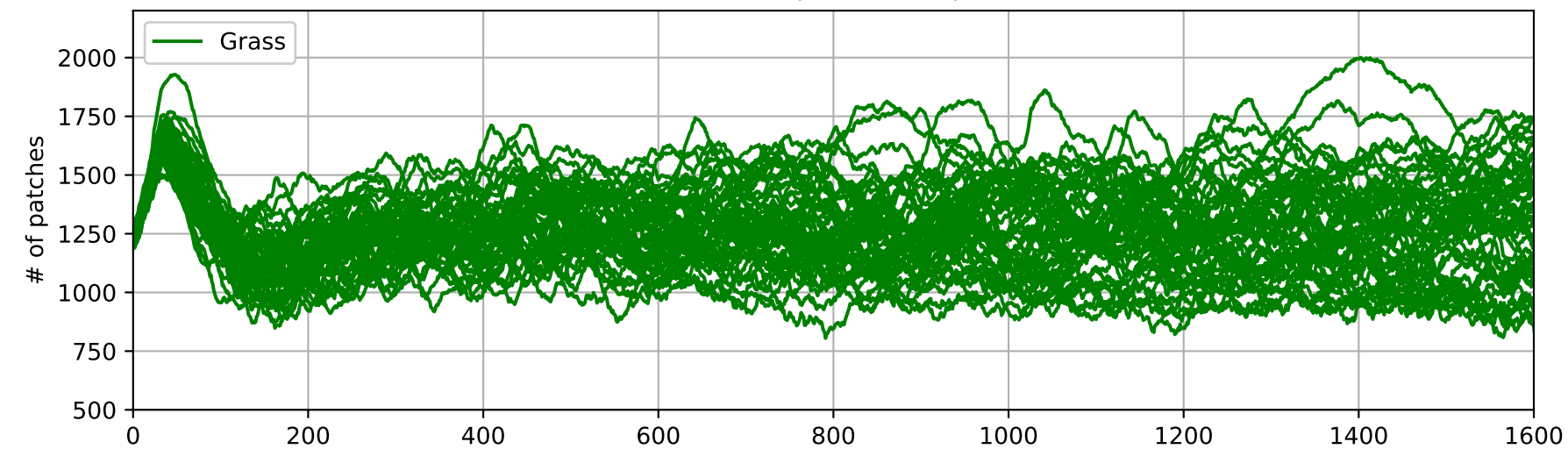
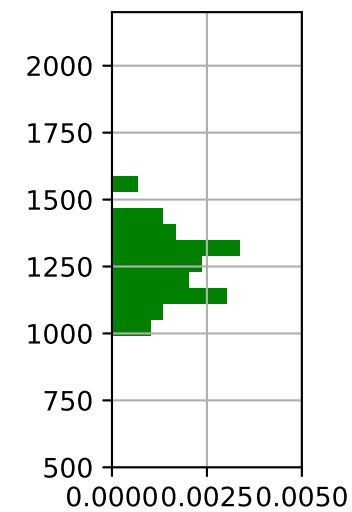


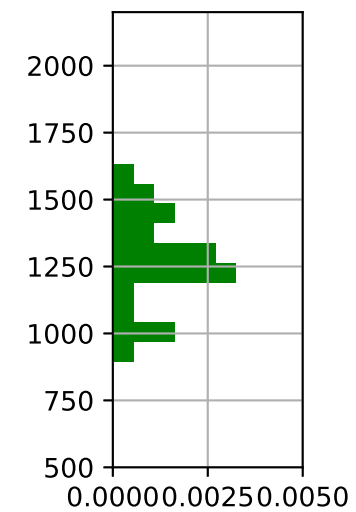
Grass (Scenario 0)



