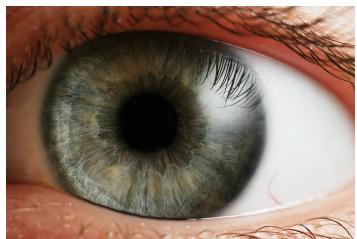


Bayesian modeling in cognitive science

Dave Kleinschmidt
University of Rochester

$6\text{cm} \pm 2\text{cm}$



size?



$4\text{cm} \pm 1\text{cm}$



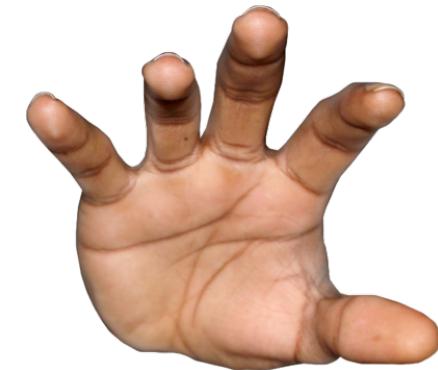
$6\text{cm} \pm 0.5\text{cm}$

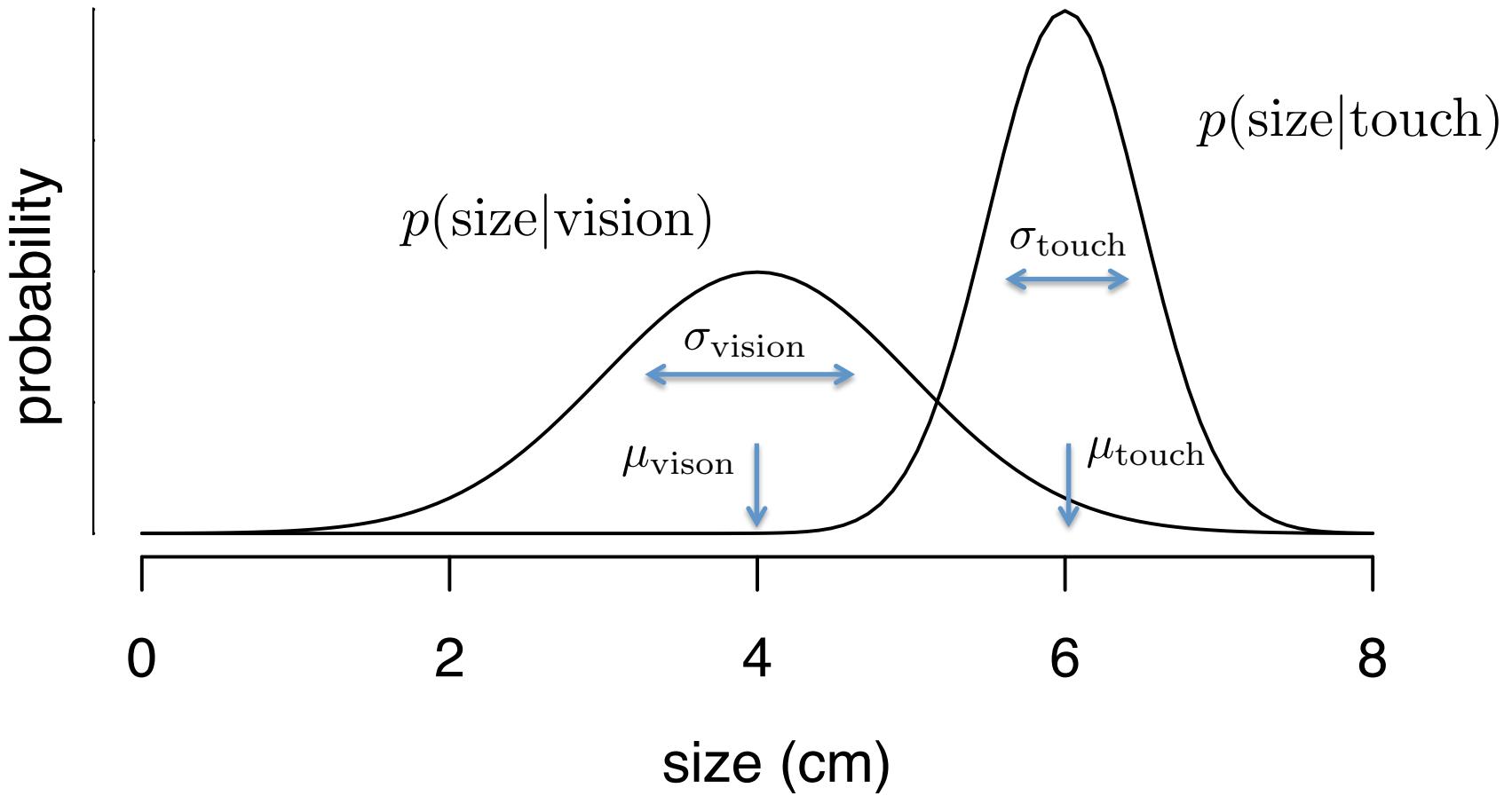


size?



