the selected image
  - 4) take a weighted average of the img labels with the selected image's labels
- (targets need to be one-hot encoded)

In fastai: callbacks are used to inject custom behavior in training loop

model = xresnet50()

learn = Learner(dls, model, loss\_func = CrossEntropyLossFlat(), metrics=accuracy,

cb = Mixup) # callback

→ more epochs are needed to train for good accuracy (eg. Imagenette LB - mixup in models > 80 epochs)

→ can be used on activations inside models (NLP use cases)

## Label Smoothing (LS)

Problem with OHE: overconfidence, labels are always 0 or 1 even if there is nuance or uncertainty. Leads to overfitting, probabilities at inference not meaningful.

LS: replace all 1s with a number bit less than 1  
— 1 — 0.5 — 1 — more than 0

→ then train. Leads to:

- training more robust, even with noisy data
- models that generalize better

① Start with OHE

② Replace all 0s with  $\frac{\epsilon}{N}$  - usually 0.1

③ Replace 1 with  $1 - \epsilon + \frac{\epsilon}{N}$

In practice we don't change, or one-hot encode labels, but apply this in the loss function.

model = xresnet50()

learn = Learner(dls, model, loss\_func = LabelSmoothingCrossEntropy(),  
metrics=accuracy)

learn.fit\_one\_cycle(5, 3e-5)

→ more epochs are needed to train for good accuracy.

## Summary

① Establish your environment for quick iteration (experimentation

- subset of dataset
- validation generalizes to test/prod.

② Start with a simple, strong baseline

③ Run many experiments:

- Augmentation
- Lots functions
- Inspect data/results for insights

+ check/read research papers

Chapter 8 - Feedback notes by Darch: @dch21

## LATENT FACTORS

common characteristics of items / user preferences

Example:

Movie is [ action: 0.9, sci-fi: 0.98, old: 0.8 ] A  
User likes [ 0.8, 0.9, -0.6 ] B

Dot Product  $A \cdot B = \text{multiply vectors together, then sum up the result}$

We don't know latent factors → need to learn them!

## Embedding from scratch in PyTorch

// Multiplying by a one-hot encoded matrix, using the computational shortcut that it can be implemented by simply indexing directly.

U1	f1	f2	f3	$u = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ ← vector
U2	1	2	3	← user3
U3	3	1	2	← matrix F
U4	2	2	3	

$F[3, :] \Rightarrow F^T * u$

We index into the embedding matrix using an integer, but calculate the derivative as if we were multiplying the matrix with OHE vector

## Bootstrap loop problem (- cold start)

- pick some user to represent avg taste
- use a tabular model based on user metadata to construct initial embedding
- ! Representation bias & feedback loops are a risk - monitor, keep humans in the loop, gradual, roll out...

## COLLABORATIVE FILTERING DEEP GIVE

= look at what products the current user has used or liked, find other users that have used or liked similar products, then recommend other products that those users have used or liked. Generalize: items vs products, e.g. diagnoses, links etc.

### dls = Colab's DataLoaders

```
from_dfl(ratings, item_name='title', bs=64)
```

n-users = len(dls.classes['user'])  
n-movies = len(dls.classes['title'])  
n-factors = 50

def create\_params(size):  
 return nn.Parameter(torch.zeros(size).normal\_(0, 0.01))

class DotProductBias(Module):  
 def \_\_init\_\_(self, n-users, n-movies, n-factors, y-range=(0, 5)): # In PyTorch we need to inherit from Module

self.user-factors = create\_params([n-users, n-factors])  
 self.user-biases = Embedding(n-users, n-factors)  
 self.user-biases = create\_params([n-users])  
 self.user-biases = Embedding(n-users, 1)  
 self.movie-factors = create\_params([n-movies, n-factors])  
 self.movie-biases = create\_params([n-movies])  
 self.y-range = y-range

def forward(self, x):  
 users = self.user-factors[x[:, 0]]  
 movies = self.movie-factors[x[:, 1]]  
 res = (users \* movies).sum(dim=1)  
 res += self.user-biases[x[:, 0]] + self.movie-biases[x[:, 1]]  
 return Sigmoid-range(res, \*self.y-range)