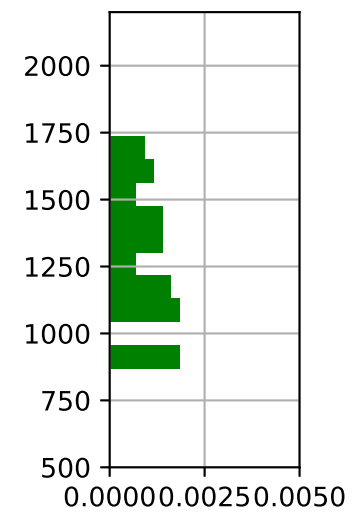
t = 600



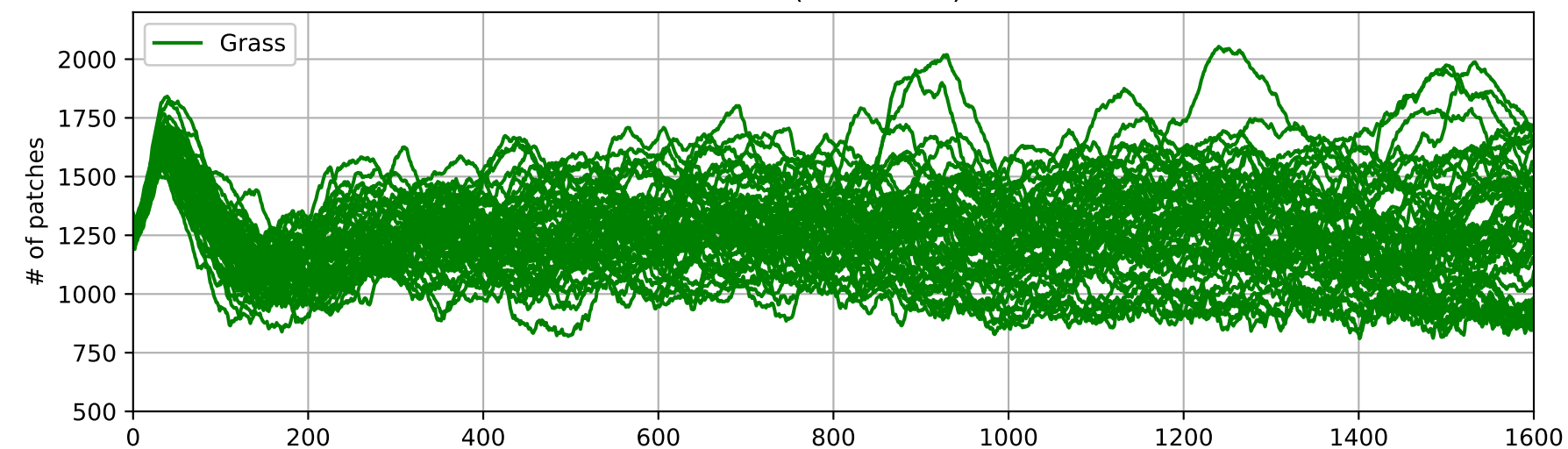
t = 1100



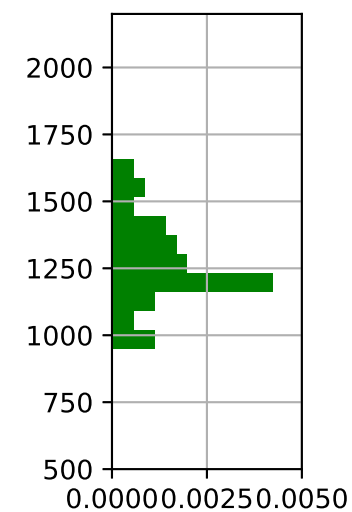
t = 1600



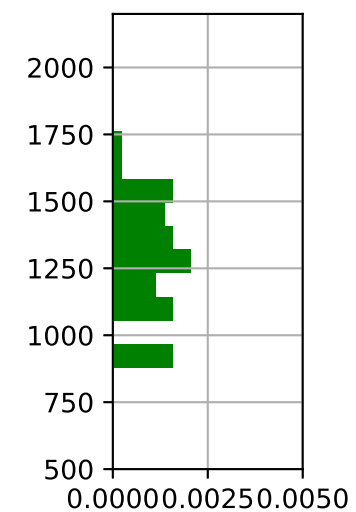
Grass (Scenario 5)



