

MATH 2023 • Multivariable Calculus
Problem Set #1 • Lines, Planes and Curves

1. (★) Consider the two straight-lines:

$$L_1 : \mathbf{r}_1(t) = \langle 1, 2, 3 \rangle + t \langle 1, -1, -1 \rangle$$

$$L_2 : \mathbf{r}_2(t) = \langle 2 + t, 3 - 3t, -2 + 3t \rangle$$

- (a) Show that L_1 and L_2 intersect each other. Find the coordinates of the intersection point.
 (b) Find an equation of the plane containing both L_1 and L_2 .
2. (★) Consider the following four points in three-dimensional space:

$$A(0, 2, -1), B(4, 0, -1), C(7, -3, 0) \text{ and } D\left(\frac{1}{3}, \frac{1}{6}, \frac{1}{9}\right)$$

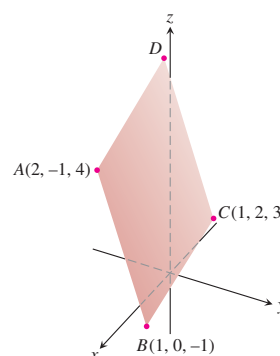
Determine whether or not these four points are coplanar (i.e. contained in a single plane).

3. (★) A parallelogram in \mathbb{R}^3 has vertices:

$$A(2, -1, 4), B(1, 0, -1), C(1, 2, 3), D(x_0, y_0, z_0)$$

as shown in the figure below. Answer the following questions:

- (a) Find the coordinates of D .
 (b) Find the area of the parallelogram $ABCD$.
 (c) Find an equation of the plane containing the parallelogram $ABCD$.
 (d) Project the parallelogram $ABCD$ orthogonally onto the plane $z = -1$. Find the coordinates the projection of each vertices, then find the area of the *projected* parallelogram.



4. (★) Consider a particle whose path is represented by:

$$\mathbf{r}(t) = (\ln(t^2 + 1)) \mathbf{i} + (\tan^{-1} t) \mathbf{j} + \sqrt{t^2 + 1} \mathbf{k}$$

Find the velocity, speed and acceleration of the particle at $t = 0$.

5. (★★) Consider a plane through the point $P_0(x_0, y_0, z_0)$ with normal vector $\mathbf{n} = \langle A, B, C \rangle$. Prove that the perpendicular distance d from a given point $Q(x_1, y_1, z_1)$ to the plane is given by:

$$d = \frac{|\overrightarrow{P_0Q} \cdot \mathbf{n}|}{|\mathbf{n}|} = \left| \frac{Ax_1 + By_1 + Cz_1 - D}{\sqrt{A^2 + B^2 + C^2}} \right|$$

where $D = Ax_0 + By_0 + Cz_0$.

6. (★) Suppose $\mathbf{r}(t)$ represents the path of a particle traveling on a sphere centered at the origin. Show that the position vector $\mathbf{r}(t)$ and the velocity $\mathbf{r}'(t)$ are orthogonal to each other at any time.

7. (★★) Suppose that the path of a particle at time t is given by $\mathbf{r}(t)$ and the force exerted on the particle at time t is $\mathbf{F}(t)$. By Newton's Second Law, $\mathbf{F}(t)$ and $\mathbf{r}(t)$ are related by:

$$\mathbf{F}(t) = m\mathbf{r}''(t),$$

where m is the mass of the particle. The angular momentum $\mathbf{L}(t)$ about the origin of the particle at time t is defined to be:

$$\mathbf{L}(t) := \mathbf{r}(t) \times m\mathbf{r}'(t)$$

- (a) Show that

$$\frac{d}{dt}\mathbf{L}(t) = \mathbf{r}(t) \times \mathbf{F}(t).$$

- (b) When $\mathbf{L}(t)$ is a constant vector, we say that the angular momentum is *conserved*. According to the result in (a), under what condition on $\mathbf{r}(t)$ and $\mathbf{F}(t)$ will the angular momentum be conserved? Also, give one example in physics that this condition is satisfied.
8. (★★) Consider two point particles with masses m_1 and m_2 , and their trajectories are $\mathbf{r}_1(t)$ and $\mathbf{r}_2(t)$ respectively. Denote $\mathbf{F}(t)$ to be the force exerted on the m_1 -particle by the m_2 -particle at time t . By Newton's Third Law, the force exerted on the m_2 -particle by the m_1 -particle at time t (i.e. the reverse force) is given by $-\mathbf{F}(t)$. Assume there are no other forces exerted on any of these particles.

