

# KEVIN BIJU MATHEW

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## ABOUT

Robotics master's student at Purdue with a Mechatronics background, specializing in path planning, hardware integration, testing, and troubleshooting. Skilled in ROS2, sensor fusion, and computer vision, with cross-disciplinary experience enabling effective design and validation of autonomous systems. Currently seeking an internship opportunity to apply technical expertise and leadership skills to real-world robotics challenges.

## EDUCATION WORK EXPERIENCE

<b>Purdue University, West Lafayette</b>	2025 - 2027
Masters in Robotics/ Interdisciplinary Engineering   <b>GPA:</b> 3.67	
<b>Vellore Institute of Technology, Chennai, India</b>	2020 - 2024
B.Tech Mechatronics and Automation   <b>CGPA:</b> 9.09/10	
<b>Gulf Asian English School, U.A.E</b>	2018-2020
Higher Secondary   Marks = 90%	

## WORK EXPERIENCE

### Research Intern

<b>Center for Human Movement Analytics, VIT Chennai, India</b>	February 2025 – July 2025
<ul style="list-style-type: none"><li>Worked on state-of-the-art exoskeleton technologies for lower-body rehabilitation.</li><li>Proposed a remote-assisted lower-limb physiotherapy exoskeleton with Digital Twin and AR integration.</li><li>Developed a control strategy to ensure safe and responsive motion across different therapy modes.</li></ul>	
<b>Intern</b>	

<b>Indian Institute of Technology, Palakkad, India</b>	December 2024 – January 2025
<ul style="list-style-type: none"><li>Assisted research scholars with their thesis and funded projects, which include reconfigurable hybrid drone/quadruped, food delivery robot, and an all-terrain vehicle.</li><li>Developed Autonomous Navigation and Trajectory tracking algorithms on an AGV.</li></ul>	

## SKILLS

- Autonomy & Simulations:** ROS2, Gazebo, Rviz, Simulink, IPG Carmaker HIL/SIL testing, PLC.
- Perception & sensors:** LiDAR (SLAMTEC A1M8), depth camera, IMU, sensor fusion using extended Kalman filter.
- Controls & Embedded Systems:** Python, C++, Java, control algorithms ( PID, LQR, MPC), Open-CV, Jetson Nano, Raspberry Pi, Teensy, Arduino.
- Communication & Integration:** Serial Interfaces, I2C, CAN, RTOS.
- Validation & Testing:** Prototyping, Additive Manufacturing, System Debugging, Machine Vision Inspection.
- Software:** SolidWorks, Autodesk Fusion 360, MATLAB, Edge Impulse, NTTopology.

## PROJECTS

<b>Trajectory Planning &amp; Tracking for UR3E Robotic Arm (Signature Light Painting) (<a href="#">link</a>)</b>	Purdue   December 2025
<ul style="list-style-type: none"><li>Converted a handwritten signature into a smooth, arc length-parameterized trajectory and executed it using trapezoidal velocity planning.</li><li>Implemented forward and inverse kinematics using screw theory, validating smooth joint motion and singularity avoidance.</li></ul>	
<b>Autonomous Guided Vehicles (AGVs) with Modular Drive Mechanisms (<a href="#">link</a>)</b>	VIT   April 2024
<ul style="list-style-type: none"><li>Developed AGVs with interchangeable differential and mecanum drives using ROS2, enabling dynamic switching based on operational requirements for logistics operations.</li></ul>	
<b>Wheeled Mobile Robot with Robotic Arm (<a href="#">link</a>)</b>	VIT   December 2023
<ul style="list-style-type: none"><li>Developed a mobile robot with an integrated robotic arm using ROS2 for picking and placing objects using ROS2.</li></ul>	
<b>Hall Effect-Based Data Glove for Gesture Recognition</b>	VIT   December 2023
<ul style="list-style-type: none"><li>Designed a glove with embedded sensors and machine learning to translate gestures into text commands for applications in robot control.</li></ul>	
<b>Machine vision-based inspection system for rear motor housings</b>	VIT   December 2023
<ul style="list-style-type: none"><li>Industry consultation project, designed and implemented a machine vision inspection system to detect abnormalities on motor housing and other parts using ML.</li></ul>	
<b>Self-Balancing Bike</b>	Eyantra Robotics Competition   October 2023

- Engineered a 3D printed bike that autonomously maintains balance and follows a path while carrying a load using LQR control.

#### **Gesture-Controlled Mecanum Robot ([link](#))**

VIT | April 2023

- Built a mecanum robot controlled via hand gestures using a glove, ESP-NOW for wireless communication and custom 3D-printed components.

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#### **HONORS & AWARDS**

<b>Best Capstone Project Award</b>	VIT Chennai   2024
<b>Tri NIT Hackathon Finalist</b>	Qualcomm & BharatX, India   2023
<b>The Most Innovative Student of the Year</b>	Gulf Asian English School, UAE   2020
<b>Best Innovative &amp; Inventive Project on Road/Traffic Safety</b>	Emirates Transport UAE   2018

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#### **PATENTS**

- Vellore Institute of Technology, Chennai; Murali Mohan, G.; Vinay, M.; **Kevin Biju Mathew**; Hrithik Parihar. 2024. **Modular Robot for Educational and Research Purposes**. India Patent No. 424531-001, filed July 24, 2024, and issued October 15, 2024.

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#### **RESEARCH**

- Mathew, Kevin Biju**, Naveen Venkatesh Sridharan, Anoop Prabhakaranpillai Sreelatha and Sugumaran, V. "A Voting-Based Approach for Monitoring Nitrogen-Filled Tire Condition Using Machine Learning and Vibration Signals." *Part D: Journal of Automobile Engineering*. Medium of Publication: Journal Article.
- Arpit Pandey, Hrithik Parihar, **Mathew, Kevin Biju**, Maazin Mohammad, Deivanathan R. "Hall Effect-Based Data Glove for Gesture Recognition and Hand Pose Tracking" *Presented at: International Mechanical Engineering Conference (IMECHCON 2025) VIT*. Medium of Publication: Conference.
- Kevin Biju Mathew**, Aaron Melvin Remedios, Phu Pham, "MG SLAM: A Collaborative Multi-Agent SLAM Using 3D Gaussian Splatting for Spatially Consistent 3D Mapping." *In Progress*. Associated with Purdue University.

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#### **LEADERSHIP AND EXTRACURRICULAR ACTIVITIES**

<b>Founder and President of AutoVIT Club</b>	VIT Chennai   2021-2024
Established and led a multi-disciplinary club focused on robotics and automation, organizing workshops, events, and seminars.	
<b>Program Representative (Mechatronics and Automation)</b>	VIT Chennai   2021-2022
Acted as the liaison between students and faculty, organizing meetings and events to support academic and personal development.	
<b>Overall Coordinator for TechnoVIT 22</b>	VIT Chennai   2022
Led the School of Mechanical Engineering's participation, organizing 35+ events and winning awards for "Best Debut" and "Best Marketing and Design".	
<b>Event Coordinator for Innovage 2022 Hackathon</b>	VIT Chennai and Raptee Energy   2022
Collaborated with industry partners to organize a 3-day hackathon on electric vehicle innovations.	
<b>Founder and President of Innovation Club</b>	Gulf Asian English School   2019 -2020
Established and managed a school club promoting innovation and creativity, organizing events and workshops for students	