# Kevin Matzen

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#### Education Cornell University

2010 - Expected 2016

Ph.D. in Computer Science - Advisors: Noah Snavely and Kavita Bala

Research Interests: Computer Vision, Computer Graphics, Robotics

 Extracting knowledge from large-scale Internet photo collections in order to automatically understand the visual world across space and time.

University of Michigan

2006 - 2010

BSE Computer Science Engineering; BSE Computer Engineering

Summa Cum Laude

Honors and Awards

**ECCV Best Paper Award** 

2014

Teaching Assistant Excellence Award

2010

Elected to Eta Kappa Nu - National EECS Honor Society

2007

Refereed **Publications**  Kevin Matzen, Noah Snavely, "BubbLeNet: Foveated imaging for visual discovery." In Proceedings of the International Conference on Computer Vision (ICCV), 2015.

Kevin Matzen, Noah Snavely, "Scene Chronology." In Proceedings of the European Conference on Computer Vision (ECCV), 2014. Best paper award.

Kevin Matzen, Noah Snavely. "NYC3DCars: A Dataset of 3D Vehicles in Geographic Context." In Proceedings of the International Conference on Computer Vision (ICCV), 2013.

#### Work Experience Google

Software Engineering Intern

Mountain View, CA

Summer 2015

Worked with the **Jump** camera team to develop new ways to capture emersive, 360 degree, stereoscopic video.

Google

Software Engineering Intern

Mountain View, CA

Summer 2014

Developed a computer vision system using Google Brain's distributed deep learning platform, Dist-Belief, to learn from the massive Street View image corpus.

Microsoft

Software Development Engineer Intern

Redmond, WA

Summer 2009

Designed, implemented, and tested .NET SDK features used in the first commercial release of Windows Azure as part of the Azure Developer Experience team. Examples include adding support for Azure Queue as a transport mechanism for Windows Communication Foundation's async task processing framework and rewriting some storage clients to reduce memory usage.

**National Instruments** 

Software Development Intern

Austin, TX

Summer 2008

Designed and implemented features to make it easier to use devices such as CompactRIO FPGAs and GE Fanuc reflective memory PCIe cards with NI LabVIEW and NI VeriStand (hardware-in-the-loop testing platform).

Aero-Metric, Inc.

Programming Intern

Sheboygan, WI

Summer 2007

Developed a flight tracking and project management system with Google Earth integration.

**Projects** 

Learning to Understand Visual Style in Large-scale Photo Collections 2014-Present Analyzing millions of social media photos of people to identify and learn style and fashion trends both geographically and temporally.

## Spatio-temporal Reconstruction for Large-scale Photo Collections

2013-2014

Robustly estimate visual change in urban scenes over time (e.g. billboards, signs, graffiti, etc.) to extend traditional 3D reconstructions to 4D.

Key result is a system that takes as input a keyword search such as "Times Square", collects millions of photos from Flickr, and produces an automated 4D reconstruction.

## Tightly Integrated Perception and Planning in Intelligent Robotics

2010-Present

Working to improve vehicle detection, pose estimation, and tracking by tightly integrating state-of-the-art vision and tracking techniques in a verifiable framework.

Work also includes sensor and embedded system development on Cornell's driverless car, Skynet.

Teaching Experience

#### Cornell Teaching Assistant

2010

**Experience** Teaching assistant for undergraduate computer vision course.

#### University of Michigan Instructional Assistant

2009

Instructional assistant for undergraduate operating systems course, EECS 482, for two semesters.

Professional Activities

#### Reviewer

3D Vision (3DV), Computer Vision and Pattern Recognition (CVPR), European Conference on Computer Vision (ECCV), International Conference on Computer Vision (ICCV), User Interface

Software and Technology (UIST)

Course Work

Machine Learning

Realistic Image Synthesis

Algorithms

Database Systems Computer Vision

Programming Languages

GPS Receiver Design Computational Motion

Data-Sparse Matrix Computation

**Popular Press** 

Scene Chronology

Featured in NewScientist

2014