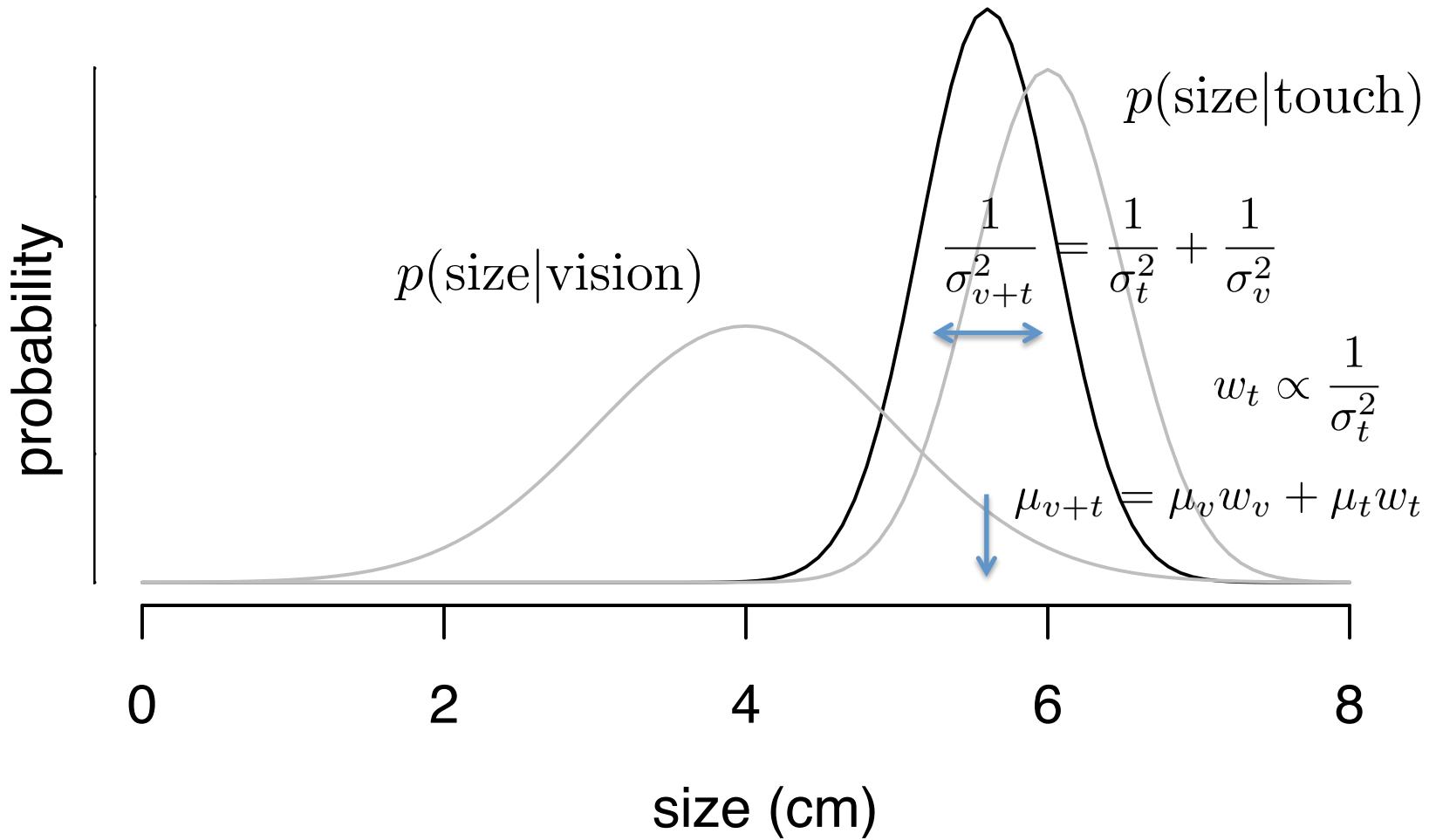
$4\text{cm} \pm 1\text{cm}$





$$p(\text{size}|\text{touch}, \text{vision})$$

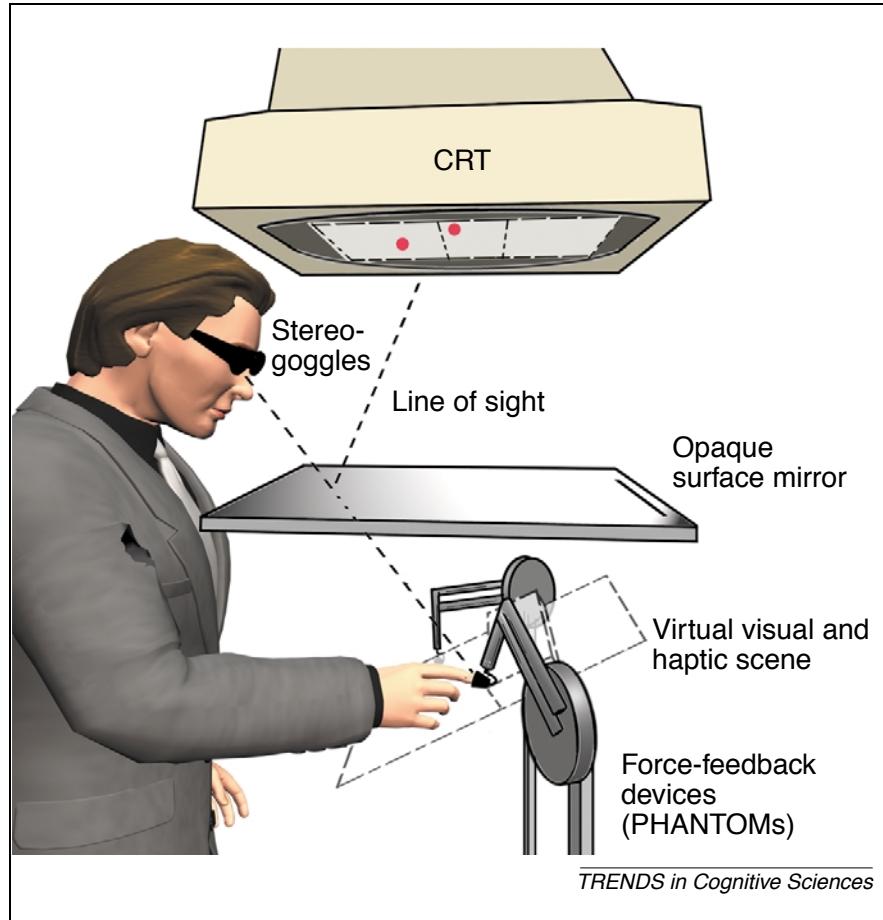
$$= p(\text{size}|\text{touch})p(\text{size}|\text{touch})$$



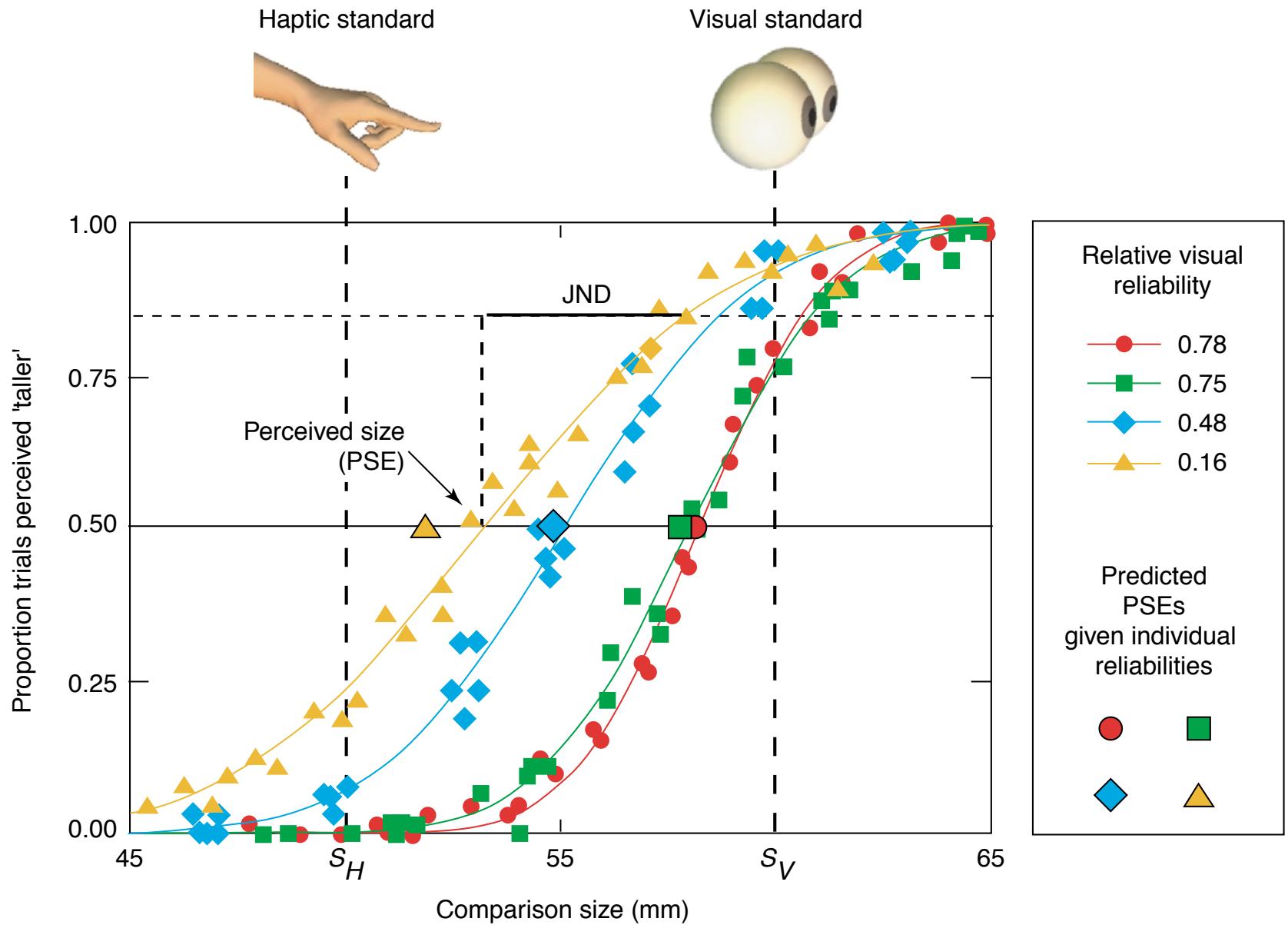
Does the brain really do this?

- Important to make **predictions** about behavior based on model.
- **Qualitative** predictions: “when I increase x , y should also increase”
- **Quantitative** predictions: “if I measure this thing, it will have value x ”

An experiment!



- Decide which of two objects are bigger.
- One object has a **cue conflict**: felt and seen size are mismatched.
- Cue combination predicts:
 - More reliable cue is weighted more
 - Weights are directly proportional to reliability
 - Reliability of two cues sums.



Bayesian modeling

- Represent uncertain information
- Everything is a probability distribution
- Usually describe **optimal** performance for a task, given certain information and assumptions about task structure.
- Not always directly related to actual cognitive processing or neural activity.

Bayesian modeling: levels of analysis

- David Marr (1982), *Vision*
- **Computational:** what is the problem that the system solves?
- **Algorithmic:** what are the **representations** and **processes** used to carry out the computations?
- **Implementation:** what is the hardware?

Bayesian modeling

- Generally at the **computational level**:
 - What is the **task** to be performed?
 - What is the **information** available to do it?
 - What is the **model** (relationship) of information and task?
- Predicts **best possible performance**.

