# **Certifying Roots** of Polynomial Systems on Macaulay 2

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# Certifying (regular) Solutions

Given a compact region  $I \subset \mathbb{C}^n$  (or  $\mathbb{R}^n$ ), apply an algorithm to certify

- (1) the existence
- (2) the uniqueness

of a root of a system in *I*.

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of a root of a system in *I*.

#### Previous Implementations

alphaCertified: Hauenstein and Sottile (2012)

implement  $\alpha$ -Theory

#### NumericalCertification.m2

Available at https://github.com/klee669/M2

#### Software Requirement

Macaulay2 version 1.14

#### **Functionality**

- M2 Internal certification package
- $\alpha$ -Theory / Interval arithmetic implementation
- Easier interface

# Two Paradigms

#### Krawczyk method

combines interval arithmetic and Newton's method

Interval arithmetic

• For any arithmetic operator  $\odot$ ,  $[a,b]\odot[c,d]=\{x\odot y\mid x\in [a,b],y\in [c,d]\}$ 

#### α-Theory

certify an approximation converges to a solution quadratically

Quadratic convergence

• For  $N_F(x) := x - F'(x)^{-1}F(x)$ (Newton operator),

$$||N_F^k(x) - x^*|| \le \left(\frac{1}{2}\right)^{2^k - 1} ||x - x^*||$$

# Two Paradigms - Krawczyk method

F: a square differentiable system on  $U \subset \mathbb{C}^n$ 

I: an interval to certify

 $\Box F(I) := \{F(x) \mid x \in I\}$ : an interval extension of F over an interval I

y: a point in I

Y: an invertible matrix

Define the Krawczyk operator

$$K_{V}(I) = y - YF(y) + (Id - Y \square F'(I))(I - y)$$

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$$K_{y}(I) = y - YF(y) + (Id - Y \square F'(I))(I - y)$$

**Theorem** (Krawczyk 1969). The following holds:

- (1) If  $x \in I$  is a root of F, then  $x \in K_{V}(I)$
- (2) If  $K_{V}(I) \subset I$ , then there is a root of F in I (existence)
- (3) If I has a root and  $\sqrt{2}||Id Y \square F'(I)|| < 1$ , then there is a root of F in I and it is unique where  $||\cdot||$  is the maximum operator norm (uniqueness)

### Two Paradigms - a-Theory

Let  $x = (x_1, \dots, x_n)$  be a point in  $\mathbb{C}^n$  and  $N_F(x) = x - F'(x)^{-1}F(x)$ .

$$\alpha(F, x) := \beta(F, x)\gamma(F, x)$$

$$\beta(F, x) := \|x - N_F(x)\| = \|F'(x)^{-1}F(x)\|$$

$$\gamma(F, x) := \sup_{k \ge 2} \left\| \frac{F'(x)^{-1}F^{(k)}(x)}{k!} \right\|^{\frac{1}{k-1}}$$

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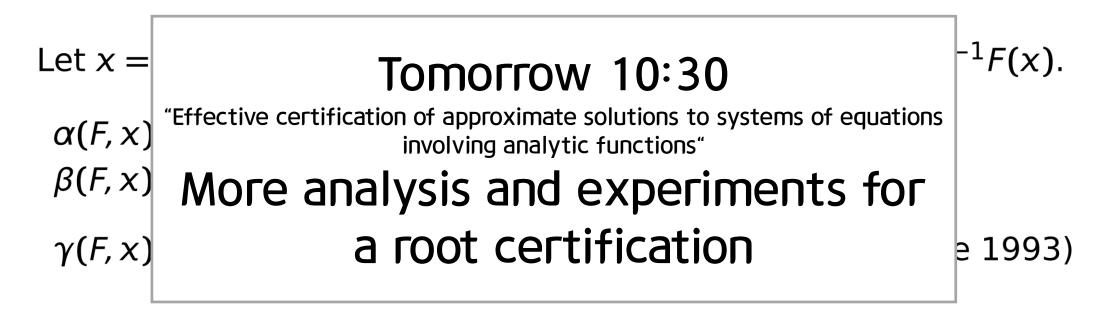
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If  $\alpha(F, x) < \frac{13 - 3\sqrt{17}}{4}$ , then x converges quadratically to  $x^*$ . Also,  $||x - x^*|| \le 2\beta(F, x)$ .

