unet-kl

November 10, 2022

0.1 prepare data

20 subjects in total, 18 will be used for training and validation, 2 will be used for independent testing raw images in nifti format, conver to png format, in order to use the existing augmentation solution.

```
[86]: import os
import numpy as np
import nibabel as nib
import matplotlib.pyplot as plt
import torch.nn as nn
from PIL import Image
import torch.nn as nn
```

```
[2]: from fastai.data.all import * from fastai.vision.all import *
```

```
[3]: #nii folder has orig/label images in nifti format, orig and label would have_
corresponding images in png formats
train_path = Path('./data/train/')
test_path = Path('./data/test/')
```

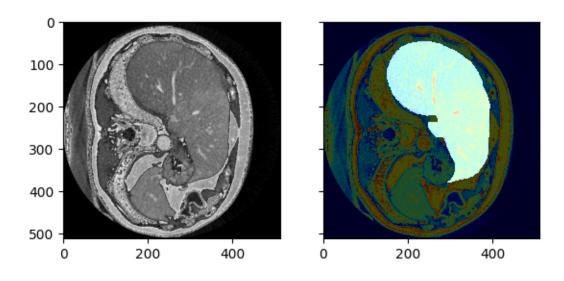
```
sub_name = raw.stem[:10] #substr, e.g., ircad_e01_
             raw_data = nib.load(raw,).get_fdata().astype(np.uint8) #intensity_
      ⇔within [0.255]
             label data = nib.load(label).get fdata().astype(np.uint8)
             assert raw data.shape == label data.shape
             print('working on subject : {}'.format(sub_name[:-1]))
             for idx in range(raw_data.shape[2]):
                 orig_name = sub_name + '{:03}.png'.format(idx) #e.q., ircad_e01_000.
      \hookrightarrow png
                 label_name = sub_name + '{:03}L.png'.format(idx) #e.g.,_
      → ircad_e01_000L.png
                 Image.fromarray(raw_data[:,:,idx]).save(png_path_orig/orig_name)
                 Image.fromarray(label_data[:,:,idx]).save(png_path_label/label_name)
[5]: # for training and validation;
     nii2png(nii_path = train_path/'nii',png_path_orig = train_path/'orig',u
      →png_path_label=train_path/'label')
    working on subject : ircad_e01
    working on subject : ircad e02
    working on subject : ircad_e03
    working on subject : ircad e04
    working on subject : ircad_e05
    working on subject : ircad e06
    working on subject : ircad e07
    working on subject : ircad e08
    working on subject : ircad_e09
    working on subject : ircad_e10
    working on subject : ircad_e11
    working on subject : ircad_e12
    working on subject : ircad_e13
    working on subject : ircad_e14
    working on subject : ircad_e15
    working on subject : ircad e16
    working on subject : ircad_e17
    working on subject : ircad_e18
[6]: # for independent testing;
    nii2png(nii_path = test_path/'nii',png_path_orig = test_path/'orig',__
      →png_path_label=test_path/'label')
    working on subject : ircad_e19
    working on subject : ircad_e20
```

0.2 verify images

```
[5]: def show_pair_overlay(seg, raw, alpha = 0.7):
    f, (ax1, ax2) = plt.subplots(1, 2, sharey=True)
    ax1.imshow(raw, cmap='gray')
    ax2.imshow(raw, cmap='jet')
    ax2.imshow(seg, cmap='gray', interpolation='none', alpha=alpha)
    return f, (ax1, ax2)
```

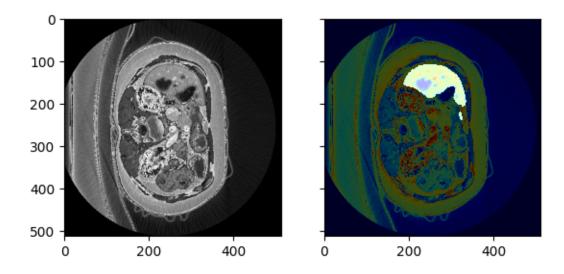
```
[6]: #verify training dataset
    orig = Image.open('data/train/orig/ircad_e01_104.png');
    label = Image.open('data/train/label/ircad_e01_104L.png')
    show_pair_overlay(label, orig, alpha = 0.7)
```

[6]: (<Figure size 640x480 with 2 Axes>, (<AxesSubplot: >, <AxesSubplot: >))