- (a) Consider the following vector:

$$\mathbf{C}(t) := \frac{m_1\mathbf{r}_1(t) + m_2\mathbf{r}_2(t)}{m_1 + m_2}.$$

In physics, this vector is pointing at the center of mass of the two particles. Show that $\mathbf{C}''(t) = \mathbf{0}$ for any t using Newton's Second and Third Laws.

- (b) Hence, show that there exist two constant vectors \mathbf{r}_0 and \mathbf{v} such that

$$\frac{m_1\mathbf{r}_1(t) + m_2\mathbf{r}_2(t)}{m_1 + m_2} = \mathbf{r}_0 + t\mathbf{v}.$$

[Question: What is the physical significance of this result?]

9. (★) For each of the following curves, first reparametrize it by arc-length and then compute its curvature function $\kappa(s)$:
- (a) $\mathbf{r}_1(t) = (R \cos \omega t) \mathbf{i} + (R \sin \omega t) \mathbf{j}, \quad 0 \leq t \leq \frac{2\pi}{\omega}.$
- (b) $\mathbf{r}_2(t) = \langle 1, 2, 3 \rangle + (\ln t) \langle 1, 0, -1 \rangle, \quad 0 < t < \infty$
- (c) $\mathbf{r}_3(t) = (\cos^3 t) \mathbf{i} + (\sin^3 t) \mathbf{j}, \quad 0 \leq t \leq \frac{\pi}{2}.$

Give an example of a path whose arc-length parametrization cannot be explicitly found even with computer softwares.

10. (★★) Suppose

$$\mathbf{r}(t) = \frac{1}{2}t^2\mathbf{i} + \frac{2\sqrt{2}}{3}t^{\frac{3}{2}}\mathbf{j} + t\mathbf{k}$$

represents the path of a race-car climbing up a hill from $(0, 0, 0)$ at $t = 0$. A truck, on the other hand, drives slowly in unit speed from $(0, 0, 0)$ at time $t = 0$ along the same path and direction as the race-car. Find a parametrization which represents the path of the truck.

11. (★★★) We define the curvature of a path by $\kappa(s) = |\mathbf{r}''(s)|$ where $\mathbf{r}(s)$ is the arc-length parametrization of the path. However, the arc-length parametrization $\mathbf{r}(s)$ is often difficult to find explicitly. The purpose of this exercise is to derive an equivalent formula for the curvature which does not require finding an arc-length parametrization.

Given a path $\mathbf{r}(t)$, we let $\mathbf{r}(s)$ be its arc-length parametrization so that s and t are related by:

$$s = \int_0^t |\mathbf{r}'(\tau)| d\tau.$$

- (a) Show, using the chain rule, that:

$$\begin{aligned}\mathbf{r}'(t) &= \mathbf{r}'(s) \frac{ds}{dt} \\ \mathbf{r}''(t) &= \mathbf{r}''(s) \left(\frac{ds}{dt}\right)^2 + \mathbf{r}'(s) \frac{d^2s}{dt^2}\end{aligned}$$

- (b) Show that:

$$\mathbf{r}'(t) \times \mathbf{r}''(t) = \left(\frac{ds}{dt}\right)^3 \mathbf{r}'(s) \times \mathbf{r}''(s)$$

- (c) Using (a) and (b), show that the curvature, which is defined as $\kappa(s) := |\mathbf{r}''(s)|$, can be expressed in terms of t as:

$$\kappa(t) = \frac{|\mathbf{r}'(t) \times \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3}$$

Although it looks more complicated, this formula does not require the procedure of finding arc-length parametrization.

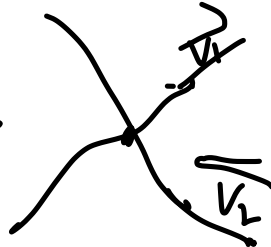
1. (★) Consider the two straight-lines:

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- (a) Show that L_1 and L_2 intersect each other. Find the coordinates of the intersection point.
(b) Find an equation of the plane containing both L_1 and L_2 .