# Two Paradigms - \alpha-Theory



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```
i1 : needsPackage "NumericalCertification";
i2 : R = RR[x1,x2,y1,y2];
```

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i1 : needsPackage "NumericalCertification";
i2 : R = RR[x1,x2,y1,y2];
i3 : f = polySystem {3*y1 + 2*y2 -1, 3*x1 + 2*x2 -3.5, x1^2 + y1^2 -1, x2^2 + y2^2 -1};
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i4 : p1 = point{{.95, .32, -.30, .95}};
```

#### Demonstration - $\alpha$ -Theory

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i1 : needsPackage "NumericalCertification";
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i4 : p1 = point{{.95, .32, -.30, .95}};
i5 : computeConstants(f,p1)
o5 = o5 = (.00621269, .0000277104, 224.2)
o5 : Sequence
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i6 : certifySolution(f,p1)
o6 = true
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i4 : p1 = point\{\{.95, .32, -.30, .95\}\};
i5 : computeConstants(f,p1)
05 = 05 = (.00621269, .0000277104, 224.2)
o5 : Sequence
i6 : certifySolution(f,p1)
06 = true
i7 : p2 = point\{\{.9, .3, -.3, 1\}\}; -- poorly approximated solution
```

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i6 : certifySolution(f,p1)
06 = true
i7 : p2 = point\{\{.9, .3, -.3, 1\}\}; -- poorly approximated solution
i8 : certifySolution(f,p2) -- not an approximate solution
08 = false
```

```
i9 : p1 = point{{.95,.32,-.30,.95}};
i10 : p3 = point{{.65,.77,.76,-.64}}; -- two approximate solutions
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```
i9 : p1 = point{{.95,.32,-.30,.95}};
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o11 = true
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i9 : p1 = point{{.95,.32,-.30,.95}};
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i11 : certifyDistinctSoln(f,p1,p3)
o11 = true

i12 : p1 = point{{.954379+ii*.001043 , .318431, -.298633, .947949}};
-- a complex approximate root close to an actual root
```

#### Demonstration - $\alpha$ -Theory

```
i9 : p1 = point{{.95,.32,-.30,.95}};
i10 : p3 = point{{.65,.77,.76,-.64}}; -- two approximate solutions

i11 : certifyDistinctSoln(f,p1,p3)
o11 = true

i12 : p1 = point{{.954379+ii*.001043 , .318431, -.298633, .947949}};
-- a complex approximate root close to an actual root

i13 : certifyRealSoln(f,p1)
o13 = true
```

```
i2 : R = RR[x1,x2,y1,y2];
i3 : f = polySystem \{3*y1 + 2*y2 - 1, 3*x1 + 2*x2 - 3.5, x1^2 + y1^2 - 1, x2^2 + y2^2 - 1\};
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i2 : R = RR[x1,x2,y1,y2];
i3 : f = polySystem \{3*y1 + 2*y2 - 1, 3*x1 + 2*x2 - 3.5, x1^2 + y1^2 - 1, x2^2 + y2^2 - 1\};
i4 : (I1, I2, I3, I4) = (interval(.94, .96), interval(.31, .33),
                          interval(-.31,-.29), interval(.94,.96));
i5 : o = intervalOptionList apply({x1 => I1, x2 => I2, y1 => I3, y2 => I4},
                                   i -> intervalOption i);
i6 : krawczykOper(f,o)
-- warning: experimental computation over inexact field begun
            results not reliable (one warning given per session)
06 = \{\{[.954149, .954609]\}, \{[.318086, .318777]\}, \{[-.298824, -.298442]\},
      {[.947663, .948236]}}
o6 : IntervalMatrix
```

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o6 : IntervalMatrix
i7 : krawczykMethod(f,o)
given interval contains a unique solution
o7 = true
```

```
i2 : R = QQ[x1,x2,y1,y2]; -- computation over Q
```

```
i2 : R = QQ[x1,x2,y1,y2]; -- computation over Q i3 : f = polySystem {3*y1 + 2*y2 -1, 3*x1 + 2*x2 -7/2, x1^2 + y1^2 -1, x2^2 + y2^2 -1}; i4 : p1 = point{{95/100, 32/100, -30/100, 95/100}}; -- exact input
```

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i2 : R = QQ[x1,x2,y1,y2];
i3 : f = polySystem \{3*y1 + 2*y2 - 1, 3*x1 + 2*x2 - 7/2, x1^2 + y1^2 - 1, x2^2 + y2^2 - 1\};
i4 : (I1, I2, I3, I4) = (interval(94/100,96/100), interval(31/100,33/100),
                       interval(-31/100,-29/100), interval(94/100,96/100));
i5 : o = intervalOptionList apply({x1 => I1, x2 => I2, y1 => I3, y2 => I4},
                                i -> intervalOption i);
i6 : krawczykOper(f,o)
       381087 381271 254087 254639 895127 893983
06 = \{\{[-----, -----]\}, \{[-----, -----]\}, \{[------, ------]\},
       399400 399400 798800 798800
                                              2995500
                                                        2995500
       1892483 1893627
     {[-----]}}
       1997000 1997000
```

o7 = true

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i7 : krawczykMethod(f,o)
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i2 : FF = QQ[i]/ideal(i^2+1) -- Gaussian rational (extension of Q with imaginary numbers) o2 = FF o2 : QuotientRing
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o2 : QuotientRing

i3 : R = FF[x1,x2,y1,y2];
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i5 : p1 = point{{95/100, 32/100, -30/100, 95/100}};

i6 : certifySolution(f,p1)
Warning: invertibility check for Jacobian is skipped for Gaussian rational inputs
o6 = true
```

# Thanks for your attention!