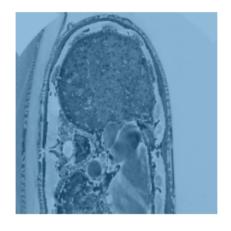
```
[7]: #verify testing dataset
orig = Image.open('data/test/orig/ircad_e19_041.png');
label = Image.open('data/test/label/ircad_e19_041L.png')
show_pair_overlay(label, orig, alpha = 0.7)
```

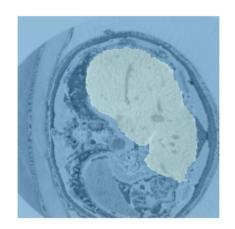
[7]: (<Figure size 640x480 with 2 Axes>, (<AxesSubplot: >, <AxesSubplot: >))

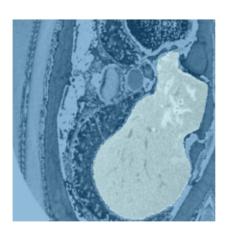


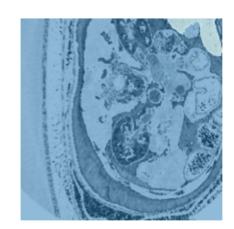
0.3 DataLoaders

[9]: dls.show_batch()









```
[11]: #check batch dims
x,y = dls.train.one_batch()
x.shape, y.shape
```

[11]: (torch.Size([4, 1, 256, 256]), torch.Size([4, 256, 256]))

0.4 vanilla unet

build and test the vanilla unet with pytorch

```
def __init__(self, ni=1, ks=3, padding =1):
               super().__init__()
               self.lconv1 = conv_block(ni, 32, ks, padding)
               self.lconv2 = conv_block(32, 64, ks, padding)
               self.lconv3 = conv_block(64, 128, ks, padding)
               self.lconv4 = conv_block(128, 256, ks, padding)
               self.lconv5 = conv_block(256, 512, ks, padding)
               self.rconv5 = conv block(32, 2, ks, padding)
               self.rconv4 = conv_block(64+32, 32, ks, padding)
               self.rconv3 = conv_block(128+64, 64, ks, padding)
               self.rconv2 = conv_block(256+128, 128, ks, padding)
               self.rconv1 = conv_block(512+256, 256, ks, padding)
               self.maxpool = nn.MaxPool2d(2)
               self.upsample = nn.Upsample(scale_factor=2, mode='bilinear',__
        →align_corners=True)
           def forward(self, x):
               conv1 = self.lconv1(x)
               conv2 = self.lconv2(self.maxpool(conv1))
               conv3 = self.lconv3(self.maxpool(conv2))
               conv4 = self.lconv4(self.maxpool(conv3))
               x = self.lconv5(self.maxpool(conv4))
               x = torch.cat([self.upsample(x),conv4], dim=1)
               x = self.rconv1(x)
               x = torch.cat([self.upsample(x),conv3], dim=1)
               x = self.rconv2(x)
               x = torch.cat([self.upsample(x),conv2], dim=1)
               x = self.rconv3(x)
               x = torch.cat([self.upsample(x),conv1], dim=1)
               x = self.rconv4(x)
               out = self.rconv5(x)
               return out
[135]: loss_func=CrossEntropyLossFlat(axis=1)
       learn_vun = Learner( dls, VanillaUnet(), lr=1e-3, opt_func = Adam, loss_func =_
        GrossEntropyLossFlat(axis=1), metrics=Dice(),moms=(0.95,0.85,0.95))
```

<IPython.core.display.HTML object>

[136]: learn_vun.summary()

<IPython.core.display.HTML object>

[136]: VanillaUnet (Input shape: 4 x 1 x 256 x 256)

	:=========		
	Output Shape		Trainable
	4 x 32 x 256 x 256		
Conv2d		320	True
ReLU Conv2d		9248	True
ReLU		3240	True
Conv2d	4 x 64 x 128 x 128	18496	True
ReLU		10100	
Conv2d		36928	True
ReLU			
	4 x 128 x 64 x 64		
Conv2d ReLU		73856	True
Conv2d		147584	True
ReLU			
	4 x 256 x 32 x 32		
Conv2d		295168	True
ReLU Conv2d		590080	True
ReLU		030000	True
	4 x 512 x 16 x 16		
Conv2d	4 x 512 x 16 x 16	1180160	True
ReLU			
Conv2d ReLU		2359808	True
C0-d	4 x 2 x 256 x 256	F70	Т
Conv2d ReLU		578	True
Conv2d		38	True
ReLU			
	4 x 32 x 256 x 256		
Conv2d		27680	True
ReLU Conv2d		9248	True
ReLU			

