

Digital Signal Processing

Class 19
04/01/2025

ENGR 71

- Class Overview
 - Circulant Matrix
 - Fast Fourier Transform
- Assignments
 - Reading:
Chapter 8: The Fast Fourier Transform
 - Problems:
Chapter 7: 7.8, 7.9, 7.11(b), 7.14, 7.18, 7.25
Pick one symmetry property from Table 7.1 and one property from Table 7.2 to prove. (Next class, say which ones.)
Due: Friday, April 4

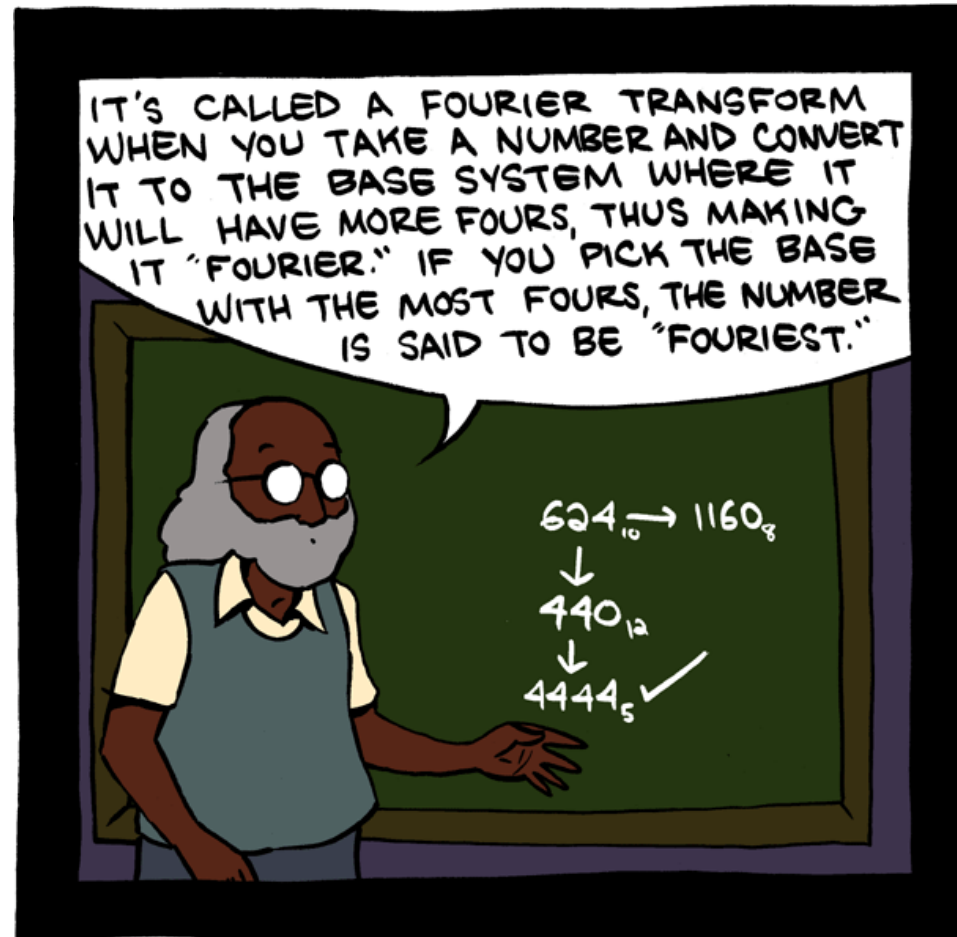
Project Ideas

- Project Ideas
 - Speech recognition (more complex than Lab 2)
 - Classifier for multiple words
 - I can provide a dataset with multiple instances of several different words
 - Musical instrument tone recognition
 - Using recordings of musical instruments, determine note being played
 - Determine if instrument is in tune, sharp, or flat.
 - Identification of musical instruments
 - I have a dataset of recordings for several different instruments
 - Identification of music genre
 - From frequency characteristics, can you determine a type of music
 - Classical, rock, etc.

Project ideas

- Filtering
 - Filtering to isolate sounds
 - Equalizer
- Noise reduction
- Audio effects processing
 - Reverb, echo, distortion
- Echo cancellation
- Several possibilities if you are interested in 2-D signal processing for image data
- Hardware projects
 - Link to site with collection of [Arduino-based projects](#)
- Theoretical research topics are also welcome
 - Paper on some interesting topic

Fourier Transform



Teaching math was way more fun after tenure.

Fourier Series

- **Fourier series for periodic signals:**

$$x(t) = x(t + T_0) \qquad f_0 = \frac{1}{T_0} \qquad \omega_0 = 2\pi f_0 = \frac{2\pi}{T_0}$$

$$x(t) = \sum_{k=-\infty}^{+\infty} X_k e^{jk\omega_0 t} \qquad \text{(Synthesis Eq.)}$$

$$X_k = \frac{1}{T_0} \int_{T_0} x(t) e^{-jk\omega_0 t} dt \qquad \text{(Analysis Eq.)}$$

Fourier Transform

- **Fourier transform aperiodic signals:**

$$X(\Omega) = \mathcal{F}[x(t)] = \int_{-\infty}^{+\infty} x(t)e^{-j\Omega t} dt \quad (\text{Analysis Equation})$$

$$x(t) = \mathcal{F}^{-1}[X(\Omega)] = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\Omega)e^{+j\Omega t} d\omega \quad (\text{Synthesis Equation})$$

Time and frequency are continuous variables

$$-\infty < t < \infty$$

$$-\infty < \Omega < \infty$$

Using Ω to distinguish it from discrete time case where frequency is between $-\pi$ and π

Discrete-Time Fourier Transform

- **Discrete-time Fourier transform**

$$X(\omega) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} \quad -\pi \leq \omega < \pi \quad (\text{Analysis equation})$$

$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\omega) e^{j\omega n} d\omega \quad (\text{Synthesis equation})$$

Time, labeled by the integer index n , is discrete ($t = nT_s$)

$$-\infty < n < \infty$$

$$-\pi < \omega < \pi$$

Limits on ω are imposed by the Nyquist condition

$$\pi \text{ represents maximum positive frequency } f_{\text{Nyquist}} = \frac{f_s}{2} = \frac{1}{2T_s}$$

(where T_s is the sampling interval or alternatively, f_s is the sampling frequency)

