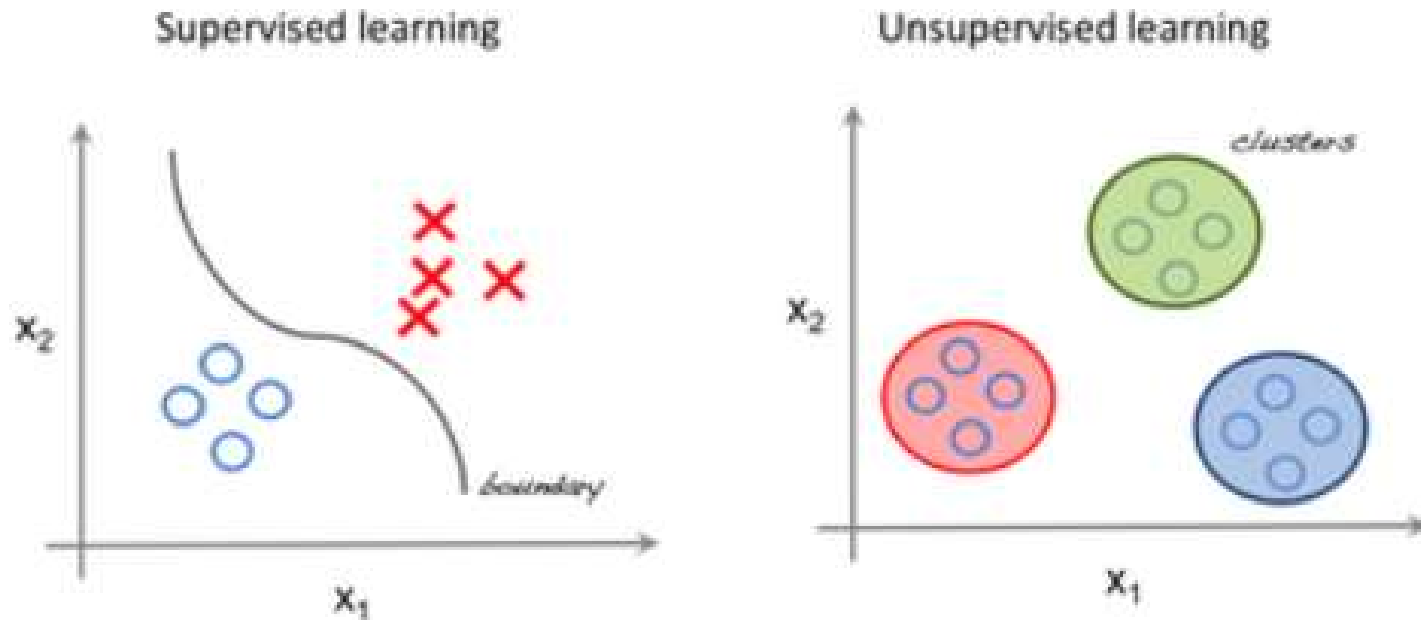


Chap.2 Learning processes

- Learning is a process by which the ^(weight)free parameters of a N.N are adapted through a process of stimulation by the environment
- Learning process:
 - (i) The N.N is stimulated by an environment
 - (ii) The N.N undergoes changes in its free parameters as a result of this stimulation
 - (iii) The N.N responds in a new way to the environment
- There is no unique learning Algorithm for the design of N.N
- Basically, learning algorithms differ from each other in the way in which the adjustment to a synaptic weight of a neuron is formulated.

The objective of learning is to find a weight matrix \mathbf{w} such that similar input data \mathbf{x} will be grouped or clustered together.