	110656 36928	True
	36928	True
	00020	1140
4 x 128 x 64 x 64		
	442496	True
	147584	True
4 x 256 x 32 x 32		
	1769728	True
	590080	True
4 x 256 x 16 x 16		
4 x 64 x 256 x 256		
	4 x 256 x 32 x 32 4 x 256 x 16 x 16	1769728 590080 4 x 256 x 16 x 16 4 x 64 x 256 x 256

Total trainable params: 7,846,664 Total non-trainable params: 0

Optimizer used: <function Adam at 0x7f071d746b80> Loss function: FlattenedLoss of CrossEntropyLoss()

Callbacks:

- TrainEvalCallback
- CastToTensor
- Recorder
- ProgressCallback

[129]: learn_vun.fit_one_cycle(10) # the vanilla model seems to work well, though_ ⇔converged slowly

<IPython.core.display.HTML object>

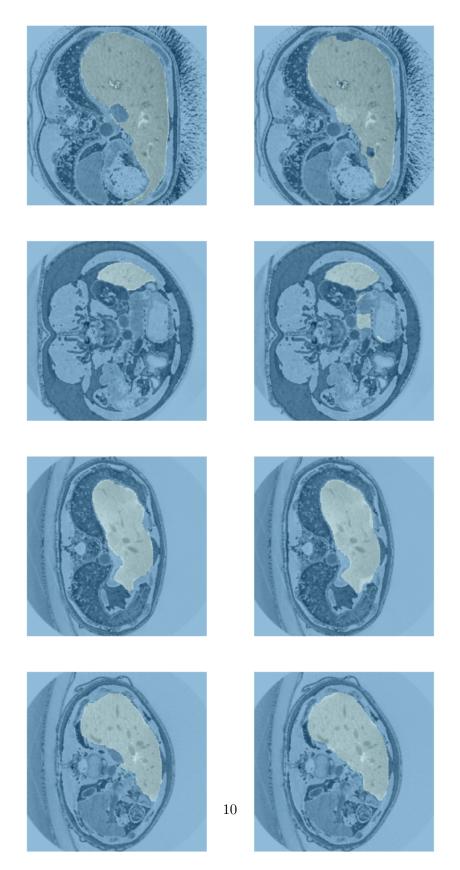
<IPython.core.display.HTML object>

[132]: learn_vun.show_results()

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

Target/Prediction



0.5 unet with pretrained resnet

```
[8]: loss func = CrossEntropyLossFlat(axis=1) #softmax over the channel dim
      learn = unet_learner(dls, resnet34, n_in = 1, n_out=2, opt_func = Adam,__
       ⇔loss_func = loss_func, metrics=Dice())
[16]: learn.model
[16]: DynamicUnet(
        (layers): ModuleList(
          (0): Sequential(
            (0): Conv2d(1, 64, kernel_size=(7, 7), stride=(2, 2), padding=(3, 3),
      bias=False)
            (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
            (2): ReLU(inplace=True)
            (3): MaxPool2d(kernel_size=3, stride=2, padding=1, dilation=1,
      ceil_mode=False)
            (4): Sequential(
              (0): BasicBlock(
                (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
                (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
                (relu): ReLU(inplace=True)
                (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
                (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
              )
              (1): BasicBlock(
                (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
                (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
                (relu): ReLU(inplace=True)
                (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
                (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
              )
              (2): BasicBlock(
                (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
```

```
(bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
          (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        )
      )
      (5): Sequential(
        (0): BasicBlock(
          (conv1): Conv2d(64, 128, kernel_size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (downsample): Sequential(
            (0): Conv2d(64, 128, kernel_size=(1, 1), stride=(2, 2), bias=False)
            (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        )
        (1): BasicBlock(
          (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (2): BasicBlock(
          (conv1): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
```

```
)
        (3): BasicBlock(
          (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
      (6): Sequential(
        (0): BasicBlock(
          (conv1): Conv2d(128, 256, kernel_size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (downsample): Sequential(
            (0): Conv2d(128, 256, kernel_size=(1, 1), stride=(2, 2), bias=False)
            (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
        (1): BasicBlock(
          (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (2): BasicBlock(
          (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
```