Discrete Fourier Series

- **Discrete Fourier series for a periodic sequence with period N**

$$x_p[n + mN] = x_p[n] \quad m = \dots, -1, 0, 1, \dots$$

$$x[n] = \sum_{k=0}^{N-1} c_k e^{j2\pi kn/N}$$

where

$$c_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j2\pi kn/N}$$

Discrete Fourier Transform

- **Discrete Fourier Transform**

Discrete Fourier Transform (DFT)

Analysis Equation

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j2\pi kn/N}, \quad k = 0, 1, 2, \dots, N-1$$

Inverse Discrete Fourier Transform (IDFT)

Synthesis Equation

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi kn/N}, \quad n = 0, 1, 2, \dots, N-1$$

Circular Convolution

- Circular Convolution

$$x_3 = x_1 \odot x_2 = \sum_{n=0}^{N-1} x_1[n] x_2[((m-n))_N]$$

Circular Convolution

– Example with N=4 length sequence

$$x_3[0] = \sum_{n=0}^3 x_1[n]x_2[((0-n))_4] = x_1[0]x_2[((0-0))_4] + x_1[1]x_2[((0-1))_4] + x_1[2]x_2[((0-2))_4] + x_1[3]x_2[((0-3))_4]$$

$$x_3[0] = x_1[0]x_2[0] + x_1[1]x_2[3] + x_1[2]x_2[2] + x_1[3]x_2[1]$$

$$x_3[1] = \sum_{n=0}^3 x_1[n]x_2[((1-n))_4] = x_1[0]x_2[((1-0))_4] + x_1[1]x_2[((1-1))_4] + x_1[2]x_2[((1-2))_4] + x_1[3]x_2[((1-3))_4]$$

$$x_3[1] = x_1[0]x_2[1] + x_1[1]x_2[0] + x_1[2]x_2[3] + x_1[3]x_2[2]$$

$$x_3[2] = \sum_{n=0}^3 x_1[n]x_2[((2-n))_4] = x_1[0]x_2[((2-0))_4] + x_1[1]x_2[((2-1))_4] + x_1[2]x_2[((2-2))_4] + x_1[3]x_2[((2-3))_4]$$

$$x_3[2] = x_1[0]x_2[2] + x_1[1]x_2[1] + x_1[2]x_2[0] + x_1[3]x_2[3]$$

$$x_3[3] = \sum_{n=0}^3 x_1[n]x_2[((3-n))_4] = x_1[0]x_2[((3-0))_4] + x_1[1]x_2[((3-1))_4] + x_1[2]x_2[((3-2))_4] + x_1[3]x_2[((3-3))_4]$$

$$x_3[3] = x_1[0]x_2[3] + x_1[1]x_2[2] + x_1[2]x_2[1] + x_1[3]x_2[0]$$

Circular Convolution

Re-written as:

$$x_3[0] = x_2[0]x_1[0] + x_2[3]x_1[1] + x_2[2]x_1[2] + x_2[1]x_1[3]$$

$$x_3[1] = x_2[1]x_1[0] + x_2[0]x_1[1] + x_2[3]x_1[2] + x_2[2]x_1[3]$$

$$x_3[2] = x_2[2]x_1[0] + x_2[1]x_1[1] + x_2[0]x_1[2] + x_2[3]x_1[3]$$

$$x_3[3] = x_2[3]x_1[0] + x_2[2]x_1[1] + x_2[1]x_1[2] + x_2[0]x_1[3]$$

This can be written in matrix form as:

$$\begin{pmatrix} x_3[0] \\ x_3[1] \\ x_3[2] \\ x_3[3] \end{pmatrix} = \begin{pmatrix} x_2[0] & x_2[3] & x_2[2] & x_2[1] \\ x_2[1] & x_2[0] & x_2[3] & x_2[2] \\ x_2[2] & x_2[1] & x_2[0] & x_2[3] \\ x_2[3] & x_2[2] & x_2[1] & x_2[0] \end{pmatrix} \begin{pmatrix} x_1[0] \\ x_1[1] \\ x_1[2] \\ x_1[3] \end{pmatrix} \quad \text{or} \quad \mathbf{x}_3 = \mathbf{C}_4^{x_2} \mathbf{x}_1$$

where \mathbf{x}_1 and \mathbf{x}_3 are length 4 sequences

and $\mathbf{C}_4^{x_2}$ is the 4×4 circulant matrix formed from the elements of sequence $x_2[n]$

Circulant Matrix

Notice that the circulant matrix consists of the columns of sequence $x_2(n)$ cyclically permuted.

The first column is the sequence;

column 2 has the last element of column 1 first, followed by the remaining elements of column 1;

column 3 has the last element of column 2 first, followed by the remaining elements of column 2;

column 4 has the last element of column 3 first, followed by the remaining elements of column 3;

This definition of the circulant matrix can be generalized for any N -length sequence.

Circulant Matrix

– Example 7.2.1 from book:

$$x_1[n] = \{2, 1, 2, 1\}; \quad x_2[n] = \{1, 2, 3, 4\}$$

Find the circular convolution of $x_1[n]$ and $x_2[n]$: $x_3[n] = x_1[n] \odot x_2[n]$

In matrix form:

$$\begin{pmatrix} x_3[0] \\ x_3[1] \\ x_3[2] \\ x_3[3] \end{pmatrix} = \begin{pmatrix} 1 & 4 & 3 & 2 \\ 2 & 1 & 4 & 3 \\ 3 & 2 & 1 & 4 \\ 4 & 3 & 2 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 14 \\ 16 \\ 14 \\ 16 \end{pmatrix}$$

> x1 = [2, 1, 2, 1];
> x2 = [1, 2, 3, 4];
> c = [1 4 3 2; 2 1 4 3; 3 2 1 4; 4 3 2 1]
> x3 = c*x1'

In Matlab, you can also use the command `toeplitz`
to construct a circulant matrix of any size based on a sequence $x[n]$:

```
c = toeplitz([x(1) fliplr(x(2:end))], x)'
```

Circulant Matrix

- Circulant Matrix

- The circulant matrix has a lot of interesting properties

- The eigenvalues are the elements of the DFT of the sequence in the first column
- The matrix formed, using the eigenvectors as columns, is the matrix with elements W_N^{kn} which is used to find the DFT: $\mathbf{X} = \mathbf{W}_N \mathbf{x}$

- This can be used to show that circular convolution in the time-domain is the product of the DFT's of the convolved sequences

If, $y[n] = x_1[n] \odot x_2[n]$, then $Y[k] = X_1[k] \cdot X_2[k]$

$$\left(W_N \equiv e^{-j2\pi/N} \right)$$

Circulant Matrix

Start with the expression for circular convolution in the time-domain: $y[n] = x_1[n] \odot x_2[n]$

In matrix notation: $\vec{y} = \mathbf{C}_N^{x_2} \vec{x}_1$ where $\mathbf{C}_N^{x_2}$ is the circulant matrix formed using sequence $x_2[n]$, and \vec{x}_1 is a sequence (represented as a column vector).