### Weight decay | L2 regularization

Addition to our loss function the sum of all the weights squared, to encourage weights to stay small to prevent overfitting

wd | weight decay-parameter, how much we add loss:  
loss\_with\_wd = loss + wd \* (parameters \*\* 2).sum()

parameters.grad += wd \* 2 \* parameters - same but faster!

In faster, we pass it in a cell to fit:  
learn.fit-one-cycle(5, 5e-3, wd=0.1)

### Embedding distance

Movie similarity can be defined by the similarity of users that like those movies, distance between embedding vectors can define that similarity

movie-factors = learn.model.i-weight.weight  
idx = dls.classes['title'].02i['Movie title 1']  
distances = nn.LosineSimilarity(dim=1)(movie-factors, movie-factors[idx][None])  
idx = distances.argsort(descending=True)[1]  
dls.classes['title'][idx]

### Colab NN

- dot product was PMF (probabilistic matrix factorization) approach, there is an option to do it with deep learning!

class ColabNN(Module):  
 def \_\_init\_\_(...):  
 ...  
 self.layers = nn.Sequential(  
 nn.Linear(user-sz[1] + item-sz[1], n-out),  
 nn.ReLU(),  
 nn.Linear(n-out, 1))  
 def forward(self, x):  
 embs = self.user-factors(x[:, 0]) self.item-factors(x[:, 1])  
 x = self.layers(torch.cat(embs, dim=1))  
 return Sigmoid-range(x, \*self.y-range)

NO SPACE

**Fastbook ch 9 notes by @thel1**

**TABULAR MODELING**  $\Rightarrow$  Data as a table; predict value in 1 column based on other cols

**Variables**

- **continuous**: numerical data, feed directly to model
- **categorical**: discrete levels (e.g. movie IDs), need to convert to numbers first
  - **Ordinal** - categories with natural ordering
  - **df['ord-cat']**  $\rightarrow$  Categorical (order, ordered=True, inplace=False)

(AT: represent via one-hot-encoding or entity embedding:  
→ reduces memory usage and speeds up NN vs OHE  
→ reveals intrinsic properties of variables - similar values close to each other in embedding space)

**Decision Trees** TIP: avoid OHE categories for DTs / RFs

- 1) Loop through each column in dataset (greedy approach)
- 2) For each col, loop through each possible level of that col.
- 3) Try splitting data into 2 groups at that level
- 4) For regression: find avg value of dependent var. for each of 2 groups, see how close it is to the actual value of dep. variable for each of the items in that group
- 5) After looping thru all cols / levels, pick split point with the best predictions
- 6) For each group based on this split, repeat the process

**Random Forests** (Breiman 1984, 2001)

- 1) Randomly choose a subset of rows and subset of columns
- 2) Train a model using this subset (decision tree)
- 3) Serve that model, return to step 1 several times
- 4) To make a prediction, predict using all served models then take average of those predictions  $\Leftarrow$  **BAGGING**
- 5) Important - errors of individual models are not correlated, so the average of those errors is ZERO

**Out of Bag Error**: measure prediction error on the training set by only including in the calculation of a row's error the rows where that row was not included in training

**BOOSTING**: another approach to ensembling (vs BAGGING)

- 1) Train a small model that underfits your dataset
- 2) Calculate predictions in the training set for this model
- 3) Subtract predictions from targets = **RESIDUALS**
- 4) Go back to step 1, now use the residuals as targets
- 5) Continue until a stopping criterion: max no trees, valid error getting worse, etc!

