

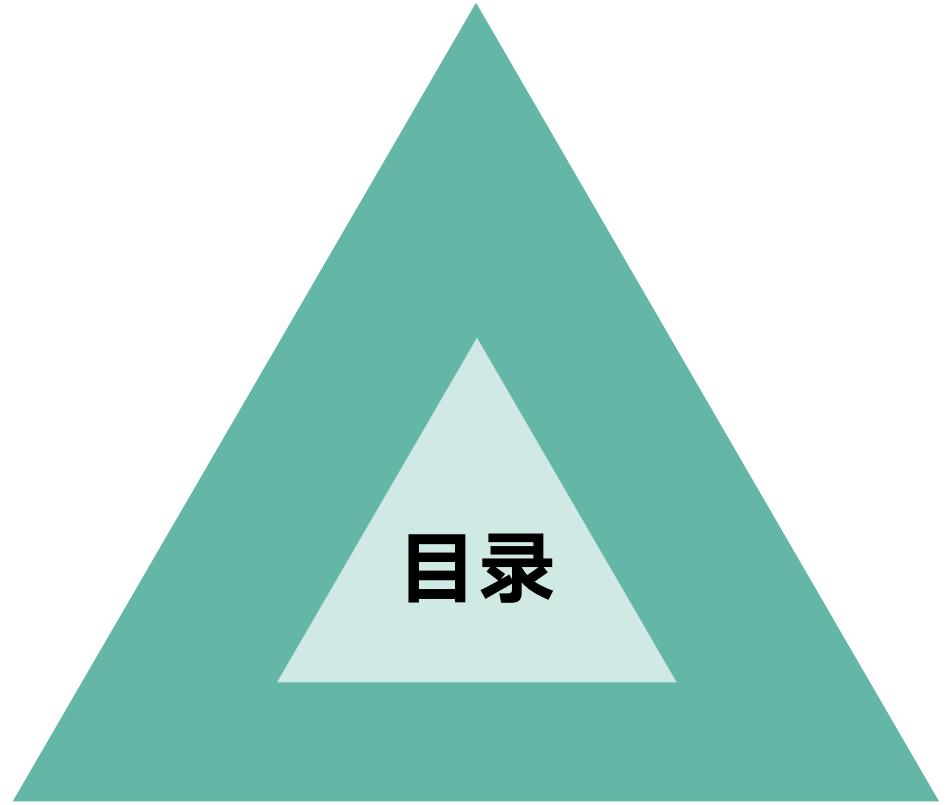
Accelerating Proposal Generation Network for Fast Face Detection on Mobile Devices

