## Liangyawei Kuang (匡梁亚伟)

kriskongloveyou@gmail.com

## EDUCATION \*\*\*\*\*\*2021.8-present the Hong Kong University of Science and Technology (HKUST) Hong Kong, China Master of Philosophy on Robotics and Autonomous System Co-advised by Prof. Fangzhen Lin and Prof. Ling Shi \*\*\*\*\*\*2020.7-2021.6 Northeastern University (NEU) MA, U.S.A. Thesis-based master of Computer Engineering on Computer Vision, Machine Learning and Algorithms (degree discontinued) GPA: 4.00/4.0 (overload with 3 courses every semester, and the regular load is 2 courses) \*\*\*\*\*\*2019.8-2020.6 University of California, Irvine (UC Irvine) CA, U.S.A. Undergraduate final year visiting in Electrical Engineering and Computer Science Three-degree curriculum: electronic circuit design, communication system, and signal processing \*\*\*\*\*\*2019.1-2019.6 Hong Kong Polytechnic University (HK PolyU) Hong Kong, China One-semester exchange in Mechanical Engineering GPA: 3.83/4.5 (overload with 6 courses, and the regular load is 3 or 4 courses); \*\*\*\*\*\*2016.8--2020.6 Harbin Institute of Technology (HIT) Harbin, China Bachelor of Engineering in Mechatronics Engineering (ME) GPA: **88.69**/100; Rank: **26**/**389** (1st year); **34**/**356** (2nd year) POSITIONS 2020.9-2020.12 Graduate-course Teaching Assistant (EECS7311: Two Dimensional Signal and Image Processing at Fall 2020) Teaching 2<sup>nd</sup> year master students and 2<sup>nd</sup> /3<sup>rd</sup> year PhD students during my office hours every week and correcting their homework **COURSES** Machinery Dynamics (92/100), Mathematical Modeling (95/100), Linear Systems and Control (A+), System Dynamics (A+), Discrete Time Signal and Systems (A+), Integrated Electronic Circuit Design (A), Introduction of Machine Vision (A-), Communication Systems II (A), Organization of Digital Computers (A-) PROJECTS 2016.10-2017.4 Multi-function (moving and grasping) Kitchen-Service Robot Design (freshman design project), leader HIT; 2017.6-2017.8 Intelligent Transport Robot Building (DIY an easy target robot) based on Explorer Suite, leader HIT; 2018.3-2018.7 Accurate Cable-Rack System based on 6-DOF Parallel Grid System (sophomore design-and-building project), leader HIT; 2018.9-2019.1 Inverted Pendulum based on Vision Control, feed-back part designing (PID) and building (3-D printing), member, Institute of Intelligent Control and System HIT;

SKILLS Programming Languages: Python, C/C++, MATLAB, Java, VHDL, SQL, Prolog, Linux Software: Anaconda for Python, Visual Studio for C/C++, Matlab, JetBrains IntelliJ IDEA, Cadence, AutoCAD, Mathematica, SolidWorks, Keil, Multisim, LabVIEW

the control part, following a 1st year Ph.D.)

Arduino (a beginner level project), leader

2019.1-2019.5 Mountain Autopilot System based on 2-D lidar SLAM (part of C/C++ coding for

2019.9-2020.6 Mobile Car Navigation based on Raspberry Pi 3 Model B with Arducam and

2020.9-2020.12 Mobile Robots Simulation Project based on ROS in Ubuntu (turtlebot) NEU

2020.9-2020.11 UC Berkeley CS188 Pac-Man Projects (AI projects based on python)

HK PolvU:

UC Irvine;

NEU:

HONORS	Champion, Freshman Basketball League Match of HIT, guard posi-	ition	Fall 2016;
AND	Excellent organizer for the New Year's Eve of HIT		Winter 2016;
AWARDS	First Place, Excellent Science and Technology Innovation Projects	of HIT	Summer 2017;
	Outstanding League Cadres of HIT at May Fourth Youth Day	Summers o	f 2017 and 2018;
	Second Prize, "Xin Rui" Cup Mathematics Competition of HIT, ra	ank #4	Summer 2017;
	Third Prize, "Xin Rui" Cup Robotic-Challenge Competition of HI	T, leader	Summer 2017;
	Outstanding Prize, Egg-Crash-Earth Structure Design Competition	on of HIT	Summer 2017;
	Second Prize, SMC scholarship of HIT		Fall 2017;
	Second Prize, "Ren Min" scholarship of HIT Fall 2017		7 and Fall 2018;
	Second Prize, National Collegiate Mathematics Competition		Winter 2017;
	First Prize, Mechanical Principles Competition in ME School of HIT		Spring 2018;
	<b>Excellent Volunteer of ME School in HIT</b>		Fall 2018;
	Meritorious winner of MCM (The Mathematical Contest in Modeli	ng)	Spring 2019;
	Third Place, HIT Robotic Summer School Competition		Summer 2019
ACTIVITIES 2016.10-2017.1 Director of the 2017 New Year's Eve of the Mechatronics Engineering School			
AND	and the Humanities School	_	HIT;
<b>EXPERIENCE</b>	2017.6-2019.6 Founder of the Academic-Special Dormitory		HIT;
	2017.7-2019.1 Founder and President of the ILS (Important learning Skills) Technical		
	<b>Community</b> (helping hundreds of students about their study issues)		HIT;
	2017.9-2019.1 Chief Lecturer of the "Lei Feng" Academic Support	t Group	HIT
<b>EXTRA</b>	Top ten progressive students in ME School of HIT (from 45% to t	op 10%),	2016 - 2017;
	Ranked as the only ME School exchange student to HK PolyU	2018 - 2	019 Semester 2;
	Ranked as the only HIT final-year visiting student to UC Irvine		2019 - 2020;
	Got three MS admissions from the NEU ECE department and several MS admissions from		
	other universities as USC, UCD, UF etc.	2019 - 202	20 Quarter 2&3;