$\langle 1, -1, -1 \rangle \neq \langle 1, -3, 3 \rangle$



$\langle 3, 0, 1 \rangle$

$$x = 1 + t_1 = 2 + t_2$$

$$y = 2 - t_1 = 3 - 3t_2$$

$$z = 3 - t_1 = -2 + 3t_2$$

$$t_1 = 1 + t_2$$

$$t_1 = -1 + 3t_2$$

$$t_1 = 5 - 3t_2$$

$$2t_1 = 4$$

$$t_1 = 2$$

$$t_1 = 2, \\ t_2 = 1.$$

$$\langle 1, -1, -1 \rangle \times \langle 1, -3, 3 \rangle$$

$$= \begin{vmatrix} i & j & k \\ 1 & -1 & -1 \\ 1 & -3 & 3 \end{vmatrix} = \langle -6, -4, -2 \rangle$$

$$= \langle 3, 2, 1 \rangle$$

$$3x + 2y + z = 10$$

2. (★) Consider the following four points in three-dimensional space:

$$A(0, 2, -1), B(4, 0, -1), C(7, -3, 0) \text{ and } D\left(\frac{1}{3}, \frac{1}{6}, \frac{1}{9}\right)$$

Determine whether or not these four points are coplanar (i.e. contained in a single plane).

$$\vec{AB} = \langle 4, -2, 0 \rangle$$

$$\vec{AC} = \langle 7, -5, 1 \rangle$$

$$\vec{AD} = \left\langle \frac{1}{3}, -\frac{11}{6}, \frac{10}{9} \right\rangle$$

$$\vec{AB} \times \vec{AC} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 4 & -2 & 0 \\ 7 & -5 & 1 \end{vmatrix} =$$

$$\langle -2, -4, -4 \rangle = -2 \langle 1, 2, 3 \rangle$$

$$\langle 1, 2, 3 \rangle \cdot \left\langle \frac{1}{3}, -\frac{11}{6}, \frac{10}{9} \right\rangle$$

$$= \frac{1}{3} - \frac{11}{3} + \frac{10}{3} = 0.$$

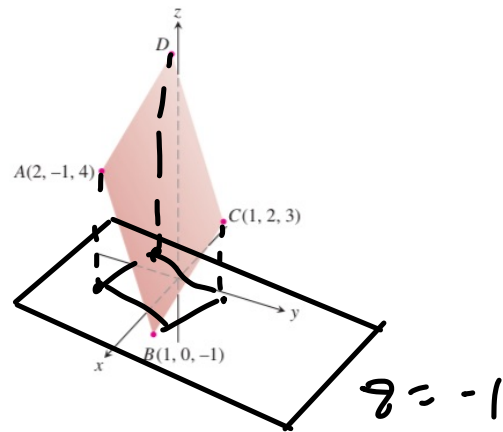
\therefore They are coplanar

3. (★) A parallelogram in \mathbb{R}^3 has vertices:

$$A(2, -1, 4), \quad B(1, 0, -1), \quad C(1, 2, 3), \quad D(x_0, y_0, z_0)$$

as shown in the figure below. Answer the following questions:

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- Find an equation of the plane containing the parallelogram $ABCD$.
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$$\vec{BC} = \langle 0, 2, 4 \rangle$$

$$\vec{AD} = \vec{BC} = \langle 0, 2, 4 \rangle$$

$$\langle x_0 - 2, y_0 + 1, z_0 - 4 \rangle = \langle 0, 2, 4 \rangle$$

$$\langle x_0, y_0, z_0 \rangle = \langle 2, 1, 8 \rangle$$

$$\begin{aligned} \text{b). } \vec{BA} &= \langle 1, -1, 5 \rangle \\ \vec{BA} \times \vec{BC} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & -1 & 5 \\ 0 & 2 & 4 \end{vmatrix} \\ &= \langle -14, -4, 2 \rangle \end{aligned}$$

$$| \langle -14, -4, 2 \rangle |$$

$$= \sqrt{14^2 + 4^2 + 2^2}$$

$$= \sqrt{196 + 16 + 4}$$

$$= \sqrt{216} \quad \checkmark$$

$$(1, 0, -1)$$

$$-14x - 4y + 2z = -16$$

$$7x + 2y - z = 8 \quad \checkmark$$

$$(d) \quad A: (2, -1)$$

$$B: (1, 0)$$

$$C: (1, 2)$$

$$D: (2, 1)$$

$$\overrightarrow{AB} = \langle -1, 1 \rangle$$

$$\overrightarrow{AC} = \langle -1, 3 \rangle$$

$$\overrightarrow{AB} \times \overrightarrow{AC} = \langle 0, 0, -2 \rangle$$

$$\begin{vmatrix} i & j & k \\ -1 & 1 & 0 \\ -1 & 3 & 0 \end{vmatrix} \quad \text{Area} = 2 \quad \checkmark$$