制作人：以若

01. Introduction

02. Structure

03. Experiments



01 Introduction



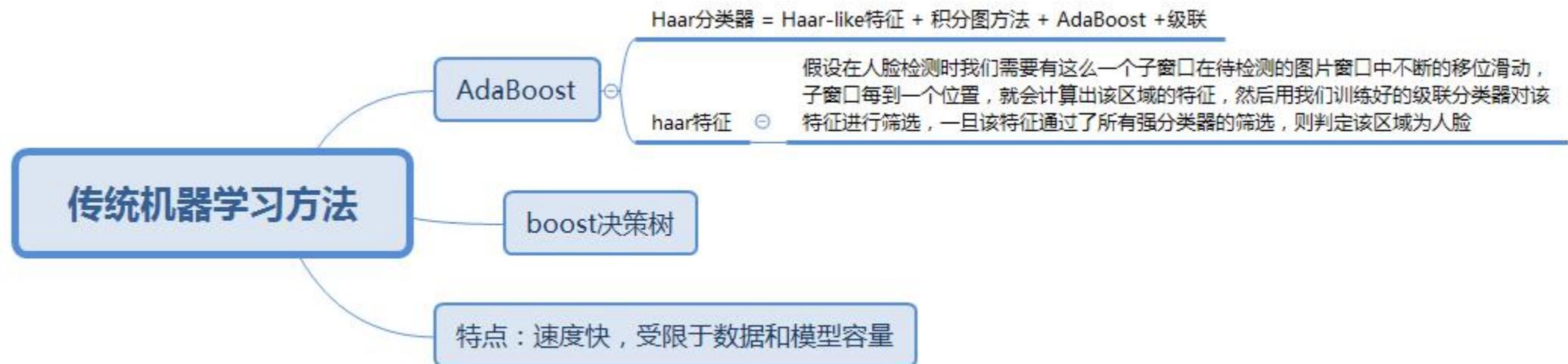
一、Introduction

- Face detection



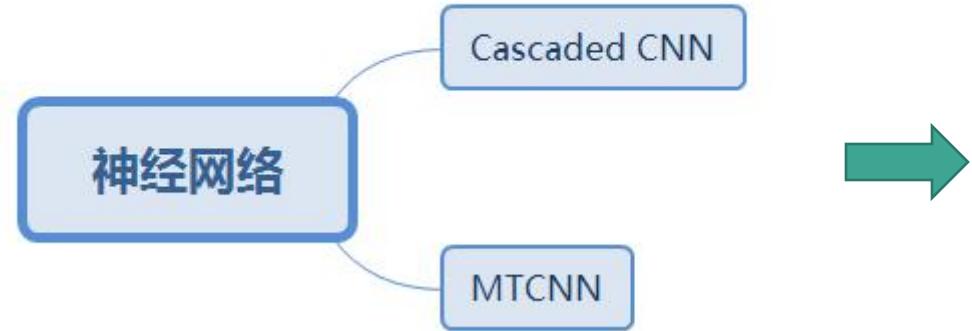
