

Homotopy techniques for analytic combinatorics in several variables

(joint work with Stephen Melczer[†] and Josip Smolčić[†])

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**Combinatorial Applications of Computational
Geometry and Algebraic Topology**



Analytic combinatorics

$(f_n) = f_1, f_2, \dots$: a sequence of complex numbers.

$F(z) = \sum_{i=1}^{\infty} f_i z^i$: the **generating function** of the sequence.

- The generating function can be considered as the power series expansion of a complex valued function.

Q. Can we study the asymptotic behavior of (f_n) using the (analytic) behavior of F ?

- (Cauchy integral formula). $f_n = \frac{1}{2\pi i} \int_{\gamma} F(z) \frac{dz}{z^{n+1}}$

Analytic combinatorics in several variables

$F(\mathbf{z}) = \sum_{\mathbf{i} \in \mathbb{N}^n} f_{\mathbf{i}} \mathbf{z}^{\mathbf{i}}$: the **multivariate** generating function of the sequence.

- Specifically, the \mathbf{r} -diagonal sequence $(f_{n\mathbf{r}})$ for any $\mathbf{r} \in \mathbb{R}^n$ is considered.
- The common situation to arise in practice is the main-diagonal $\mathbf{r} = \mathbf{1}$. Ex) (Furstenberg 1967), (Christol 1984), (Chudnovsky-Chudnovsky 1985), (André 2000)
- Applications : Lattice path enumeration, random walks, and so on.

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ACSV + Numerical algebraic geometry

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(Need a system of equations)

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- It is important to find where the singularity locates.

- Define $\text{Abs} : (z_1, \dots, z_n) \mapsto |z_1 \dots z_n|$.
- We are interested in critical points of Abs .
- $\mathcal{V} := \{\mathbf{z} \in \mathbb{C}^n \mid H(\mathbf{z}) = 0\}$: the **singular variety** of $F = \frac{G}{H}$
- The smooth critical points for Abs on \mathcal{V} are obtained by solving a polynomial system
- $H(\mathbf{z}) = 0, \quad z_1 \frac{\partial H}{\partial z_1} = \dots = z_n \frac{\partial H}{\partial z_n}$ (**critical-point equations**)
- Especially, we are interested in **minimal** critical points (i.e. critical points lie in $\partial \mathcal{D} \cap \mathcal{V}$).

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- $\mathcal{V} := \{\mathbf{z} \in \mathbb{C}^n \mid H(\mathbf{z}) = 0\}$: the **singular variety** of $F = \frac{G}{H}$

- The smooth critical points for Abs on \mathcal{V} are obtained by solving a polynomial system

- $H(\mathbf{z}) = 0, \quad z_1 \frac{\partial H}{\partial z_1} = \cdots = z_n \frac{\partial H}{\partial z_n}$ (**critical-point equations**)

- Especially, we are interested in **minimal** critical points (i.e. critical points lie in $\partial \mathcal{D} \cap \mathcal{V}$).

ACSV + Numerical algebraic geometry (how to construct a system of equations)

- $F(\mathbf{z}) = \frac{G(\mathbf{z})}{H(\mathbf{z})}$ where G and H are co-prime

polynomials with $H(\mathbf{0}) \neq 0$.

- $F(\mathbf{z}) = \sum_{\mathbf{i} \in \mathbb{N}^n} f_{\mathbf{i}} \mathbf{z}^{\mathbf{i}}$: The Taylor expansion of F centered at the origin with a nonempty open domain of convergence $\mathcal{D} \subset \mathbb{C}^n$.

- Interested in computing the asymptotic behavior of coefficients of $(f_{\mathbf{i}})_{\mathbf{i}}$.

$$f_{i_1, \dots, i_n} = \frac{1}{(2\pi i)^n} \int_{\gamma} \frac{F(\mathbf{z})}{z_1^{i_1} \cdots z_n^{i_n}} \cdot \frac{dz_1 \cdots dz_n}{z_1 \cdots z_n}$$

- It is important to find where the singularity locates.

