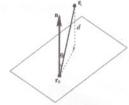
- (a) Find the distance (in terms of n, r_0 and r_1 only) from the point r_1 to the plane $(r-r_0) \cdot n = 0$.
- (b) A rigid body rotates about an axis through point O with angular velocity ω.
 - (i) Find the linear velocity v of a point P of the body with position vector r.
 - (ii) Show that the vector -ω× (ω×r) is directed away from the axis of rotation and lies on the plane containing the vector ω and r.

Solution:

(a)
$$\begin{split} d &= ||\mathbf{r}_1 - \mathbf{r}_0|| \; |\cos \theta| \\ &= ||\mathbf{r}_1 - \mathbf{r}_0|| \cdot ||\widehat{\mathbf{n}}|| \; |\cos \theta| \end{split}$$

 $= |(\mathbf{r}_1 - \mathbf{r}_0) \cdot \hat{\mathbf{n}}|$



(b) (i) Since P travels in a circle of radius $r\sin\theta$, the magnitude of the linear velocity \mathbf{v} is $\omega(r\sin\theta) = ||\omega \times \mathbf{r}||$. Also, \mathbf{v} must be perpendicular to both ω and \mathbf{r} and is such that \mathbf{r} , ω and \mathbf{v} form a right-handed system, i.e.

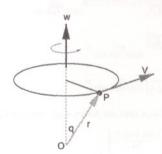
$$v = \omega \times r$$

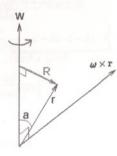
(ii)
$$[\boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r})]_i = \varepsilon_{ijk} \omega_j (\boldsymbol{\omega} \times \mathbf{r})_k$$

 $= \varepsilon_{kij} \varepsilon_{kpq} \omega_j \omega_p r_q$
 $= (\delta_{ip} \delta_{jq} - \delta_{iq} \delta_{jp}) \omega_j \omega_p r_q$
 $= \omega_j \omega_i r_j - \omega_j \omega_j r_i$
 $= (\boldsymbol{\omega} \cdot \mathbf{r}) \omega_i - (\boldsymbol{\omega} \cdot \boldsymbol{\omega}) r_i$
 $\boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}) = (\boldsymbol{\omega} \cdot \mathbf{r}) \boldsymbol{\omega} - (\boldsymbol{\omega} \cdot \boldsymbol{\omega}) \mathbf{r}$

i.e. the vector $\boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r})$ is on the plane containing $\boldsymbol{\omega}$ and \mathbf{r} since $\boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r})$ is a linear combination of $\boldsymbol{\omega}$ and \mathbf{r} .

From the right-hand system, we can see from the figure $R=-\omega\times(\omega\times r)$ is directed away from the axis of rotation.



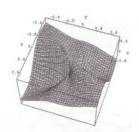


The direction of the centripetal force

- (a) Can the function $f(x,y) = \frac{\sin x \sin^3 y}{1 \cos(x^2 + y^2)}$ be defined at (0,0) in such a way that it becomes continuous there? If so, how?
- (b) Let $f(x,y) = \begin{cases} \frac{x^3}{x^2 + y^2}, & \text{if } (x,y) \neq (0,0), \\ 0, & \text{if } (x,y) = (0,0). \end{cases}$

Calculate each of the following partial derivatives or explain why it does not exist: (i) $f_x(0,0)$, (ii) $f_y(0,0)$, (iii) $f_{yx}(0,0)$, (iv) $f_{xy}(0,0)$ and (v) $f_{xx}(0,0)$. Is the function f(x,y) differentiable at (0,0)? Explain.

Solution:



(a) Along the x-axis, i.e. y = 0, then

$$\lim_{(x,y)\to(0,0)} f(x,y) = \lim_{x\to 0} f(x,0) = 0,$$

so the limit must be 0 if it exists at all. However, along the straight line y = mx, then

$$f(x, mx) = \frac{\sin x \sin^3 mx}{1 - \cos(m^2 + 1)x^2}.$$

In particular, if m = 1, we have

$$\begin{split} f(x,x) &= \frac{\sin^4 x}{1 - \cos(2x^2)} = \frac{\sin^4 x}{2\sin^2(x^2)} \\ &\lim_{x \to 0} f(x,x) = \lim_{x \to 0} \frac{4\sin^3 x \cos x}{2 \cdot 2\sin(x^2) \cdot 2x} = \lim_{x \to 0} \left[\frac{1}{2} \cdot \frac{\sin^3 x}{x^3} \cdot \frac{x^2}{\sin(x^2)} \cdot \cos x \right] = \frac{1}{2} \end{split}$$

- : $\lim_{(x,y)\to(0,0)} f(x,y)$ does not exist since difference paths end up different limits.
- f(x,y) cannot be defined at (0,0).