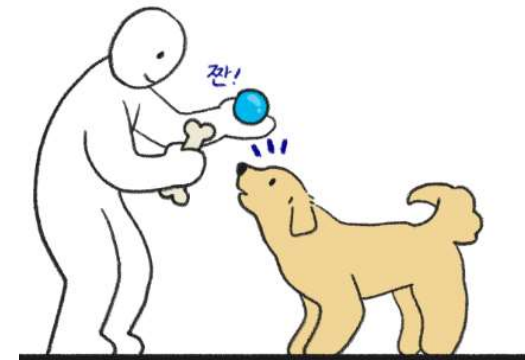
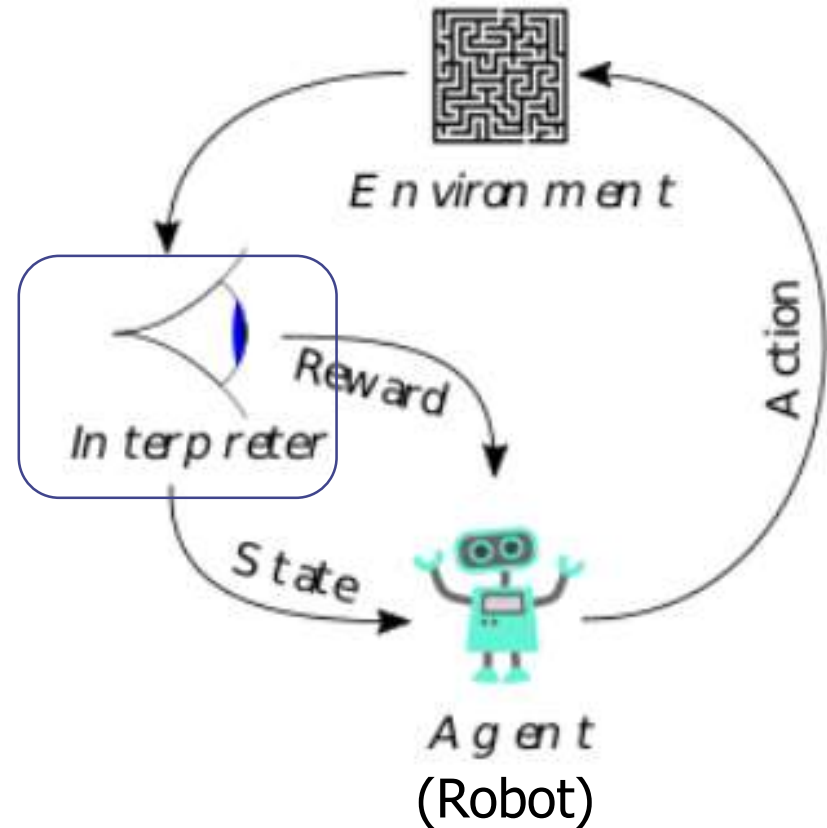


Learning paradigm

- (i) Learning with Teacher: supervised learning with label (answer)
- (ii) Learning w/o teacher : unsupervised learning
- (iii) Reinforcement learning: unsupervised learning with reward

[Reinforcement Learning]

- The typical framing of a Reinforcement Learning (RL) scenario: an **agent** takes actions in an environment, which is interpreted into a **reward/penalty** and a representation of **the state**, which are fed back into the agent.
- RL is the ML that tries to maximize some notion of **cumulative reward**.



2.1 Error Correction Learning (delta rule, Widrow–Hoff rule)

- ◆ Consider a neuron k
- ◆ Find an error signal, $e_k(n)$, such that minimize a cost function ($\mathcal{E}(n)$), or index of performance:

$$e_k(n) = d_k(n) - y_k(n)$$

$$\mathcal{E}(n) = \frac{1}{2} e_k^2(n) \quad \leftarrow \text{instantaneous value of error energy}$$

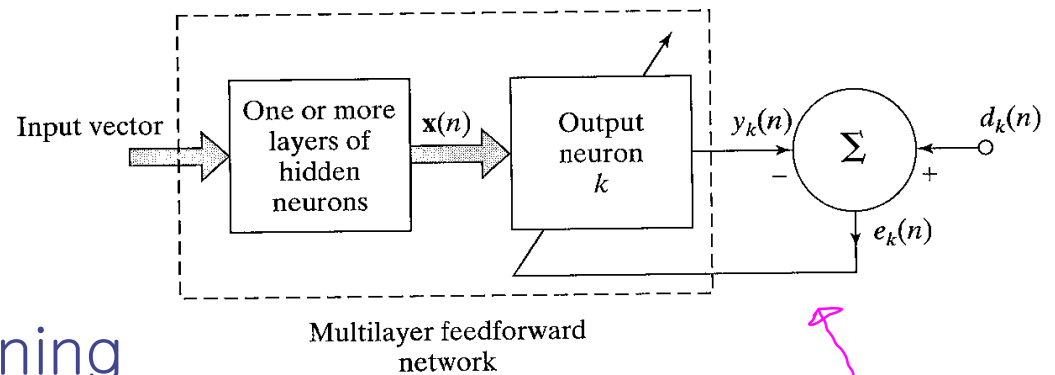
, where n denotes time step

- ◆ The **step-by-step adjustment** are continued until the system reaches steady state, i.e., synaptic weights are Stabilized.