4. (★) Consider a particle whose path is represented by:

$$\mathbf{r}(t) = (\ln(t^2 + 1)) \mathbf{i} + (\tan^{-1} t) \mathbf{j} + \sqrt{t^2 + 1} \mathbf{k}$$

Find the velocity, speed and acceleration of the particle at $t = 0$.

$$\vec{v}'(t) = \frac{2t}{t^2+1} \mathbf{i} + \frac{1}{1+t^2} \mathbf{j} + \frac{1}{2}(t^2+1)^{-\frac{1}{2}}(2t) \mathbf{k}$$

$$\text{at } t=0: \langle 0, 1, 0 \rangle$$

$$= \frac{2t}{t^2+1} \mathbf{i} + \frac{1}{1+t^2} \mathbf{j} + \frac{t}{\sqrt{t^2+1}} \mathbf{k}$$

$$\text{speed} = |\vec{v}'(t)| = \sqrt{\frac{4t^2 + t^2 + 1}{(t^2+1)^2}}$$

$$|\vec{v}'(t)| = \sqrt{\frac{5t^2 + 1}{(t^2+1)^2}}$$

$$|\vec{v}'(t)| = 1$$

$$\vec{a}(t) = \frac{2(t^2+1) - (t)(2t)}{(t^2+1)^2} \hat{i} +$$

$$\frac{-(t^2+1)}{(t^2+1)^2} \hat{j} +$$

$$\frac{(t^2+1) - t(2t)}{(t^2+1)^2} \hat{k}$$

$$= \frac{2-2t^2}{(t^2+1)^2} \hat{i} -$$

$$\frac{1}{t^2+1} \hat{j} +$$

$$\frac{1-t^2}{(t^2+1)^2} \hat{k}$$

At $t=0$, $\vec{a}(0) = \langle 2, 1, 1 \rangle$

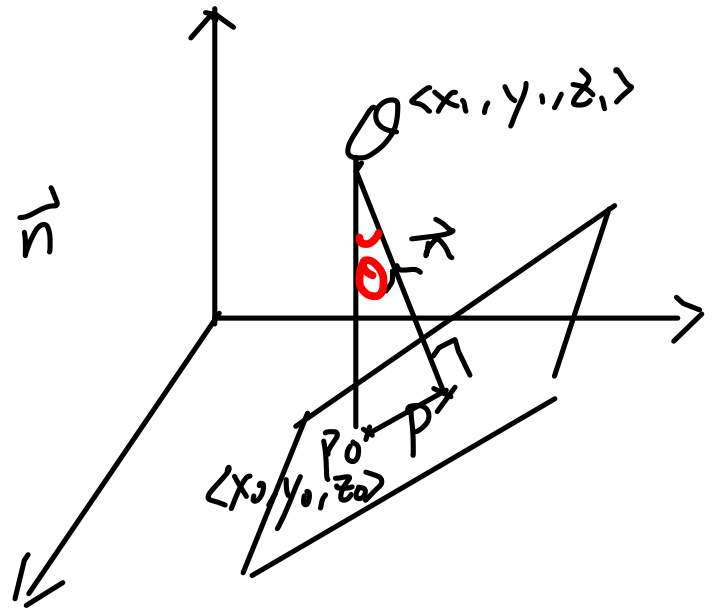
5. (★★) Consider a plane through the point $P_0(x_0, y_0, z_0)$ with normal vector $\mathbf{n} = \langle A, B, C \rangle$. Prove that the perpendicular distance d from a given point $Q(x_1, y_1, z_1)$ to the plane is given by:

$$d = \frac{|\overrightarrow{P_0Q} \cdot \mathbf{n}|}{|\mathbf{n}|} = \left| \frac{Ax_1 + By_1 + Cz_1 - D}{\sqrt{A^2 + B^2 + C^2}} \right|$$

where $D = Ax_0 + By_0 + Cz_0$.

