

1 Review

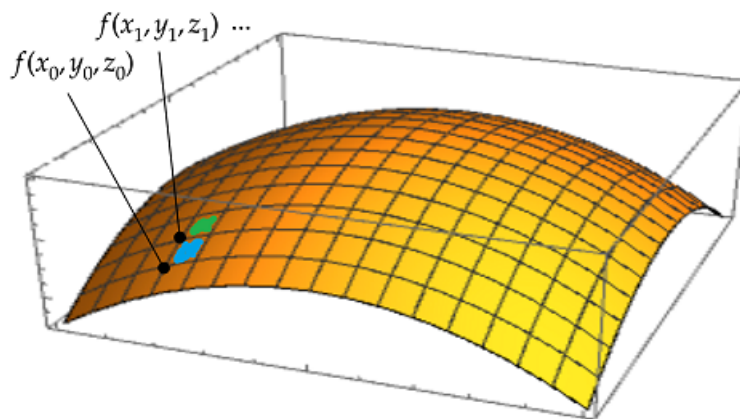
- The **surface area** of S parametrized by $\mathbf{r}(u, v)$ is given by

$$A(S) = \int \int_D |\mathbf{r}_u \times \mathbf{r}_v| dA.$$

- The **surface integral for function f** over S is defined by

$$\int_S f dS = \int \int_D f(x(u, v), y(u, v), z(u, v)) |\mathbf{r}_u \times \mathbf{r}_v| dv du.$$

Interpretation: We are summing the value of function a point multiplied by a differential area of a small patch.

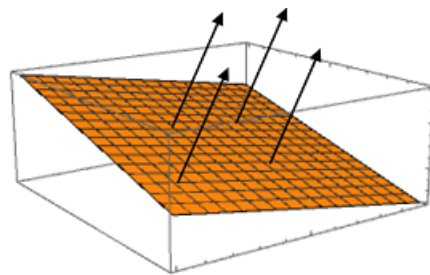


- The **surface integral for vector field** over S is defined by

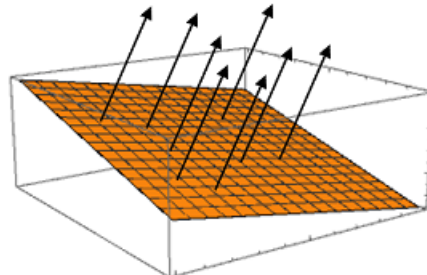
$$\int_S \mathbf{F} \cdot \mathbf{n} dS = \int \int_D \langle P(u, v), Q(u, v), R(u, v) \rangle \cdot \langle n_1(u, v), n_2(u, v), n_3(u, v) \rangle du dv$$

for normal vector of S \mathbf{n} (**very important:** \mathbf{n} necessary to be unit in length).

Interpretation: The measure of flux of vector field (component of the vector field parallel to the normal vector) through a surface (you may non-rigorously think of it as counting the number of vector field line passing through the surface).



fewer flux



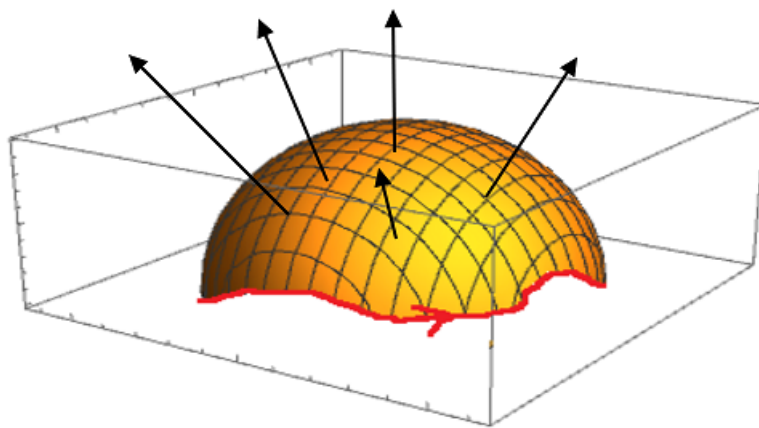
more flux

- **Stoke's Theorem:** The line integral over a closed curve is:

$$\oint_{\partial S} \mathbf{F} \cdot d\mathbf{r} = \int \int_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} dA$$

where S is a surface with ∂S as boundary and \mathbf{n} is the unit normal vector of the surface of obeying the *positive orientation* (satisfying the right hand grip rule).

Interpretation: Stoke's theorem said the loop integral of a vector field can be calculated by measuring the flux of the *curl* through the surface with the concerned curve as the boundary.