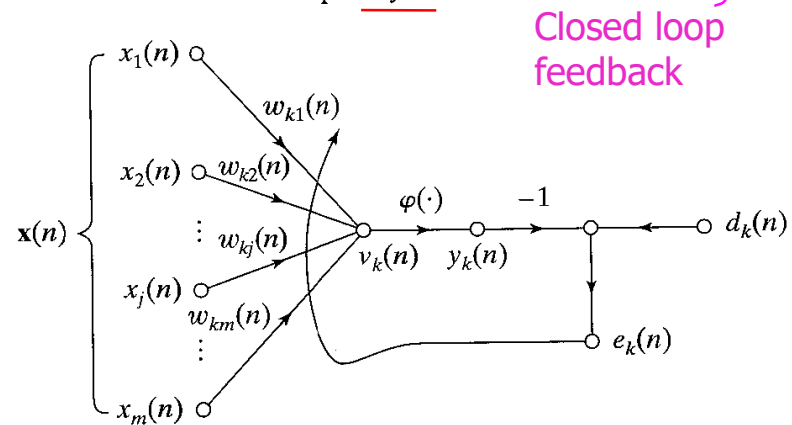
The $e_k(n)$ is used for producing a sequence of **corrective adjustments** to the **synaptic weight** of neuron

$$\Delta w_{kj}(n) = \eta \cdot e_k(n) \cdot x_j(n)$$

where η : the rate of learning



(a) Block diagram of a neural network, highlighting the only neuron in the output layer