一、Introduction

- State-of-art machine learning



一、Introduction

- State-of-art deep learning

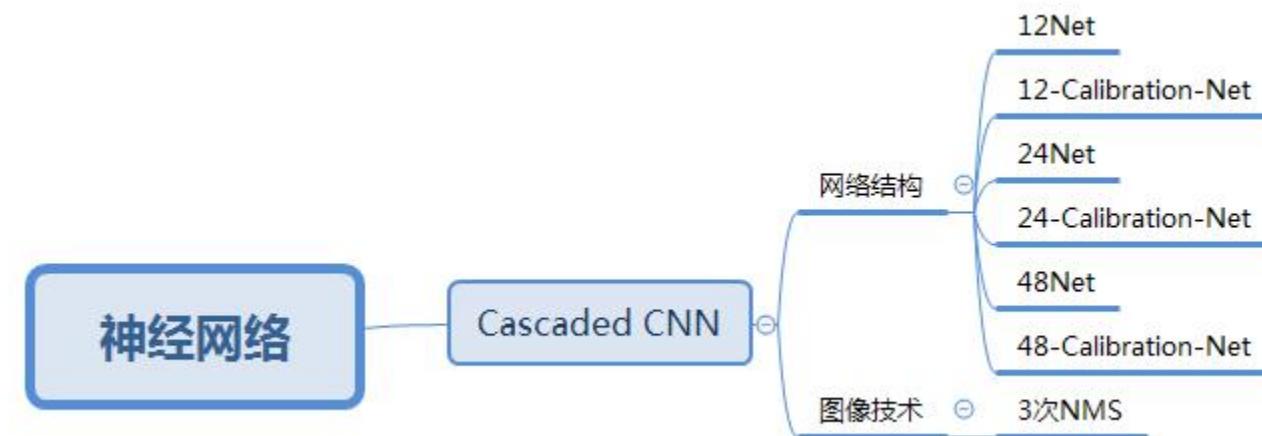
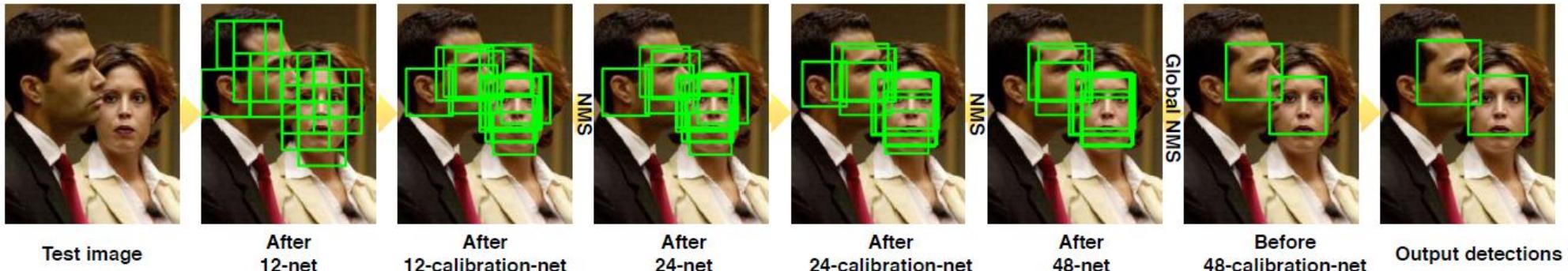