GBMs, GDTs, XGBoost  $\rightarrow$  Risk of overfitting  
 $\rightarrow$  very sensitive to hyperparameter choices

**TABULAR MODELING WORKFLOW**

- 1) Start with RF - easiest to train, most relevant to hyperparameter choices
- 2) Use RF model for feature selection, PDP
- 3) Then try NNs or GBMs, try adding embeddings of cat. variables to the data

**MODEL INTERPRETATION**

For a particular row:

- 1) How confident are we in our prediction?
- 2) What were the most important factors for this row?
- 3) Which columns are influencing prediction? ignore?
- 4) Which columns are least used with each other?
- 5) Which columns are very similar to each other?

**TREE VARIANCE**

Check std deviation of predictions across trees:  
preds = np.stack([t.predict(valid\_xs) for t in m.estimators])  
preds\_std = preds.std(0)  
high std  $\Rightarrow$  low confidence

**REMOVING LOW IMPORTANCE VARIABLES**

Generally the 1st step to improve the model is simplifying it, so that it's easier to study, roll out, maintain  $\Rightarrow$

Remove columns / variables of low importance  
 $\rightarrow$  Retrain the model  $\rightarrow$  check improved accuracy

**REMOVING REDUNDANT FEATURES**

cluster-columns (xs) - shows similarity of columns. We determine similarity by calculating the rank correlation - all values are replaced by their rank, then correlation is calculated

$\rightarrow$  try removing each of potentially redundant features one at a time then multiple from overlapping groups, observe OOB score / accuracy

**TREE INTERPRETER + WATERFALL CHARTS**

What were the most imp factors for predicting with a particular row of data? How did they influence that prediction? Calculated similarly to feature importances.

$\rightarrow$  display feature contributions with waterfall chart  
 $\rightarrow$  use it to provide useful information to users of your data product - reasons behind predictions

**EXTRAPOLATION** - Decision Trees / RF can never predict values outside of the range of training data (e.g. trend). NN can help. Also finding **out-of-domain data**:

- 1) combine train & valid sets
- 2) use RF to predict if a row is in train or valid set
- 3) get feature importances - for the columns that differ significantly between train/valid by removing them and see how it impacts accuracy. It can improve it, and make the model more robust

$\rightarrow$  Try to avoid using old data - it may no longer be predictive

**DATA LEAKAGE**

= giving model information about the target which normally should not be available at the time of prediction. How to detect it?

- check if the accuracy is too good to be true
- look for imp factors that don't make sense
- look for PDP plots that don't make sense in practice

**Using a Neural Network**

- 1) Decide which cols should be treated as cat vs cont
- 2) Create embeddings for categorical variables
- 3) Add normalization (in proc)
- 4) Consider adding y-range to regression models
- 5) Adjust hidden layer sizes to size of dataset

**fastai! TabularPandas** (handles df + convenience)

Tabular Proc Tabular\_learner Other:  
Category TabularModel dtreeviz  
Fill Missing Study source code add\_datapart



ULMFit Approach: fine-tune pretrained LM on the target corpus prior to transfer learning to classification task.

**Language Model:** model trained to guess the next word in a text, after reading the words before

**Self-supervised learning:** training a model using labels that are embedded in the independent variable, rather than requiring external labels. Usually used for pretraining in transfer learning.

## TEXT PREPROCESSING IN 3 STEPS

### ① TOKENIZATION

= converting a text into a list of tokens

- word-based: split sentence on spaces and language-specific rules
- subword-based: analyze a corpus of documents to find the most commonly occurring groups of letters. These substrings become the vocab.
- character-based

fastai adds some functionality with **Text Tokenizer class**, e.g. special tokens:

xxbos : beginning of text

xxusei : next word begins with a capital

xxunk : next word is unknown

• see rules: `defaults.text_proc_rules`

Setup creates the vocab that is used in tokenization

`[txt]` - collection of text documents

`spacy = WordTokenizer()` displays first n print(`coll-repr(toks, 3)`) elems of collection