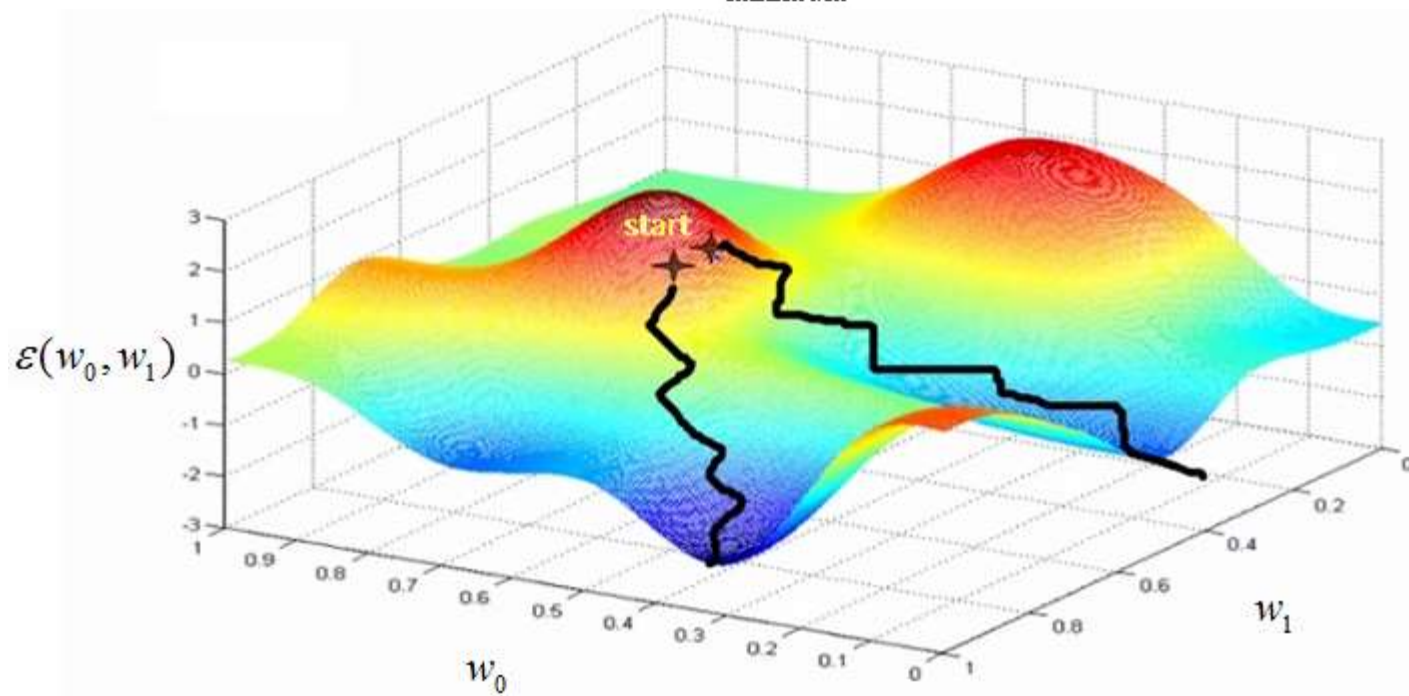
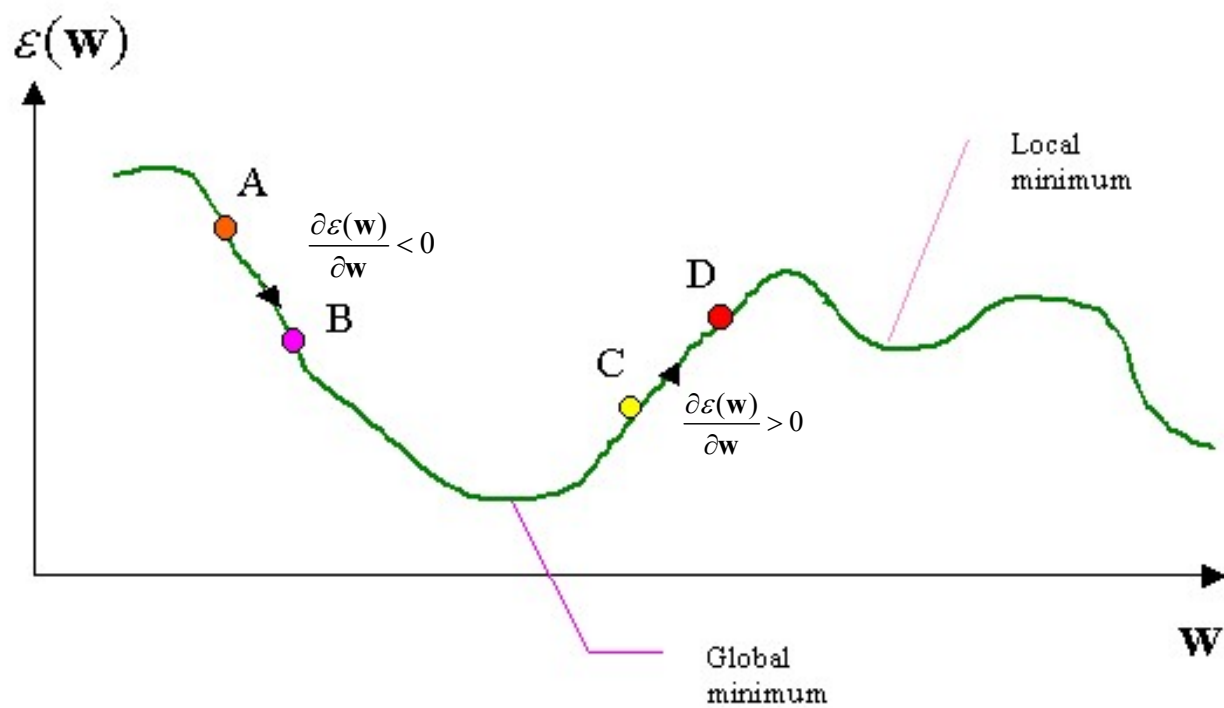


(b) Signal-flow graph of output neuron

FIGURE 2.1 Illustrating error-correction learning.

$$w_{kj}(n+1) = w_{kj}(n) + \Delta w_{kj}(n)$$

The η is carefully selected to ensure that the stability or convergence of the iterative learning process is achieved ($\because \eta$ is one of parameters that constitute feedback loop)



Gradient (Steepest) Descent Algorithm

- ✓ the successive adjustments applied to \mathbf{w} are in the direction of steepest descent, that is, the choice of **direction** is where $\varepsilon(\mathbf{w})$ decreases most quickly, which is in the direction **opposite** to the gradient vector $\nabla \varepsilon(\mathbf{w})$