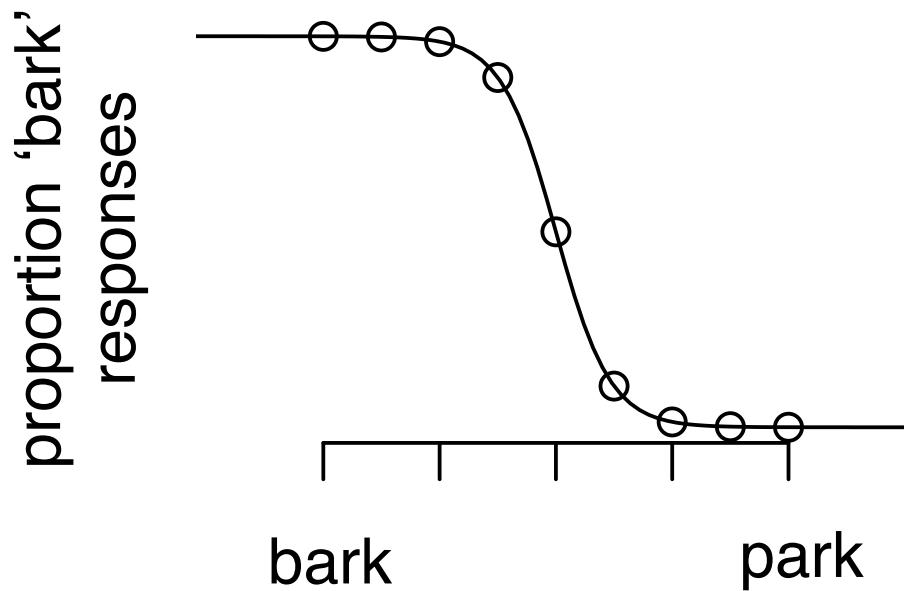
Bayesian modeling: Cue combination

- **task:** figure out how big a thing is
- **information:** multiple noisy/uncertain estimates
- **model:** all estimates generated by same actual size in the world

How to make a model

- Start with a theory
 - “People combine information about size from different senses by weighting each sense according to its reliability”
- Express the theory quantitatively
 - Information is a probability distribution
 - Reliability is the inverse variance of that distribution.

Categorical speech perception



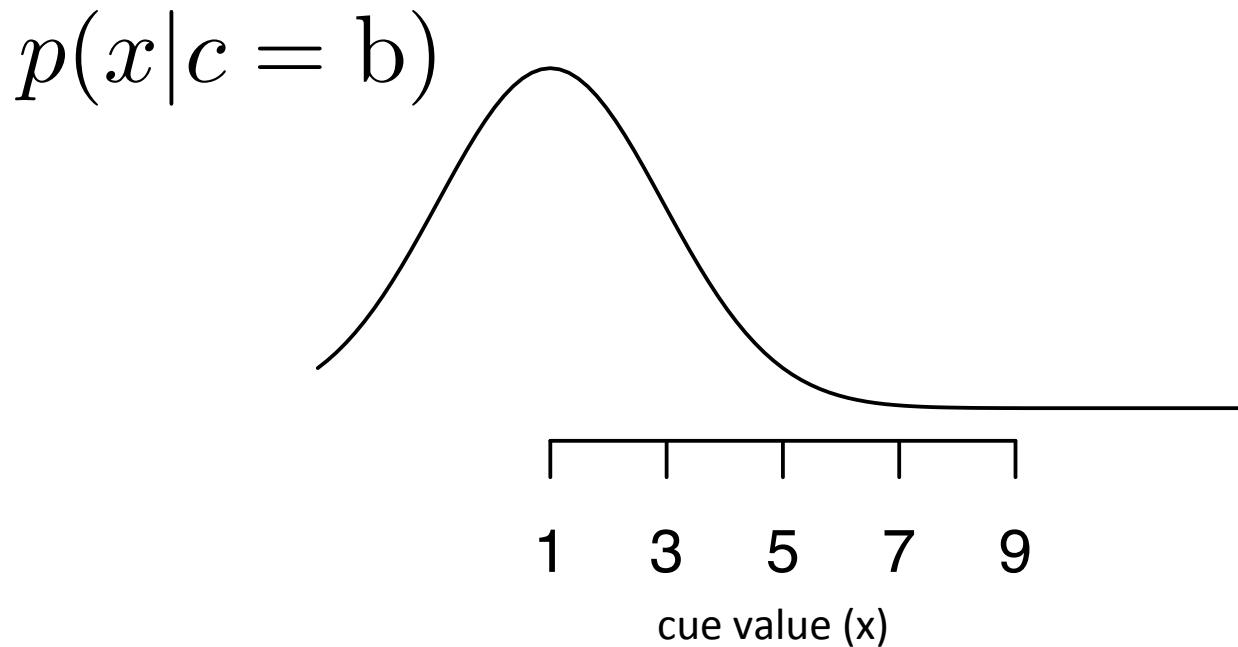
Categorical speech perception

- Bayesian model: combination of
 - The task (infer word/phonetic category)
 - Information available (distributions of sounds)