distance = $\overrightarrow{P_0Q}$ project on \vec{n}

$$\frac{\overrightarrow{P_0Q} \cdot \vec{n}}{|\vec{n}|}$$



$$= \frac{\langle x_1 - x_0, y_1 - y_0, z_1 - z_0 \rangle \cdot \langle A, B, C \rangle}{\sqrt{A^2 + B^2 + C^2}}$$

6. (★) Suppose $\mathbf{r}(t)$ represents the path of a particle traveling on a sphere centered at the origin. Show that the position vector $\mathbf{r}(t)$ and the velocity $\mathbf{r}'(t)$ are orthogonal to each other at any time.

$$\mathbf{r}(t) \cdot \mathbf{r}(t) = |\mathbf{r}(t)|^2$$

$$2 \mathbf{r}(t) \cdot \mathbf{r}'(t) = 0$$

$$|\mathbf{r}(t)|^2 = c^2$$

$$\frac{d}{dt} c^2 = 0.$$

7. (★★) Suppose that the path of a particle at time t is given by $\mathbf{r}(t)$ and the force exerted on the particle at time t is $\mathbf{F}(t)$. By Newton's Second Law, $\mathbf{F}(t)$ and $\mathbf{r}(t)$ are related by:

$$\mathbf{F}(t) = m\mathbf{r}''(t),$$

where m is the mass of the particle. The angular momentum $\mathbf{L}(t)$ about the origin of the particle at time t is defined to be:

$$\mathbf{L}(t) := \mathbf{r}(t) \times m\mathbf{r}'(t)$$

- (a) Show that

$$\frac{d}{dt}\mathbf{L}(t) = \mathbf{r}(t) \times \mathbf{F}(t).$$

- (b) When $\mathbf{L}(t)$ is a constant vector, we say that the angular momentum is *conserved*. According to the result in (a), under what condition on $\mathbf{r}(t)$ and $\mathbf{F}(t)$ will the angular momentum be conserved? Also, give one example in physics that this condition is satisfied.

$$\begin{aligned} \frac{d}{dt} \mathbf{L}(t) &= \mathbf{r}(t) \times \frac{d}{dt} m\mathbf{r}'(t) + \\ &\quad \mathbf{r}'(t) \times m\mathbf{r}'(t) \end{aligned}$$

$$= \mathbf{r}(t) \times m\mathbf{r}''(t) + \mathbf{r}'(t) \times m\mathbf{r}'(t)$$

$$= \mathbf{r}(t) \times \mathbf{F}(t) + 0$$

$$= \mathbf{r}(t) \times \mathbf{F}(t).$$

b). When $\mathbf{L}(t) = \text{constant}$, $\frac{d}{dt} \mathbf{L}(t) = 0$

$$\mathbf{r}(t) \times \mathbf{F}(t) = 0$$

$$\mathbf{r}(t) = \mathbf{F}(t)$$

反力 = 外力
parallel. 同向.

→ straight line motion.

8. (★★) Consider two point particles with masses m_1 and m_2 , and their trajectories are $\mathbf{r}_1(t)$ and $\mathbf{r}_2(t)$ respectively. Denote $\mathbf{F}(t)$ to be the force exerted on the m_1 -particle by the m_2 -particle at time t . By Newton's Third Law, the force exerted on the m_2 -particle by the m_1 -particle at time t (i.e. the reverse force) is given by $-\mathbf{F}(t)$. Assume there are no other forces exerted on any of these particles.

(a) Consider the following vector:

$$\mathbf{C}(t) := \frac{m_1 \mathbf{r}_1(t) + m_2 \mathbf{r}_2(t)}{m_1 + m_2}.$$

In physics, this vector is pointing at the center of mass of the two particles. Show that $\mathbf{C}''(t) = \mathbf{0}$ for any t using Newton's Second and Third Laws.

(b) Hence, show that there exist two constant vectors \mathbf{r}_0 and \mathbf{v} such that

$$\frac{m_1 \mathbf{r}_1(t) + m_2 \mathbf{r}_2(t)}{m_1 + m_2} = \mathbf{r}_0 + t\mathbf{v}.$$

[Question: What is the physical significance of this result?]