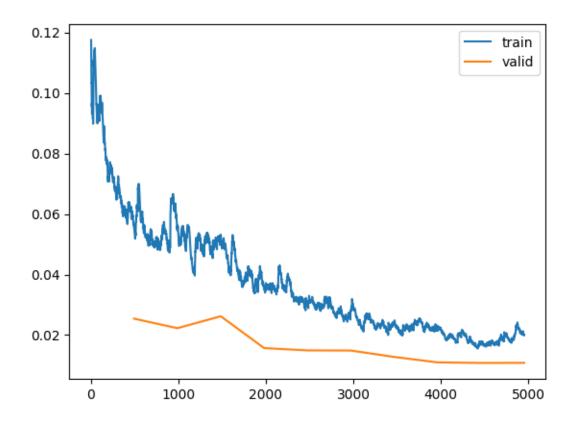
```
(conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (3): BasicBlock(
          (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (4): BasicBlock(
          (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (5): BasicBlock(
          (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
      )
      (7): Sequential(
        (0): BasicBlock(
          (conv1): Conv2d(256, 512, kernel_size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
```

```
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (downsample): Sequential(
            (0): Conv2d(256, 512, kernel_size=(1, 1), stride=(2, 2), bias=False)
            (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          )
        )
        (1): BasicBlock(
          (conv1): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (2): BasicBlock(
          (conv1): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
      )
    )
    (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (2): ReLU()
    (3): Sequential(
      (0): ConvLayer(
        (0): Conv2d(512, 1024, kernel size=(3, 3), stride=(1, 1), padding=(1,
1))
        (1): ReLU()
      )
      (1): ConvLayer(
        (0): Conv2d(1024, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1))
        (1): ReLU()
      )
```

```
)
    (4): UnetBlock(
      (shuf): PixelShuffle_ICNR(
        (0): ConvLayer(
          (0): Conv2d(512, 1024, kernel_size=(1, 1), stride=(1, 1))
          (1): ReLU()
        )
        (1): PixelShuffle(upscale_factor=2)
      (bn): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      (conv1): ConvLayer(
        (0): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): ReLU()
      )
      (conv2): ConvLayer(
        (0): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): ReLU()
      (relu): ReLU()
    (5): UnetBlock(
      (shuf): PixelShuffle_ICNR(
        (0): ConvLayer(
          (0): Conv2d(512, 1024, kernel_size=(1, 1), stride=(1, 1))
          (1): ReLU()
        (1): PixelShuffle(upscale_factor=2)
      (bn): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      (conv1): ConvLayer(
        (0): Conv2d(384, 384, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): ReLU()
      )
      (conv2): ConvLayer(
        (0): Conv2d(384, 384, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): ReLU()
      )
      (relu): ReLU()
    (6): UnetBlock(
      (shuf): PixelShuffle ICNR(
        (0): ConvLayer(
          (0): Conv2d(384, 768, kernel_size=(1, 1), stride=(1, 1))
          (1): ReLU()
        )
```

```
(1): PixelShuffle(upscale_factor=2)
      )
      (bn): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      (conv1): ConvLayer(
        (0): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): ReLU()
      )
      (conv2): ConvLayer(
        (0): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): ReLU()
      (relu): ReLU()
    (7): UnetBlock(
      (shuf): PixelShuffle_ICNR(
        (0): ConvLayer(
          (0): Conv2d(256, 512, kernel_size=(1, 1), stride=(1, 1))
        (1): PixelShuffle(upscale_factor=2)
      (bn): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (conv1): ConvLayer(
        (0): Conv2d(192, 96, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): ReLU()
      )
      (conv2): ConvLayer(
        (0): Conv2d(96, 96, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): ReLU()
      )
      (relu): ReLU()
    (8): PixelShuffle_ICNR(
      (0): ConvLayer(
        (0): Conv2d(96, 384, kernel_size=(1, 1), stride=(1, 1))
        (1): ReLU()
      )
      (1): PixelShuffle(upscale_factor=2)
    (9): ResizeToOrig()
    (10): MergeLayer()
    (11): ResBlock(
      (convpath): Sequential(
        (0): ConvLayer(
          (0): Conv2d(97, 97, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
```

```
(1): ReLU()
               )
               (1): ConvLayer(
                  (0): Conv2d(97, 97, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
               )
             (idpath): Sequential()
             (act): ReLU(inplace=True)
           (12): ConvLayer(
             (0): Conv2d(97, 2, kernel_size=(1, 1), stride=(1, 1))
           (13): fastai.layers.ToTensorBase(tensor_cls=<class</pre>
       'fastai.torch_core.TensorBase'>)
       )
  [9]: learn.fine_tune(10)
      <IPython.core.display.HTML object>
      <IPython.core.display.HTML object>
      <IPython.core.display.HTML object>
      <IPython.core.display.HTML object>
[145]: learn.recorder.plot_loss() #seems to converge and a few more epochs would be__
        \hookrightarrowbetter.
```