$\mathbf{C}_N^{x_2}$ is diagonalized by \mathbf{W}_N with eigenvalues: $X_2[k]$ which is the DFT of $x_2[n]$, so $\mathbf{C}_N^{x_2} = \mathbf{W}_N^{-1} \text{diag}(\vec{\mathbf{X}}_2) \mathbf{W}_N$.
($\text{diag}(\vec{\mathbf{X}}_2)$ is a **diagonal matrix** with $X_2[k]$ as the diagonal elements.)

Substituting this in the the matrix equation for convolution:

$$\vec{y} = \left(\mathbf{W}_N^{-1} \text{diag}(\vec{\mathbf{X}}_2) \mathbf{W}_N \right) \vec{x}_1 \Rightarrow \mathbf{W}_N \vec{y} = \left(\mathbf{W}_N \mathbf{W}_N^{-1} \right) \text{diag}(\vec{\mathbf{X}}_2) (\mathbf{W}_N \vec{x}_1) \Rightarrow \mathbf{W}_N \vec{y} = \text{diag}(\vec{\mathbf{X}}_2) (\mathbf{W}_N \vec{x}_1)$$

The DFT's of \vec{x}_1 and \vec{y} are: $\vec{\mathbf{X}}_1 = \mathbf{W}_N \vec{x}_1$ and $\vec{\mathbf{Y}} = \mathbf{W}_N \vec{y}$, showing that $\vec{\mathbf{Y}} = \vec{\mathbf{X}}_2^T \vec{\mathbf{X}}_1$.

Note that this is the element-by-element product: $\vec{\mathbf{X}}_2^T \vec{\mathbf{X}}_1 : Y[k] = X_2[k] X_1[k]$ for each $k = 0, 1, \dots, N-1$, since in the matrix equation, $\text{diag}(\vec{\mathbf{X}}_2)$ is a diagonal matrix.

Therefore for $y[n] = x_1[n] \odot x_2[n]$, $Y[k] = X_1[k] \cdot X_2[k]$

Fast Fourier Transform

- Fast Fourier Transform
 - Cooley and Tukey (1965)
 - Actually, Gauss knew about this algorithm in 1805

Fast Fourier Transform

- Fast Fourier Transform
 - Recall equations for DFT and IDFT

Discrete Fourier Transform (DFT)

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi kn/N}, \quad k = 0, 1, 2, \dots, N-1$$

Inverse Discrete Fourier Transform (IDFT)

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j2\pi kn/N}, \quad n = 0, 1, 2, \dots, N-1$$

Fast Fourier Transform

– Define W_N as: $W_N = e^{-j2\pi/N}$ which is the N'th primitive root of unity.

• Then:

$$W_N^{kn} = e^{-j2\pi kn/N}, \quad W_N^{-nk} = e^{j2\pi nk/N}$$

– The DFT and IDFT in terms of W_N are:

Discrete Fourier Transform (DFT)

$$X(k) = \sum_{n=0}^{N-1} x(n) W_N^{kn}, \quad k = 0, 1, 2, \dots, N-1$$

Inverse Discrete Fourier Transform (IDFT)

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) W_N^{-nk}, \quad n = 0, 1, 2, \dots, N-1$$

Fast Fourier Transform

- Algorithms for DFT and IDFT can be made more efficient by exploiting symmetry and periodicity properties of W_N
 - Symmetry property: $W_N^{k+N/2} = -W_N^k$

$$\begin{aligned}W_N^{k+N/2} &= e^{-j2\pi(k+N/2)n/N} \\&= e^{-j2\pi kn/N} e^{-j2\pi(N/2)n/N} \\&= e^{-j2\pi kn/N} e^{-j\pi n} \\&= -e^{-j2\pi kn/N}\end{aligned}$$

$$W_N^{k+N/2} = -W_N^k$$

Fast Fourier Transform

- Algorithms for DFT and IDFT can be made more efficient by exploiting symmetry and periodicity properties of W_N

– Periodicity property: $W_N^{(k+N)n} = W_N^{k(n+N)} = W_N^{kn}$

$$\begin{aligned}W_N^{(k+N)n} &= e^{-j2\pi(k+N)n/N} \\&= e^{-j2\pi kn/N} e^{-j2\pi(N)n/N} \\&= e^{-j2\pi kn/N} e^{-j2\pi n} \\&= e^{-j2\pi kn/N}\end{aligned}$$

$$\begin{aligned}W_N^{k(n+N)} &= e^{-j2\pi k(n+N)/N} \\&= e^{-j2\pi kn/N} e^{-j2\pi k(N)/N} \\&= e^{-j2\pi kn/N} e^{-j2\pi k} \\&= e^{-j2\pi kn/N}\end{aligned}$$

$$W_N^{(k+N)n} = W_N^{k(n+N)} = W_N^{kn}$$

Fast Fourier Transform

- Algorithms for DFT and IDFT can be made more efficient by exploiting symmetry and periodicity properties of W_N

– Complex conjugate symmetry: $W_N^{k(N-n)} = W_N^{-kn} = (W_N^{kn})^*$

$$\begin{aligned} W_N^{k(N-n)} &= e^{-j2\pi k(N-n)/N} \\ &= e^{-j2\pi kN/N} e^{+j2\pi kn/N} \\ &= e^{-j2\pi k} e^{+j2\pi n/N} \\ &= e^{+j2\pi kn/N} \\ &= W_N^{-kn} = (W_N^{kn})^* \end{aligned}$$