`tkn = Tokenizer(spacy)` adds special print(`coll-repr(tkn(txt), 3)`) tokens etc

`sp = SubwordTokenizer(vocab_sz=52)`  
`sp.setup(txts)`

### ② NUMERICALIZATION

= mapping tokens to integers

- make a list of all possible levels of a variable (the vocab)
- replace each level with its index in the vocab

`num = Numericalize()  
num.setup(toks)  
coll-repr(num.vocab, 20)`

class methods

### ③ PUTTING TEXT INTO BATCHES

for a language model

- we want LM to read text in order
- we use a model that maintains a state - remembers what it read previously when predicting what comes next

- transform indiv. texts into a stream by concatenating them, shuffle docs order before each epoch
- cut this stream into a certain number of batches (batch size)  
mini-streams preserve order of tokens
- Each batch step read seq-len from mini-streams

→ dependent variable is offset from the independent variable by 1 token // **LM Data Loader**

Potential to generate disinformation campaigns, flood social media with fake content etc → see ch. 3 on ethics

**Collating items in a batch**

- use padding to make texts all the same size
- sort (ish) docs by length prior to each epoch - batch together docs with similar lengths, pad to length of longest doc in a batch

`get-imdb = partial(get_text_files, folders=['train', 'test', 'unsup'])`

`dls_lm = DataBlock(when fastbook passed, fastai handles tokenization and numericalization)`

`blocks = TextBlock.from_folder(path, is_lm=True),`

`get_items = get-imdb, splitter=RandomSplitter(0.1)`

`).dataloaders(path, path=path, bs=128, seq_len=50)`

`dls_lm.show_batch(max_n=2)` Words that are not in the vocab of pretrained lm will be added with random embeddings

### # FINE-TUNING LANGUAGE MODEL

`learn = language_model_learner(dls_lm, AWD_LSTM,`

`drop_mult=0.3, metrics=[accuracy, Perplexity()]).to_fp16()`

loss function: cross entropy &

perplexity metric: exponential of  $\text{torch.exp(cross_entropy)}$

`learn.fit_one_cycle(1, 2e-2)` automatically proven, this will only train embeddings

`learn.save('1epoch')` use fit-one-cycle to save/load intermediate model results

`learn.unfreeze()`

`learn.fit_one_cycle(10, 2e-3)` ENCODER = model without task-specific final layers, like body in CNNs

`learn.save_encoder('finetuned')` TEXT GENERATION

`TEXT = 'I liked this movie because'`

`N_WORDS = 60`

`pred = learn.predict(TEXT, N_WORDS, temperature=0.25)`

# creating the classifier dataloader ! `is_lm=False`

`dls_clas = DataBlock(poss vocab to use fine-tuned encoder)`

`blocks = (TextBlock.from_folder(path, vocab=dls_lm.vocab), CategoryBlock),`

`get_y = parent_label,`

`get_items = partial(get_text_files, folders=['train', 'test']),`

`splitter = GrandparentSplitter(valid_name='test')`

`).dataloaders(path, path=path, bs=128, seq_len=72)`

`learn = text_classifier_learner(dls_clas, AWD_LSTM, drop_mult=0.5,`

`metrics=accuracy).to_fp16()`

`learn = learn.load_encoder('finetuned')` Gradual unfreezing + discriminative learning rates

`learn.fit_one_cycle(1, 2e-2)`

`learn.freeze_to(-2)`

`learn.fit_one_cycle(1, slice(1e-2 / (2.6 ** 4), 1e-2))`

`... (freeze_to(-3)) ...`

`learn.unfreeze()`

`learn.fit_one_cycle(2, slice(1e-3 / (2.6 ** 4), 1e-3))`

FastText Ch. 11 Data Mining with  
notes by @dh21 Father's Mid-Level API

FastText is built on a layered API:

Top layer = applications - train a model  
in 5 lines of code, eg:

TextDataLoaders.from\_folder()