基于分目标级联检测思想

一、Introduction

- State-of-art deep learning --- Cascaded CNN

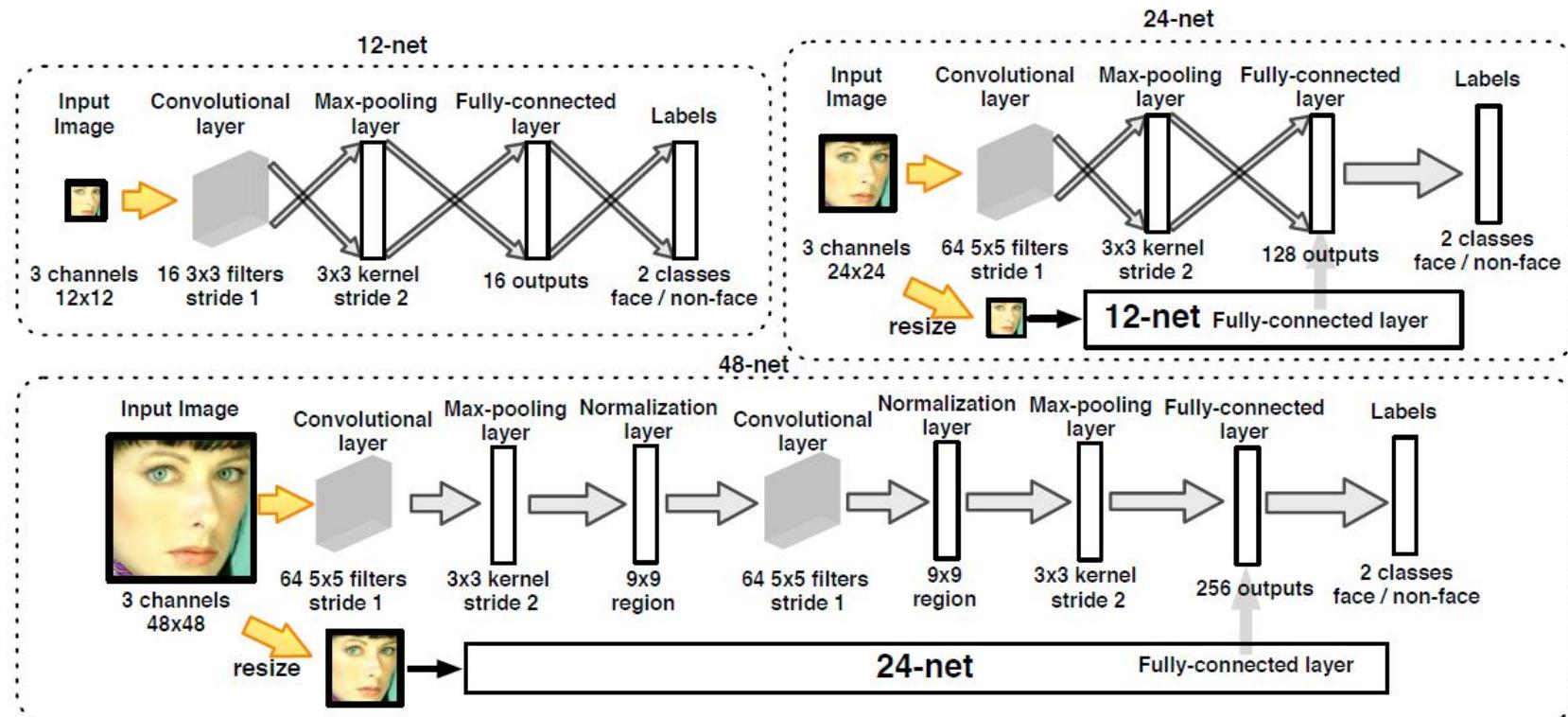