$$W_N^{k(N-n)} = W_N^{-kn} = (W_N^{kn})^*$$

Fast Fourier Transform

– Other relationships for W_N

- If N can be factored into a product of integers: $N = LM$

$$W_N^{mqL} = e^{-j2\pi mqL/N} = e^{-j2\pi mq/(N/L)}$$

$$W_N^{mqL} = W_{N/L}^{mq} = W_M^{mq}$$

$$W_N^{Mpl} = e^{-j2\pi plM/N} = e^{-j2\pi pl/(N/M)}$$

$$W_N^{Mpl} = W_{N/M}^{pl} = W_L^{pl}$$

For N factored as $N = ML$

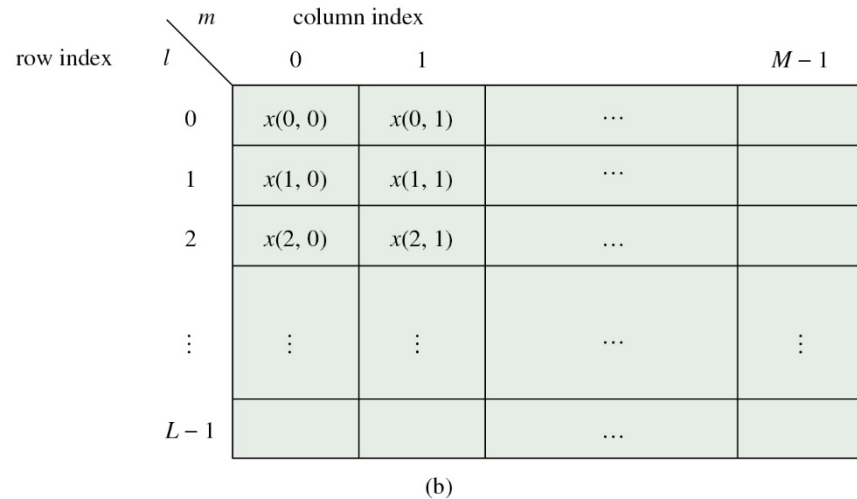
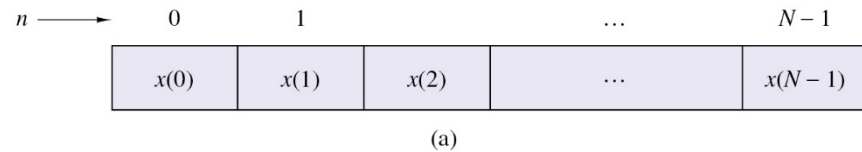
$$W_N^{mqL} = W_{N/L}^{mq} = W_M^{mq}$$

$$W_N^{Mpl} = W_{N/M}^{pl} = W_L^{pl}$$

for integers: m , q , p , and l

Fast Fourier Transform

- Divide and Conquer Algorithms
 - Consider the case where $N=ML$
 - Represent the input sequence $x[n]$ and output DFT $X[k]$ as 2-D arrays rather than linear sequences



Fast Fourier Transform

Map the sequence into $x(n) \rightarrow x(l, m)$: $n = l + mL$

Column-wise

$n = l + mL$

$l \backslash m$	0	1	2	...	$M-1$
0	$x(0)$	$x(L)$	$x(2L)$...	$x((M-1)L)$
1	$x(1)$	$x(L+1)$	$x(2L+1)$...	$x((M-1)L+1)$
2	$x(2)$	$x(L+2)$	$x(2L+2)$...	$x((M-1)L+2)$
...	\vdots	\vdots	\vdots	...	\vdots
$L-1$	$x(L-1)$	$x(2L-1)$	$x(3L-1)$...	$x(LM-1)$

(b)

Map the DFT into $X(k) \rightarrow X(p, q)$: $k = Mp + q$

Row-wise

$k = Mp + q$

$p \backslash q$	0	1	2	...	$M-1$
0	$X(0)$	$X(L)$	$X(2L)$...	$X((M-1)L)$
1	$X(M)$	$X(M+L)$	$X(M+2L)$...	$X((M-1)L+M)$
2	$X(2M)$	$X(2M+L)$	$X(2M+2L)$...	$X((M-1)L+2M)$
...	\vdots	\vdots	\vdots	...	\vdots
$L-1$	$X((L-1)M)$	$X((L-1)M+L)$	$X((L-1)M+2L)$...	$X(LM-1)$

(a)

Fast Fourier Transform

Transform with 1-D n, k :

$$X(k) = \sum_{n=0}^{N-1} x(n) W_N^{kn}$$

Transform with 2-D indices: $n = l + mL$; $k = Mq + p$

$$X(p, q) = \sum_{m=0}^{M-1} \sum_{l=0}^{L-1} x(l, m) W_N^{(Mp+q)(mL+l)}$$

$$W_N^{(Mp+q)(mL+l)} = W_N^{MLmp+mqL+Mpl+lq} = W_N^{MLmp} W_N^{mqL} W_N^{Mpl} W_N^{lq}$$

Take advantage of symmetry properties:

$$W_N^{MLmp} = W_N^{Nmp} = 1; \quad W_N^{mLq} = W_{N/L}^{mq} = W_M^{mq}; \quad W_N^{Mpl} = W_{N/M}^{pl} = W_L^{pl}$$

Fast Fourier Transform

Using $W_N^{MLmp} = 1$; $W_N^{mLq} = W_M^{mq}$; $W_N^{Mpl} = W_L^{pl}$

$$X(p, q) = \sum_{m=0}^{M-1} \sum_{l=0}^{L-1} x(l, m) W_N^{(Mp+q)(mL+l)} = \sum_{m=0}^{M-1} \sum_{l=0}^{L-1} x(l, m) W_M^{mq} W_L^{pl} W_N^{lq}$$

Rearranging:

$$X(p, q) = \sum_{l=0}^{L-1} W_N^{lq} \left[\sum_{m=0}^{M-1} x(l, m) W_M^{mq} \right] W_L^{pl}$$

Fast Fourier Transform

(Repeating the last equation from previous slide)

$$X(p, q) = \sum_{l=0}^{L-1} W_N^{lq} \left[\sum_{m=0}^{M-1} x(l, m) W_M^{mq} \right] W_L^{pl}$$

The innermost term is an M -point DFT over index m

$$F(l, q) = \sum_{m=0}^{M-1} x(l, m) W_M^{mq}, \quad 0 \leq q \leq M-1 \text{ for each row } l$$

The remaining sum is :

$$X(p, q) = \sum_{l=0}^{L-1} \left[W_N^{lq} F(l, q) \right] W_L^{pl}$$

is an L -point DFT over new array: $G(l, q) = W_N^{lq} F(l, q)$; $0 \leq l \leq L-1$; $0 \leq q \leq M-1$