(b) If $(x, y) \neq (0, 0)$, we have

$$f_x(x,y) = \frac{(x^2 + y^2)3x^2 - x^3 \cdot (2x)}{(x^2 + y^2)^2} = \frac{x^4 + 3x^2y^2}{(x^2 + y^2)^2}$$

$$f_y(x,y) = x^3(-1)(x^2 + y^2)^{-2} \cdot 2y = -\frac{2x^3y}{(x^2 + x^2)^2}.$$

If (x, y) = (0, 0), then

(i)
$$f_x(0,0) = \lim_{\Delta x \to 0} \frac{f(\Delta x, 0) - f(0,0)}{\Delta x} = \lim_{\Delta x \to 0} \frac{(\Delta x)^3 / [(\Delta x)^2 - 0]}{\Delta x} = 1$$

(ii)
$$f_y(0,0) = \lim_{\Delta y \to 0} \frac{f(0,\Delta y) - f(0,0)}{\Delta y} = \lim_{\Delta y \to 0} \frac{0 - 0}{\Delta y} = 0$$

(iii)
$$f_{xy}(0,0) = \lim_{\Delta y \to 0} \frac{f_x(0,\Delta y) - f_x(0,0)}{\Delta y} = \lim_{\Delta y \to 0} \frac{0-1}{\Delta y} \text{ does not exist}$$

$$(\mathrm{iv}) \hspace{1cm} f_{yx}(0,0) = \lim_{\Delta x \to 0} \frac{f_y(\Delta x,0) - f_y(0,0)}{\Delta x} = \lim_{\Delta x \to 0} \frac{0-0}{\Delta x} = 0$$

(v)
$$f_{xx}(0,0) = \lim_{\Delta x \to 0} \frac{f_x(\Delta x, 0) - f_x(0,0)}{\Delta x} = \lim_{\Delta y \to 0} \frac{1-1}{\Delta x} = 0.$$

Note that

$$\lim_{(\Delta x, \Delta y) \to (0,0)} \frac{|f(\Delta x, \Delta y) - f(0,0) - \Delta x f_x(0,0) - \Delta y f_y(0,0)|}{\sqrt{(\Delta x)^2 + (\Delta y)^2}}$$

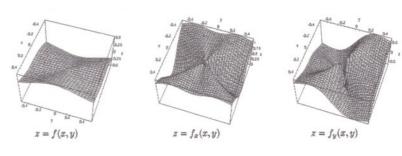
$$= \lim_{(\Delta x, \Delta y) \to (0,0)} \frac{|\frac{(\Delta x)^3}{(\Delta x)^2 + (Dy)^2} - 0 - \Delta x \cdot 1 - \Delta y \cdot 0|}{\sqrt{(\Delta x)^2 + (\Delta y)^2}}$$

$$= \lim_{(\Delta x, \Delta y) \to (0,0)} \left| \frac{-\Delta x \Delta y}{[(\Delta x)^2 + (\Delta y)^2]^{3/2}} \right|.$$

Let $\Delta x = r \cos \theta$, $\Delta y = r \sin \theta$, the limit equals

$$\left| \frac{r^3 \cos \theta \, \sin \theta}{r^3} \right| = \left| \cos \theta \, \sin \theta \right|,$$

which depends on θ . So the limit does not exist and hence f is not differentiable at (0,0).



- (a) Show that the curve $\mathbf{r}(t) = t \cos t \mathbf{i} + t \sin t \mathbf{j} + t \mathbf{k}$, $t \ge 0$, lies on the surface of the form z = f(x,y). Find f(x,y). Describe (or sketch) the curve.
- (b) Find a vector equation of the line tangent to the graph of

$$\mathbf{r}(t) = t^2 \mathbf{i} - \frac{1}{t+1} \mathbf{j} + (4-t^2) \mathbf{k}$$

at the point (4,1,0) on the curve. Find also the arc length of the curve $\mathbf{r}(t)$ from point (4,1,0) to point (0,-1,4).