Cascaded CNN Pipeline



一、Introduction

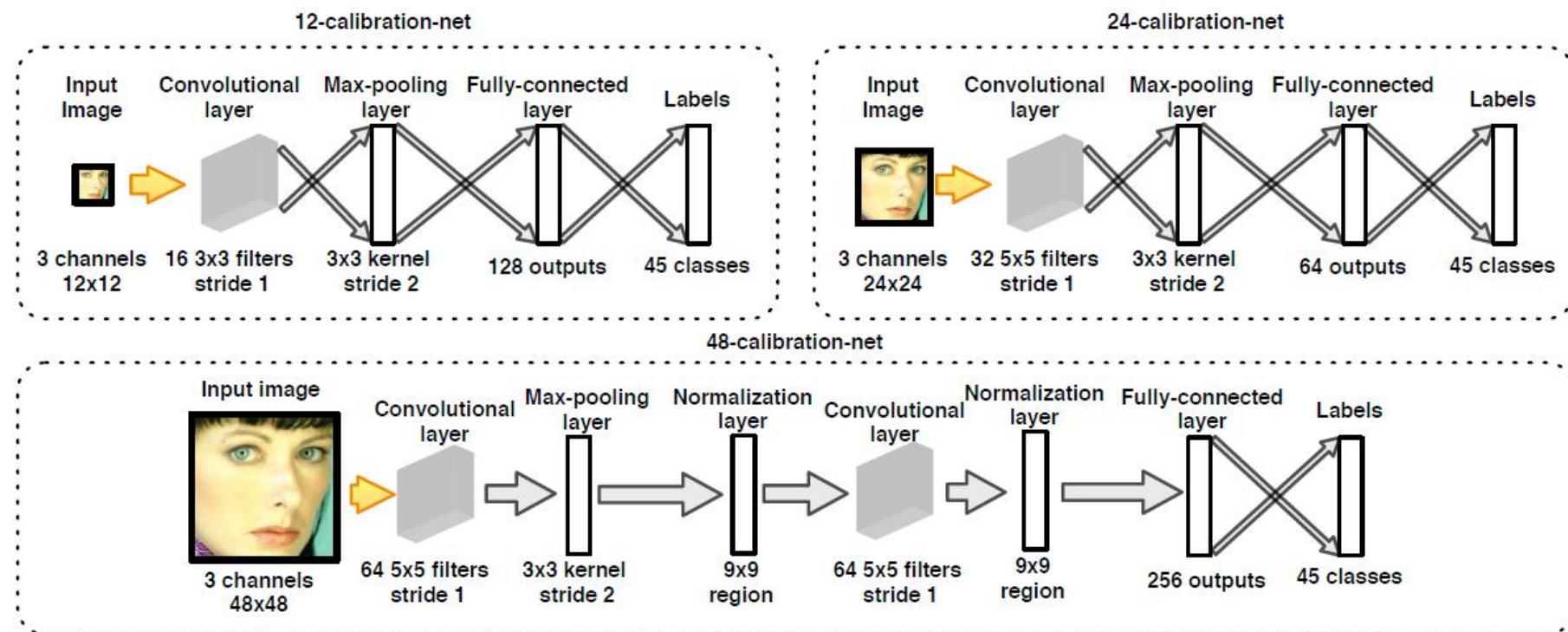
- State-of-art deep learning --- Cascaded CNN