For any cost func $\varepsilon(\mathbf{w})$
 $\mathbf{w}(n+1) = \mathbf{w}(n) - \eta \cdot \nabla \varepsilon(\mathbf{w})$ ← $\mathbf{g}(n)$: 1st derivative for cost function !!!
 where $\eta(>0)$: step size or learning rate ← find \mathbf{w} such that minimize the cost function $\varepsilon(\mathbf{w})$

$$\mathbf{g}(n) = \nabla \varepsilon(\mathbf{w}) = \left[\frac{\partial \varepsilon}{\partial w_1}, \frac{\partial \varepsilon}{\partial w_2}, \dots, \frac{\partial \varepsilon}{\partial w_m} \right]^T \quad (m \times 1) \text{ gradient matrix}$$

$$\therefore \Delta \mathbf{w}(n) = \mathbf{w}(n+1) - \mathbf{w}(n) = -\eta \cdot \mathbf{g}(n) \quad (1)^*$$

By considering 1st order taylor series (assuming $\eta \approx 0$)

$$\varepsilon(\mathbf{w}(n+1)) \approx \varepsilon(\mathbf{w}(n)) + \mathbf{g}(n)^T \cdot \Delta \mathbf{w}(n) \quad (2)$$

$$- \eta \cdot \mathbf{g}(n)$$

Therefore,

Substituting (1)* into (2) yields:

$$\begin{aligned} \varepsilon(\mathbf{w}(n+1)) &= \varepsilon(\mathbf{w}(n)) - \eta \cdot \mathbf{g}^T(n) \cdot \mathbf{g}(n) \\ &= \varepsilon(\mathbf{w}(n)) - \eta \cdot \|\mathbf{g}(n)\|^2 \end{aligned}$$

$$\Rightarrow \varepsilon(\mathbf{w}(n+1)) < \varepsilon(\mathbf{w}(n)) \text{ only if } \eta \approx 0$$

Taylor series:

$$f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots + \frac{f^{(n-1)}(a)}{(n-1)!}(x-a)^{n-1} + \frac{f^{(n)}(a)}{n!}(x-a)^n + \dots$$

Annotations: $\varepsilon(\mathbf{w}(n+1))$ points to $f(x)$, $\varepsilon(\mathbf{w}(n))$ points to $f(a)$, and $\Delta \mathbf{w}(n)$ points to $(x-a)$.

convergence

if η is not small enough to ignore :

$$\varepsilon(\mathbf{w}(n+1)) = \varepsilon(\mathbf{w}(n)) + \mathbf{g}^T(n) \cdot \Delta \mathbf{w}(n) + \frac{1}{2} \cdot \Delta \mathbf{w}^T(n) \cdot \mathbf{H}(n) \cdot \Delta \mathbf{w}(n) \quad (3)$$

where $\Delta \mathbf{w}(n) = \mathbf{w}(n+1) - \mathbf{w}(n)$

$\mathbf{H}(n)$: Hessian matrix of $\varepsilon(\mathbf{w}(n))$

Therefore,

Substituting (1)* into (3) yields :

$$\begin{aligned} \varepsilon(\mathbf{w}(n+1)) &= \varepsilon(\mathbf{w}(n)) - \eta \cdot \mathbf{g}^T(n) \cdot \mathbf{g}(n) + \frac{1}{2} \cdot \eta^2 \cdot \mathbf{g}^T(n) \cdot \mathbf{H}(n) \cdot \mathbf{g}(n) \\ &= \varepsilon(\mathbf{w}(n)) - \eta \cdot \|\mathbf{g}(n)\|^2 + \frac{1}{2} \cdot \eta^2 \cdot \mathbf{g}^T(n) \cdot \mathbf{H}(n) \cdot \mathbf{g}(n) \end{aligned}$$

$\Rightarrow \varepsilon(\mathbf{w}(n+1)) \text{ ? } \varepsilon(\mathbf{w}(n)) \Rightarrow$ We can't guarantee it's convergence

Hessian

Gradient

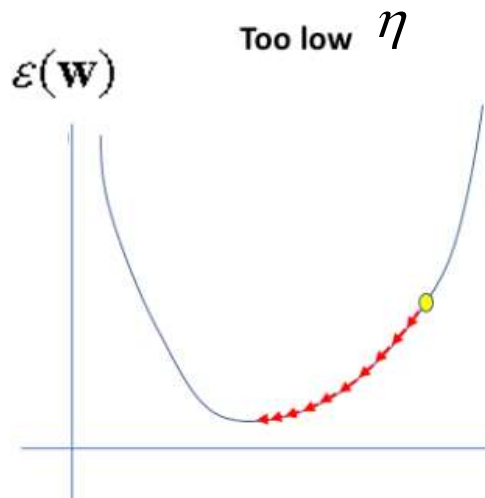
$$\nabla \varepsilon(\mathbf{w}) = \left[\frac{\partial \varepsilon}{\partial w_1}, \frac{\partial \varepsilon}{\partial w_2}, \dots, \frac{\partial \varepsilon}{\partial w_m} \right]^T$$

