Liangyawei Kuang

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https://www.deadsecond.com

Introduction

I am a postgraduate researcher at the Hong Kong University of Science and Technology (HKUST). My research goal is to develop learning algorithms and techniques that could endow machines and systems with greater autonomy and intelligence to acquire the skills for executing complex tasks. I am interested in the intersection of multi-agent systems, reinforcement learning, game theory, robotics, vision, and machine learning. Currently, I focus on both solving Multi-Agent Reinforcement Learning problems under scalability and reliability consideration & diving theoretical and algorithmic foundation of Reinforcement Learning.

Education

HKUST, Hong Kong, China

Aug. 2021 - present

Master of Philosophy in Robotics and Autonomous Systems Advisor: Prof. Fangzhen Lin and Prof. Ling Shi

Northeastern University, MA, U.S.A.

Jul. 2020 - Jun. 2021

Thesis-based Master of Computer Engineering in Computer Vision, Machine Learning and Algorithms (degree discontinued)

University of California, Irvine, CA, U.S.A. Aug. 2019 - Jun. 2020 Final year visiting in Electrical Engineering & Computer Science Department

Hong Kong Polytechnic University, Hong Kong, China Jan. 2019 - Jun. 2019 One-semester exchange in Mechanical Engineering Department

Harbin Institute of Technology, Harbin, China Aug. 2016 - Jun. 2020 Bachelor of Engineering in Mechatronics Engineering

Teaching

HKUST, Lecturer

Spring 2022

Multi-Robot Systems (course link)

Northeastern University, Teaching Assistant

Fall 2020

EECS 7311 Two Dimensional Signal and Image Processing

Skills Programming Libraries

Python, C/C++, MATLAB
NumPy, Matplotlib, Scikit-Learn,
OpenAI Gym, PyTorch, TensorFlow2
Mandarin, Classical Chinese, English, Latin

Honours

Postgraduate Studentship, HKUST

Meritorious Winner, Mathematical Contest in Modeling

Second Class Scholarship, Harbin Institute of Technology

SMC Scholarship, Harbin Institute of Technology

2017 & 2018

2017