Face / No Face Classifier



一、Introduction

- State-of-art deep learning --- Cascaded CNN



Bounding Box Calibration

一、Introduction

- State-of-art deep learning --- Cascaded CNN

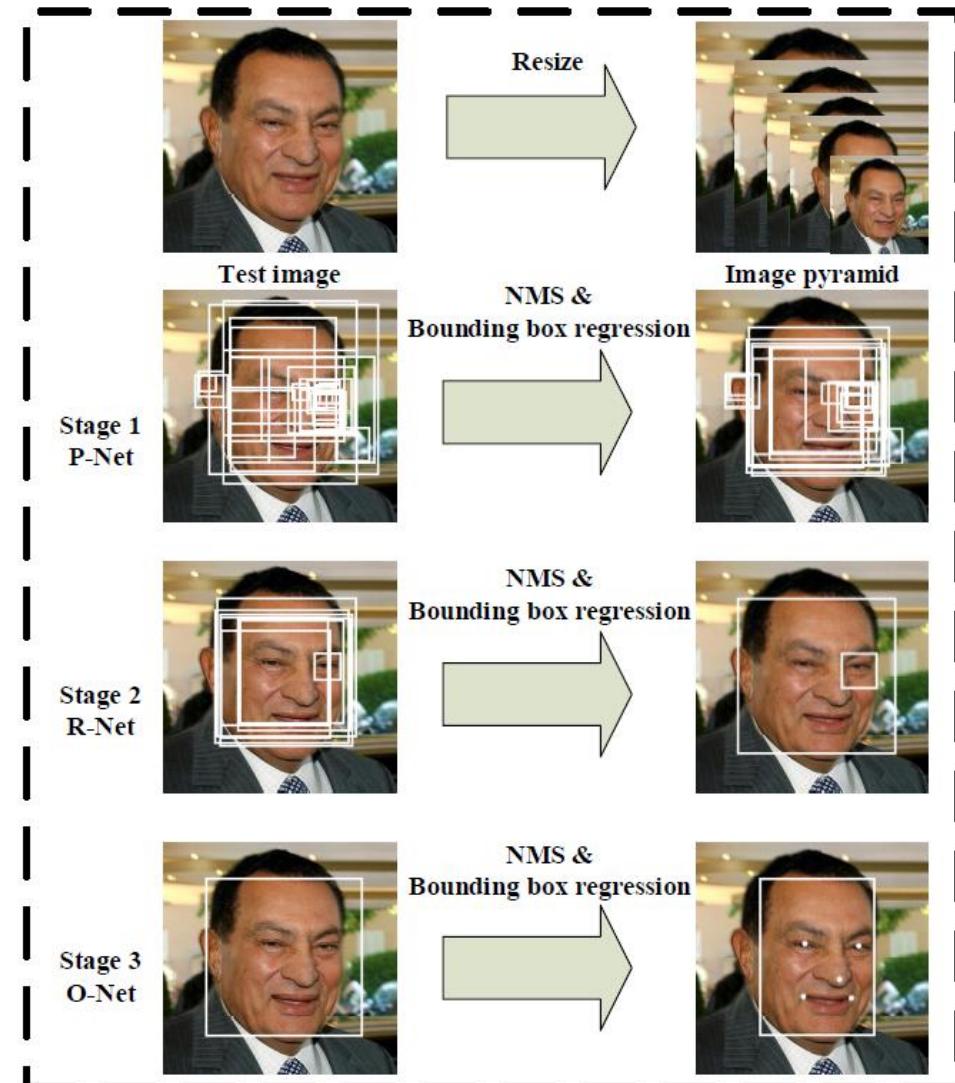
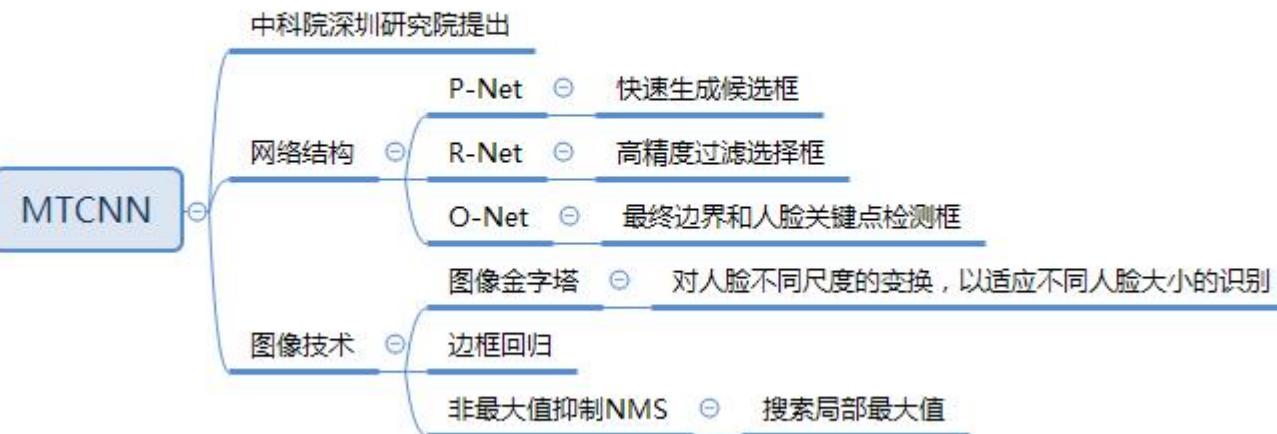
Non-maximum suppression (NMS)

