



prescribes the *relative error* in  $\hat{x}$ . Relative error in the  $\infty$ -norm can be translated into a statement about the number of correct significant digits in  $\hat{x}$ . In particular, if

$$\frac{\|\hat{x} - x\|_{\infty}}{\|x\|_{\infty}} \approx 10^{-p},$$

then the largest component of  $\hat{x}$  has approximately  $p$  correct significant digits. For example, if  $x = [1.234 \ .05674]^T$  and  $\hat{x} = [1.235 \ .05128]^T$ , then  $\|\hat{x} - x\|_{\infty}/\|x\|_{\infty} \approx .0043 \approx 10^{-3}$ . Note that  $\hat{x}_1$  has about three significant digits that are correct while only one significant digit in  $\hat{x}_2$  is correct.

## 2.2.4 Convergence

We say that a sequence  $\{x^{(k)}\}$  of  $n$ -vectors *converges* to  $x$  if

$$\lim_{k \rightarrow \infty} \|x^{(k)} - x\| = 0.$$

Because of (2.2.4), convergence in *any* particular norm implies convergence in *all* norms.

### Problems

**P2.2.1** Show that if  $x \in \mathbb{R}^n$ , then  $\lim_{p \rightarrow \infty} \|x\|_p = \|x\|_{\infty}$ .

**P2.2.2** By considering the inequality  $0 \leq (ax + by)^T(ax + by)$  for suitable scalars  $a$  and  $b$ , prove (2.2.3).

**P2.2.3** Verify that  $\|\cdot\|_1$ ,  $\|\cdot\|_2$ , and  $\|\cdot\|_{\infty}$  are vector norms.

**P2.2.4** Verify (2.2.5)-(2.2.7). When is equality achieved in each result?

**P2.2.5** Show that in  $\mathbb{R}^n$ ,  $x^{(i)} \rightarrow x$  if and only if  $x_k^{(i)} \rightarrow x_k$  for  $k = 1:n$ .

**P2.2.6** Show that for any vector norm on  $\mathbb{R}^n$  that  $|\|x\| - \|y\|| \leq \|x - y\|$ .

**P2.2.7** Let  $\|\cdot\|$  be a vector norm on  $\mathbb{R}^n$  and assume  $A \in \mathbb{R}^{m \times n}$ . Show that if  $\text{rank}(A) = n$ , then  $\|x\|_A = \|Ax\|$  is a vector norm on  $\mathbb{R}^n$ .

**P2.2.8** Let  $x$  and  $y$  be in  $\mathbb{R}^n$  and define  $\psi: \mathbb{R} \rightarrow \mathbb{R}$  by  $\psi(\alpha) = \|x - \alpha y\|_2$ . Show that  $\psi$  is minimized if  $\alpha = x^T y / y^T y$ .

**P2.2.9** Prove or disprove:

$$v \in \mathbb{R}^n \Rightarrow \|v\|_1 \|v\|_{\infty} \leq \frac{1 + \sqrt{n}}{2} \|v\|_2^2.$$

**P2.2.10** If  $x \in \mathbb{R}^3$  and  $y \in \mathbb{R}^3$  then it can be shown that  $|x^T y| = \|x\|_2 \|y\|_2 |\cos(\theta)|$  where  $\theta$  is the angle between  $x$  and  $y$ . An analogous result exists for the *cross product* defined by

$$x \times y = \begin{bmatrix} x_2 y_3 - x_3 y_2 \\ x_3 y_1 - x_1 y_3 \\ x_1 y_2 - x_2 y_1 \end{bmatrix}.$$

In particular,  $\|x \times y\|_2 = \|x\|_2 \|y\|_2 |\sin(\theta)|$ . Prove this.

**P2.2.11** Suppose  $x \in \mathbb{R}^n$  and  $y \in \mathbb{R}^m$ . Show that

$$\|x \otimes y\|_p = \|x\|_p \|y\|_p$$

for  $p = 1, 2$ , and  $\infty$ .

### Notes and References for §2.2

Although a vector norm is “just” a generalization of the absolute value concept, there are some noteworthy subtleties:

J.D. Pryce (1984). “A New Measure of Relative Error for Vectors,” *SIAM J. Numer. Anal.* 21, 202–221.



## 2.2. Vector Norms

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norms are the  $p$ -norms defined by

$$\|x\|_p = (|x_1|^p + \cdots + |x_n|^p)^{\frac{1}{p}}, \quad p \geq 1. \quad (2.2.1)$$

The 1-, 2-, and  $\infty$ -norms are the most important:

$$\begin{aligned} \|x\|_1 &= |x_1| + \cdots + |x_n|, \\ \|x\|_2 &= (|x_1|^2 + \cdots + |x_n|^2)^{\frac{1}{2}} = (x^T x)^{\frac{1}{2}}, \\ \|x\|_\infty &= \max_{1 \leq i \leq n} |x_i|. \end{aligned}$$

A *unit vector* with respect to the norm  $\|\cdot\|$  is a vector  $x$  that satisfies  $\|x\| = 1$ .

