

KEVIN BIJU MATHEW

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ABOUT

Robotics master's student at Purdue with a Mechatronics background, specializing in path planning, hardware integration, testing, and troubleshooting. Skilled in ROS2, sensor fusion, and computer vision, with cross-disciplinary experience enabling effective design and validation of autonomous systems. Currently seeking an internship opportunity to apply technical expertise and leadership skills to real-world robotics challenges.

EDUCATION WORK EXPERIENCE

Purdue University, West Lafayette Masters in Robotics/ Interdisciplinary Engineering GPA: 3.67	2025 - 2027
Vellore Institute of Technology, Chennai, India B.Tech Mechatronics and Automation CGPA: 9.09/10	2020 - 2024
Gulf Asian English School, U.A.E Higher Secondary Marks = 90%	2018-2020

WORK EXPERIENCE

Research Intern

Center for Human Movement Analytics, VIT Chennai, India	February 2025 – July 2025
<ul style="list-style-type: none">Worked on state-of-the-art exoskeleton technologies for lower-body rehabilitation.Proposed a remote-assisted lower-limb physiotherapy exoskeleton with Digital Twin and AR integration.Developed a control strategy to ensure safe and responsive motion across different therapy modes.	

Intern	December 2024 – January 2025
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Indian Institute of Technology, Palakkad, India

- Assisted research scholars with their thesis and funded projects, which include reconfigurable hybrid drone/quadrapet, food delivery robot, and an all-terrain vehicle.
- Developed Autonomous Navigation and Trajectory tracking algorithms on an AGV.

SKILLS

- Autonomy & Simulations:** ROS2, Gazebo, Rviz, Simulink, IPG Carmaker HIL/SIL testing, PLC.
- Perception & sensors:** LiDAR (SLAMTEC A1M8), depth camera, IMU, sensor fusion using extended Kalman filter.
- Controls & Embedded Systems:** Python, C++, Java, control algorithms (PID, LQR, MPC), Open-CV, Jetson Nano, Raspberry Pi, Teensy, Arduino.
- Communication & Integration:** Serial Interfaces, I2C, CAN, RTOS.
- Validation & Testing:** Prototyping, Additive Manufacturing, System Debugging, Machine Vision Inspection.
- Software:** SolidWorks, Autodesk Fusion 360, MATLAB, Edge Impulse, NTopology.

PROJECTS

Trajectory Planning & Tracking for UR3E Robotic Arm (Signature Light Painting) (link)	Purdue December 2025
<ul style="list-style-type: none">Converted a handwritten signature into a smooth, arc length-parameterized trajectory and executed it using trapezoidal velocity planning.Implemented forward and inverse kinematics using screw theory, validating smooth joint motion and singularity avoidance.	
Autonomous Guided Vehicles (AGVs) with Modular Drive Mechanisms (link)	VIT April 2024
<ul style="list-style-type: none">Developed AGVs with interchangeable differential and mecanum drives using ROS2, enabling dynamic switching based on operational requirements for logistics operations.	
Wheeled Mobile Robot with Robotic Arm (link)	VIT December 2023
<ul style="list-style-type: none">Developed a mobile robot with an integrated robotic arm using ROS2 for picking and placing objects using ROS2.	
Hall Effect-Based Data Glove for Gesture Recognition	VIT December 2023
<ul style="list-style-type: none">Designed a glove with embedded sensors and machine learning to translate gestures into text commands for applications in robot control.	
Machine vision-based inspection system for rear motor housings	VIT December 2023
<ul style="list-style-type: none">Industry consultation project, designed and implemented a machine vision inspection system to detect abnormalities on motor housing and other parts using ML.	
Self-Balancing Bike	Eyantra Robotics Competition October 2023

- Engineered a 3D printed bike that autonomously maintains balance and follows a path while carrying a load using LQR control.

Gesture-Controlled Mecanum Robot ([link](#))

VIT | April 2023

- Built a mecanum robot controlled via hand gestures using a glove, ESP-NOW for wireless communication and custom 3D-printed components.

HONORS & AWARDS

- Best Capstone Project Award** VIT Chennai | 2024
- Tri NIT Hackathon Finalist** Qualcomm & BharatX, India | 2023
- The Most Innovative Student of the Year** Gulf Asian English School, UAE | 2020
- Best Innovative & Inventive Project on Road/Traffic Safety** Emirates Transport UAE | 2018

PATENTS

- Vellore Institute of Technology, Chennai; Murali Mohan, G.; Vinay, M.; **Kevin Biju Mathew**; Hrithik Parihar. 2024. **Modular Robot for Educational and Research Purposes**. India Patent No. 424531-001, filed July 24, 2024, and issued October 15, 2024.

RESEARCH

- Mathew, Kevin Biju**, Naveen Venkatesh Sridharan, Anoop Prabhakaranpillai Sreelatha and Sugumaran, V. "**A Voting-Based Approach for Monitoring Nitrogen-Filled Tire Condition Using Machine Learning and Vibration Signals.**" *Part D: Journal of Automobile Engineering*. Medium of Publication: Journal Article.
- Arpit Pandey, Hrithik Parihar, **Mathew, Kevin Biju**, Maazin Mohammad, Deivanathan R. "**Hall Effect-Based Data Glove for Gesture Recognition and Hand Pose Tracking**" **Presented at: International Mechanical Engineering Conference (iMECHCON 2025) VIT**. Medium of Publication: Conference.
- Kevin Biju Mathew**, Aaron Melvin Remedios, Phu Pham, "**MG SLAM: A Collaborative Multi-Agent SLAM Using 3D Gaussian Splatting for Spatially Consistent 3D Mapping.**" **In Progress**. Associated with Purdue University.

LEADERSHIP AND EXTRACURRICULAR ACTIVITIES

- Founder and President of AutoVIT Club** VIT Chennai | 2021-2024
Established and led a multi-disciplinary club focused on robotics and automation, organizing workshops, events, and seminars.
- Program Representative (Mechatronics and Automation)** VIT Chennai | 2021-2022
Acted as the liaison between students and faculty, organizing meetings and events to support academic and personal development.
- Overall Coordinator for TechnoVIT 22** VIT Chennai | 2022
Led the School of Mechanical Engineering's participation, organizing 35+ events and winning awards for "Best Debut" and "Best Marketing and Design".
- Event Coordinator for Innovage 2022 Hackathon** VIT Chennai and Raptee Energy | 2022
Collaborated with industry partners to organize a 3-day hackathon on electric vehicle innovations.
- Founder and President of Innovation Club** Gulf Asian English School | 2019 -2020
Established and managed a school club promoting innovation and creativity, organizing events and workshops for students