The arrows are the vector field lines of the curl of the vector field.

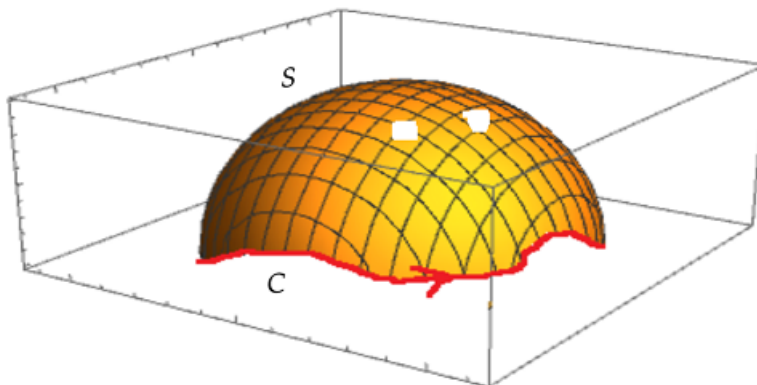
2 Problems

1. True or False

- (a) The constant vector field $\mathbf{F}(x, y, z) = \langle 1, -1/2, -1/2 \rangle$ has a non-vanishing flux through the surface $x + y + z = 1$.

False. Normal of surface: $\mathbf{n} = \frac{1}{\sqrt{3}}\langle 1, 1, 1 \rangle$. So $\mathbf{F} \cdot \mathbf{n} = 0$, vanishing.

- (b) In the following diagram, $\oint_C \mathbf{F} \cdot d\mathbf{r} = \int_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} dS$ is still satisfied, where S is a surface with holes.



False. Intuitively: if we got another surface with the holes covered, the contribution will be different in the surface integral.

More mathematically: The boundary of the surface is not only the curve, the curve at the boundary of the holes are also counted as the boundaries (see generalized Stoke's Theorem).

2. Evaluate $\int \int_S (x^2 z + y^2 z) dS$, where S is the upper hemisphere with radius 2.

Solution: Using the parametrization $\mathbf{r}(u, v) = \langle r_0 \sin u \cos v, r_0 \sin u \sin v, r_0 \cos u \rangle$, then $|\mathbf{r}_u \times \mathbf{r}_v| = r_0^2 \sin u$ (refer to tutorial 10). Then,

$$\int \int_S (x^2 z + y^2 z) dS = \int_0^{2\pi} \int_0^{\pi/2} [(r_0 \sin u \cos v)^2 r_0 \cos u + (r_0 \sin u \sin v)^2 r_0 \cos u] r_0^2 \sin u du dv$$

3. Let $\mathbf{F}(x, y, z) = \mathbf{r}/|\mathbf{r}|^3$, where $\mathbf{r} = \langle x, y, z \rangle$. Show that the flux through the surface of the sphere is independent of the radius.

Solution: Using the spherical parametrization (denote it by $\mathbf{R}(u, v)$ in this question to avoid confusion), then $|\mathbf{R}_u \times \mathbf{R}_v| = r_0^2 \sin u$, where r_0 is the radius of the sphere, then the evaluation of the surface integral is as follows:

$$\begin{aligned} \int \int_S \mathbf{F} \cdot \mathbf{n} dS &= \int_0^{2\pi} \int_0^{\pi} \frac{\mathbf{r}}{|\mathbf{r}|^3} \cdot \frac{\mathbf{r}}{|\mathbf{r}|} r_0^2 \sin u du dv \\ &= \int_0^{2\pi} \int_0^{\pi} \sin u du dv \quad (\mathbf{r} \cdot \mathbf{r} = x^2 + y^2 + z^2 = r_0^2) \\ &= 4\pi \quad (\text{independent of } r_0) \end{aligned}$$