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2. Construct the subset points $(\boldsymbol{\zeta}, \lambda, t) \in \mathcal{S}$ which are candidates for minimal critical points.
 - \mathbf{z} is minimal if and only if the line segment $\{(t|z_1|, \dots, t|z_n|) \mid 0 < t < 1\}$ doesn't intersect \mathcal{V} .
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Doesn't hold if F is not combinatorial



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$$a_j \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_R = 0 \quad j = 1, \dots, n$$

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2. For checking emptiness of $\mathcal{V} \cap D(\mathbf{z}) = \emptyset$, we consider equations

$$H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0$$

$$x_j^2 + y_j^2 - t(a_j^2 + b_j^2) = 0 \quad j = 1, \dots, n$$

Want to have no solutions with $\mathbf{x}, \mathbf{y}, t$ real and $0 < t < 1$.

3. For checking extremity for values of t , we add equations

$$(y_j - \nu x_j) \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{x}, \mathbf{y}) - (x_j + \nu y_j) \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{x}, \mathbf{y}) = 0, \quad j = 1, \dots, n$$

Want to have no solutions with $\mathbf{x}, \mathbf{y}, \nu, t$ real and $0 < t < 1$.

ACSV for non-combinatorial case (Melczer-Salvy 2021)

Q. How to deal with non-combinatorial case?

Lemma (Melczer-Salvy 2021)

Let $D(\mathbf{z}) := \{\mathbf{w} \in \mathbb{C}^n \mid |w_i| < |z_i|, i = 1, \dots, n\}$ be the open polydisk. If $\mathbf{z} \in \mathcal{V}$ and $\mathcal{V} \cap D(\mathbf{z}) = \emptyset$, then $\mathbf{z} \in \partial\mathcal{D}$.

Q. How to deal with polydisk using polynomial equations?

A. Decompose polynomials into the real and imaginary part.

$$f(\mathbf{x} + i\mathbf{y}) = f^{(R)}(\mathbf{x}, \mathbf{y}) + if^{(I)}(\mathbf{x}, \mathbf{y})$$

For derivatives, applying Cauchy-Riemann equations,

$$\frac{\partial f}{\partial z_j}(\mathbf{x} + i\mathbf{y}) = \frac{1}{2} \cdot \frac{\partial}{\partial x_j} (f^{(R)}(\mathbf{x}, \mathbf{y}) + if^{(I)}(\mathbf{x}, \mathbf{y})) - \frac{i}{2} \cdot \frac{\partial}{\partial y_j} (f^{(R)}(\mathbf{x}, \mathbf{y}) + if^{(I)}(\mathbf{x}, \mathbf{y}))$$

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$$H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0$$

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$$H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0$$

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 \end{aligned} \right\} \quad (\star)$$

(\star) is a square polynomial system with $4n + 4$ variables $(\mathbf{a}, \mathbf{b}, \mathbf{x}, \mathbf{y}, \lambda_R, \lambda_I, \nu, t)$.

ACSV for combinatorial case

1. Determine the set \mathcal{S} of zeros (\mathbf{z}, λ, t) of the system $\left[H, z_1 \frac{\partial H}{\partial z_1} - \lambda, \dots, z_n \frac{\partial H}{\partial z_n} - \lambda, H(tz_1, \dots, tz_n) \right]$. If \mathcal{S} is not finite, then FAIL.
2. Construct the subset points $(\zeta, \lambda, t) \in \mathcal{S}$ which are candidates for minimal critical points.
 - \mathbf{z} is minimal if and only if the line segment $\{(t|z_1|, \dots, t|z_n|) \mid 0 < t < 1\}$ doesn't intersect \mathcal{V} .
3. Identify ζ among the elements of \mathcal{C} (critical points Abs on \mathcal{V}).
4. Return $\mathcal{U} := \{\mathbf{z} \in \mathbb{C}^n \mid |z_1| = |\zeta_1|, \dots, |z_n| = |\zeta_n| \text{ for some } (\mathbf{z}, \lambda) \in \mathcal{C}\}$

ACSV for non-combinatorial case

1. Determine the set \mathcal{S} of zeros $(\mathbf{a}, \mathbf{b}, \mathbf{x}, \mathbf{y}, \lambda_R, \lambda_I, \nu, t)$ of the system (★). If \mathcal{S} is not finite, then FAIL.
2. Construct the set of minimal critical points $\mathcal{U} := \{\mathbf{a} + i\mathbf{b} \mid (\mathbf{a}, \mathbf{b}, \mathbf{x}, \mathbf{y}, \lambda_R, \lambda_I, \nu, t) \in \mathcal{S}_{\mathbb{R}}, t \notin (0,1)\} \subset \mathcal{S}$
3. If $\mathcal{U} = \emptyset$ or $\lambda_R = \lambda_I = 0$ or the elements of \mathcal{U} do not all belong to the same torus, then FAIL.
4. Identify elements of \mathcal{U} from \mathcal{C} and return them.