$$p(\text{cue value} | \text{category}) = p(x|c)$$

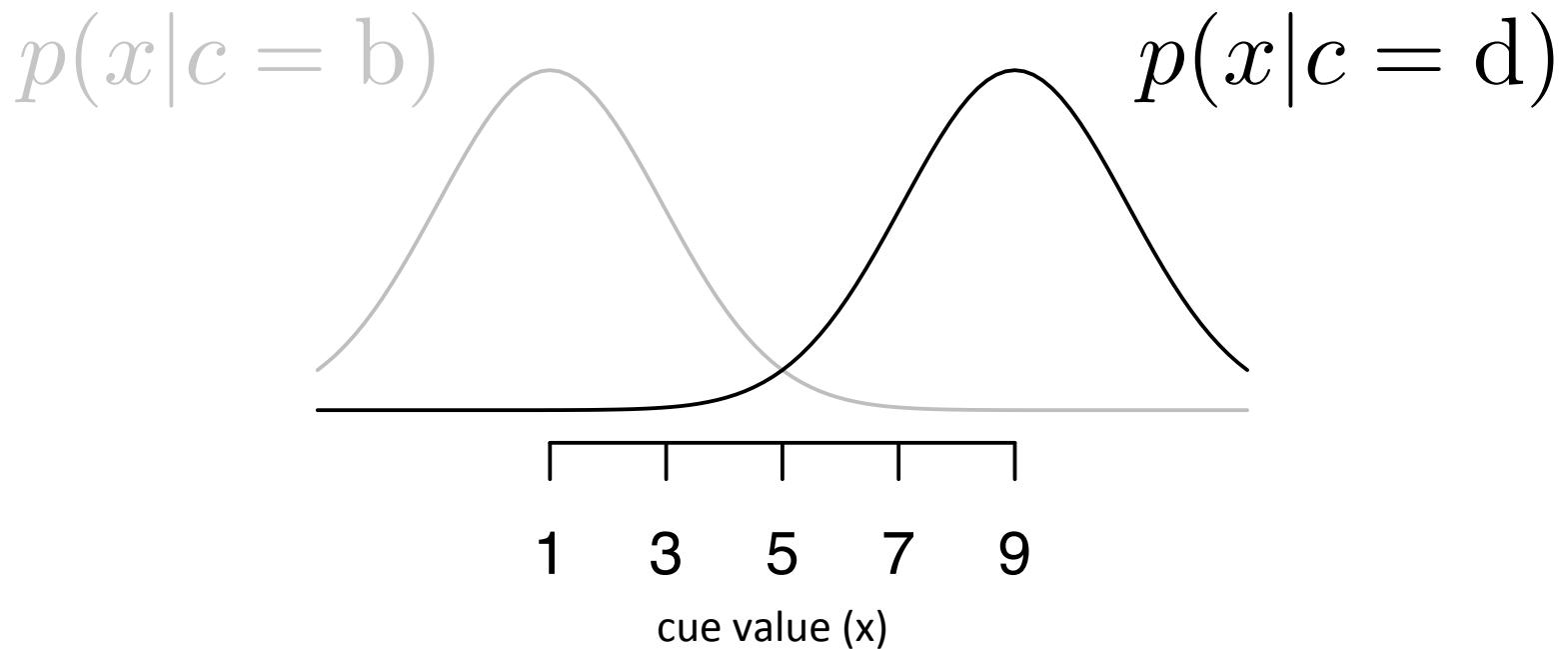
Categorical speech perception

$$p(\text{cue value} | \text{category}) = p(x|c)$$



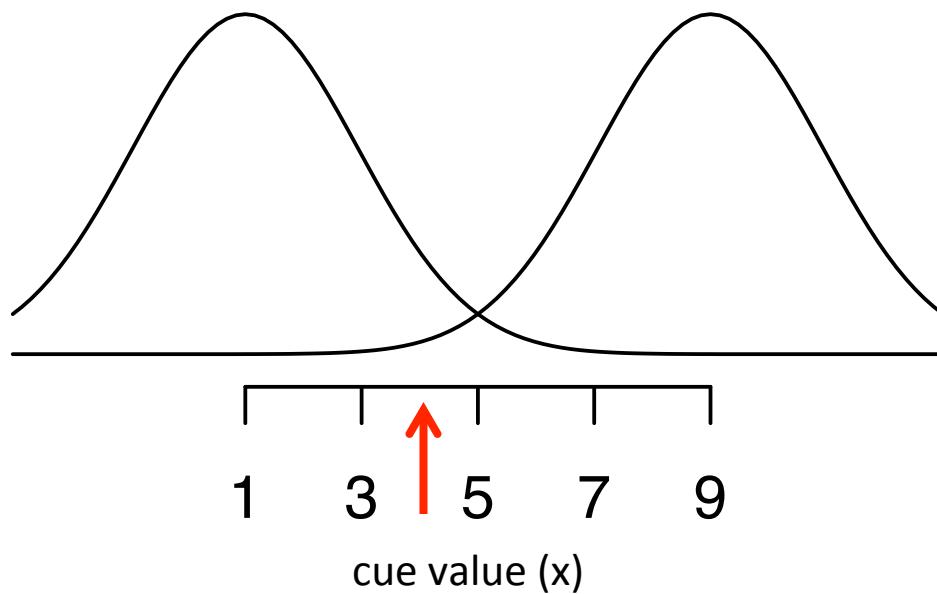
Categorical speech perception

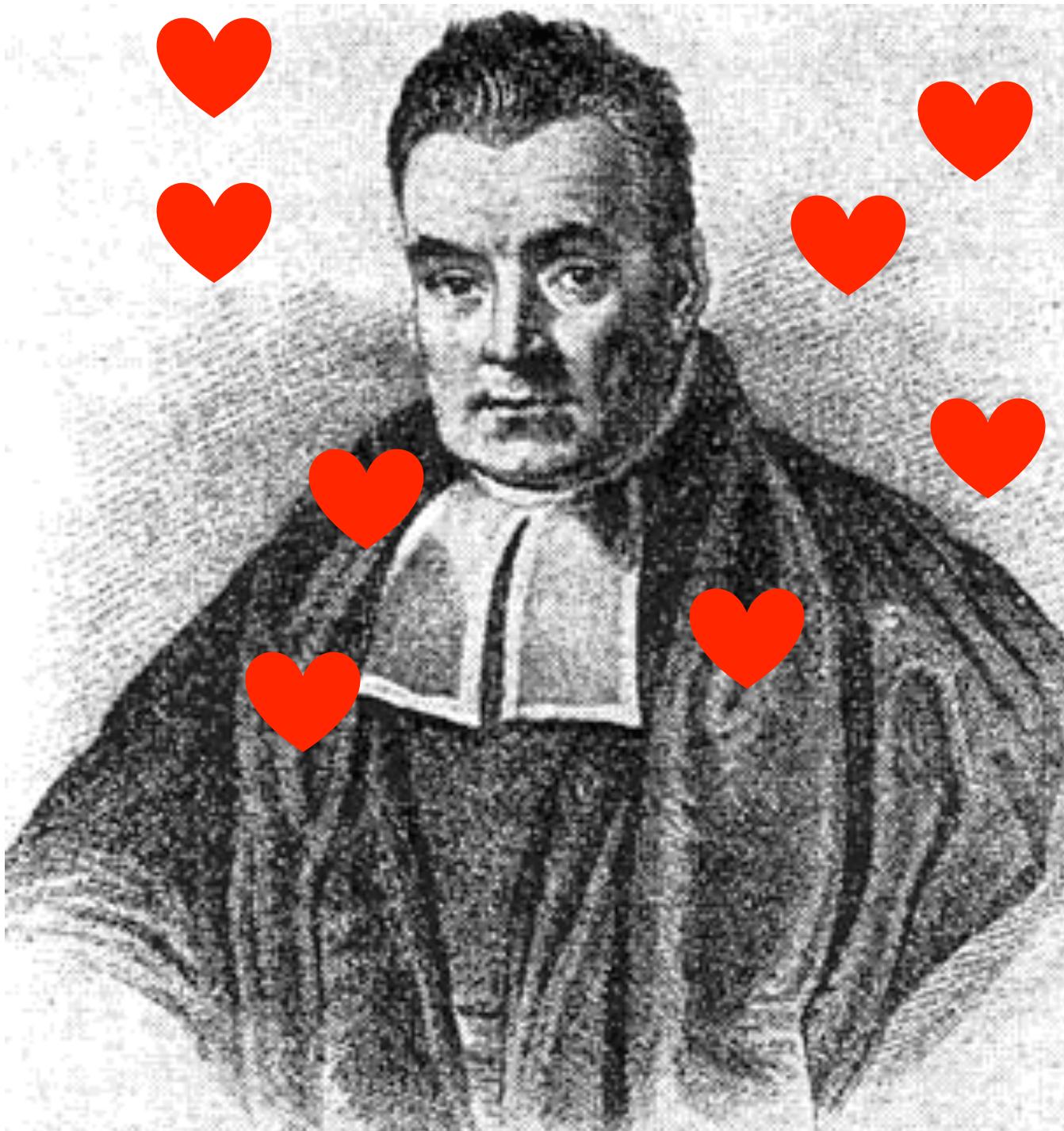
$$p(\text{cue value} | \text{category}) = p(x|c)$$