4. Find the center of mass of a hemisphere shell assuming uniform density.

Solution: Suppose σ is the constant density of mass, then again use the parametrization

of sphere with radius r_0 : $\mathbf{r}(u, v) = \langle r_0 \sin u \cos v, r_0 \sin u \sin v, r_0 \cos u \rangle$, then $|\mathbf{r}_u \times \mathbf{r}_v| = r_0^2 \sin u$. Then, then center of mass is given by

$$\begin{aligned}\bar{\mathbf{r}} &= \int \int_S \mathbf{r} dm \bigg/ \int \int_S dm \quad (\text{integrate the center of mass coordinates all at once}) \\ &= \int_0^{2\pi} \int_0^{\pi/2} \mathbf{r} \sigma |\mathbf{r}_u \times \mathbf{r}_v| du dv \bigg/ \int_0^{2\pi} \int_0^{\pi/2} \sigma |\mathbf{r}_u \times \mathbf{r}_v| du dv \\ &= \int \int_S \mathbf{r} \sigma dS \bigg/ \int \int_S \sigma dS \\ &= \int_0^{2\pi} \int_0^{\pi/2} \sigma r_0^3 \langle (\sin u)^2 \cos v, (\sin u)^2 \sin v, \sin u \cos u \rangle du dv \bigg/ \sigma (2\pi r_0^2) \\ &= \langle 0, 0, r_0/2 \rangle\end{aligned}$$

5. Use Stoke's Theorem to evaluate the close loop integral $\oint_C \mathbf{F} \cdot d\mathbf{r}$, where $\mathbf{F}(x, y, z) = \langle x + y^2, y + z^2, z + x^2 \rangle$ over C , where C is the triangle with vertices $(1, 0, 0)$, $(0, 1, 0)$, $(0, 0, 1)$, where the loop is running counterclockwise if we view from infinitely far away in the positive quadrant.

Solution: Parametrization of the concerned plane: $\mathbf{r}(u, v) = \langle u, v, 1 - u - v \rangle$. $\mathbf{r}_u \times \mathbf{r}_v = \langle 1, 1, 1 \rangle$. Notice that $|\mathbf{r}_u \times \mathbf{r}_v| \mathbf{n} = \mathbf{r}_u \times \mathbf{r}_v$ (given \mathbf{n} pointing in the appropriate direction up to sign). So we can calculate the integral through Stoke's Theorem

$$\begin{aligned}\oint_C \mathbf{F} \cdot d\mathbf{r} &= \int \int_R (\nabla \times \mathbf{F}) \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA \\ &= \int_0^1 \int_0^{1-u} (-2(1 - u - v) - 2u - 2v) dv du \\ &= -1\end{aligned}$$

6. Let C be the closed simple curve lies in the plane $x + y + z = 1$. Show that the line integral

$$\oint_C z dx - 2x dy + 3y dz$$

depends only on the area of the region enclosed by C and not on the shape of C or its location in the plane.

Solution:

$$\nabla \times \mathbf{F} = \langle 3, 1, -2 \rangle.$$

A parametrization of the plane is $\mathbf{r}(u, v) = \langle u, v, 1 - u - v \rangle$. Meanwhile, unit normal vector of the plane is $\mathbf{n} = \frac{1}{\sqrt{3}} \langle 1, 1, 1 \rangle$. From Stoke's Theorem,

$$\begin{aligned}\oint_C z dx - 2x dy + 3y dz &= \int \int_{D(C)} \langle 3, 1, -2 \rangle \cdot \mathbf{n} |\mathbf{r}_u \times \mathbf{r}_v| dA \\ &= M \int \int_{D(C)} |\mathbf{r}_u \times \mathbf{r}_v| dA\end{aligned}$$

where M is certain constant. Notice that the integral multiplied by M is the area enclosed on the plane. This proved the claim.

7. Evaluate

$$\oint_C (y + \sin x)dx + (z^2 + \cos y)dy + x^3 dz$$

where C is the curve $\mathbf{r}(t) = \langle \sin t, \cos t, \sin 2t \rangle$ for $0 \leq t \leq 2\pi$.

Solution: Notice that $z = 2xy$. Meanwhile,

$$\nabla \times \mathbf{F} = \langle -2z, -3x^2, -1 \rangle.$$

Positive orientation normal vector of the surface: $\mathbf{n} = \langle -z_x, -z_y, 1 \rangle = \langle -2y, -2x, 1 \rangle$.
So from Stoke's Theorem, we have

$$\begin{aligned} \oint_C z dx - 2x dy + 3y dz &= \int_0^1 \int_0^1 \langle -2z, -3x^2, -1 \rangle \cdot \langle -2y, -2x, 1 \rangle dy dx \\ &= \int_0^1 \int_0^1 \langle -4xy, -3x^2, -1 \rangle \cdot \langle -2y, -2x, 1 \rangle dy dx \\ &= \int_0^1 \int_0^1 (8xy^2 + 6x^3 - 1) dy dx \\ &= \int_0^1 \left(4y^2 + \frac{3}{2} - 1 \right) dx \\ &= \frac{4}{3} + \frac{1}{2} = \frac{15}{6}. \end{aligned}$$