Fast Fourier Transform

The final DFT is

$$X(p, q) = \sum_{l=0}^{L-1} G(l, q) W_L^{pl}$$

The linear index for the DFT is: $k = qL + p$

Fast Fourier Transform

- Have we done any good here?
- Remember, an N -point DFT requires N^2 multiplication and $N(N - 1)$ additions

$$X(k) = \sum_{n=0}^{N-1} x(n)W_N^{kn}$$

- Step 1 of the new algorithm finds L , m -point DFT's

$$F(l, q) = \sum_{m=0}^{M-1} x(l, m)W_M^{mq}$$

Number of multiplications: LM^2

Number of additions: $LM(M - 1)$

Fast Fourier Transform

- Step 2: (getting an $L \times M$ array)

$$G(l, q) = W_N^{lq} F(l, q) ; \quad 0 \leq l \leq L-1; \quad 0 \leq q \leq M-1$$

Number of multiplications: LM

Number of additions: none

- Step 3 (Finds M , L -point DFT's)

$$X(p, q) = \sum_{l=0}^{L-1} G(l, q) W_L^{pl}$$

Number of multiplications: ML^2

Number of additions: $ML(L-1)$

Fast Fourier Transform

- Total number of multiplications and additions:

Number of multiplications: $LM^2 + LM + ML^2 = ML(M + L + 1) = N(M + L + 1)$

Number of additions: $LM(M - 1) + 0 + ML(L - 1) = ML(M + L - 2) = N(M + L - 2)$

Comparison :

Multiplications: $N^2 \rightarrow N(M + L + 1)$

Additions: $N(N - 1) \rightarrow N(M + L - 2)$

Comparison : Example for $N = 1000$, $M = 500$, $L = 2$

Multiplications: $N^2 \rightarrow N(M + L + 1): 1,000,000 \rightarrow 503,000$

Additions: $N(N - 1) \rightarrow N(M + L - 2): 999,000 \rightarrow 500,000$

Fast Fourier Transform

- Previous algorithm shows how divide and conquer works, but it is not how the usual FFT works
 - Rather than a single factorization of N , factorize it many times and repeat the procedure.
 - Factors of: $N = r_1 r_2 \cdots r_\nu$
 - Radix algorithms for when N is a power of some value, $N = r^\nu$
 - Most common one is when N is a power of 2.
 - You can always pad a sequence to make this the case
 $N = 2^\nu$
 - Divide and conquer by recursively splitting sequence into 2 equal parts.
 - This will reduce computational complexity from $N^2 \rightarrow N \log_2 N$

Fast Fourier Transform

- Radix-2 FFT (decimation in time) Algorithm
 - For this algorithm, number of samples is a power of 2: $N = 2^v$
 - If it isn't you could pad it.
 - Start by dividing the sequence in 2: $M=N/2$; $L=2$

Separate sum into separate sums of even and odd elements of original sequence:

$$X(k) = \sum_{n=\text{even}} x(n)W_N^{kn} + \sum_{n=\text{odd}} x(n)W_N^{kn}$$

$$X(k) = \sum_{r=0}^{N/2-1} x(2r)W_N^{k(2r)} + \sum_{r=0}^{N/2-1} x(2r+1)W_N^{k(2r+1)}$$

even indices : $n = 2r$

odd indices : $n = 2r + 1$

$$r = 0, 1, \dots, \frac{N}{2} - 1$$

Fast Fourier Transform

$$X(k) = \sum_{r=0}^{N/2-1} x(2r)W_N^{k(2r)} + \sum_{r=0}^{N/2-1} x(2r+1)W_N^{k(2r+1)}$$

$$X(k) = \sum_{r=0}^{N/2-1} x(2r)W_N^{k(2r)} + W_N^k \sum_{r=0}^{N/2-1} x(2r+1)W_N^{k(2r)}$$

$$X(k) = \sum_{r=0}^{N/2-1} x(2r)W_{N/2}^{kr} + W_N^k \sum_{r=0}^{N/2-1} x(2r+1)W_{N/2}^{kr}$$

$N/2$ DFT of
even samples

$N/2$ DFT of
odd samples

$$X(k) = X_e(k) + W_N^k X_o(k) \leftarrow \text{Sum of 2 } N/2 \text{ point DFT's}$$