Solution:

(a) Let

$$x = t \cos t$$

$$y = t \sin t$$

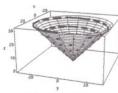
$$x = t$$

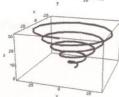
$$\therefore x^2 + y^2 = t^2 = x^2$$

$$\therefore x^{2} + y^{2} = t^{2} = x^{2}$$
 i.e., $z = f(x, y) = \sqrt{x^{2} + y^{2}}$

(only take +ve root since z = t > 0).

The curve lies on the cone $z = \sqrt{x^2 + y^2}$ ($\phi = \pi/4$).





(b)
$$\mathbf{r}'(t) = 2t \, \mathbf{i} + \frac{1}{(t+1)^2} \, \mathbf{j} - 2t \, \mathbf{k}.$$

At (4,1,0), t = -2, so r'(-2) = -4i + j + 4k. Therefore

$$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$$

= $(4, 1, 0) + t(-4, 1, 4)$.

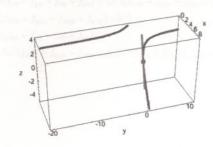
At (0,-1,4), t=0, the required arc length is with starting point at t=-2 to the end point t=0. Note that the graph does not define at t=-1, hence the arc length from t=-2 to t=0 cannot be defined. Even if you don't realize that, from one variable calculus, you have some problem too in the integrand, because

$$\mathbf{r}'(t) = 2t\mathbf{i} - (-1)(t+1)^{-2}\mathbf{j} + (-2t)\mathbf{k}$$
$$\|\mathbf{r}'\|^2 = 4t^2 + \frac{1}{(t+1)^4} + 4t^2$$

and

$$s = \int_{-2}^{0} ||\mathbf{r}'(t)|| dt.$$

The integrand yet is not defined at l = -1.



Problem 4 (20 points)

Your Score:

- (a) Find the equation of the level curve of the function x = g(x, y) = xf(xy) at the point (x_0, y_0) , where both f and g are differentiable. Show that $\nabla g(x_0, y_0)$ is normal to the tangent line to the level curve at (x_0, y_0) .
- (b) If w = f(x, y) (assume f is differentiable) and $x = s^2 + t^2$, $y = s^2 t^2$, use the chain rule to find (i) w_s , (ii) w_{st} and (iii) w_{stt} .

Solution:

(a) The equation of the level curve at the point (x_0, y_0) is

$$xf(xy) = x_0 f(x_0 y_0).$$

Differentiation both sides of the equation wrt x, then

$$xf'(xy)\left[x\frac{dy}{dx} + y\right] + f(xy) = 0$$
$$\frac{dy}{dx} = -\frac{xyf'(xy) + f(xy)}{x^2f'(xy)}.$$

Also

$$\nabla g = \left(\frac{\partial g}{\partial x}, \frac{\partial g}{\partial y}\right) = (xyf'(xy) + f(xy), x^2f'(xy)).$$

Therefore $\left. \frac{dy}{dx} \right|_{(x_0,y_0)} \times [\text{slope of } \nabla g(x_0,y_0)] = -1,$

i.e. they must be normal to each other.

(b)

f or its higher order derivative



(i)
$$w_s = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial f}{\partial s}$$
$$= f_x(2s) + f_y(2s)$$
$$= 2s(f_x + f_y)$$

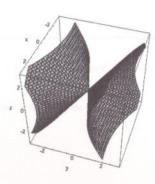
(ii)
$$\begin{aligned} w_{st} &= 2s \frac{\partial}{\partial t} (f_x + f_y) \\ &= 2s \left[\frac{\partial}{\partial x} (f_x + f_y) \frac{\partial x}{\partial t} + \frac{\partial}{\partial y} (f_x + f_y) \frac{\partial y}{\partial t} \right] \\ &= 2s [(f_{xx} + f_{yx})(2t) + (f_{xy} + f_{yy})(-2t)] \\ &= 4st [f_{xx} - f_{yy} - f_{xy} + f_{yx}] = 4stG \\ \text{where } G = f_{xx} - f_{yy} - f_{xy} + f_{yx}. \end{aligned}$$