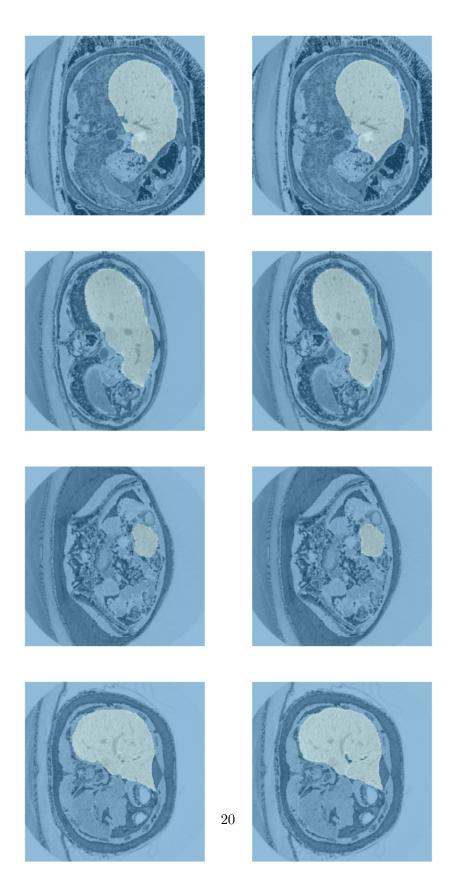


[23]: learn.show_results()

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

Target/Prediction



```
[12]: mdl_name = 'unet-resnet34-liverseg'
[11]: learn.save(mdl_name) # target: path/models/mdl_name
[11]: Path('models/unet-resnet34-liverseg.pth')
     0.6 predict on independent testing dataset
[24]: def dice_coef(y_true, y_pred, eps=1e-8):
          y_true_f = torch.flatten(y_true)
          y_pred_f = torch.flatten(y_pred)
          intersection = torch.sum(y_true_f * y_pred_f)
          return ((2. * intersection + eps) / (torch.sum(y_true_f) + torch.
       →sum(y_pred_f) + eps)).item()
[10]: path = Path('./')
      dlsT = SegmentationDataLoaders.from_label_func(
          path, bs=4, fnames = get_image_files(path/'data/test/orig'),
          valid_pct = 0.99, #
          label_func = lambda o: path/'data/test/label'/f'{o.stem}L{o.suffix}',
          img_cls=PILImageBW, #only one channel, gray, not rgb;
          #item_tfms=Resize(256, method=ResizeMethod.Squish), # change to this resize_
       →reduces the performance slightly
          item_tfms=RandomResizedCrop(256, min_scale=0.3), # works on each pair of_
       ⇔(orig, label)
[13]: loss_func = CrossEntropyLossFlat(axis=1) #softmax over the channel dim
      test = unet_learner(dlsT, resnet34, n_in = 1, n_out=2, opt_func = Adam,__
       ⇔loss_func = loss_func, metrics=Dice()) #
      test.load(mdl_name)
[13]: <fastai.learner.Learner at 0x7f9f82dda3d0>
 [8]: test.freeze()
 [9]: _, test_dice = test.validate()
      print('independent testing subjects, dice: {:6f}'.format(test_dice))
     <IPython.core.display.HTML object>
     <IPython.core.display.HTML object>
     independent testing subjects, dice: 0.951924
```

```
[38]: test.show_results()

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>
```

Target/Prediction