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ACSVHomotopy.jl (Melczar-Lee-Smolčić 2022)

- Implemented using
HomotopyContinuation.jl
(Breiding-Timme 2018)
- Available at
github.com/ACSVMath/ACSVHomotopy
- Competitive to other ACSV software for combinatorial cases.
 - Solve the critical-point equations using the polyhedral homotopy
- The first software of ACSV for non-combinatorial cases.
 - Solve the decomposed critical-point equations (★) using the polyhedral homotopy
 - Provide faster heuristics including the monodromy method.

Implementation details

The polyhedral homotopy is the default for solving critical point equations.

- Returns reliable results via interval arithmetic certification.
- Effective for combinatorial case compared to other software based on symbolic algorithm.
- May be slow for non-combinatorial.
 - Faster heuristics used.

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 - Faster [heuristics](#) used.

Implementation details

Heuristics for non-combinatorial case.

1. Approximating critical points

$$\left. \begin{array}{l} H^{(R)}(\mathbf{a}, \mathbf{b}) = H^{(I)}(\mathbf{a}, \mathbf{b}) = 0 \\ a_j \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_R = 0 \quad j = 1, \dots, n \\ a_j \frac{\partial H^{(I)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(I)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_I = 0 \quad j = 1, \dots, n \\ H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0 \\ x_j^2 + y_j^2 - t(a_j^2 + b_j^2) = 0 \quad j = 1, \dots, n \\ (y_j - \nu x_j) \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{x}, \mathbf{y}) - (x_j + \nu y_j) \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{x}, \mathbf{y}) = 0 \quad j = 1, \dots, n \end{array} \right\} \quad (\star)$$

Implementation details

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 \end{aligned} \right\} \quad (A)$$

$$\left. \begin{aligned}
 &H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0 \\
 &x_j^2 + y_j^2 - t(a_j^2 + b_j^2) = 0 \quad j = 1, \dots, n \\
 &(y_j - \nu x_j) \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{x}, \mathbf{y}) - (x_j + \nu y_j) \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{x}, \mathbf{y}) = 0 \quad j = 1, \dots, n
 \end{aligned} \right\} \quad (B)$$

1. Approximating critical points

- Solve the subsystem (A) to get an approximation of (\mathbf{a}, \mathbf{b}) .
- Using the approximations, solve the subsystem (B) .

Implementation details

Heuristics for non-combinatorial case.

$$\begin{array}{l}
 \left. \begin{array}{l}
 H^{(R)}(\mathbf{a}, \mathbf{b}) = H^{(I)}(\mathbf{a}, \mathbf{b}) = 0 \\
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 \end{array} \right\} \begin{array}{l} j = 1, \dots, n \\ j = 1, \dots, n \end{array} \quad (A)
 \end{array}$$

$$\left. \begin{array}{l}
 H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0 \\
 x_j^2 + y_j^2 - t(a_j^2 + b_j^2) = 0 \\
 (y_j - \nu x_j) \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{x}, \mathbf{y}) - (x_j + \nu y_j) \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{x}, \mathbf{y}) = 0
 \end{array} \right\} \begin{array}{l} j = 1, \dots, n \\ j = 1, \dots, n \end{array} \quad (B)$$

1. Approximating critical points

- Solve the subsystem (A) to get an approximation of (\mathbf{a}, \mathbf{b}) .
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Implementation details

Heuristics for non-combinatorial case.

$$\begin{array}{lcl}
 H^{(R)}(\mathbf{a}, \mathbf{b}) = H^{(I)}(\mathbf{a}, \mathbf{b}) = 0 & & \\
 a_j \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_R = 0 & j = 1, \dots, n & \\
 a_j \frac{\partial H^{(I)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(I)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_I = 0 & j = 1, \dots, n & \\
 \hline
 H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0 & & \\
 x_j^2 + y_j^2 - t(a_j^2 + b_j^2) = 0 & j = 1, \dots, n & \\
 (y_j - \nu x_j) \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{x}, \mathbf{y}) - (x_j + \nu y_j) \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{x}, \mathbf{y}) = 0 & j = 1, \dots, n &
 \end{array}
 \left. \begin{array}{l} (A) \\ (B) \end{array} \right\}$$

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- Using the approximations, solve the subsystem (B).