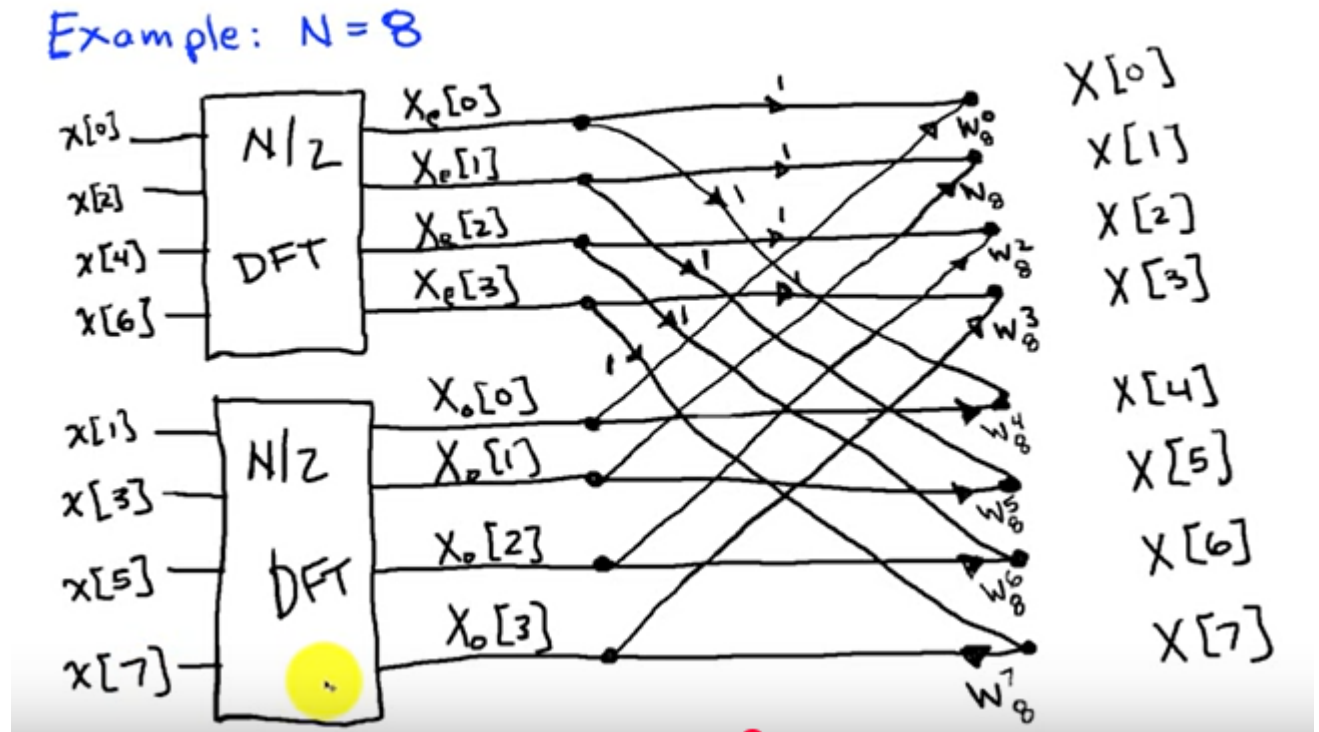
Fast Fourier Transform

$$X(k) = X_e(k) + W_N^k X_o(k)$$

Operation count:

$$2 \times \left(\frac{N}{2}\right)^2 + N = \frac{N^2}{2} + N \text{ multiplies}$$

Original without splitting would be N^2 multiplies



Fast Fourier Transform

You can keep splitting each of the $N/2$ sub-DFT's:

$$\text{Split } \frac{N}{2} \text{ DFT's} \rightarrow 2 \times \frac{N}{4}$$

$$\text{Split } \frac{N}{4} \text{ DFT's} \rightarrow 2 \times \frac{N}{8}$$

etc.

How many times can you split for $N = 2^p$?

$$\frac{N}{2}, \frac{N}{4}, \frac{N}{8}, \dots, \frac{N}{2^{p-1}}, \frac{N}{2^p}$$

$p = \log_2 N$ splits

Fast Fourier Transform

$$\frac{N}{2}, \frac{N}{4}, \frac{N}{8}, \dots, \frac{N}{2^{p-1}}, \frac{N}{2^p}$$

$p = \log_2 N$ splits

Operation count for multiplies:

$$1: \frac{N}{2} DFT's: 2 \left(\frac{N}{2} \right)^2 + N = \frac{N^2}{2} + N = \frac{N^2}{2^1} + N$$

$$2: \frac{N}{4} DFT's: 2 \left[2 \left(\frac{N}{4} \right)^2 + \frac{N}{2} \right] + N = \frac{N^2}{4} + 2N = \frac{N^2}{2^2} + 2N$$

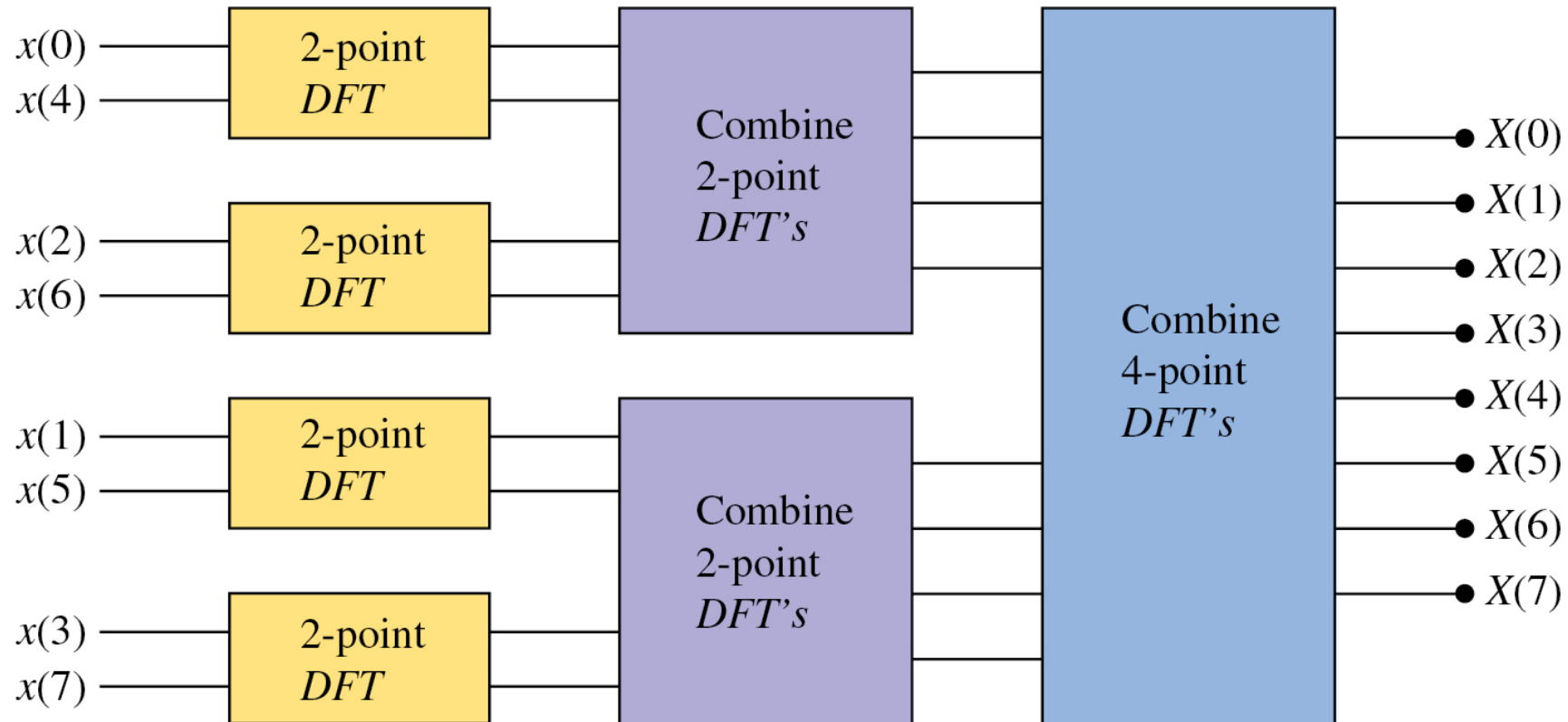
$$3: \frac{N}{8} DFT's: 2 \left\{ 2 \left[2 \left(\frac{N}{8} \right)^2 + \frac{N}{4} \right] + \frac{N}{2} \right\} + N = \frac{N^2}{8} + 3N = \frac{N^2}{2^3} + 3N$$

$$p: \frac{N}{2^p} DFT's \rightarrow \frac{N^2}{2^p} + 3N = \frac{N^2}{N} + pN = N + N \log_2 N$$