Categorical speech perception

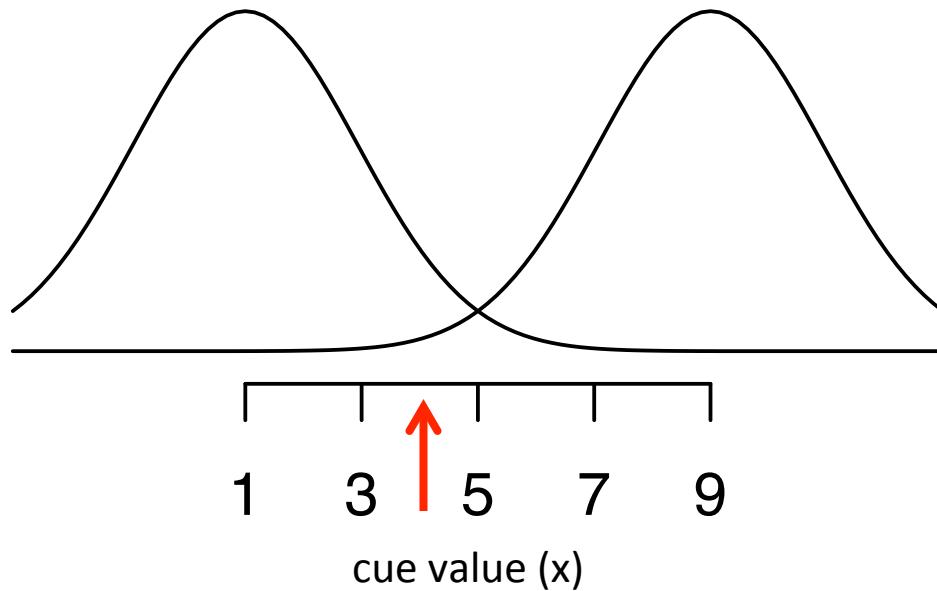
$$p(c = b|x = 4) = ?$$





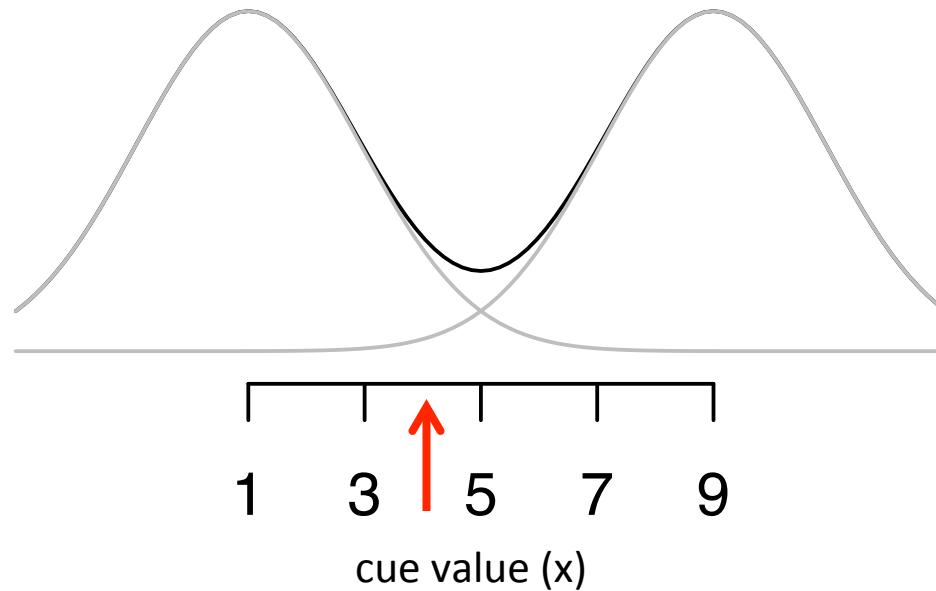
Categorical speech perception

$$p(c = b|x = 4) = \frac{p(x = 4|c = b)p(c = b)}{p(x = 4)}$$



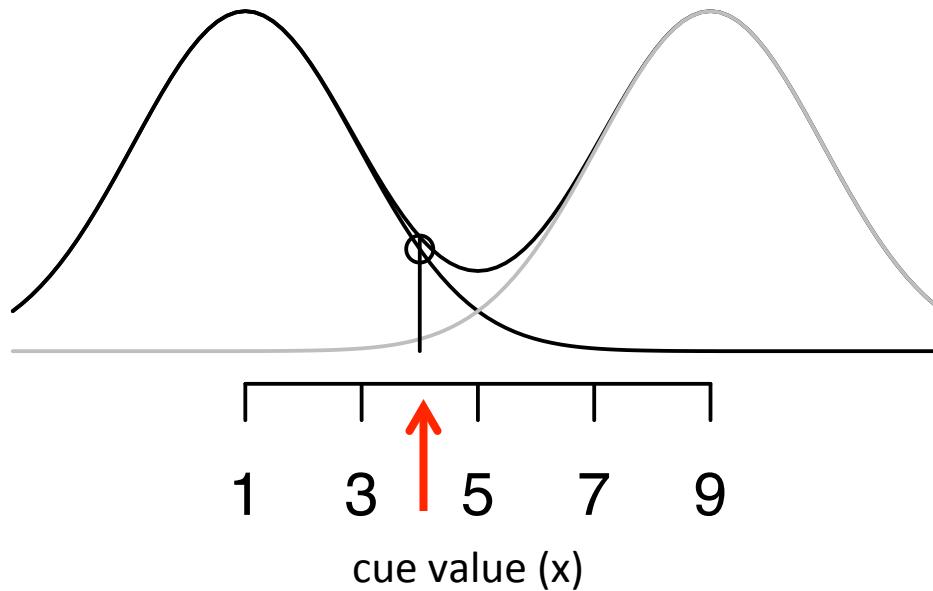
Categorical speech perception

$$p(c = b|x = 4) = \frac{p(x = 4|c = b)p(c = b)}{p(x = 4)}$$



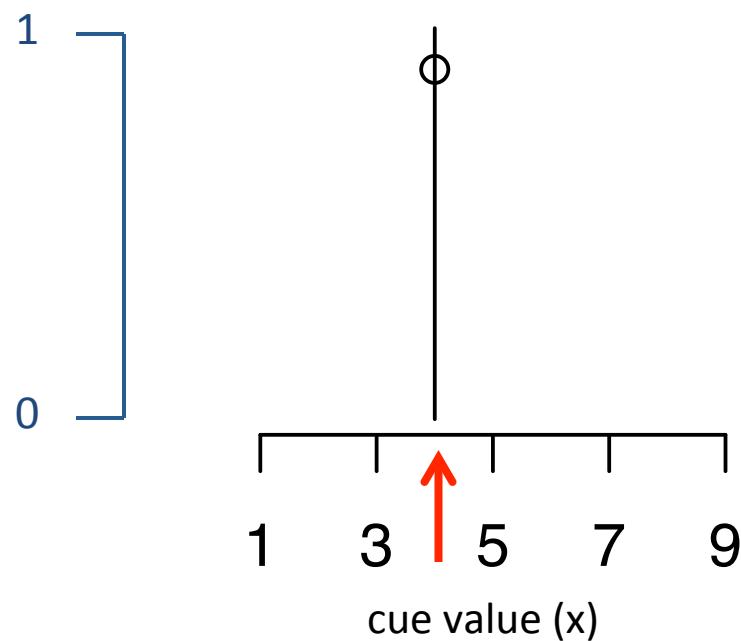
Categorical speech perception

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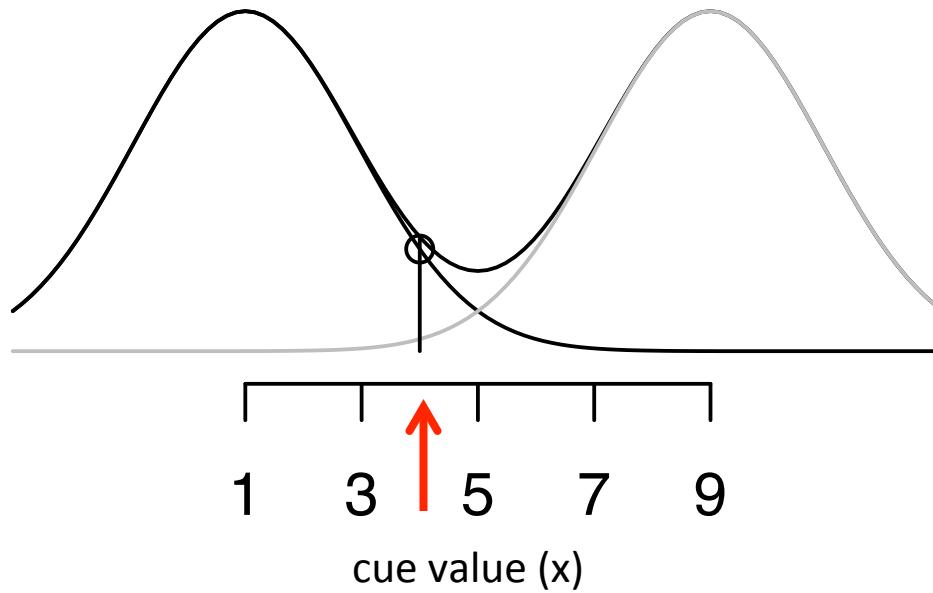
Categorical speech perception