$\nabla^2 \varepsilon(\mathbf{w})$
Laplacian

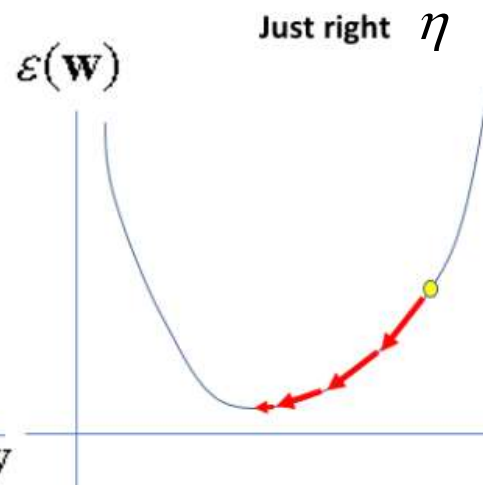
$H[\varepsilon(\mathbf{w})] =$

$$\begin{bmatrix} \frac{\partial^2 \varepsilon}{\partial w_1^2} & \frac{\partial^2 \varepsilon}{\partial w_1 w_2} & \dots & \frac{\partial^2 \varepsilon}{\partial w_1 w_m} \\ \frac{\partial^2 \varepsilon}{\partial w_2 w_1} & \frac{\partial^2 \varepsilon}{\partial w_2^2} & \dots & \frac{\partial^2 \varepsilon}{\partial w_2 w_m} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 \varepsilon}{\partial w_m w_1} & \frac{\partial^2 \varepsilon}{\partial w_m w_2} & \dots & \frac{\partial^2 \varepsilon}{\partial w_m^2} \end{bmatrix}^T$$

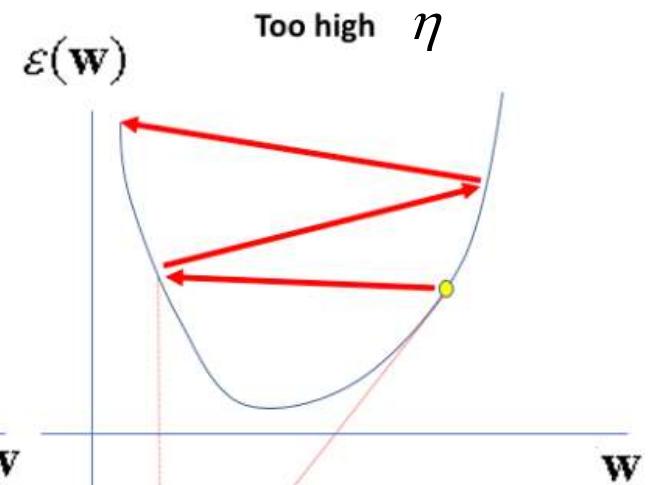




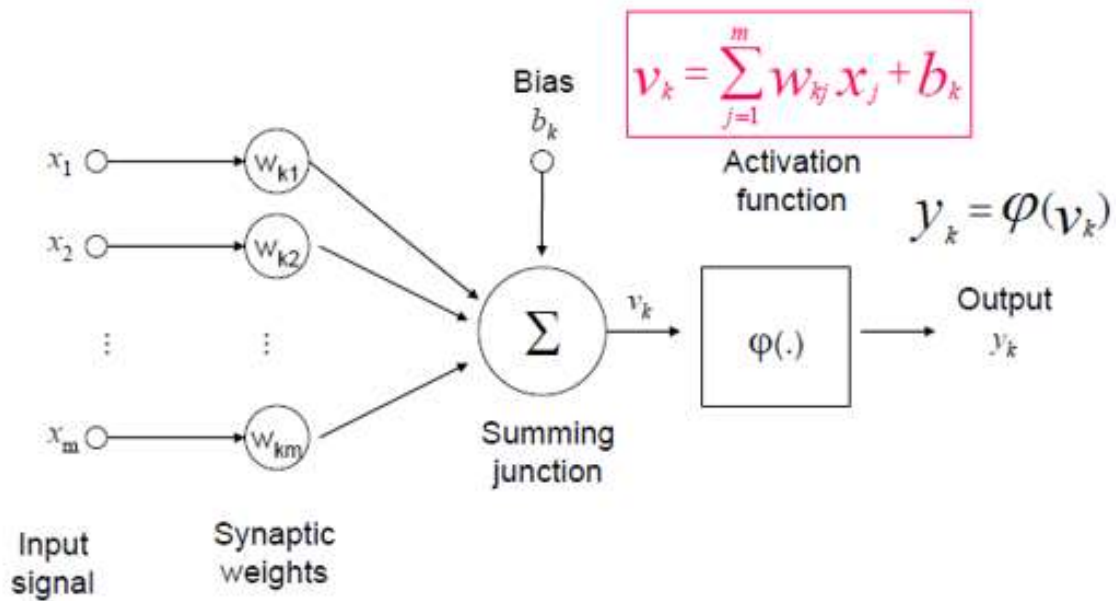
A small learning rate requires many updates before reaching the minimum point