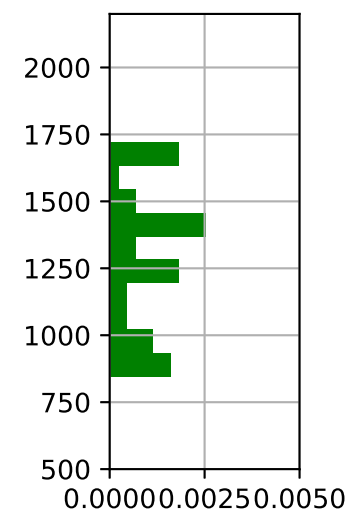
t = 600



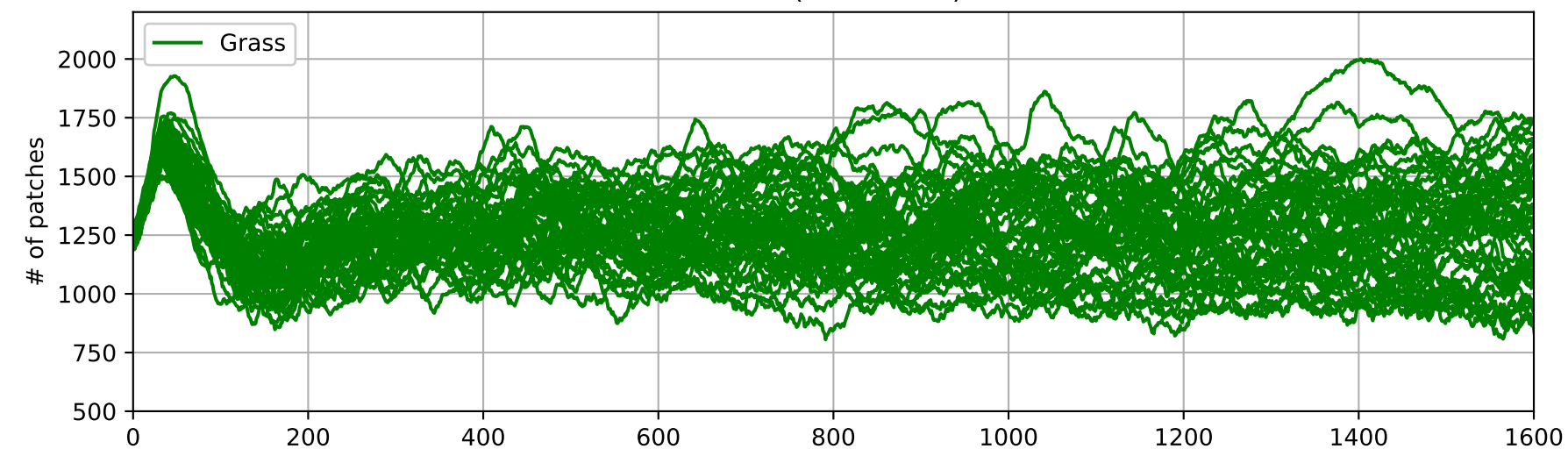
t = 1100



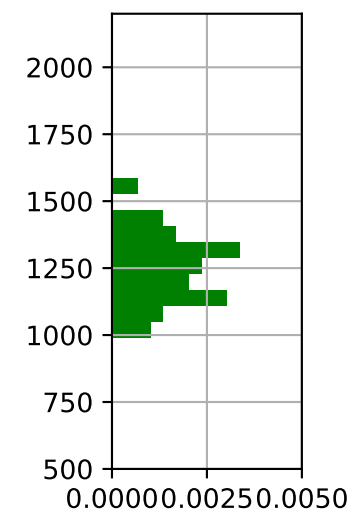
t = 1600



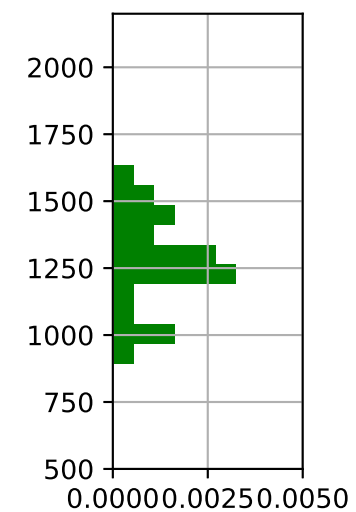
Grass (Scenario 6)