$$p(c = b|x = 4) = \frac{p(x = 4|c = b)p(c = b)}{p(x = 4)}$$



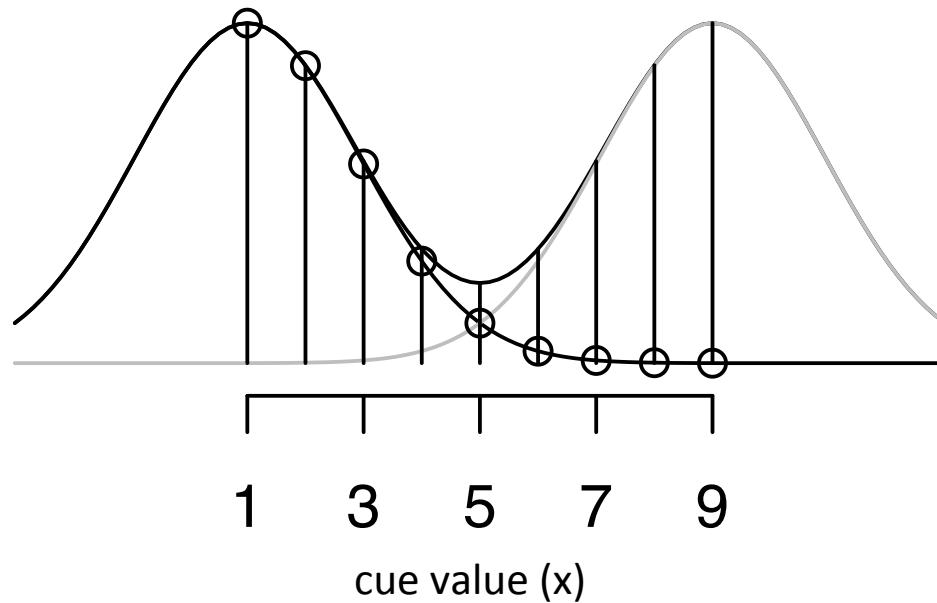
Categorical speech perception

$$p(c = b|x = 4) = \frac{p(x = 4|c = b)p(c = b)}{p(x = 4)}$$



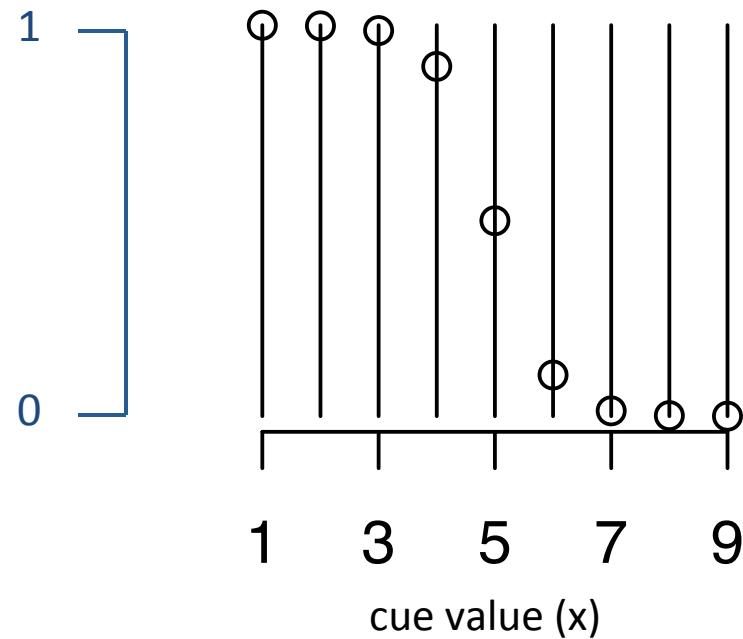
Categorical speech perception

$$p(c = b|x) = \frac{p(x|c = b)p(c = b)}{p(x)}$$



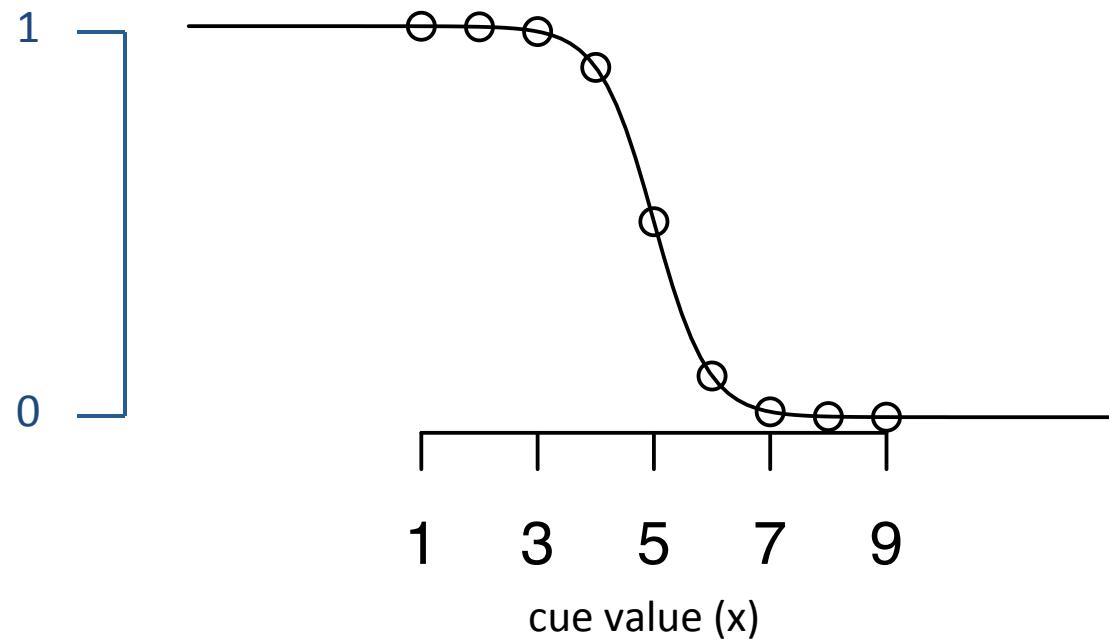
Categorical speech perception

$$p(c = b|x) = \frac{p(x|c = b)p(c = b)}{p(x)}$$



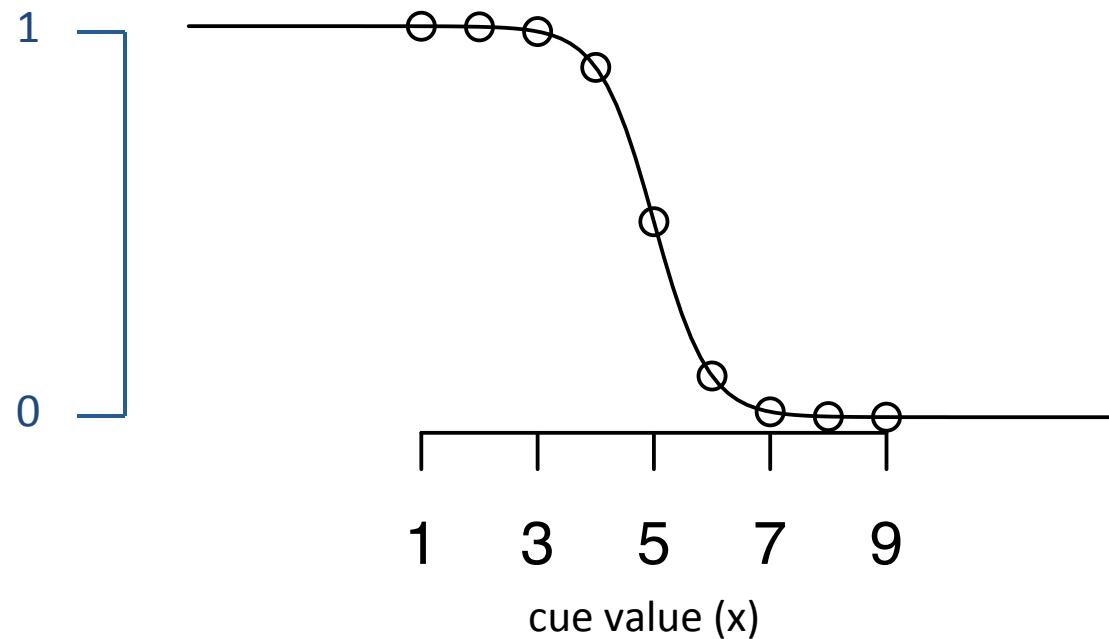
Categorical speech perception

$$p(c = b|x) = \frac{p(x|c = b)p(c = b)}{p(x)}$$



Categorical speech perception

$$p(c = b|x) = \frac{p(x|c = b)p(c = b)}{p(x)}$$



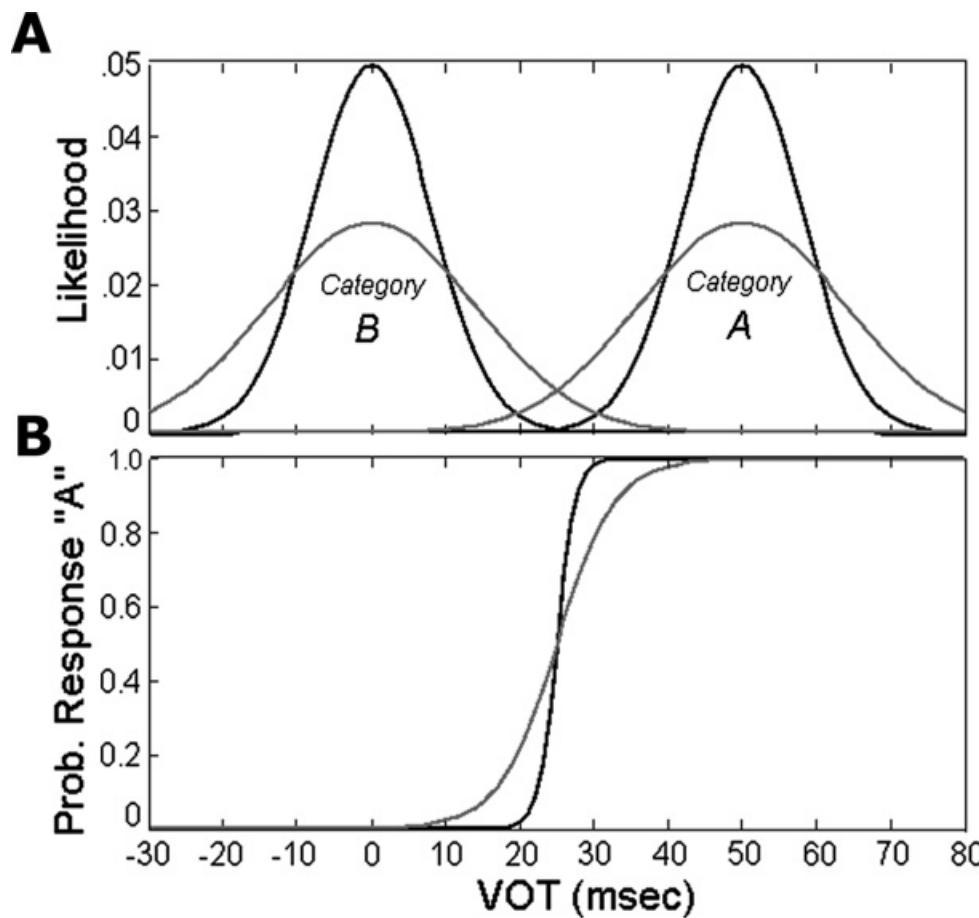
PREDICTIONS

- If people are behaving like an ideal listener, they should be sensitive to cue statistics
- Clayards et al. (2008) set out to test for sensitivity to **variance**