### 2.2.2 Some Vector Norm Properties

A classic result concerning  $p$ -norms is the *Hölder inequality*:

$$|x^T y| \leq \|x\|_p \|y\|_q, \quad \frac{1}{p} + \frac{1}{q} = 1. \quad (2.2.2)$$

A very important special case of this is the *Cauchy-Schwarz inequality*:

$$|x^T y| \leq \|x\|_2 \|y\|_2. \quad (2.2.3)$$

All norms on  $\mathbb{R}^n$  are *equivalent*, i.e., if  $\|\cdot\|_\alpha$  and  $\|\cdot\|_\beta$  are norms on  $\mathbb{R}^n$ , then there exist positive constants  $c_1$  and  $c_2$  such that

$$c_1 \|x\|_\alpha \leq \|x\|_\beta \leq c_2 \|x\|_\alpha \quad (2.2.4)$$

for all  $x \in \mathbb{R}^n$ . For example, if  $x \in \mathbb{R}^n$ , then

$$\|x\|_2 \leq \|x\|_1 \leq \sqrt{n} \|x\|_2, \quad (2.2.5)$$

$$\|x\|_\infty \leq \|x\|_2 \leq \sqrt{n} \|x\|_\infty, \quad (2.2.6)$$

$$\|x\|_\infty \leq \|x\|_1 \leq n \|x\|_\infty. \quad (2.2.7)$$

Finally, we mention that the 2-norm is preserved under orthogonal transformation. Indeed, if  $Q \in \mathbb{R}^{n \times n}$  is orthogonal and  $x \in \mathbb{R}^n$ , then

$$\|Qx\|_2^2 = (Qx)^T (Qx) = (x^T Q^T)(Qx) = x^T (Q^T Q)x = x^T x = \|x\|_2^2.$$

### 2.2.3 Absolute and Relative Errors

Suppose  $\hat{x} \in \mathbb{R}^n$  is an approximation to  $x \in \mathbb{R}^n$ . For a given vector norm  $\|\cdot\|$  we say that

$$\epsilon_{\text{abs}} = \|\hat{x} - x\|$$

is the *absolute error* in  $\hat{x}$ . If  $x \neq 0$ , then

$$\epsilon_{\text{rel}} = \frac{\|\hat{x} - x\|}{\|x\|}$$

**P2.2.2** By considering the inequality  $0 \leq (ax + by)^T(ax + by)$  for suitable scalars  $a$  and  $b$ , prove (2.2.3).

$$|x^T y| \leq \|x\|_2 \|y\|_2$$

$$\left[ \begin{array}{c} 0 \\ \vdots \\ 0 \end{array} \right]^T \left[ \begin{array}{c} a \\ b \end{array} \right] (ax + by)^T (ax + by) = \|ax + by\|_2^2 \geq 0$$

$$= \sum_{i=1}^n (ax_i + by_i)(ax_i + by_i) \geq 0$$

$$= \sum_{i=1}^n (a^2 x_i^2 + 2ax_i by_i + b^2 y_i^2) \geq 0$$

$$= a^2 \|x\|_2^2 + 2ab \sum_{i=1}^n x_i y_i + b^2 \|y\|_2^2 \geq 0$$

$$p(t) = \|t\vec{y} - \vec{x}\|^2 \geq 0$$

$$p(t) = (\vec{y} \cdot \vec{y}) t^2 - 2(\vec{x} \cdot \vec{y}) t + \vec{x} \cdot \vec{x} \geq 0$$

$$p(t) = at^2 - bt + c \geq 0$$

$$p\left(\frac{b}{2a}\right) = a \frac{b^2}{4a^2} - b\left(\frac{b}{2a}\right) + c \geq 0$$

$$= \frac{b^2}{4a} - \frac{2b^2}{4a} + c \geq 0$$

$$= -\frac{b^2}{4a} + c \geq 0$$

$$c \geq \frac{b^2}{4a}$$

$$4ac \geq b^2$$

$$4(\|\vec{y}\|_2^2 \|\vec{x}\|_2^2) \geq (-2(\vec{x} \cdot \vec{y}))^2$$

$$4\|\vec{x}\|_2^2 \|\vec{y}\|_2^2 \geq 4(\vec{x} \cdot \vec{y})^2$$

$$\|\vec{x}\|_2 \|\vec{y}\|_2 \geq |\vec{x}^T \vec{y}|$$