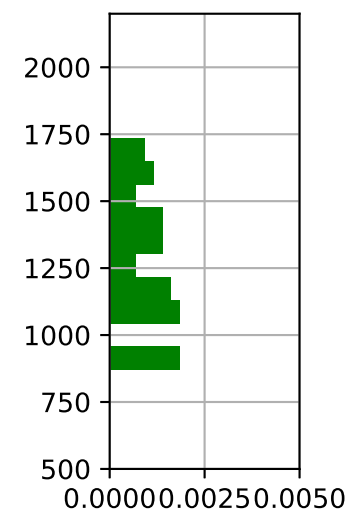
t = 600



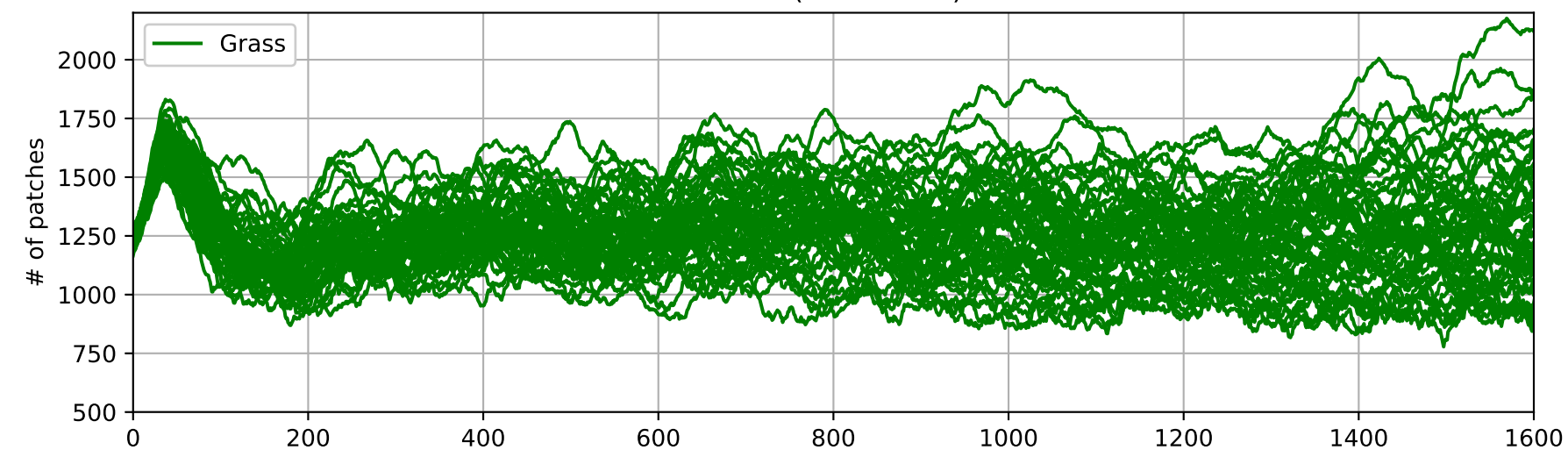
t = 1100



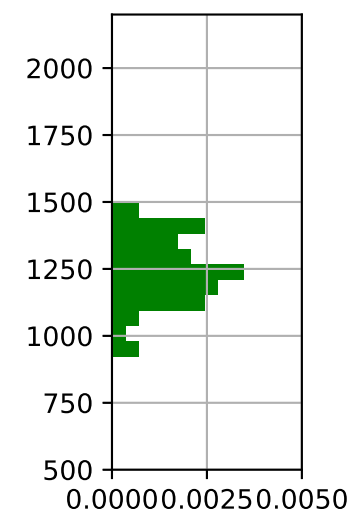
t = 1600



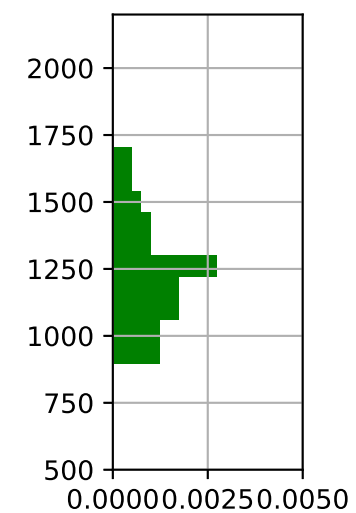
Grass (Scenario 7)



t = 600



t = 1100



t = 1600