- 所有bbox取最大score
- 筛选出所有与之iou比较大的bbox
- 再迭代地选择次大的score
- 再继续筛选
- 直至所有bbox筛选完毕

一、Introduction

- State-of-art deep learning

Multi-Task Cascaded CNN



一、Introduction

- State-of-art deep learning -- MTCNN

Multi-Task Cascaded CNN Pipeline

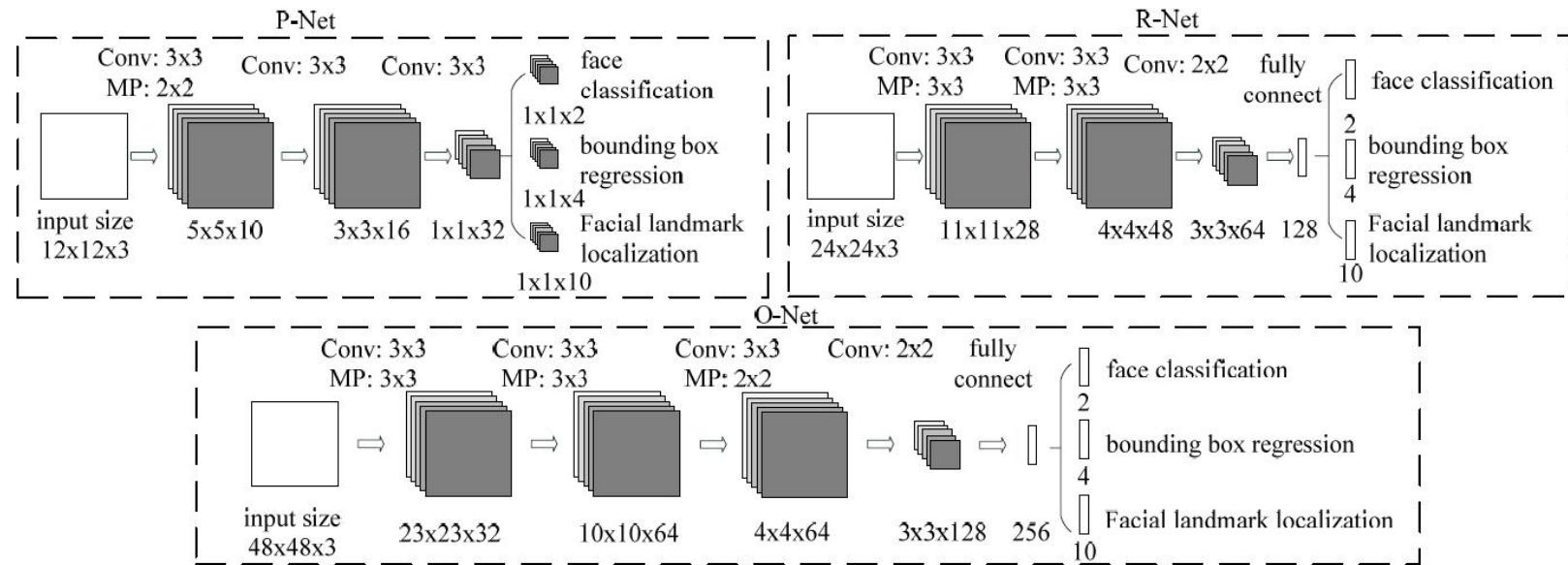


Fig. 2. The architectures of P-Net, R-Net, and O-Net, where “MP” means max pooling and “Conv” means convolution. The step size in convolution and pooling is 1 and 2, respectively.

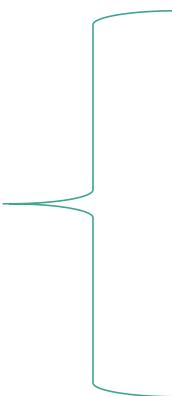
- 每个网络同时做人脸分类+校准+landmark定位的输出；
- 相当于一个网络做三个任务；
- 训练时分类+定位都有loss、测试时只有o-net输出landmark)；

一、Introduction

- State-of-art deep learning -- MTCNN

Multi-Task Cascaded CNN Loss

Loss function



face	$L_i^{det} = -(y_i^{det} \log(p_i) + (1 - y_i^{det})(1 - \log(p_i))) \quad (1)$
box	$L_i^{box} = \ \hat{y}_i^{box} - y_i^{box}\ _2^2$
landmark	$L_i^{landmark} = \ \hat{y}_i^{landmark} - y_i^{landmark}\ _2^2$

02 **Structure**

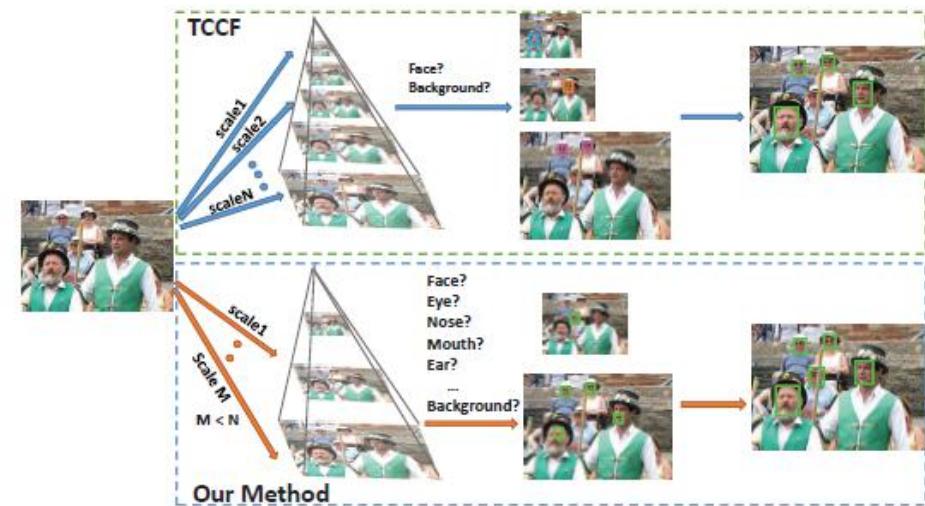
A series of teal-colored geometric shapes, including triangles and rectangles, are arranged in the bottom left corner of the slide. They overlap each other to create a sense of depth and structure.