$\sim O(N \log_2 N) \text{ for large } N$

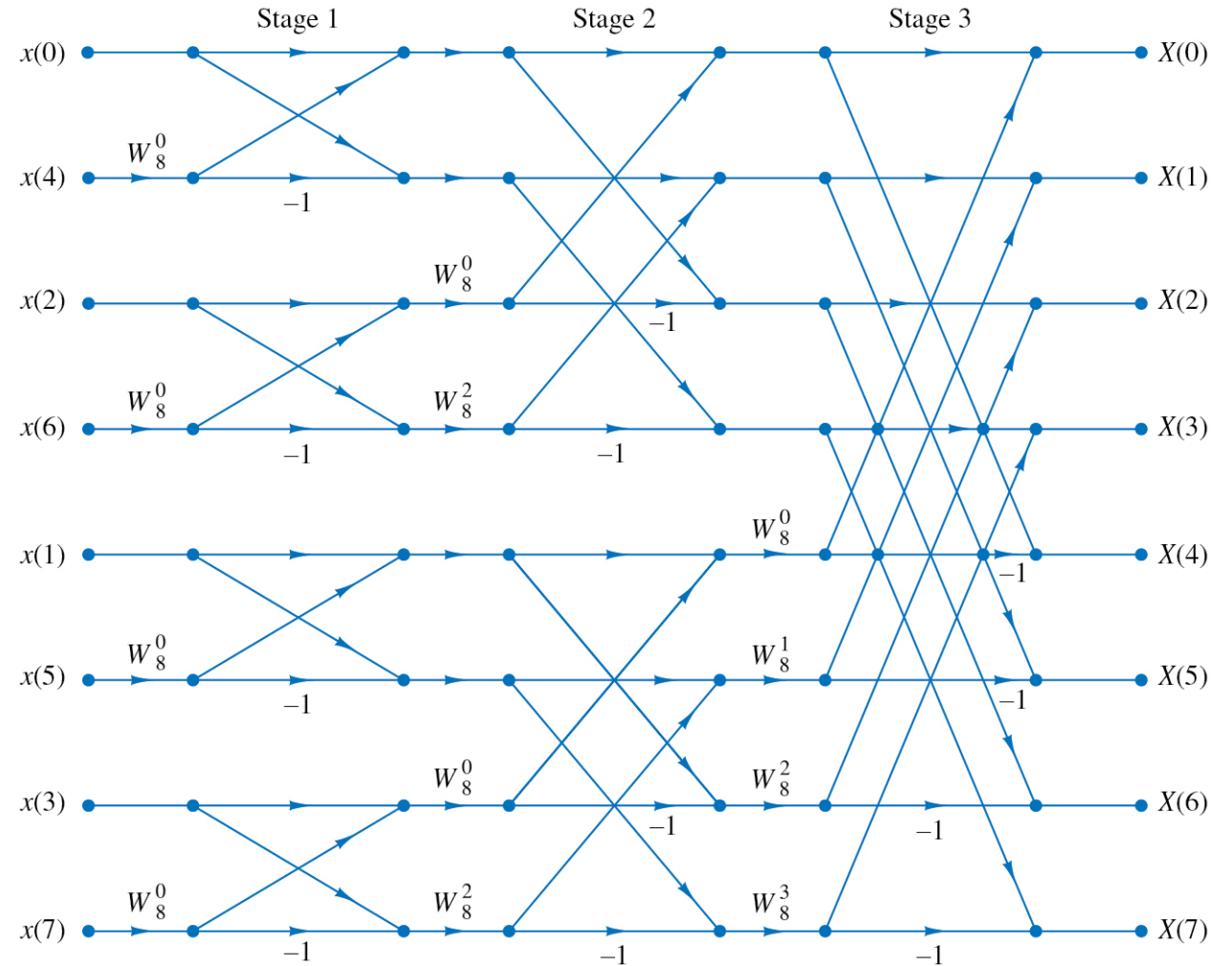
Fast Fourier Transform

Diagram for 3 stages of $N = 8$ point DFT



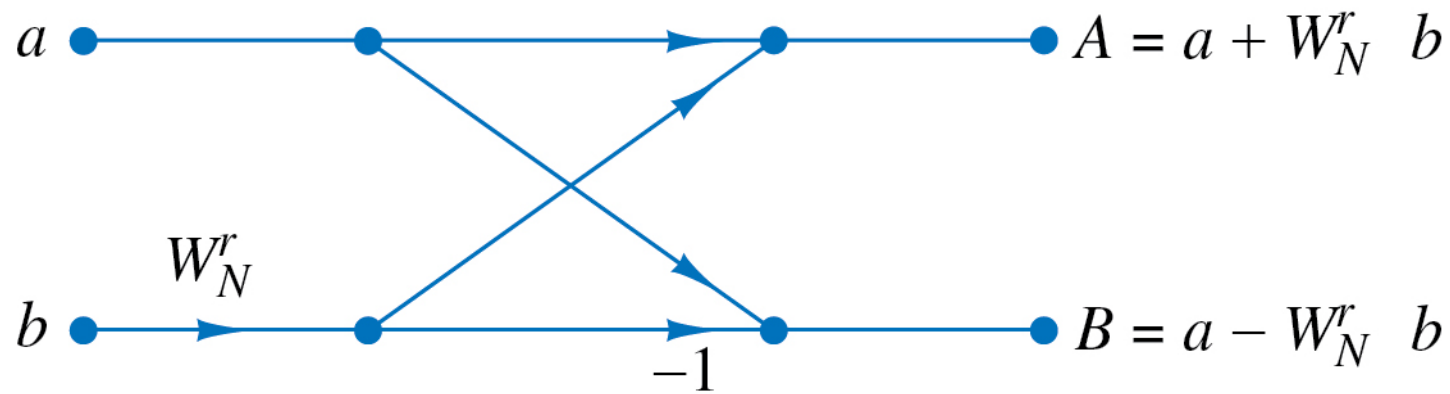
Fast Fourier Transform

Signal Flow Graph for $N = 8$ point DFT



Fast Fourier Transform

The basic operation that takes place at each stage is a "butterfly"