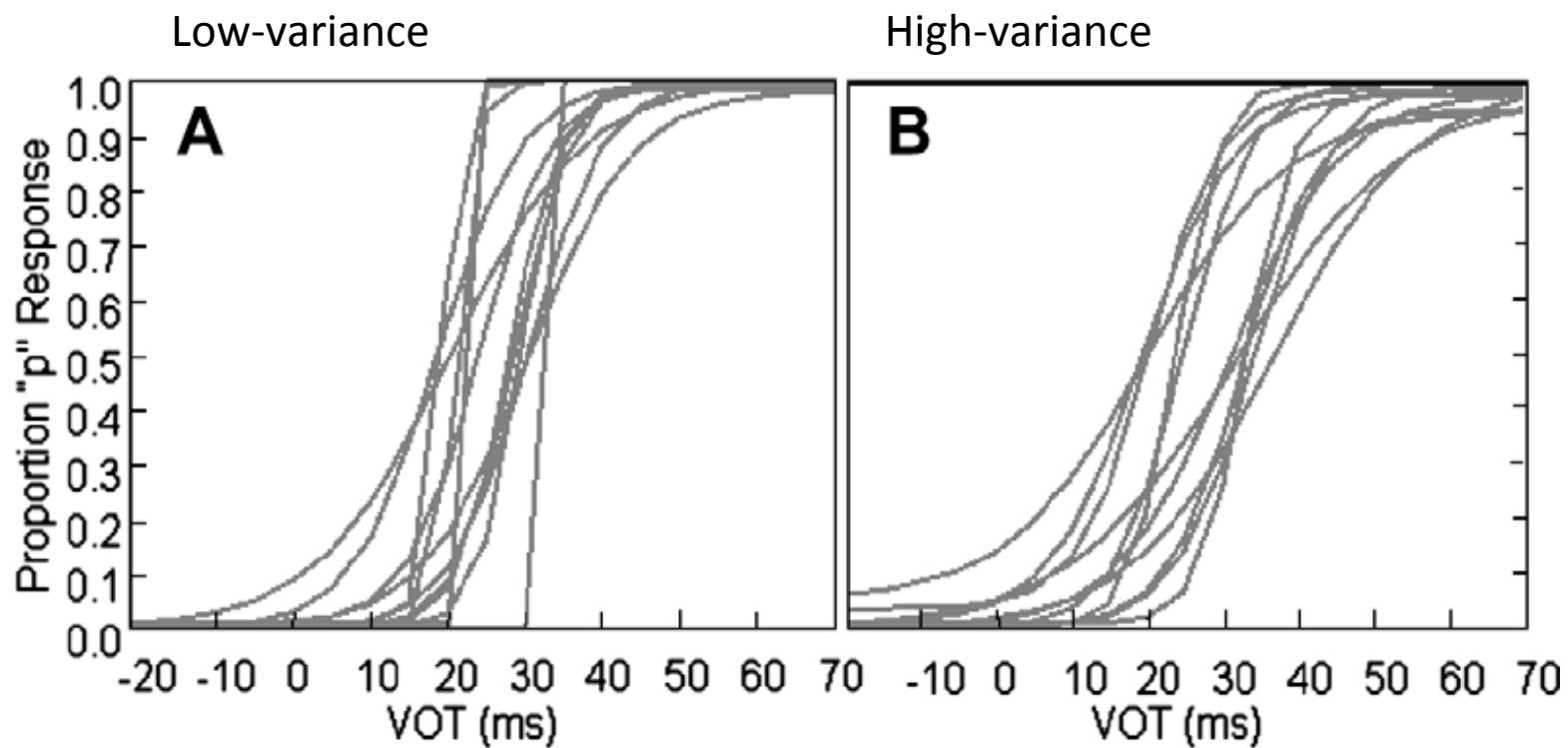
CLAYARDS ET AL. (2008)

- /b/-/p/ minimal pairs (VOT continuum)
- Two conditions: high variance and low variance VOT distributions.