9. (★) For each of the following curves, first reparametrize it by arc-length and then compute its curvature function $\kappa(s)$:

(a) $\mathbf{r}_1(t) = (R \cos \omega t) \mathbf{i} + (R \sin \omega t) \mathbf{j}, \quad 0 \leq t \leq \frac{2\pi}{\omega}.$

(b) $\mathbf{r}_2(t) = \langle 1, 2, 3 \rangle + (\ln t) \langle 1, 0, -1 \rangle, \quad 0 < t < \infty$

(c) $\mathbf{r}_3(t) = (\cos^3 t) \mathbf{i} + (\sin^3 t) \mathbf{j}, \quad 0 \leq t \leq \frac{\pi}{2}.$

Give an example of a path whose arc-length parametrization cannot be explicitly found even with computer softwares.

$$a). \mathbf{r}'(t) = (-R\omega \sin \omega t) \mathbf{i} + (R\omega \cos \omega t) \mathbf{j}$$

$$|\mathbf{r}'(t)| = R\omega$$

$$s = \int_0^t R\omega \, dt$$

$$s = R\omega t$$

$$t = \frac{s}{R\omega}$$

$$\mathbf{r}(s) = R \cos\left(\frac{s}{R}\right) \mathbf{i} + R \sin\left(\frac{s}{R}\right) \mathbf{j}$$

b)- (b) $\mathbf{r}_2(t) = \langle 1, 2, 3 \rangle + (\ln t) \langle 1, 0, -1 \rangle, \quad 0 < t < \infty$

$$\mathbf{r}_2'(t) = \left\langle \frac{1}{t}, 0, -\frac{1}{t} \right\rangle$$

$$|\mathbf{r}_2'(t)| = \sqrt{\frac{2}{t^2}} = \frac{\sqrt{2}}{t}$$

$$s = \int_1^t \frac{\sqrt{2}}{t} dt$$

$$s = \left[\sqrt{2} \ln t \right]_1^t$$

$$s = \sqrt{2} \ln t$$

$$\frac{s}{\sqrt{2}} = \ln t$$

$$t = e^{\frac{s}{\sqrt{2}}}$$

$$\mathbf{r}_2(t) = \langle 1, 2, 3 \rangle + \left(\ln e^{\frac{s}{\sqrt{2}}} \right) \langle 1, 0, -1 \rangle$$

$$\mathbf{r}_2(t) = \langle 1, 2, 3 \rangle + \frac{s}{\sqrt{2}} \langle 1, 0, -1 \rangle$$

$$|\mathbf{r}'(s)| = \text{curvature.}$$

$$(c) \mathbf{r}_3(t) = (\cos^3 t) \mathbf{i} + (\sin^3 t) \mathbf{j}, \quad 0 \leq t \leq \frac{\pi}{2}.$$

$$\mathbf{r}_3'(t) = (-3\cos^2 t \sin t) \mathbf{i} + (3\sin^2 t \cos t) \mathbf{j}$$

$$|\mathbf{v}_3'(t)| = \sqrt{9\cos^4 t \sin^2 t + 9\sin^4 t \cos^2 t}$$

$$|\mathbf{v}_3'(t)| = 3.$$

$$s = \int_0^t 3 \, d\tau$$

$$s = 3t$$

$$t = \frac{s}{3}$$

$$\vec{r}_3(t) = \cos^3\left(\frac{s}{3}\right) \mathbf{i} + \sin^3\left(\frac{s}{3}\right) \mathbf{j}$$

10. (★★) Suppose

$$\mathbf{r}(t) = \frac{1}{2}t^2\mathbf{i} + \frac{2\sqrt{2}}{3}t^{\frac{3}{2}}\mathbf{j} + t\mathbf{k}$$

represents the path of a race-car climbing up a hill from $(0,0,0)$ at $t = 0$. A truck, on the other hand, drives slowly in unit speed from $(0,0,0)$ at time $t = 0$ along the same path and direction as the race-car. Find a parametrization which represents the path of the truck.

$$\mathbf{r}'(t) = t\mathbf{i} + \sqrt{2}t^{\frac{1}{2}}\mathbf{j} + \mathbf{k}$$

$$|\mathbf{r}'(t)| = t+1$$

$$s = \int_0^t \tau+1 d\tau$$

$$s = \left[\frac{\tau^2}{2} + \tau \right]_0^t$$

$$s = \frac{t^2}{2} + t$$