Fast Fourier Transform

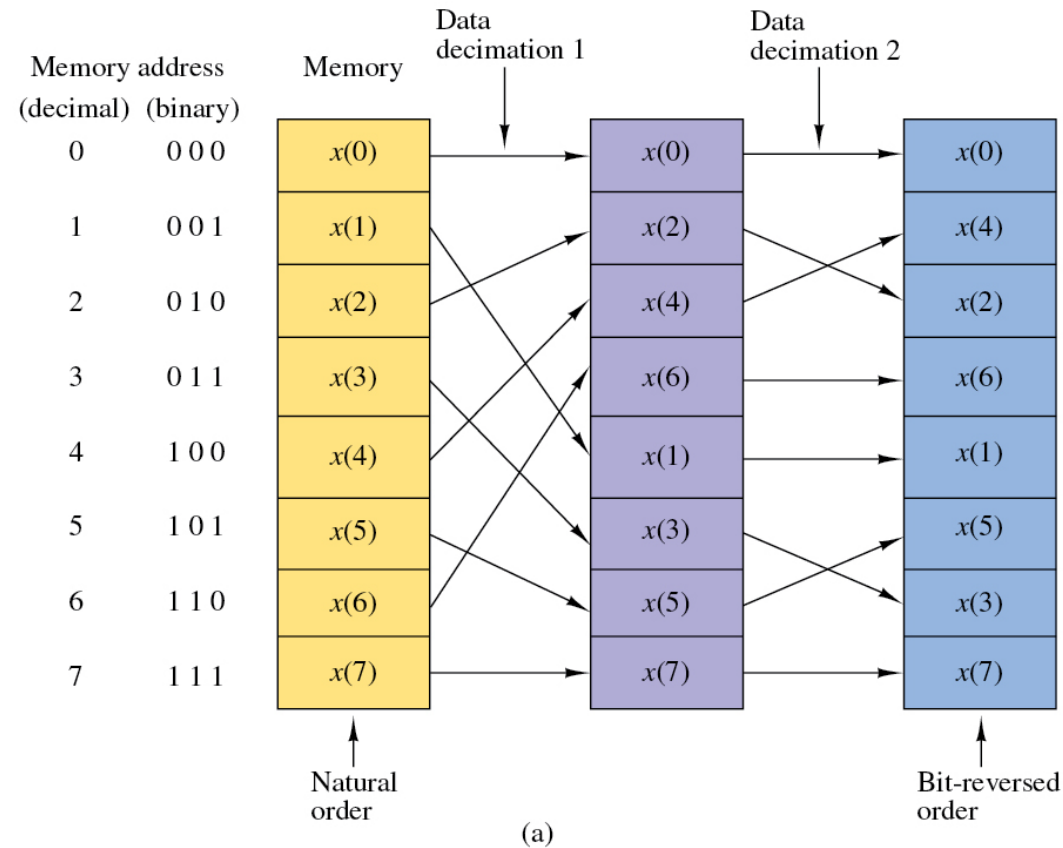
A careful operation count shows that there are $N/2$ butterflies at each stage and $\log_2 N$ stages

	Number of Points, N	Complex Multiplications in Direct Computation, N^2	Complex Multiplications in FFT Algorithm, $(N/2) \log_2 N$	Speed Improvement Factor
Multiplies: $\frac{N}{2} \log_2 N$	4	16	4	4.0
Additions: $N \log_2 N$	8	64	12	5.3
	16	256	32	8.0
	32	1,024	80	12.8
	64	4,096	192	21.3
	128	16,384	448	36.6
	256	65,536	1,024	64.0
	512	262,144	2,304	113.8
	1,024	1,048,576	5,120	204.8

If you had a signal with 10^9 samples, and it took 1 nsec per multiply.
DFT would take 31 years. FFT would take 30 sec.

Fast Fourier Transform

Notice that the order of the inputs is "weird" because of all of the sub-DFT suffling: $\{x(0), x(4), x(2), x(6), x(1), x(5), x(3), x(7)\}$



$(n_2 n_1 n_0)$	\rightarrow	$(n_1 n_0 n_2)$	\rightarrow	$(n_0 n_1 n_2)$
(0 0 0)	\rightarrow	(0 0 0)	\rightarrow	(0 0 0)
(0 0 1)	\rightarrow	(0 1 0)	\rightarrow	(1 0 0)
(0 1 0)	\rightarrow	(1 0 0)	\rightarrow	(0 1 0)
(0 1 1)	\rightarrow	(1 1 0)	\rightarrow	(1 1 0)
(1 0 0)	\rightarrow	(0 0 1)	\rightarrow	(0 0 1)
(1 0 1)	\rightarrow	(0 1 1)	\rightarrow	(1 0 1)
(1 1 0)	\rightarrow	(1 0 1)	\rightarrow	(0 1 1)
(1 1 1)	\rightarrow	(1 1 1)	\rightarrow	(1 1 1)

(b)

Fast Fourier Transform

- If you are into matrix stuff, another way to think of the radix-2 fft is as factorization of the W_N matrix
 - The fft becomes a product of $\log_2 N$ matrices where each matrix has only N non-zero elements
 - For an 8-point fft:

$$W_8 = (B_1 B_2 B_3) P_8$$

where P_8 reorders the inputs (bit-reversal)

Each B represents a butterfly

In general, FFT would be:

$$\mathbf{X} = (\mathbf{B}_{\log_2 N} \mathbf{L} \mathbf{B}_3 \mathbf{B}_2 \mathbf{B}_1) \mathbf{P}_N \mathbf{x}$$

Fast Fourier Transform

For $N = 8$, the bit-reversal permutation matrix is:

$$P_8 = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Second stage (Grouping pairs of 4)

$$B_2 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & W_8^1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & W_8^3 \\ 1 & 0 & 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & W_8^1 & 0 & 0 & 0 & -W_8^1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & W_8^3 & 0 & 0 & 0 & -W_8^3 \end{bmatrix}$$

First stage (Grouping pairs of 2)

$$B_1 = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & -1 \end{bmatrix}$$

Third stage (Final Combination)

$$B_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & W_8^1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & W_8^2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & W_8^3 \end{bmatrix}$$

Fast Fourier Transform

- There are several other FFT algorithms
 - The book covers a couple of others
 - The Matlab fft uses radix-2 if signal is power of 2
 - If not, and has a few small factors, uses a mixed radix algorithm
 - If the sequence has a prime number number of samples, it uses the Bluestein (or chirp-z) algorithm
- A good video on fft for reference:
 - <https://www.youtube.com/watch?v=lGCA1v3G8Oc>