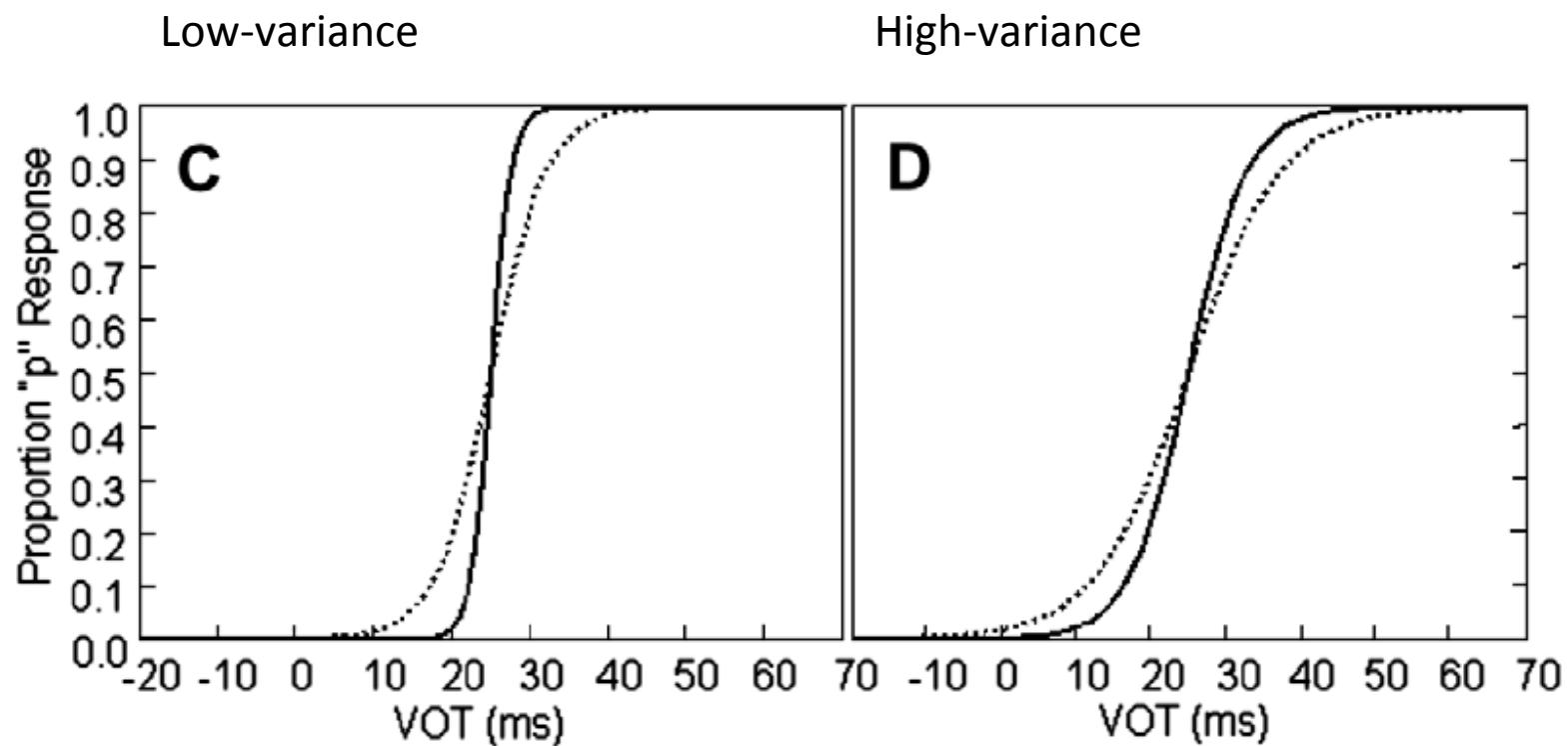
CLAYARDS ET AL. (2008) PREDICTIONS



CLAYARDS ET AL. (2008) RESULTS

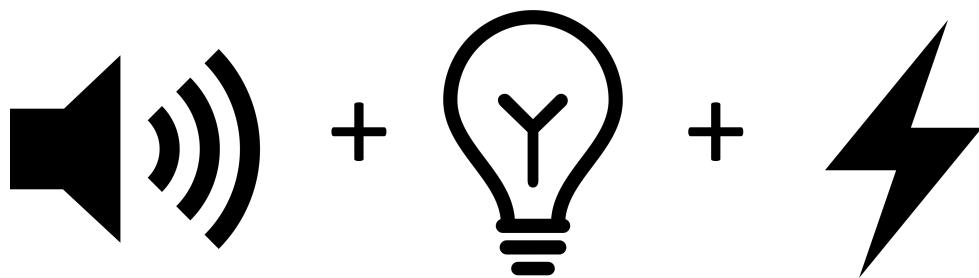


CLAYARDS ET AL. (2008) RESULTS

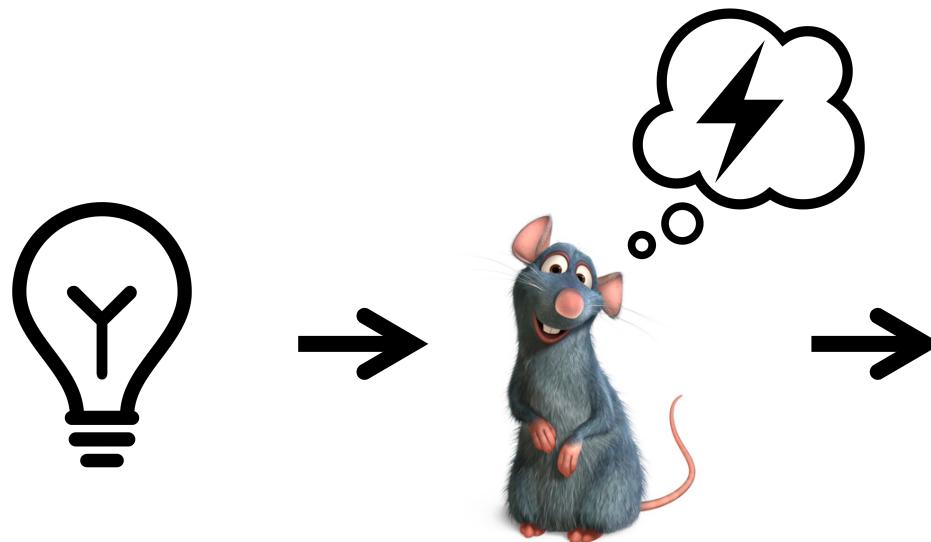
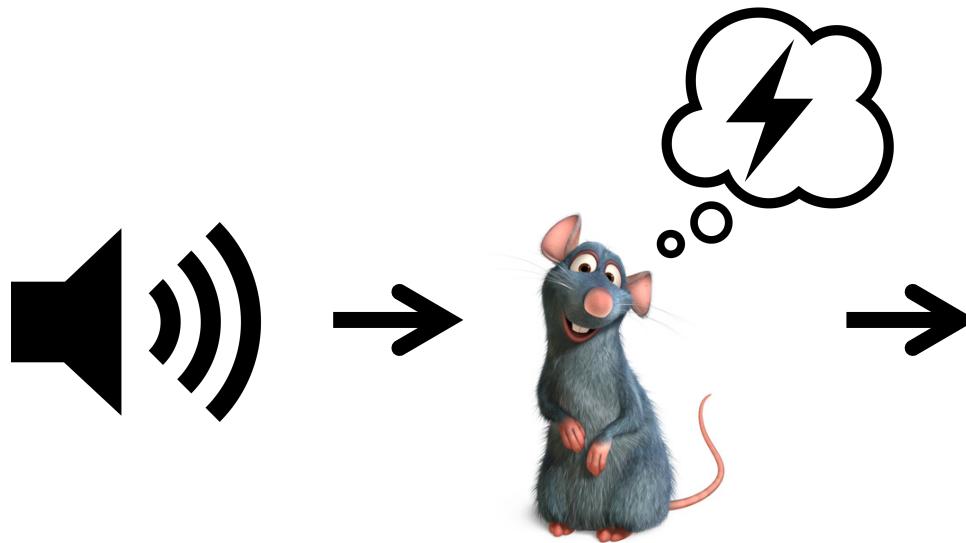
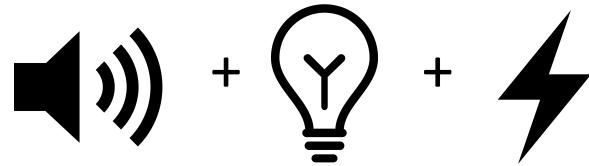


Backwards blocking/ Explaining away

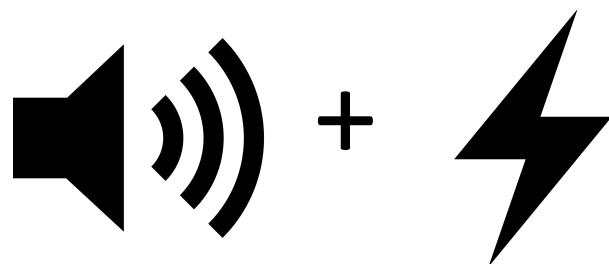
Phase 1



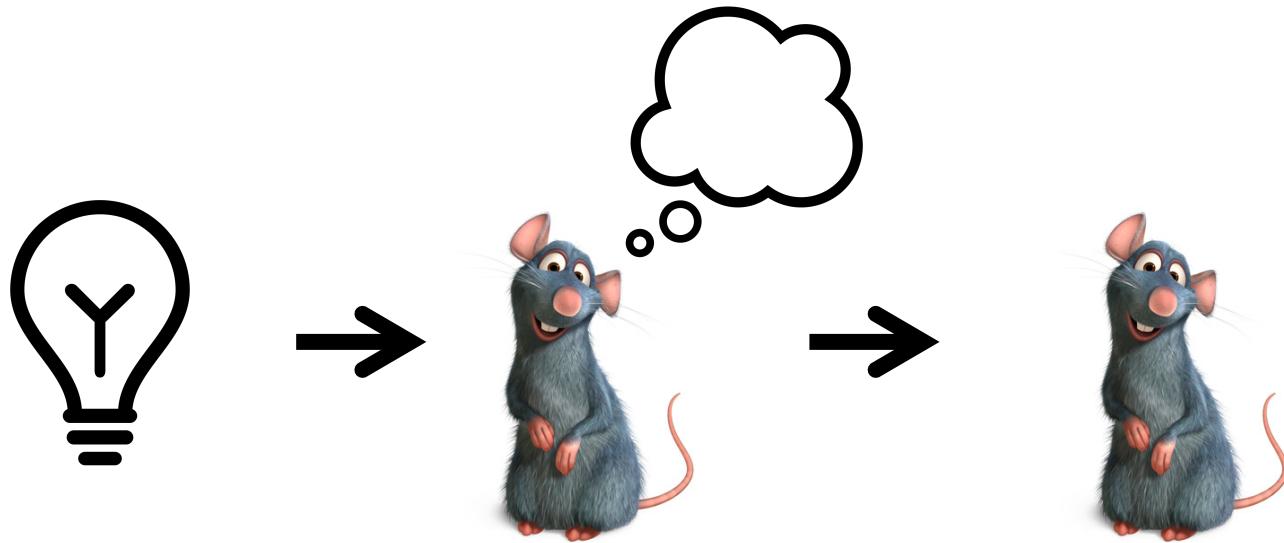
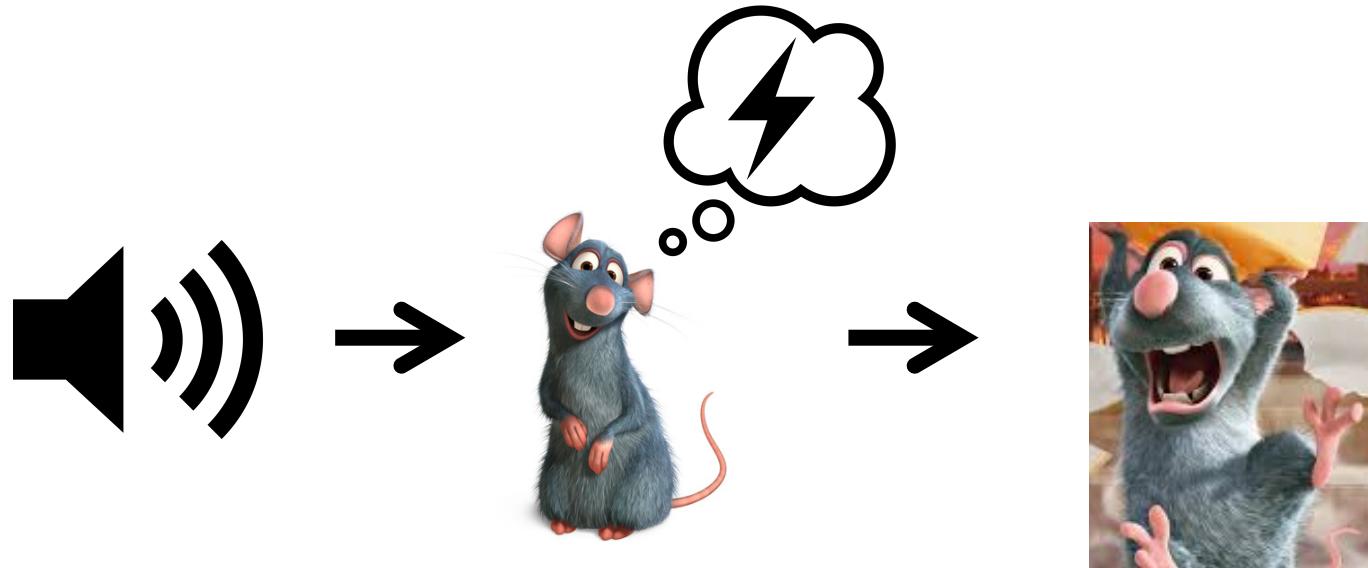
Phase 1: test



Phase 2



Phase 2: test



Explaining away & backward blocking

- Bayesian model:
- Cue weights (how well cue predicts shock), sum to 1.
- After exposure to light+sound+shock, could be anywhere from all light to all sound and mixtures in between.
- After exposure to sound+shock, high weight for sound is supported, and hence weight for light drops.