一、Structure

- Structure

Spotlight

- 抓住全局和局部面部特征去减少输入图片金字塔的level;
- 满足手机设备的存储和速度;
- 使用局部特征可以快速检测到脸的位置，相比于全脸检测来说；



一、Structure

- Structure

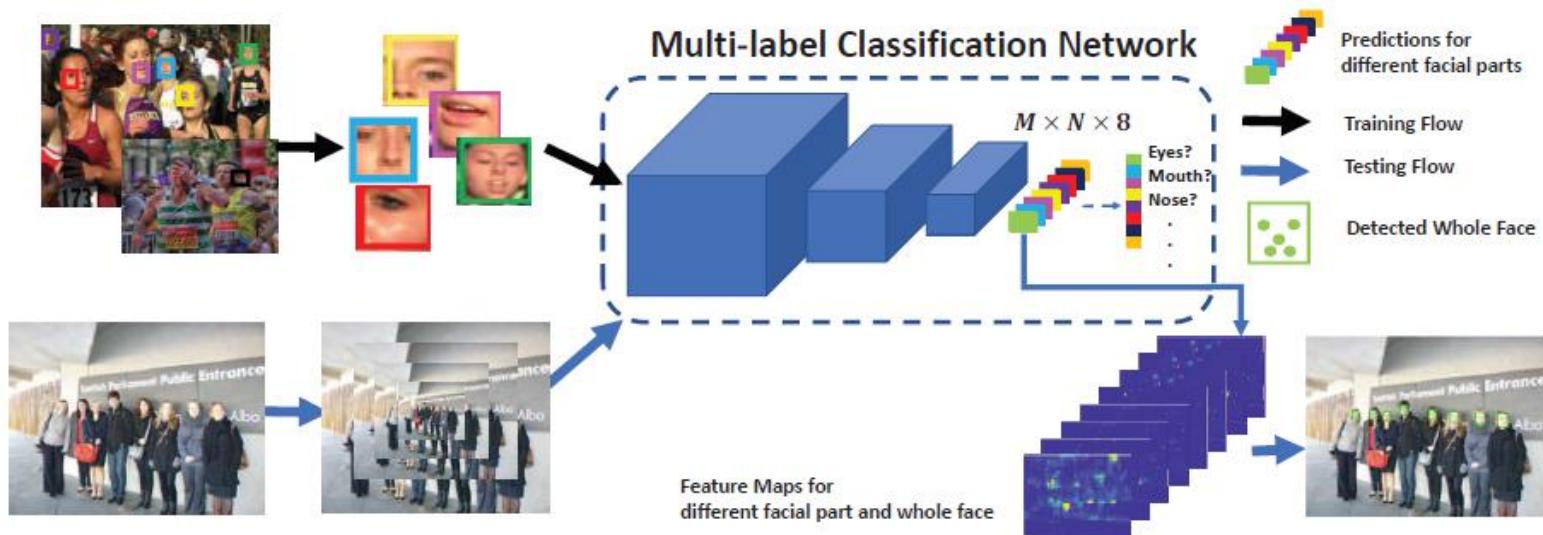


Table 1. Proposal network architecture

Layer	Kernel size	Output size
Input		$12 \times 12 \times 3$
Conv1	3×3	$12 \times 12 \times 16$
Pool1	3×3	$6 \times 6 \times 16$
Conv2	3×3	$4 \times 4 \times 32$
Conv3	3×3	$2 \times 2 \times 32$
Conv4	2×2	$1 \times 1 \times 64$
Conv5	1×1	$1 \times 1 \times 8$

寻找局部最优值

step1

使用模板生成bounding box

step2

将box组合

step3

R-Net
O-Net

final

03

Experiments



一、Structure

- Structure

Table 2. Comparisons of model size with state-of-the-art networks.

Work	Model size
CEDN [20]	1.1GB*
DDFD [10]	233MB*
HR [14]	98.9MB
LCDF+ [9]	2.33MB
MTCNN [2]	1.9MB
Nested [19]	1.6MB*
Ours	1.96MB

Table 3. Comparisons of detection performance with MTCNN[2] on WIDER-face validation set [13] with different scale factors.

Scale factor		0.79	0.50	0.25
Easy	MTCNN [2]	0.836	0.817	0.755
	Ours	0.844	0.842	0.826
Medium	MTCNN [2]	0.809	0.798	0.744
	Ours	0.809	0.805	0.794
Hard	MTCNN [2]	0.622	0.600	0.529
	Ours	0.603	0.568	0.519

Speed (Matlab Code)
MTCNN: 40.1ms
本文: 39.1ms



THANKS