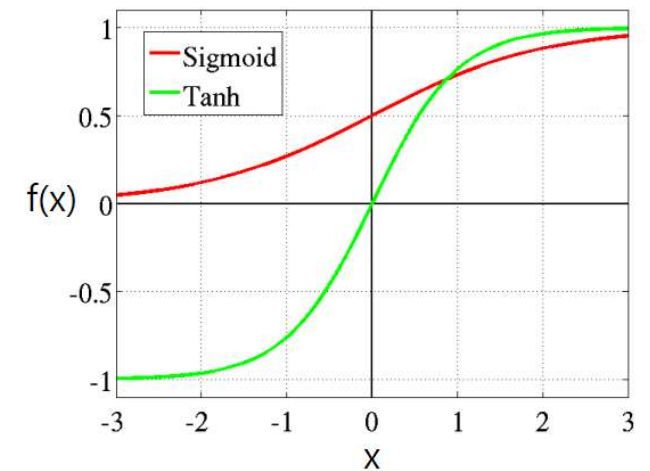
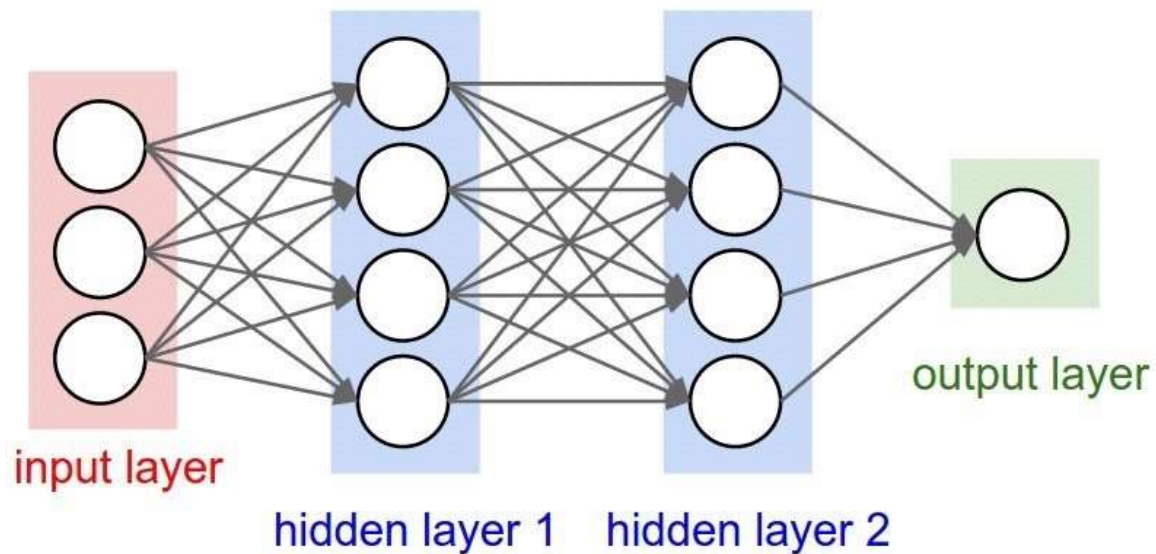
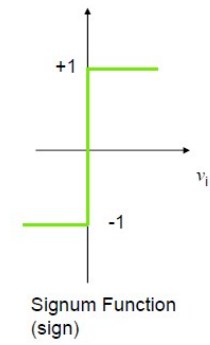
The optimal learning rate swiftly reaches the minimum point