Mid level API:  
- create new DataLoaders  
- apply just part of transforms  
- has the collab system, which  
allows to customize training loop any  
way we like  
- has general optimizers

Transform: an object that behaves like  
a function, has optional setup method to  
initialize hidden state (eg vocabs) and an  
optional decode that reverses the function.  
Special behavior - always gets applied over  
tuples (input, target)

Exemples: Tokenizer, Numericalize

- 1) Create object
  - 2) call setup method
  - 3) apply to input by calling  
object as a function
  - 4) decode result back to  
understandable representation
- usage:  
fasttext.enapsulates these steps in the  
Transform class

Write your own Transform

1) Write a function / + decorator

def f(x: int): return x+1  
    <sup>function only gets applied to int</sup>

tfn = Transform(f)  
2) **Decorator** - Python syntax for passing a function  
to another function (or callable) so that  
it behaves like a function

@Transform

def f(x: int): return x+1

3) If we need setup or decode, then need to  
subclass Transform and implement encode

FROM: → → → →

path = untar\_data(URLs.IMDB)

dls = DataBlock(

blocks=(TextBlock.from\_folder(path),  
        CategoryBlock),

get\_y=parent\_label,

get\_items=partial(get\_text\_files,  
              folders=['train', 'test']),

splits=GrandParentSplitter(valid\_name='test')(files)

).dataloaders(path)

→ class NormalizeMean(Transform)

def setups(self, items): self.mean = sum(items)/len(items)

def encodes(self, x): return x - self.mean

def decodes(self, x): return x + self.mean

tfn = NormalizeMean()

tfn.setup([1, 2, 3, 4, 5])

↑ note we call setup  
but implement  
setups

Pipeline: compose several Transforms together

tfms = Pipeline([tok, num]) define it by  
passing a list of transforms

t = tfms(txt) automatically applies transforms

tfms.decode(t) decode result of encoding

TfmDLists and Datasets: Transformed Collections

cut = int(len(files)\*0.8)

splits = [list(range(cut)), list(range(cut, len(files)))]

tls = TfmDLists(files, [Tokenizer.from\_folder(path),  
                      Numericalize], splits=splits)

t = tls[0]

TfmDLists = class that groups  
data as a set of raw items

tls.decode(t) (filenames, dt rows...) and Pipeline

of Transforms. At initiation will setup th each

Transform in order. We index into it to get results

of pipeline on raw elements. Can handle train/valid: tls.valid[0]. Convert it to dataloader w/ dataloader mode!

TO: (equivalent, but can be customized):

tfms = [[Tokenizer.from\_folder(path), Numericalize],  
        [parent\_label, Categorize]]

files = get\_text\_files(path, folders=['train', 'test'])

splits = GrandParentSplitter(valid\_name='test')(files)

dsets = Datasets(files, tfms, splits=splits)

dls = dsets.dataloaders(dl\_type=SortedDL,  
                      before\_batch=pad\_input)

Datasets: apply 2 (or more) Pipelines in parallel  
to the same raw object and build a tuple with  
the result. → automatically do Setup for us

→ When indexed, return a tuple with result of  
each pipeline!

x\_tfms = [Tokenizer.from\_folder(path), Numericalize]

y\_tfms = [parent\_label, Categorize]

dsets = Datasets(files, [x\_tfms, y\_tfms], splits=splits)

x, y = dsets.valid[0]

→ convert it to dataloader (here: need to pad input):

dls = dsets.dataloaders(bs=64, before\_batch=pad\_input)

DataLoader: collects the items from our datasets  
into batches. Many ways to customize:

1) after\_item: applied on each item after grabbing  
it inside the dataset (~item\_tfms in DataBlock)

2) before\_batch: applied on list of items before  
they are collated. Ideal place to pad items  
to the same size.

3) after\_batch: applied on the batch as a  
whole after its construction (~batch\_tfms)

{ Application Example: Siamese Pair  
Siamese model takes two images and  
has to determine if they are same class or not