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Modbus Protocol

Weight Transmitter

Ver.1.0.3

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This Device is able to support the MODBUS RTU communication protocol on 2 wires RS485 serial line. With the MODBUS communication protocol you can read the data state on multiple online device and check them through software, standards supervisory software provided by third parties or through interface with equipment such as MODBUS PLC terminals and data processing. The MODBUS protocol is based on a Master-Slave architecture, where requests for interrogating are unidirectional and executed only by the master (usually a PC) to the Slave . Indeed, if the Slave does not questioned by the Master, do not send any signal. The Slave when interviewed by the Master meet on predefined rules (defined by the MODBUS protocol) and not ever generate messages on its own initiative while remaining in the passive state pending Master request. All slave devices must have a different address in order to be recognized by the Master, if not, the whole system may still have some problems during operation. RTU protocol is a binary code and is the most common, besides being fast, having a message length below by almost 50% compared to the ASCII protocol.To be able to converse with each other, the master and all slaves should have the same protocol (RTU), speed, stop bits and parity. For more information you can contact us.

1 MODBUS structure Protocol

The MODBUS protocol common structure that is independent of the communication type (serial, TCP/IP) is characterized by 2 communication fields which are: data and function code.

On serial line, however, the command string consists of 4 communication fields:

- Device address;
- Function code:
- Data;
- CRC.



1.1 Slave Address

The field address (Slave Address) serves to indicate what Slave is called by Master. The valid slave address can be between 1 and 128. Please, note that the Slaves must have different addresses. To communicate with a slave, the Master into the address field the value of the slave address, which in turn will use in the reply message. The values that the Master may enter inside the string are:

- 0 = address 0, or "Broadcasting", was sent to all slave who must not be answered;
- $1 \div 128$ = free addresses for the Slave devices addressing;

1.2 Function Code

The function code used to indicate to the slave the request of the master, and then the operation type to be performed, if the slave could not make this request will send an error code. The codes that can be sent must be between 1 and 83.

To determine which functions are manageable refer to maps on the next page.

1.3 Data

The data field contains data sent from master to slave, or sent in response from Slave to Master. The data fields are multiples of 16-bit registers (1WORD = 2byte, 1byte = 8bit). Each WORD is always transmitted from the most significant byte. Depending on how the Slave records are set, you can view or change values in sequence, and it's possible if the records in question are adjacent to each other.

1.4 CRC

This field is used to verify the integrity of the received message. Is calculated and attached to the message by the transmitting station. The receiving station, as a first step, recalculate this field and compare it with that received. Is generated in the case of RTU (CRC Cyclic Redundancy Checking).

2 Introduction to MODBUS RTU

2.1 MODBUS RTU protocol

The string of communication consists of:

- T1 T2 T3 T4
- device address (1 byte)
- data (N x 2 byte; N = contiguous registers numbers to read or send)
- CRC (2 byte)
- T1 T2 T3 T4
- "T1 T2 T3 T4"

indicates the time that must elapse before a subsequent communication to avoid collisions of messages, the overall structure of the byte is composed of:

- 1 start bit:
- 8 data bits (transmitted from the least significant bit);
- 1 parity bit + 1 stop bit, if there is no parity bit using 2 stop bits.



2.2 EXAMPLE

• Read register:

Address: 01h
Function code: 03h
Start Address: 0000h
Read number: 001Ah
CRC: CRC16
01 30 00 00 00 1A C4 01

• Write single register:

Address: 01h
Function code: 06h
Data Address: 00F1h
Data Value: 0001h
CRC: CRC16
01 06 00 F1 00 01 19 F9

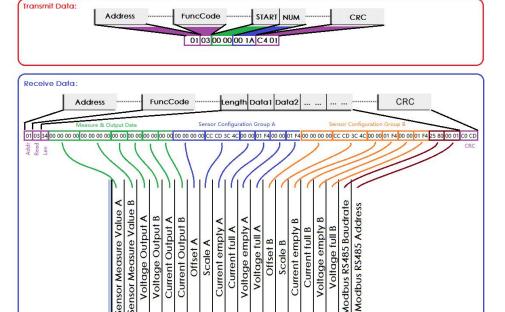
• Write multiple register:

Address: 01h
Function code: 10h
Data Address: 0000h
Register number: 0002h
Bytes number: 04h

Data Value: 0000 4348h(200f)

CRC: CRC16

01 10 00 00 00 02 04 00 00 43 48 C2 A9



3 Mappings

To enable the "system integrator" to develop a levels management software, following the mapping is represented in the device series.

3.1 MODBUS possible functions

Modality: RTU

Parity: none (bit not sent)

Times: minimum waiting time between two successive transmissions: time of 1 character multiplied by 3.5

Read / write:

03, 04 - "read register"

06 - "write single register"

10 - "write multiple register"

Diagnostics: unmanaged

Information Management: field data up to 100 bytes

DATA MAPPINGS										
Register Dec.	Address Hex.	Dim.word (16bit)	Description	unit	type	Function				
01	00	2	Sensor Measure Value A	kg	float	03h 10h				
03	02	2	Sensor Measure Value B	kg	float	03h 10h				
05	04	1	Voltage Output A	mV	float	03h				
06	05	1	Voltage Output B	mV	float	03h				
07	06	1	Current Output A	υA	float	03h				
08	07	1	Current Output B	υA	float	03h				
09	08	2	Offset A	Cnt	float	03h 10h				
11	А	2	Scale A	kg/cnt	float	03h 10h				
13	С	1	Current empty A	kg	uint16_t	03h 06h				
14	D	1	Current full A	kg	uint16_t	03h 06h				
15	Ε	1	Voltage empty A	kg	uint16_t	03h 06h				
16	F	1	Voltage full A	kg	uint16_t	03h 06h				
17	10	2	Offset B	Cnt	float	03h 10h				

19	12	2	Scale B	kg/cnt	float	03h 10h
21	14	1	Current empty B	kg	uint16_t	03h 06h
22	15	1	Current full B	kg	uint16_t	03h 06h
23	16	1	Voltage empty B	kg	uint16_t	03h 06h
24	17	1	Voltage full B	kg	uint16_t	03h 06h
25	18	1	Modbus RS485 Baudrate	bps	uint16_t	03h 06h
26	19	1	Modbus RS485 Address		uint16_t	03h 06h
242	FI	1	ChA Zero cmd		uint16_t	06h
243	F2	1	ChB Zero cmd		uint16_t	06h

4. Combination

4.1 Data feature

In receive array the data distribution follows the following characteristics:

```
mode LHuint16_t 21float 2143
```

4.2 function demo

```
•float data
float Char_To_Float(void *p)
{
    float f;
    char *ch = (char *)p;
    char *pf = (char *)&f;
    pf[0] = ch[1];
    pf[1] = ch[0];
    pf[2] = ch[3];
    pf[3] = ch[2];
    return f;
}
•integer data
int16_t Char_To_int16(void *p)
{
    char *ch = p;
    return ((int16_t)ch[0]<<8)+ch[1];
}</pre>
```

5. Command

To calibration device data base and measure value in linear transformation command.

5.1 Calibration

Zero-scale calibration

To eliminate static bias D-value after cleared pressure.

Write register command:

Address: Device Address

Function code: 06h

Data Address: 00F1h(CHA:00F1 CHB:00F2)

Data Value: 0001h CRC: CRC16

Example: 01 06 00 F1 00 01 19 F9

Measure value calibration

To measure value linear transformation after set standard pressure(ex: 200kg).

Write register command:

Address: 01h
Function code: 10h
Data Address: 0000h
Register number: 0002h
Bytes number: 04h

Data Value: 0000 4348h(200f)

CRC: CRC16

Example: 01 10 00 00 00 02 04 00 00 43 48 C2 A9