(iii)
$$\begin{aligned} w_{stt} &= 4s(f_{xx} - f_{yy} - f_{xy} + f_{yz}) + 4st \left[\frac{\partial G}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial G}{\partial y} \frac{\partial y}{\partial t} \right] \\ &= 4s(f_{xx} - f_{yy} - f_{xy} + f_{yx}) + 4st \left\{ [f_{xxx} - f_{yyx} - f_{xyx} + f_{yxx}](2t) \right. \\ &+ [f_{xxy} - f_{yyy} - f_{xyy} + f_{yxy}](-2t) \} \\ &= 4s(f_{xx} - f_{yy} - f_{xy} + f_{yx}) \\ &+ 8st^2 (f_{xxx} - f_{yyx} - f_{xyx} + f_{yxx} - f_{xxy} + f_{yyy} + f_{xyy} - f_{yxy}). \end{aligned}$$

Find the point(s) on the surface $z^2 = -\frac{1}{2}x^2 + 2y^2 + xy$ that are closest to the point $\left(-\frac{1}{2}, -3, 0\right)$

- (a) by reducing the problem to an unconstrained problem in two variables, and
- (b) using the method of Lagrange multipliers.

Solution:



(a)

$$D_{s} = d^{2} = \left(x + \frac{1}{2}\right)^{2} + (y + 3)^{2} + z^{2}$$

$$= x^{2} + x + \frac{1}{4} + y^{2} + 6y + 9 - \frac{1}{2}x^{2} + 2y^{2} + xy$$

$$= \frac{1}{2}x^{2} + 3y^{2} + xy + x + 6y + 9\frac{1}{4}.$$

$$\frac{\partial D_{s}}{\partial x} = x + y + 1$$

$$\frac{\partial D_{s}}{\partial y} = 6y + x + 6.$$

For critical point, $\frac{\partial D_s}{\partial x} = \frac{\partial D_s}{\partial y} = 0 \quad \Rightarrow \quad x = 0, \ y = -1,$

$$\frac{\partial^2 D_s}{\partial x^2} = 1, \quad \frac{\partial^2 D_s}{\partial y^2} = 6, \quad \frac{\partial^2 D_s}{\partial x \partial y} = 1.$$

so $D=1\times 6-1=5>0$ and $\frac{\partial^2 D_s}{\partial x^2}>0,$ therefore (0,-1) is a min point.

When x = 0, y = -1, $z = \pm \sqrt{2}$, therefore the required point are $(0, -1, \pm \sqrt{2})$.

(b) Alternatively, minimize

$$D_s = f(x, y, z)$$
$$= \left(x + \frac{1}{2}\right)^2 + (y + 3)^2 + z^2$$

subject to

$$g(x, y, z) = z^2 + \frac{1}{2}x^2 - 2y^2 - xy = 0.$$

Then

$$\nabla f = \left(2\left(x + \frac{1}{2}\right), 2(y+3), 2z\right)$$
$$\nabla g = (x - y, -4y - x, 2z)$$

from Lagrange multipliers, $\nabla f = \lambda \nabla g$, we have

$$2\left(x + \frac{1}{2}\right) = \lambda(x - y) \tag{1}$$

$$2(y+3) = \lambda(4y-x) \tag{2}$$

$$2z = \lambda 2z \tag{3}$$

from (3), $\lambda = 1$, then from (1) and (2)

$$\begin{cases} 2x+1=x-y \\ 2y+6=-4y-x \end{cases} \Rightarrow \begin{cases} x=0 \\ y=-1 \end{cases}.$$

From the constant equation

$$z = \pm \sqrt{2}$$

... The required points are $(0, -1, \pm \sqrt{2})$.

If z=0 and $\lambda \neq 1$, then we need to solve these two equations $-0.5x^2+2y^2+xy=0$ and $2x^2-2y^2-6xy-10y+7x=0$. By using some numerical methods!!, you should obtain three points (x,y)=(0,0), (-2.721,2,201) and (86.721,26.798) to satisfy the above two equations. Compute the distance from (-0.5,-3) to these three points and we find that they are not the shortest distance.