Implementation details

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 &a_j \frac{\partial H^{(I)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(I)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_I = 0 \quad j = 1, \dots, n
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 \end{aligned} \right\} \quad (B)$$

2. Monodromy

- Solve the subsystem (A) to get an approximation of (\mathbf{a}, \mathbf{b}) .
- Solve the subsystem (B) using monodromy with $(\mathbf{x}, \mathbf{y}, t) = (\mathbf{a}, \mathbf{b}, 1)$.
(ν can be found from the Jacobian)
- Caveat : the subsystem (B) may have several irreducible components. (Fail to find all critical points)

Implementation details

Heuristics for non-combinatorial case.

$$\left. \begin{aligned}
 &H^{(R)}(\mathbf{a}, \mathbf{b}) = H^{(I)}(\mathbf{a}, \mathbf{b}) = 0 \\
 &a_j \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_R = 0 \quad j = 1, \dots, n \\
 &a_j \frac{\partial H^{(I)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(I)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_I = 0 \quad j = 1, \dots, n
 \end{aligned} \right\} \quad (A)$$

$$\left. \begin{aligned}
 &H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0 \\
 &x_j^2 + y_j^2 - t(a_j^2 + b_j^2) = 0 \quad j = 1, \dots, n \\
 &(y_j - \nu x_j) \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{x}, \mathbf{y}) - (x_j + \nu y_j) \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{x}, \mathbf{y}) = 0 \quad j = 1, \dots, n
 \end{aligned} \right\} \quad (B)$$

2. Monodromy

- Solve the subsystem (A) to get an approximation of (\mathbf{a}, \mathbf{b}) .
- Solve the subsystem (B) using monodromy with $(\mathbf{x}, \mathbf{y}, t) = (\mathbf{a}, \mathbf{b}, 1)$.
(ν can be found from the Jacobian)
- Caveat : the subsystem (B) may have several irreducible components. (Fail to find all critical points)

Implementation details

Heuristics for non-combinatorial case.

$$\left. \begin{aligned}
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 &a_j \frac{\partial H^{(I)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(I)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_I = 0 \quad j = 1, \dots, n
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Experiments : Combinatorial examples

Examples Elapsed time (s)	square-root	Apéry $\zeta(2)$	Apéry $\zeta(3)$	Random	3D Walk
ACSVHomotopy.jl	0.01	0.025	0.7	0.9	0.08
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Polyhedral homotopy	29.5	670	INC	236	INC
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Monodromy	14.9	8.5	31.9	3.8	583.1

INC indicates the code did not complete after running for an hour.

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Future directions

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 &a_j \frac{\partial H^{(I)}}{\partial x_j}(\mathbf{a}, \mathbf{b}) + b_j \frac{\partial H^{(I)}}{\partial y_j}(\mathbf{a}, \mathbf{b}) - \lambda_I = 0 \quad j = 1, \dots, n \\
 &H^{(R)}(\mathbf{x}, \mathbf{y}) = H^{(I)}(\mathbf{x}, \mathbf{y}) = 0 \\
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 &(y_j - \nu x_j) \frac{\partial H^{(R)}}{\partial x_j}(\mathbf{x}, \mathbf{y}) - (x_j + \nu y_j) \frac{\partial H^{(R)}}{\partial y_j}(\mathbf{x}, \mathbf{y}) = 0 \quad j = 1, \dots, n
 \end{aligned} \right\} (\star)$$

- Geometric understanding of (\star)
 - What is degree for generic H ?
- Numerical techniques for (\star)
 - How to improve the performance of monodromy?
 - Solving equation-by-equation (i.e. regeneration)
- How to verify the completeness?

Thank you for your attention

**The paper is available at
(<https://arxiv.org/pdf/2208.04490.pdf>)**