Too large of a learning rate causes drastic updates which lead to divergent behaviors

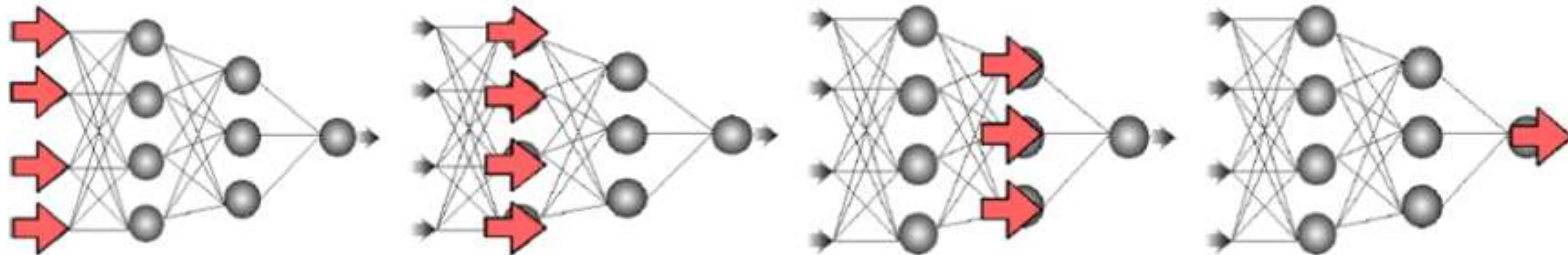


<activation function>



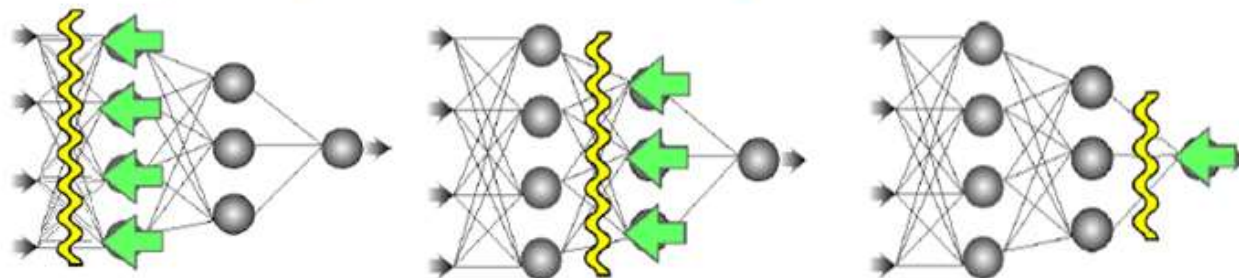
Back propagation training cycle

1) Feedforward of the input training pattern



2) Backpropagation of the **associated error**

3) Adjustement of the weights



Back-Propagation Algorithm

- ✓ Error signal for neuron j at iteration n :

$$e_j(n) = d_j(n) - y_j(n) \quad \text{----} \textcircled{1}$$

- ✓ Total error energy:

$$\varepsilon(n) = \frac{1}{2} \sum_{j \in C} e_j^2(n) \quad \text{---} \textcircled{2}$$

, where the set C includes all the neurons in the output layer

- ◆ Average squared error energy:

$$\varepsilon_{av} = \frac{1}{N} \sum_{n=1}^N \varepsilon(n) \quad \text{---} \textcircled{3} \quad \text{:Cost func}$$

N : the total # of patterns in the train set every update (batch size)



Matlab Tutorial 2

<https://www.youtube.com/watch?v=RQ8I6xVEpMU&list=PLnVYEpTNGNtX6FcQm90I0WXdvhoEJPp3p&index=6>

<https://www.youtube.com/watch?v=TgARZWgXWS4&list=PLnVYEpTNGNtX6FcQm90I0WXdvhoEJPp3p&index=7>

<https://www.youtube.com/watch?v=kqtPdDaMUEk&list=PLnVYEpTNGNtX6FcQm90I0WXdvhoEJPp3p&index=8>

<https://www.youtube.com/watch?v=bVu8a-upOBM&list=PLnVYEpTNGNtX6FcQm90I0WXdvhoEJPp3p&index=9>

<https://www.youtube.com/watch?v=IuI9cONtwFY&list=PLnVYEpTNGNtX6FcQm90I0WXdvhoEJPp3p&index=10>